



University of Minho
Department of Informatics



LABORATÓRIO DE INSTRUMENTAÇÃO E
FÍSICA EXPERIMENTAL DE PARTICULAS

EFFICIENT PROCESSING OF ATLAS EVENTS ANALYSIS IN HOMOGENEOUS AND HETEROGENEOUS PLATFORMS WITH ACCELERATOR DEVICES

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Overview

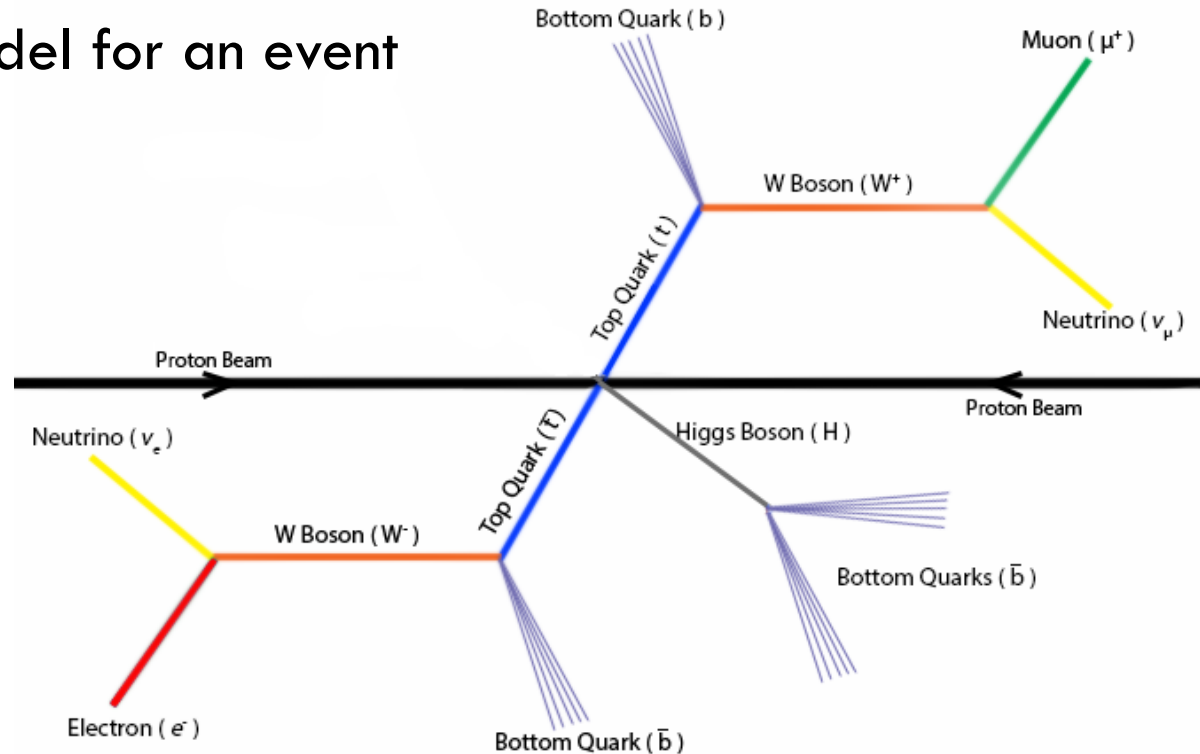
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- Motivation
- Structure of ttH_dilep
 - ▣ Analysis of critical regions
- Improving efficiency through parallelism
 - ▣ On shared memory homogeneous systems
 - ▣ On heterogeneous systems with a GPU accelerator
 - ▣ On heterogeneous systems with a MIC accelerator
 - ▣ Efficient data & workload scheduling

