





Using KNITRO for AMPL

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INFORMS Conference on Business Analytics & Operations Research

Chicago — April 10-12, 2011 — Ziena Workshop

Example: Traffic Network

Given

- *N* Set of nodes representing intersections
- *e* Entrance to network
- f Exit from network
- $A \subseteq N \cup \{e\} \times N \cup \{f\}$

Set of arcs representing road links

and

- b_{ii} Base travel time for each road link $(i,j) \in A$
- c_{ii} Capacity for each road link $(i,j) \in A$
- s_{ij} Traffic sensitivity for each road link $(i,j) \in A$
- *T* Desired throughput from *e* to *f*

Example: Traffic Network

Determine

 x_{ij} Traffic flow through road link $(i,j) \in A$

 t_{ij} Actual travel time on road link $(i,j) \in A$

to minimize

$$\Sigma_{(i,j)\in A} t_{ij} x_{ij}/T$$

Average travel time from *e* to *f*

Example: Traffic Network

Subject to
$$t_{ij} = b_{ij} + \frac{s_{ij}x_{ij}}{1 - x_{ij}/c_{ij}} \quad \text{for all } (i,j) \in A$$

Travel times increase as flow approaches capacity

$$\Sigma_{(i,j)\in A} x_{ij} = \Sigma_{(j,i)\in A} x_{ji}$$
 for all $i \in N$

Flow out equals flow in at any intersection

$$\Sigma_{(e,j)\in A} x_{ej} = T$$

Flow into the entrance equals the specified throughput

Traffic network: symbolic data

Algebraic modeling language: symbolic model

```
var Flow {(i,j) in ROADS} >= 0, <= .9999 * cap[i,j];
var Time {ROADS} >= 0;
minimize Avg_Time:
    (sum {(i,j) in ROADS} Time[i,j] * Flow[i,j]) / through;
subject to Travel_Time {(i,j) in ROADS}:
    Time[i,j] = base[i,j] + (sens[i,j]*Flow[i,j]) / (1-Flow[i,j]/cap[i,j]);
subject to Balance_Node {i in INTERS}:
    sum{(i,j) in ROADS} Flow[i,j] = sum{(j,i) in ROADS} Flow[j,i];
subject to Balance_Enter:
    sum{(EN,j) in ROADS} Flow[EN,j] = through;
```

Explicit data independent of symbolic model

Model + *data* = *problem to solve*

```
ampl: model traffic_c.mod;
ampl: data traffic_c.dat;
ampl: option solver knitroampl;
ampl: solve;
KNITRO 7.0.0: Locally optimal solution.
objective 8.178571439; feasibility error 2.23e-12
7 iterations; 8 function evaluations
ampl: display Flow, Time;
        Flow
                    Time
                            :=
ab 2
                   5.25
               2.92857
               2.92857
c b 2.79497e-08
                   5.25
```

Example: Portfolio Management

Standard Markowitz, quadratic model

- General fractional shares
- Discrete fractional shares
- Discrete investment rules
 - * min/max share
 - * diversification

Symbolic model

```
set A;
                            # asset categories
set T := {1973..1994}; # years
param R {T,A};  # returns on asset categories
param mu default 2;  # weight on variance
param mean \{j \text{ in } A\} = (sum \{i \text{ in } T\} R[i,j]) / card(T);
param Rtilde {i in T, j in A} = R[i,j] - mean[j];
var Frac \{A\} >=0:
var Mean = sum {j in A} mean[j] * Frac[j];
var Variance =
   sum {i in T} (sum {j in A} Rtilde[i,j]*Frac[j])^2 / card{T};
minimize RiskReward: mu * Variance - Mean;
subject to TotalOne: sum {j in A} Frac[j] = 1;
```

