

HW7

1

1.1 Adams Bashforth

1.1.1 1 step

$$\begin{aligned}\sigma(\zeta) &= 1 \\ \rho(\zeta) &= \zeta - 1\end{aligned}$$

1.1.2 2 step

$$\begin{aligned}\sigma(\zeta) &= \frac{-1}{2} + \frac{3}{2}\zeta \\ \rho(\zeta) &= \zeta^2 - \zeta\end{aligned}$$

1.1.3 3 step

$$\begin{aligned}\sigma(\zeta) &= \frac{5}{12} - \frac{16}{12}\zeta + \frac{23}{12}\zeta^2 \\ \rho(\zeta) &= \zeta^3 - \zeta^2\end{aligned}$$

1.2 Adams Moulton

1.2.1 1 step

$$\begin{aligned}\sigma(\zeta) &= \frac{1}{2} + \frac{1}{2}\zeta \\ \rho(\zeta) &= \zeta - 1\end{aligned}$$

1.2.2 2 step

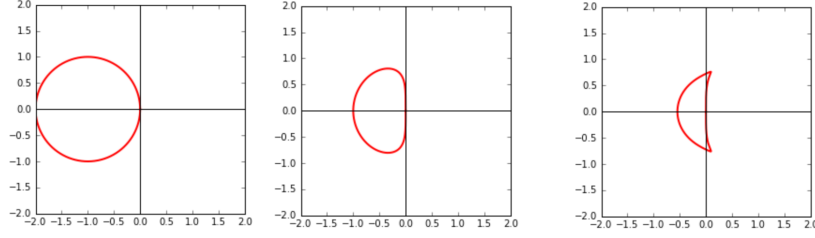
$$\begin{aligned}\sigma(\zeta) &= \frac{1}{12}(-1 + 8\zeta + 5\zeta^2) \\ \rho(\zeta) &= \zeta^2 - \zeta\end{aligned}$$

1.2.3 3 step

$$\begin{aligned}\sigma(\zeta) &= \frac{1}{24}(1 - 5\zeta + 19\zeta^2 + 9\zeta^3) \\ \rho(\zeta) &= \zeta^3 - \zeta^2\end{aligned}$$

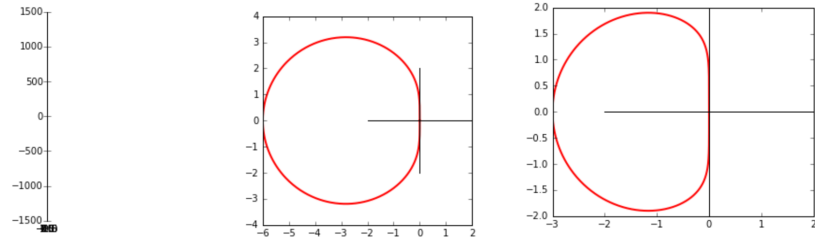
1.3

Adam-Bashforth figures



They are ordered, 1-, 2-, and 3- step.

Adam-Moulton figures



They are ordered, 1-, 2-, and 3-step.

Region of stability decreases as accuracy increases. Region of stability by the way is within the red shapes. For the Adam-Moulton 1 step I believe it is the entire left side of the axis.

2 Crank Nicolson LTE

$$\begin{aligned} \frac{U_i^{n+1} - U_i^n}{k} &= \frac{1}{2}D^2U_i^n + \frac{1}{2}D^2U_i^{n+1} \\ D^2U &= \frac{1}{h^2}(U(\bar{x} - h) - 2U(\bar{x}) + U(\bar{x} + h)) \\ \tau &= \frac{U(x, t+k) - U(x, t)}{k} - \frac{1}{2h^2}(U(x-h, t) - 2U(x, t) + U(x+h, t)) \\ &\quad - \frac{1}{2h^2}(U(x-h, t+k) - 2U(x, t+k) + U(x+h, t+k)) \end{aligned}$$

Expansions:

$$\begin{aligned} U(x+h, t) &= U(x, t) + hU_x(x, t) + \frac{h^2}{2}U_{xx}(x, t) + \frac{h^3}{3!}U_{xxx}(x, t) + \frac{h^4}{4!}U_{xxxx}(x, t) + \mathcal{O}(h^5) \\ U(x, t) &= U(x, t) \\ U(x-h, t) &= U(x, t) - hU_x(x, t) + \frac{h^2}{2}U_{xx}(x, t) - \frac{h^3}{3!}U_{xxx}(x, t) + \frac{h^4}{4!}U_{xxxx}(x, t) + \mathcal{O}(h^5) \end{aligned}$$