Motivation

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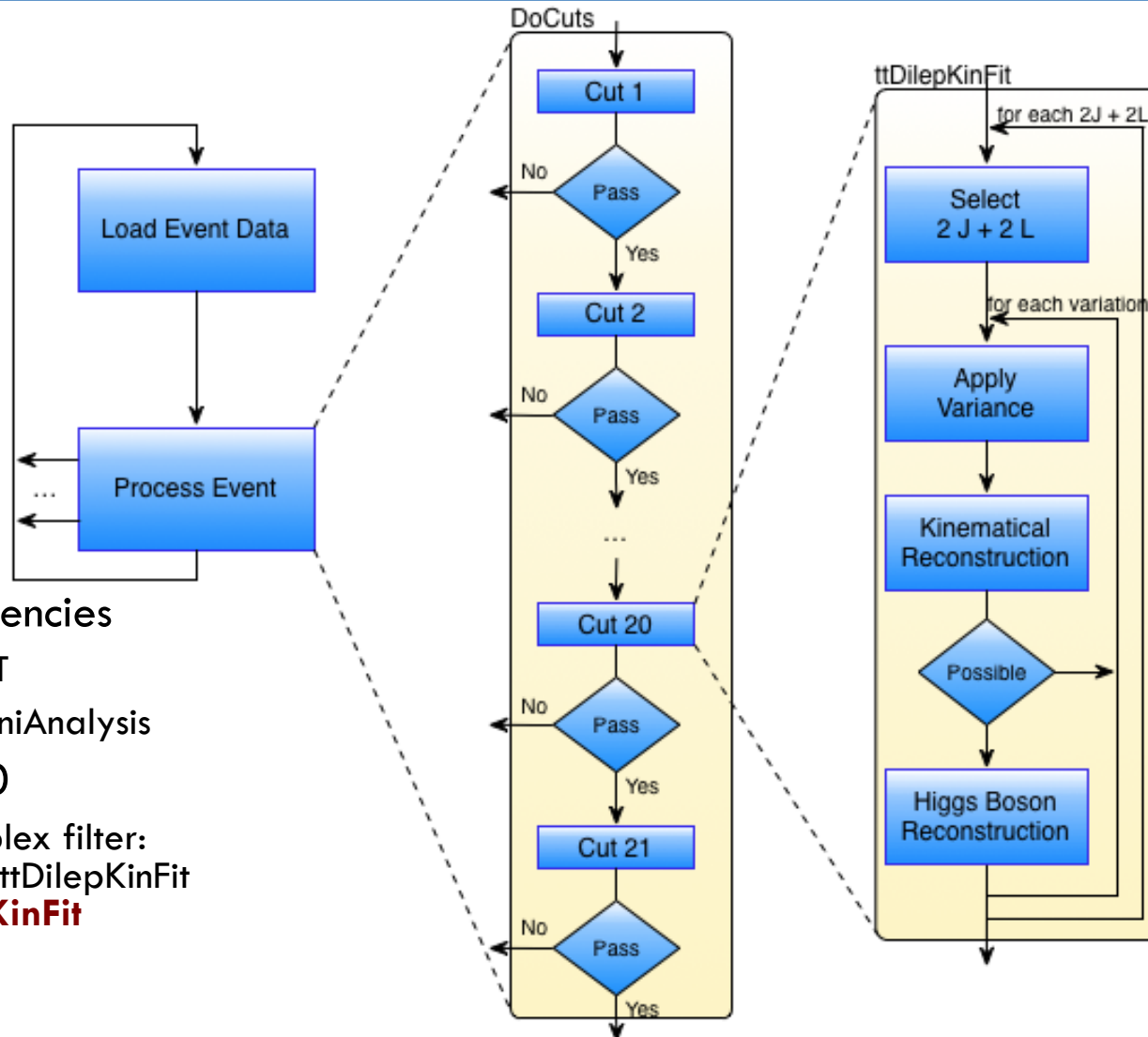
- The target model for an event



- Reconstruction of the Top Quarks ($t\bar{t}$) system with Higgs boson
 - the analysis and reconstruction code => `ttH_dilep`
- Goal: to improve the efficiency of `ttH_dilep`

Structure of ttH_dilep (3)