Example of data

```
set A :=
 US 3-MONTH T-BILLS US GOVN LONG BONDS SP 500 WILSHIRE 5000
 NASDAQ_COMPOSITE CORPORATE_BONDS_INDEX EAFE GOLD;
param R:
 US_3-MONTH_T-BILLS US_GOVN_LONG_BONDS SP_500 WILSHIRE_5000
 NASDAQ_COMPOSITE CORPORATE_BONDS_INDEX EAFE GOLD :=
     1.075
           0.942 0.852 0.815 0.698 1.023 0.851
1973
                                                  1.677
1974
    1.084 1.020 0.735 0.716 0.662 1.002 0.768 1.722
1975
    1.061 1.056 1.371 1.385 1.318 1.123 1.354 0.760
1976
    1.052 1.175 1.236 1.266 1.280 1.156 1.025 0.960
                                            1.181
1977
    1.055 1.002 0.926 0.974 1.093 1.030
                                                  1.200
1978
    1.077 0.982 1.064 1.093 1.146 1.012 1.326
                                                  1.295
1979
    1.109 0.978 1.184 1.256 1.307 1.023 1.048
                                                  2.212
1980
    1.127 0.947 1.323 1.337 1.367 1.031 1.226 1.296
1981
    1.156 1.003 0.949 0.963 0.990 1.073
                                            0.977
                                                  0.688
1982
     1.117 1.465 1.215 1.187 1.213 1.311 0.981
                                                  1.084
1983
     1.092 0.985 1.224 1.235 1.217 1.080 1.237
                                                  0.872
1984
    1.103 1.159 1.061 1.030 0.903 1.150
                                            1.074
                                                  0.825 ...
```

Solving with KNITRO

```
ampl: model markowitz.mod;
ampl: data markowitz.dat;
ampl: option solver knitroampl;
ampl: option knitro_options 'opttol 1e-12';
ampl: solve;
8 variables, all nonlinear
1 constraint, all linear; 8 nonzeros
1 nonlinear objective; 8 nonzeros.
KNITRO 7.0.0: Locally optimal solution.
objective -1.098362476; feasibility error 1.11e-16
10 iterations; 11 function evaluations
ampl:
```

Optimal portfolio

Solving with KNITRO: Discrete fractions

```
var Share {A} integer >= 0, <= 20;
var Frac {j in A} = Share[j] / 20;</pre>
```

```
ampl: solve;

KNITRO 7.0.0: Locally optimal solution.
objective -1.098266447; integrality gap -6.13e-13
13 nodes; 13 subproblem solves

ampl: display Frac;

CORPORATE_BONDS_INDEX 0.4

EAFE 0.2

GOLD 0.2

WILSHIRE_5000 0.2
```

Solving with KNITRO: Investment rules

```
param leastUse = 5;
param leastFrac = .10;
param mostFrac = .35;

var Use {A} binary;

subject to UseDefn {j in A}:  # upper limit on fraction of asset
    Frac[j] <= mostFrac * Use[j];

subject to LeastFrac {j in A}:  # lower limit on fraction of asset
    Frac[j] >= leastFrac * Use[j];  # if the asset is used at all

subject to LeastUse:  # lower limit on number of assets
    sum {j in A} Use[j] >= leastUse;
```

Solving with KNITRO: Investment rules (cont'd)

```
ampl: solve;

KNITRO 7.0.0: Locally optimal solution.
objective -1.098228448; integrality gap -1.98e-14
5 nodes; 5 subproblem solves

ampl: display Frac;

CORPORATE_BONDS_INDEX 0.35

EAFE 0.2

GOLD 0.2

SP_500 0.1

WILSHIRE_5000 0.15
```

How KNITRO Interacts with AMPL

```
User types . . .
   option solver knitroampl;
   option knitro_options 'opttol 1e-12';
    solve;
AMPL...
   Writes at 13151.nl
   Executes knitroampl at 13151 - AMPL
KNITRO "driver"...
   Reads at 13151.nl
   Gets environment variable knitro_options
   Calls KNITRO routines to solve the problem
   Writes at 13151, sol
AMPL...
   Reads at 13151.sol
```

What the KNITRO Driver Does

Reads .nl problem file

Loads everything into ASL data structure

Copies linear coefficients, bounds, etc. to solver's arrays Sets directives indicated by _options string

Runs algorithm

Uses ASL data structure to compute nonlinear expression values, 1st & 2nd derivatives

Writes .sol solution file

Generates result message Writes values of variables

AMPL's .nl File Format

File contents

Numbers of variables, constraints, integer variables, nonlinear constraints, *etc*.