Expansions:

$$\begin{aligned}
U(x+h, t+k) &= U(x, t) + hU_x(x, t) + kU_t(x, t) + \frac{h^2}{2}U_{xx}(x, t) + \frac{k^2}{2}U_{tt}(x, t) + hkU_{tx}(x, t) + \frac{h^3}{6}U_{xxx}(x, t) \\
&\quad + \frac{h^2k}{2}U_{xxt}(x, t) + \frac{hk^2}{2}U_{xtt}(x, t) + \frac{k^3}{6}U_{ttt}(x, t) + \mathcal{O} \\
U(x-h, t+k) &= U(x, t) - hU_x(x, t) + kU_t(x, t) + \frac{h^2}{2}U_{xx}(x, t) + \frac{k^2}{2}U_{tt}(x, t) - hkU_{tx}(x, t) \\
&\quad - \frac{h^3}{6}U_{xxx}(x, t) + \frac{h^2k}{2}U_{xxt}(x, t) - \frac{hk^2}{2}U_{xtt}(x, t) + \frac{k^3}{6}U_{ttt}(x, t) + \mathcal{O}
\end{aligned}$$

Expansions:

$$\begin{aligned}
U(x, t+k) &= U(x, t) + kU_t(x, t) + \frac{k^2}{2}U_{tt}(x, t) + \frac{k^3}{3!}U_{ttt}(x, t) + \frac{k^4}{4!}U_{tttt}(x, t) + \mathcal{O}(k^5) \\
\tau &= \frac{U(x, t) + kU_t(x, t) + \frac{k^2}{2}U_{tt}(x, t) + \frac{k^3}{3!}U_{ttt}(x, t) + \frac{k^4}{4!}U_{tttt}(x, t) + \mathcal{O}(h^5) - U(x, t)}{k} \\
&\quad - \frac{1}{2h^2}(U(x-h, t) - U(x, t) + U(x+h, t)) - \frac{1}{2h^2}(U(x-h, t+k) - U(x, t+k) + U(x+h, t+k)) \\
&\quad = \frac{kU_t(x, t) + \frac{k^2}{2}U_{tt}(x, t) + \frac{k^3}{3!}U_{ttt}(x, t) + \frac{k^4}{4!}U_{tttt}(x, t) + \mathcal{O}(k^5)}{k} \\
&\quad - \frac{1}{2h^2}(U(x-h, t) - U(x, t) + U(x+h, t)) - \frac{1}{2h^2}(U(x-h, t+k) - U(x, t+k) + U(x+h, t+k))
\end{aligned}$$

In the interest of saving space just focus on this part:

$$\begin{aligned}
&U(x-h, t) - 2U(x, t) + U(x+h, t) \\
&= U(x, t) - hU_x(x, t) + \frac{h^2}{2}U_{xx}(x, t) - \frac{h^3}{3!}U_{xxx}(x, t) + \frac{h^4}{4!}U_{xxxx}(x, t) - 2U(x, t) \\
&\quad + U(x, t) + hU_x(x, t) + \frac{h^2}{2}U_{xx}(x, t) + \frac{h^3}{3!}U_{xxx}(x, t) + \frac{h^4}{4!}U_{xxxx}(x, t) + \mathcal{O}(h^5) \\
&= h^2U_{xx}(x, t) + \frac{h^4}{12}U_{xxxx}(x, t) + \mathcal{O}(h^5)
\end{aligned}$$

In the interest of saving space just focus on this part:

$$\begin{aligned}
&U(x-h, t+k) - 2U(x, t+k) + U(x+h, t+k) \\
&= U(x, t) - hU_x(x, t) + kU_t(x, t) + \frac{h^2}{2}U_{xx}(x, t) + \frac{k^2}{2}U_{tt}(x, t) - hkU_{tx}(x, t) \\
&\quad - \frac{h^3}{6}U_{xxx}(x, t) + \frac{h^2k}{2}U_{xxt}(x, t) - \frac{hk^2}{2}U_{xtt}(x, t) + \frac{k^3}{6}U_{ttt}(x, t) - 2U(x, t) - 2kU_t(x, t) - \frac{2k^2}{2}U_{tt}(x, t) - \\
&\quad \frac{2k^3}{3!}U_{ttt}(x, t) - \frac{2k^4}{4!}U_{tttt}(x, t) + U(x, t) + hU_x(x, t) + kU_t(x, t) + \frac{h^2}{2}U_{xx}(x, t) + \frac{k^2}{2}U_{tt}(x, t) + hkU_{tx}(x, t) \\
&\quad + \frac{h^3}{6}U_{xxx}(x, t) + \frac{h^2k}{2}U_{xxt}(x, t) + \frac{hk^2}{2}U_{xtt}(x, t) + \frac{k^3}{6}U_{ttt}(x, t) + \mathcal{O}
\end{aligned}$$

$$= h^2 U_{xx}(x, t) + h^2 k U_{xxt}(x, t) + \mathcal{O}$$

I added in higher order terms just incase and already crossed them out.