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Dependencies

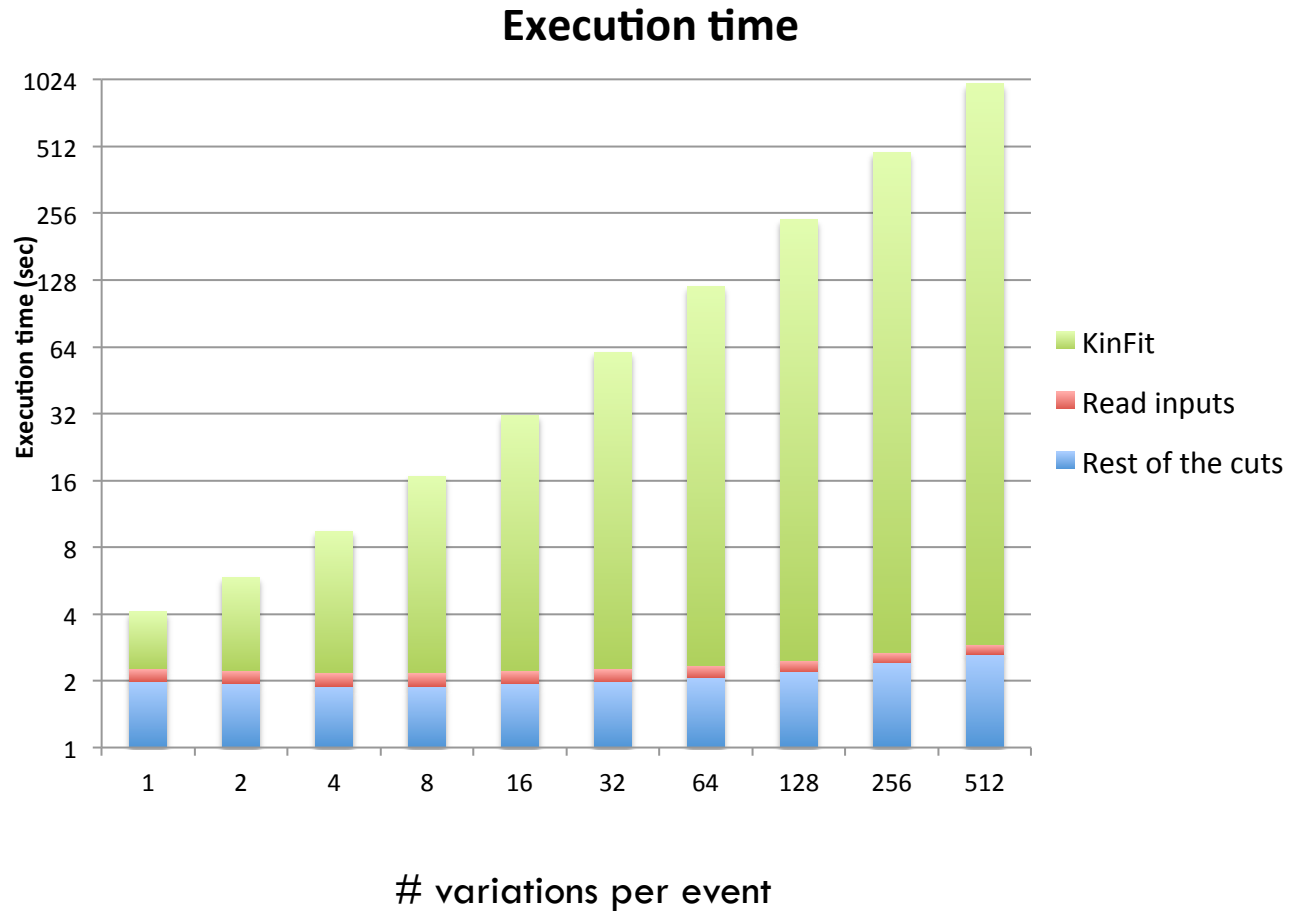
- ROOT
- LipMiniAnalysis

Cut #20

- Complex filter:
`ttDilepKinFit`
aka **KinFit**

Critical regions

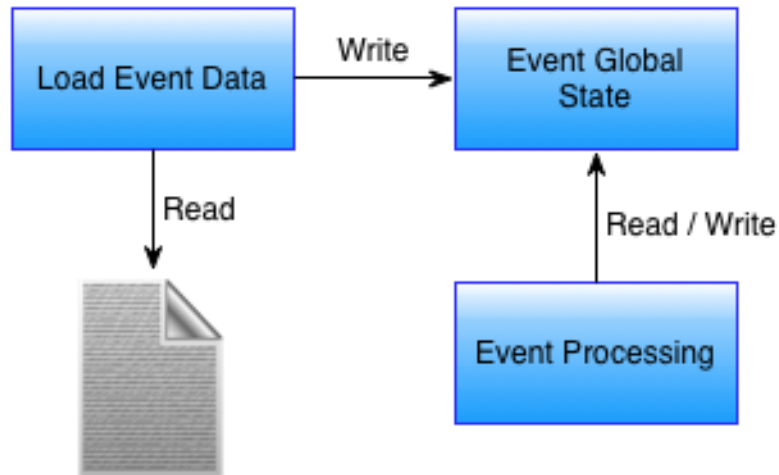
5



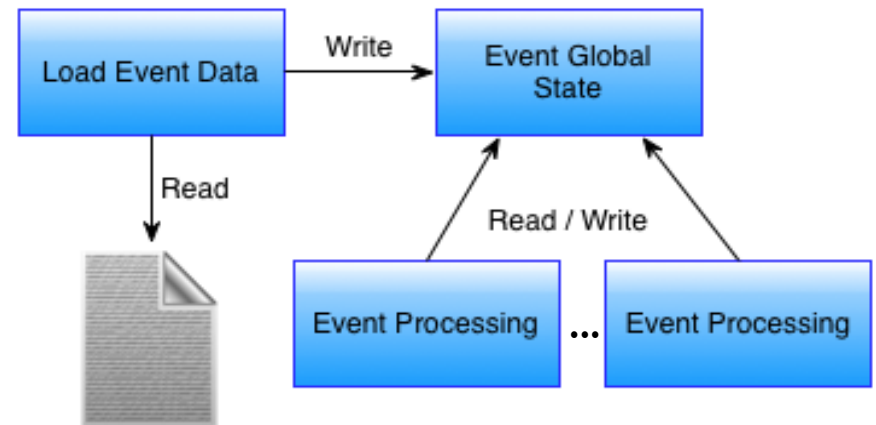
Improving efficiency with parallelism...