Coefficient lists for linear part

Expression tree for nonlinear part plus sparsity pattern of derivatives

Expression tree nodes

Variables, constants

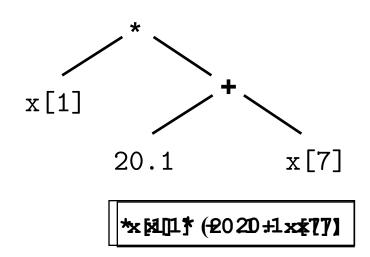
Binary, unary operators

Summations

Functions

Variables

Constants



Example of .nl File

Header

```
g3 0 1 0  # problem sum-of-norms3

14 11 1 0 9  # vars, constraints, objectives, ranges, eqns

2 0  # nonlinear constraints, objectives

0 0  # network constraints: nonlinear, linear

11 0 0  # nonlinear vars in constraints, objectives, both

0 0 0 1  # linear network variables; functions; arith, flags

0 0 0 0 0 0  # discrete variables: binary, integer, nonlinear (b,c,o)

41 2  # nonzeros in Jacobian, gradients

0 0  # max name lengths: constraints, variables

0 0 0 0 0 0 0  # common exprs: b,c,o,c1,o1
```

Example of .nl File

Expression trees for nonlinear constraints

```
CO
      #MaxDefinition[1]
      #sumlist
o54
                                   subj to MaxDefinition {i in 1..p}:
                                      sum {k in 1..m[i]} Fxplusg[i,k]^2
      #^
о5
                                          <= Max[i]^2;
      #Fxplusg[1,1]
v2
n2
о5
      #^
      #Fxplusg[1,2]
v3
n2
      #^
о5
      #Fxplusg[1,3]
v4
n2
      #^
о5
      #Fxplusg[1,4]
v5
n2
о5
      #^
      #Fxplusg[1,5]
v6
n2
016
      #-
о5
      #^
      #Max[1]
v0
n2
      #MaxDefinition[2]
C1
```

How AMPL Computes Derivatives

"Backward" Automatic Differentiation

- * Forward sweep: compute f(x), save info on $\partial f(x)/\partial o$ for each operation o
- * Backward sweep: recur to compute $\nabla f(x)$

Complexity

- * Small multiple of time for f(x) alone
- Potentially large multiple of space

Advantages

- More accurate, efficient than finite differencing
- * O(n) vs. $O(n^2)$ for symbolic differentiation or forward AD

2nd Derivative (Hessian) Options

Hessian-vector products: $\nabla^2 f(x) v$

- * Apply backward AD to compute gradients of $v^T \nabla f(x)$
- Equivalently, compute $\nabla_x (df(x + \tau v) / d\tau |_{\tau = 0})$

General case

• $\nabla^2 f(x) e_j$ for each $j = 1, \ldots, n$

Partially separable case

•
$$f(x) = \sum_{t=1}^{q} f_t(U_t x)$$
 where U_t is $m_t \times n$, $m_t >> n$

•
$$\nabla^2 f(x) = \sum_{t=1}^q U_t^{\mathrm{T}} \nabla^2 f_t(U_t x) U_t$$
, a sum of outer products

How AMPL Computes Hessians

Detect partially separable structure

- Walk expression tree
- Use a hashing scheme to spot common subexpressions

... sometimes useful in itself

Compute derivative information

- General or partially separable computations
- Dense or sparse
- Full or lower triangle
 - ... using general and/or partially separable approach

Further complications

- Hessian of Lagrangian
- Defined variables

KNITRO Derivative Options

Gradient (1st derivatives) — gradopt

- 1: use exact gradients
- **2:** compute forward finite-difference approximations
- 3: compute centered finite-difference approximations

Hessian (2nd derivatives) — hessopt

- 1: use exact Hessian derivatives
- 2: use dense quasi-Newton BFGS Hessian approximation
- **3:** use dense quasi-Newton SR1 Hessian approximation
- **4:** compute Hessian-vector products by finite differences
- **5:** compute exact Hessian-vector products
- **6:** use limited-memory BFGS Hessian approximation

Tradeoffs

- More information: Reduction in iterations
- Less information: Reduction in work per iteration