$$= h^2 U_{xx}(x, t) + h^2 k U_{xxt}(x, t) + \frac{h^4}{12} U_{xxxx}(x, t) + \frac{h^2 k^2}{2} U_{xxtt}(x, t) + \mathcal{O}$$

Back to the main equation:

$$= U_t(x, t) + \frac{k}{2} U_{tt}(x, t) + \frac{k^2}{3!} U_{ttt}(x, t) + \frac{k^3}{4!} U_{tttt}(x, t) - \frac{1}{2h^2} (h^2 U_{xx}(x, t) + \frac{h^4}{12} U_{xxxx}(x, t)) - \frac{1}{2h^2} (h^2 U_{xx}(x, t) + h^2 k U_{xxt}(x, t) + \frac{h^4}{12} U_{xxxx}(x, t) + \frac{h^2 k^2}{2} U_{xxtt}(x, t) + \mathcal{O})$$

I took out all the terms that don't have a h or k in front of it because it won't contribute to LTE.

$$= U_t(x, t) + \frac{k}{2} U_{tt}(x, t) + \frac{k^2}{3!} U_{ttt}(x, t) + \frac{k^3}{4!} U_{tttt}(x, t) - \frac{1}{2} (U_{xx}(x, t) + \frac{h^2}{12} U_{xxxx}(x, t)) - \frac{1}{2} (U_{xx}(x, t) + k U_{xxt}(x, t) + \frac{h^2}{12} U_{xxxx}(x, t) + \frac{k^2}{2} U_{xxtt}(x, t) + \mathcal{O})$$

Then I used the fact that $U_t = U_{xx}$ so $U_{tt} = U_{xxt}$

$$= \frac{k^2}{3!} U_{ttt}(x, t) + \frac{k^3}{4!} U_{tttt}(x, t) - \frac{1}{2} (\frac{h^2}{12} U_{xxxx}(x, t)) - \frac{1}{2} (\frac{h^2}{12} U_{xxxx}(x, t) + \frac{k^2}{2} U_{xxtt}(x, t) + \mathcal{O})$$

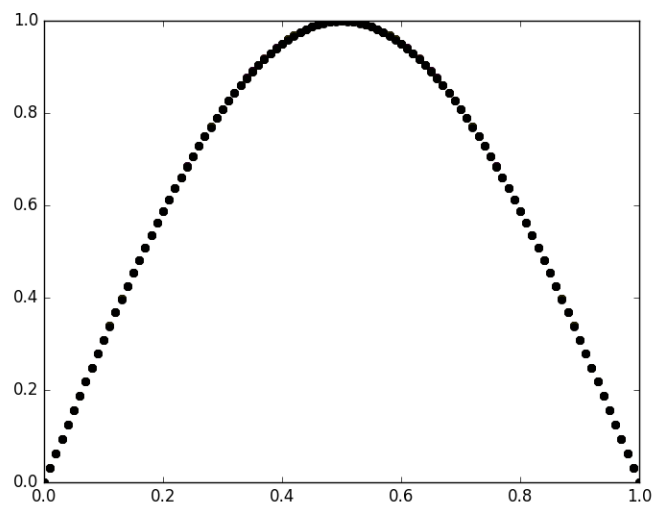
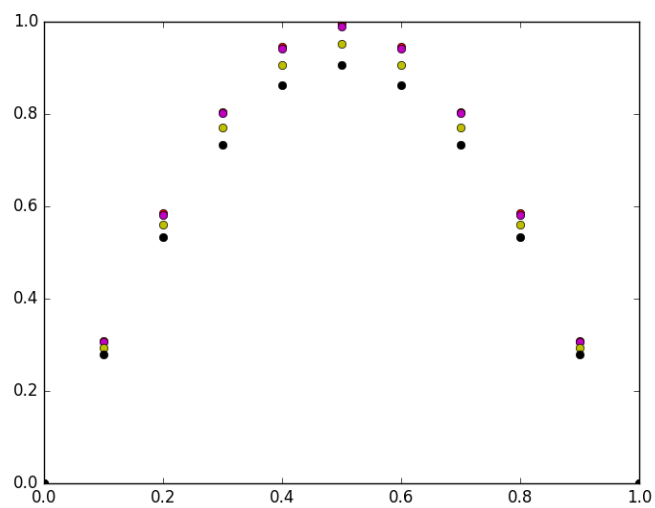
Therefore error is of order $\mathcal{O}(h^2 + k^2)$.

3 Solve equations using MOL

Stability condition is below

$$\frac{k}{h^2} \leq \frac{1}{2}$$

For given $h=0.1$, $k_{max} = 0.005$. For given $h=0.01$, $k_{max} = 0.00005$



Points are extremely close together in the 2nd graph. Pictured here is the graph of $U(x,t)$ (Temperature equation?) for different t . The same t values were used for the 1st and second graph.