6

Sequential



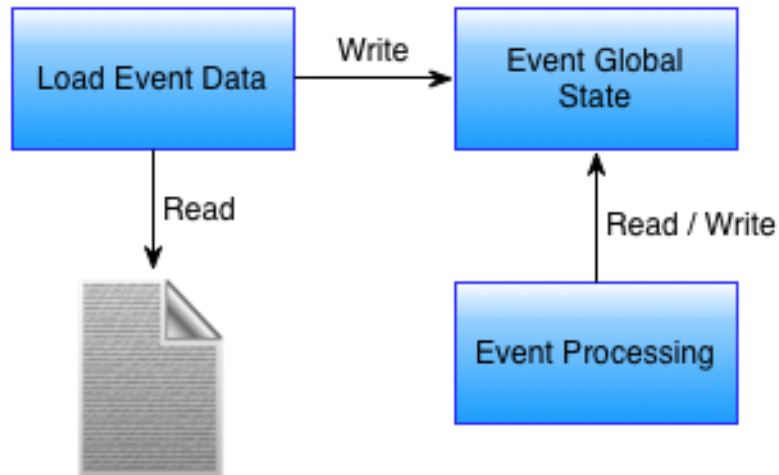
Parallel



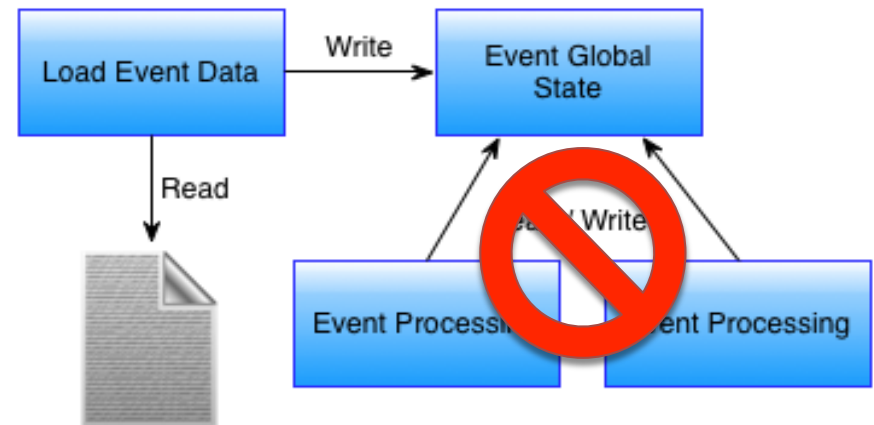
... no way with single global state!

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Sequential



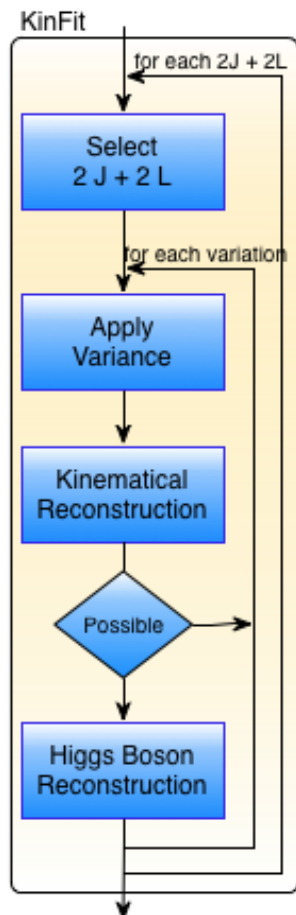
Parallel



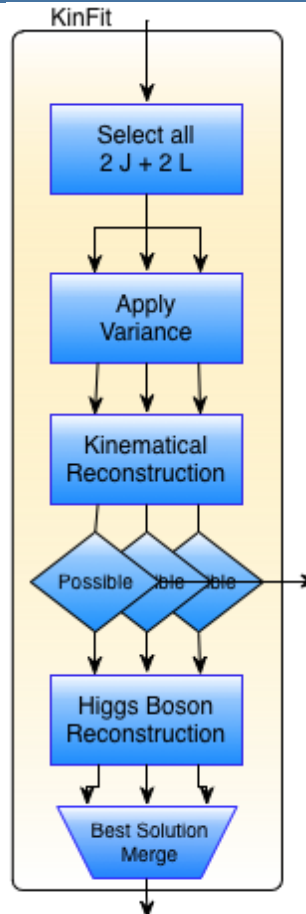
Approach 1: parallelize KinFit, shared memory, no h/w accelerators

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Sequential



Parallel



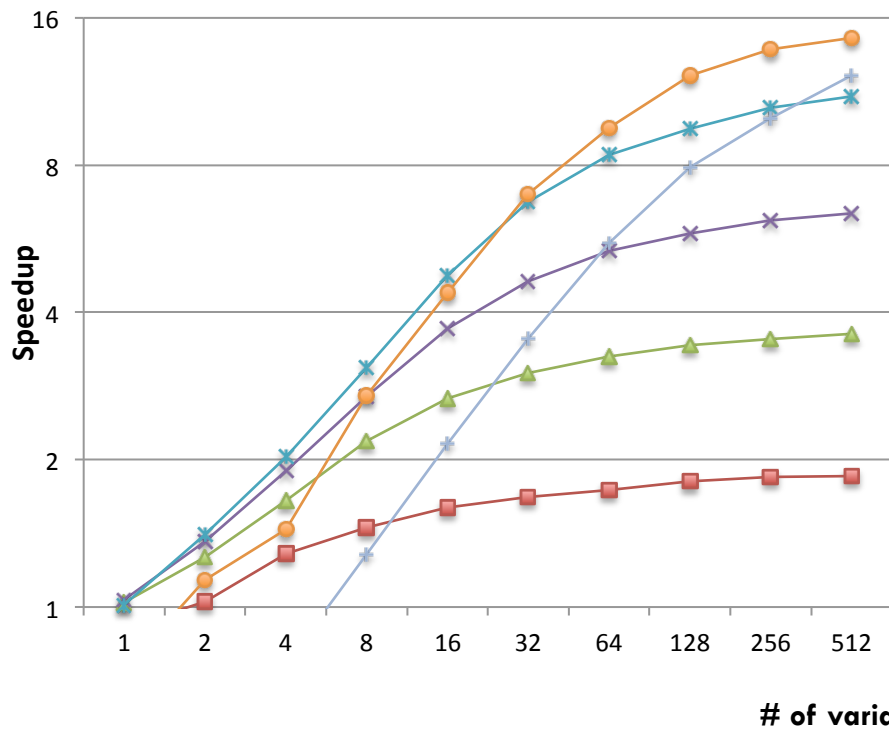
- Selects all sets of 2 jets & 2 leptons, and builds a new data structure for each set
- In parallel:
 - applies a tolerance (variation) to each measure
 - performs a kinematical and Higgs boson reconstructions
 - selects the best solution (reduction)
- The new data structure:
 - all data are replicated; or
 - common data share a pointer