Multiple Solutions

Best n binary solutions

- * AMPL scripting
- Modeling flexibility

Multiple starts for nonconvex problems

- ❖ Set starts in AMPL
- Generate starts automatically in KNITRO

Solving with KNITRO: 10 best portfolios

```
param nSols default 0;
param maxSols = 10;
set U {1..nSols} within A;
subject to exclude {k in 1..nSols}:
    sum {j in U[k]} (1-Use[j]) + sum {j in A diff U[k]} Use[j] >= 1;
repeat {
    solve;
    display Frac;
    let nSols := nSols + 1;
    let U[nSols] := {j in A: Use[j] > .5};
} until nSols = maxSols;
```

Solving with KNITRO: 10 best portfolios (cont'd)

```
ampl: include portfolios.run;
KNITRO 7.0.0: Locally optimal solution.
objective -1.098228448; integrality gap -1.98e-14
5 nodes; 5 subproblem solves
CORPORATE_BONDS_INDEX 0.35
                EAFE 0.2
                GOLD 0.2
              SP_500 0.1
       WILSHIRE_5000 0.15;
KNITRO 7.0.0: Locally optimal solution.
objective -1.097809549; integrality gap -1.88e-12
13 nodes; 13 subproblem solves
CORPORATE_BONDS_INDEX 0.35
                EAFE 0.2
                 GOLD 0.15
  US_3-MONTH_T-BILLS 0.1
        WILSHIRE_5000 0.2;
```

Solving with KNITRO: 10 best portfolios (cont'd)

```
KNITRO 7.0.0: Locally optimal solution.
objective -1.097743771; integrality gap 3.19e-07
23 nodes; 23 subproblem solves
CORPORATE_BONDS_INDEX 0.25
                EAFE 0.2
                GOLD 0.2
               SP 500 0.1
  US_3-MONTH_T-BILLS 0.1
       WILSHIRE_5000 0.15;
KNITRO 7.0.0: Locally optimal solution.
objective -1.097696799; integrality gap -2.37e-13
45 nodes; 45 subproblem solves
CORPORATE_BONDS_INDEX 0.25
                EAFE 0.2
                GOLD 0.2
              SP 500 0.25
  US_3-MONTH_T-BILLS 0.1 ;
```

Multiple Starting Points

Nonconvex transportation problem

```
set ORIG; # origins
set DEST; # destinations
param supply {ORIG} >= 0;  # amounts available at origins
param demand {DEST} >= 0;  # amounts required at destinations
param rate {ORIG,DEST} >= 0; # base shipment costs per unit
param limit {ORIG,DEST} > 0;  # limit on units shipped
var Trans {i in ORIG, j in DEST} >= 1e-10, <= .9999 * limit[i,j];</pre>
                              # actual units to be shipped
minimize Total Cost:
   sum {i in ORIG, j in DEST}
      rate[i,j] * Trans[i,j]^0.8 / (1 - Trans[i,j]/limit[i,j]);
subject to Supply {i in ORIG}: sum {j in DEST} Trans[i,j] = supply[i];
subject to Demand {j in DEST}: sum {i in ORIG} Trans[i,j] = demand[j];
```

Multiple Starting Points

Set starts in AMPL

```
for {init in 1..9} {
   let {i in ORIG, j in DEST} Trans[i,j] := UniformO1() * limit[i,j];
   solve;
}
```

```
KNITRO 7.0.0: Locally optimal solution.
objective 379000.7333; feasibility error 6.82e-13
26 iterations; 27 function evaluations

KNITRO 7.0.0: Locally optimal solution.
objective 370807.9426; feasibility error 0
47 iterations; 73 function evaluations

KNITRO 7.0.0: Locally optimal solution.
objective 356531.4679; feasibility error 0
79 iterations; 103 function evaluations
......
```

Multiple Starting Points

Generate starts automatically in KNITRO

```
ampl: option knitro_options 'alg=3 ms_enable=1 ms_maxsolves=25';
ampl: solve;
KNITRO 7.0.0: Locally optimal solution.
objective 354276.7169; feasibility error 2.27e-13
1013 iterations; 1448 function evaluations
```