Performance analysis (1)

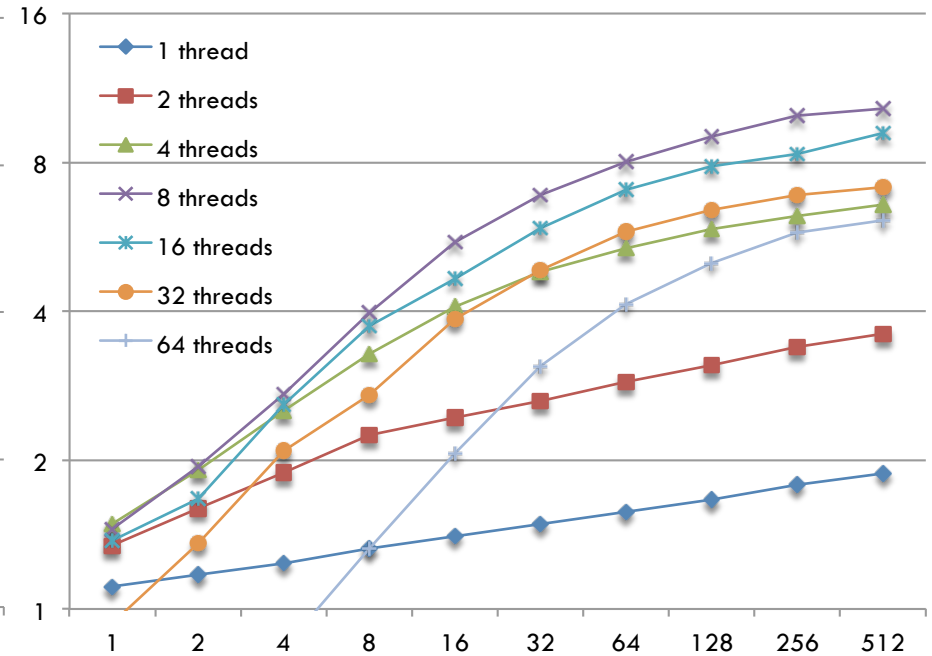
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System: 2 x Intel E5-2670 (total 16 cores, 32 threads)

All data replicated



Pointer to shared data

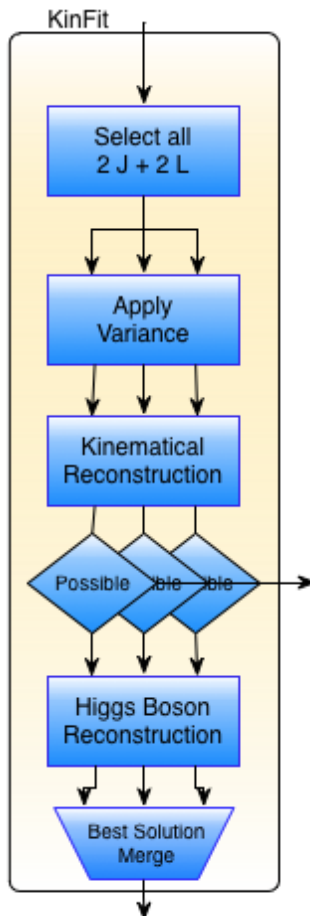


Plots: speedup *versus* the original sequential version

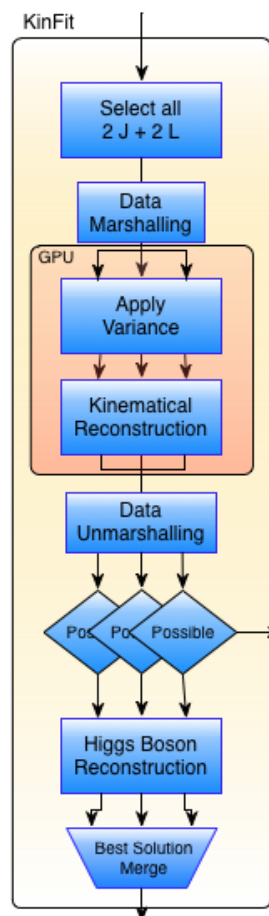
Approach 2: parallelize KinFit, with GPU accelerator (distributed memory)

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Parallel, no accelerator



Parallel: multicore + GPU

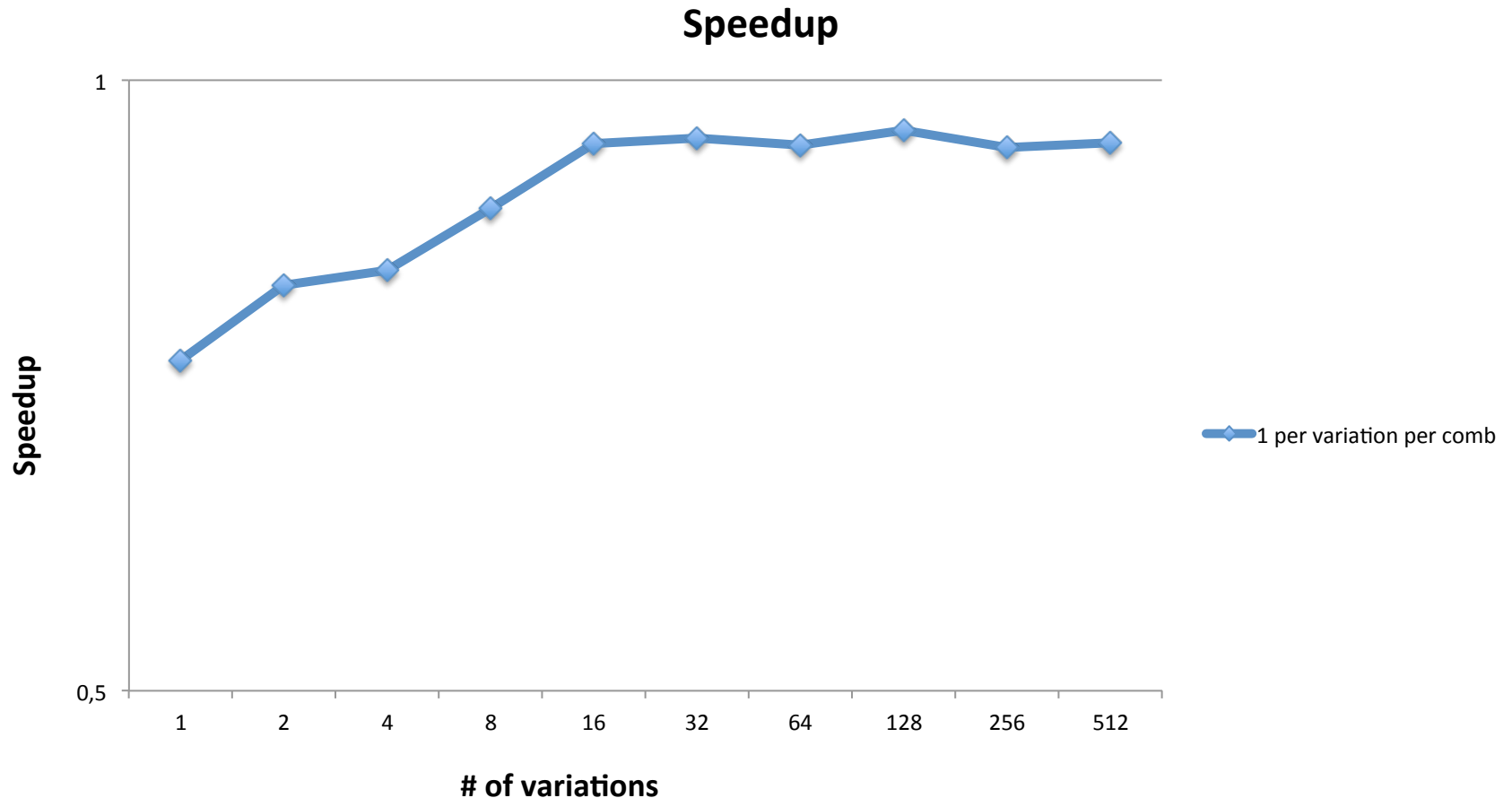


- Data (un)marshalling:
- Transform ROOT (and application classes) in arrays to transfer to and from the GPU
- In the GPU:
 - Apply the variance on the inputs
 - Perform the kinematical reconstruction
- Parallel reconstruction of the Higgs boson on CPU

Performance analysis (1)

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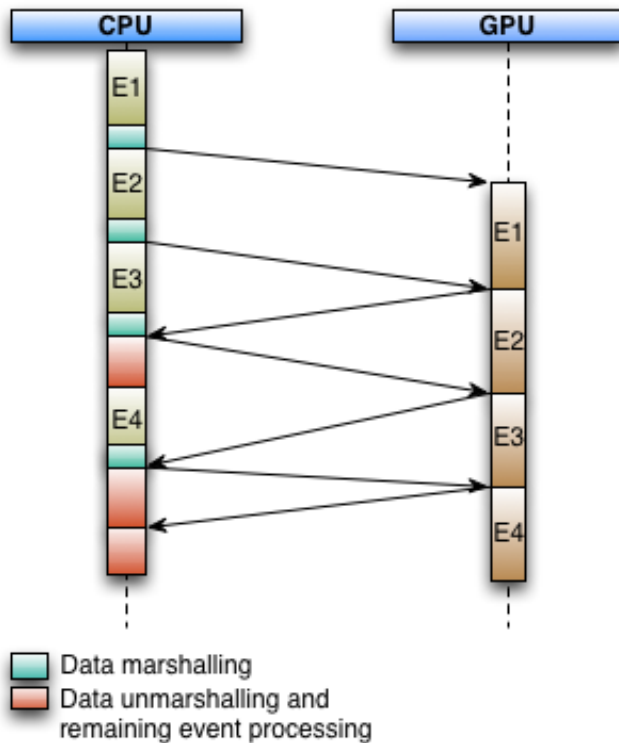
System: 2 x AMD Opteron 6174 (total 24 cores) and NVidia Tesla Fermi C2050 GPU



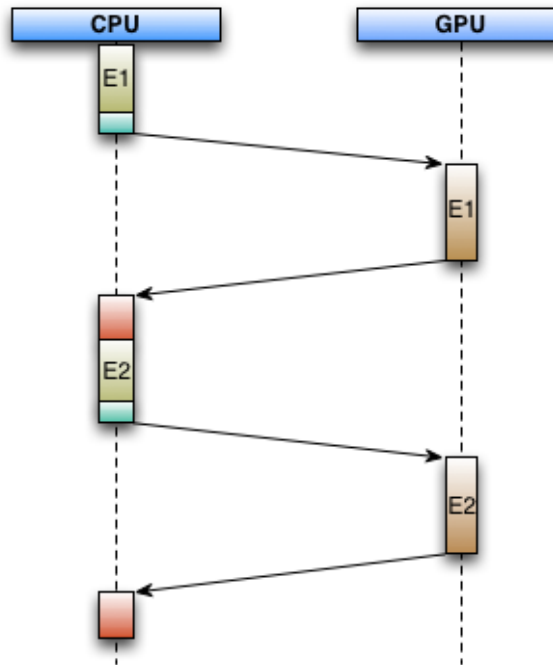
Performance analysis (2)

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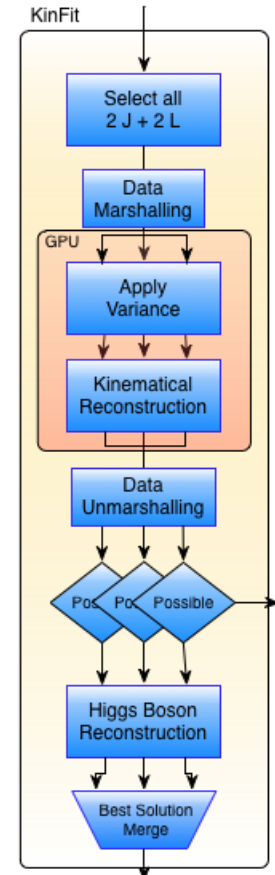
Ideal execution



Current execution



For 256 variations the
CPU is idle
31% of the time...

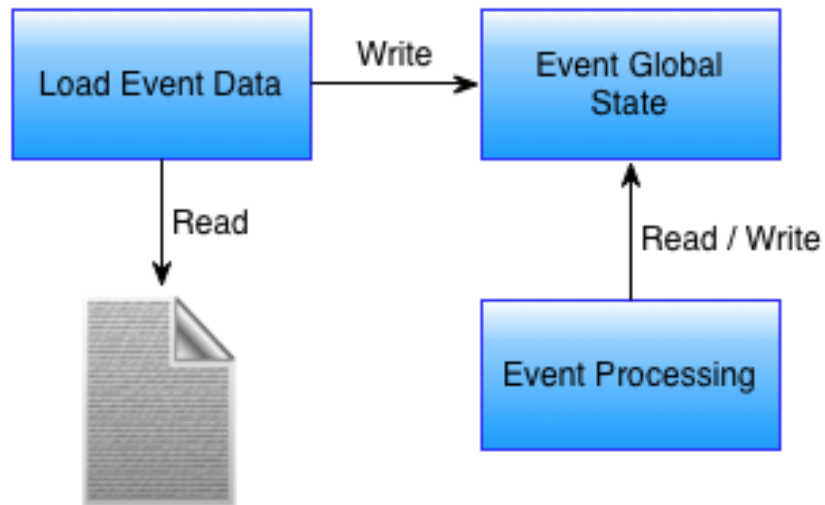


A single global state
prevents simultaneous
CPU & GPU processing

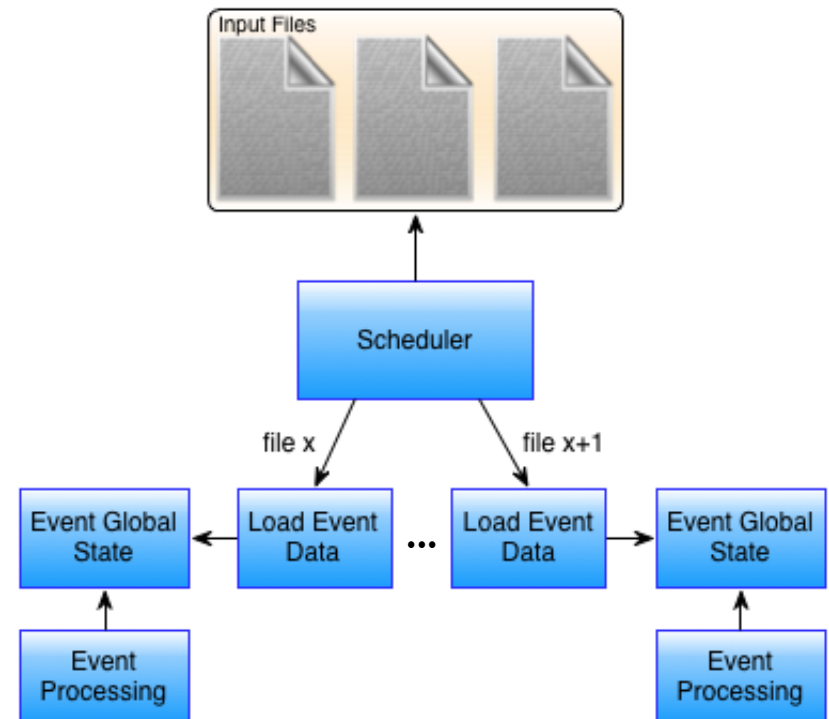
Approach 3: events from different files

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Sequential



Parallel

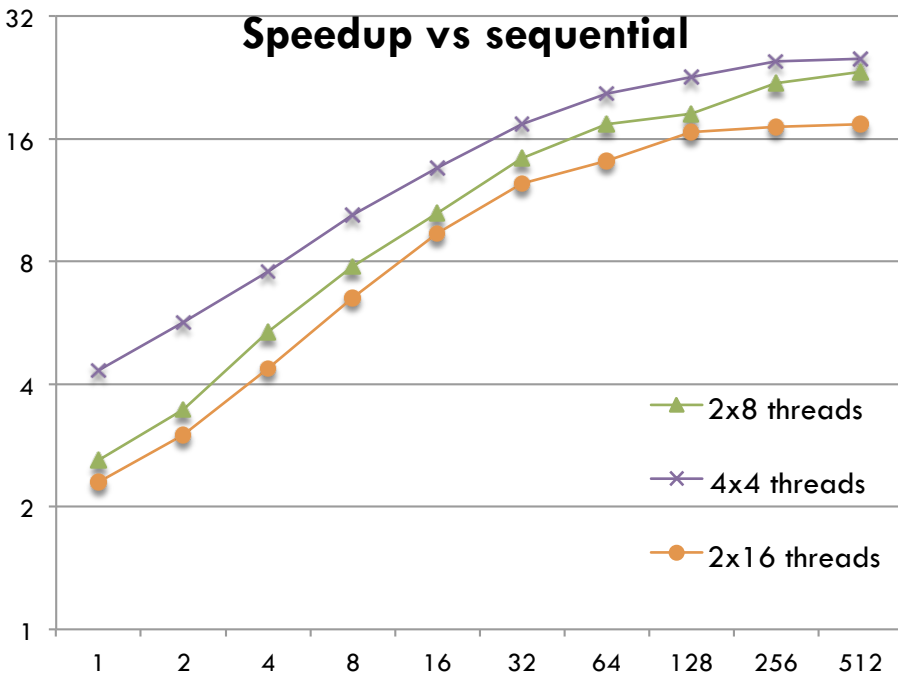


Performance analysis (1)

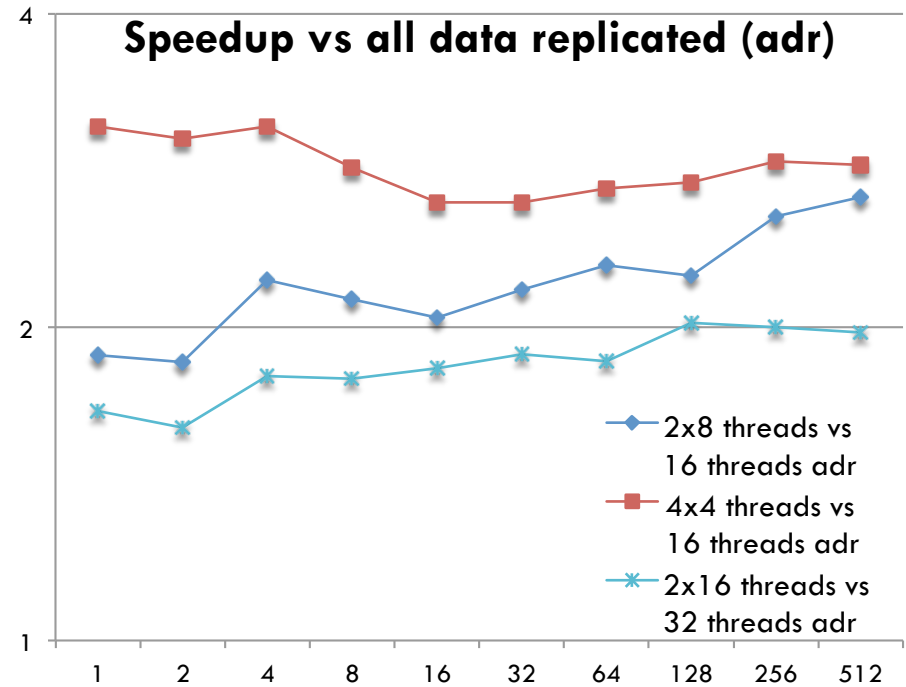
14

System: 2x Intel E5-2670 (total 16 cores, 32 threads)

Speedup vs sequential



Speedup vs all data replicated (adr)



of variations

Conclusions

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□ Homogeneous systems

- ▣ All data replicated provides the best performance (multiple CPUs)
- ▣ Pointer to shared data provides the best efficiency (single CPU)

□ Heterogeneous systems

- ▣ Unefficient GPU usage due to the lack of a global data structure
- ▣ Xeon Phi preliminary implementation limited by the drivers

□ Scheduler provides the best efficiency for multi-CPU systems

- ▣ Allied to a parallelization of LipMiniAnalysis a tool can be developed that automatically extracts parallelism



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