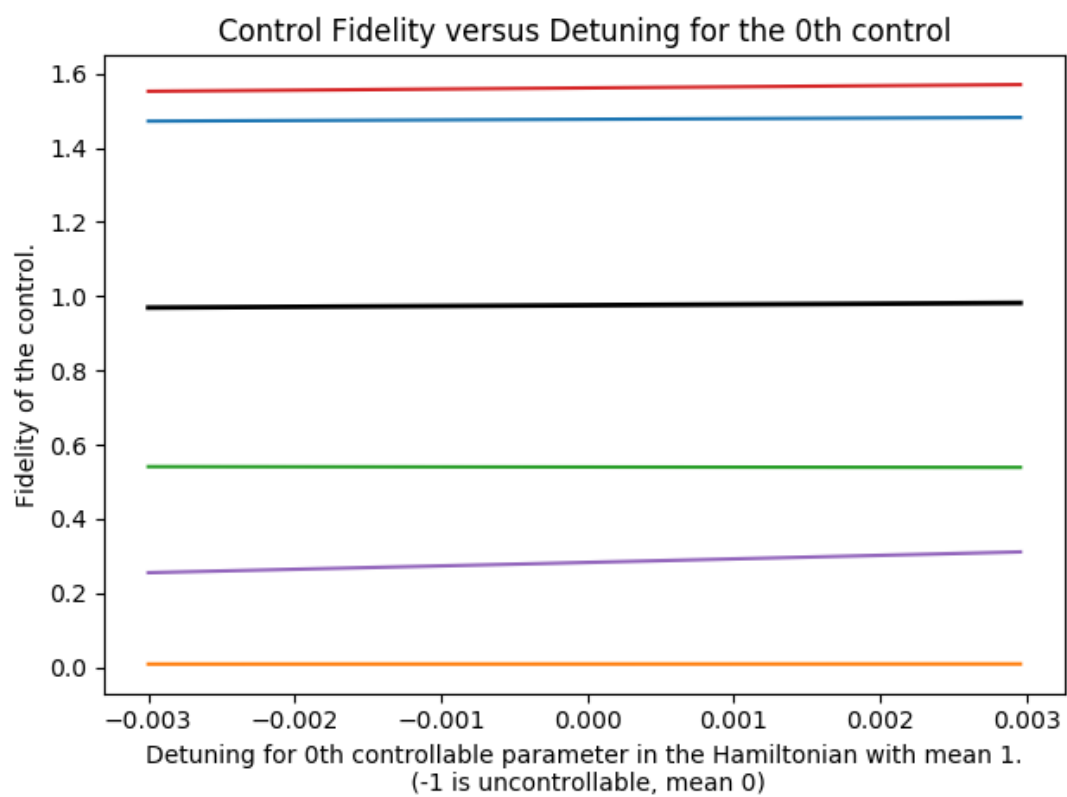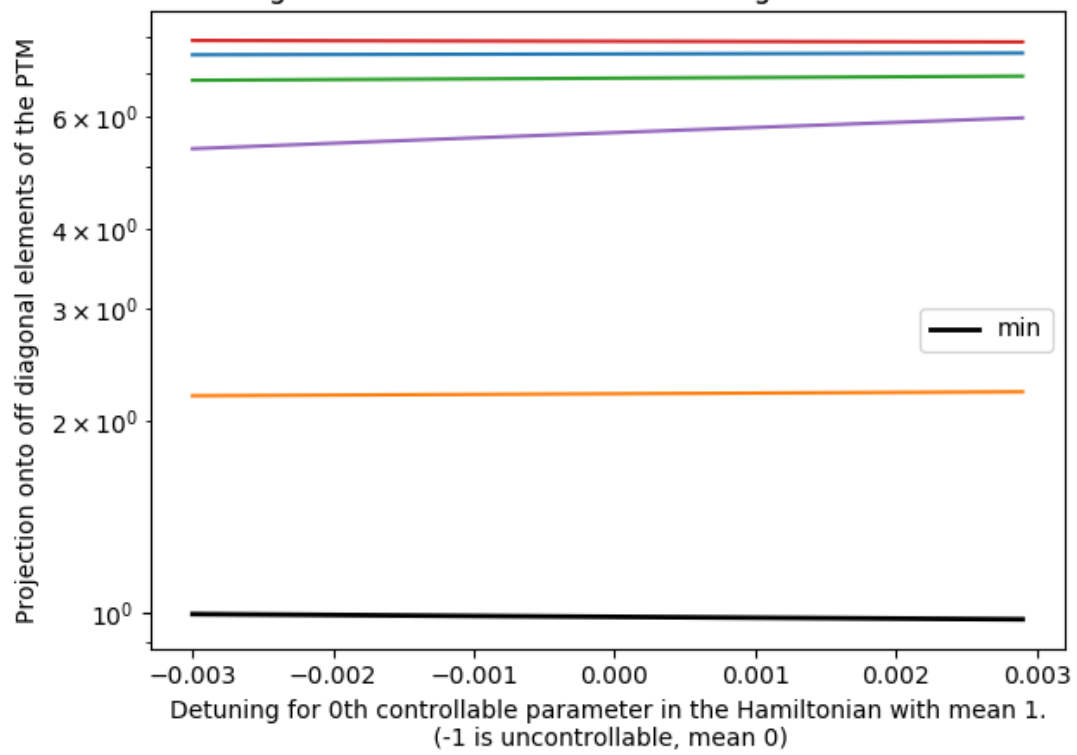Ambient Hamiltonian: [[1 0] [0 -1]]

Control Hamiltonians:[array([[0, 1], [1, 0]]), array([[0.+0.j, -0.-1.j], [0.+1.j, 0.+0.j]]), array([[1, 0], [0, -1]])]

Detunings: [0, 0.001, 0.001, 0.001]

dt: 0.125663706144

Probs: [0.34705097 0.11284269 0.23929045 0.19387268 0.10694321]

Target Operator: [[0 1] [1 0]]

Time: 131.798390865

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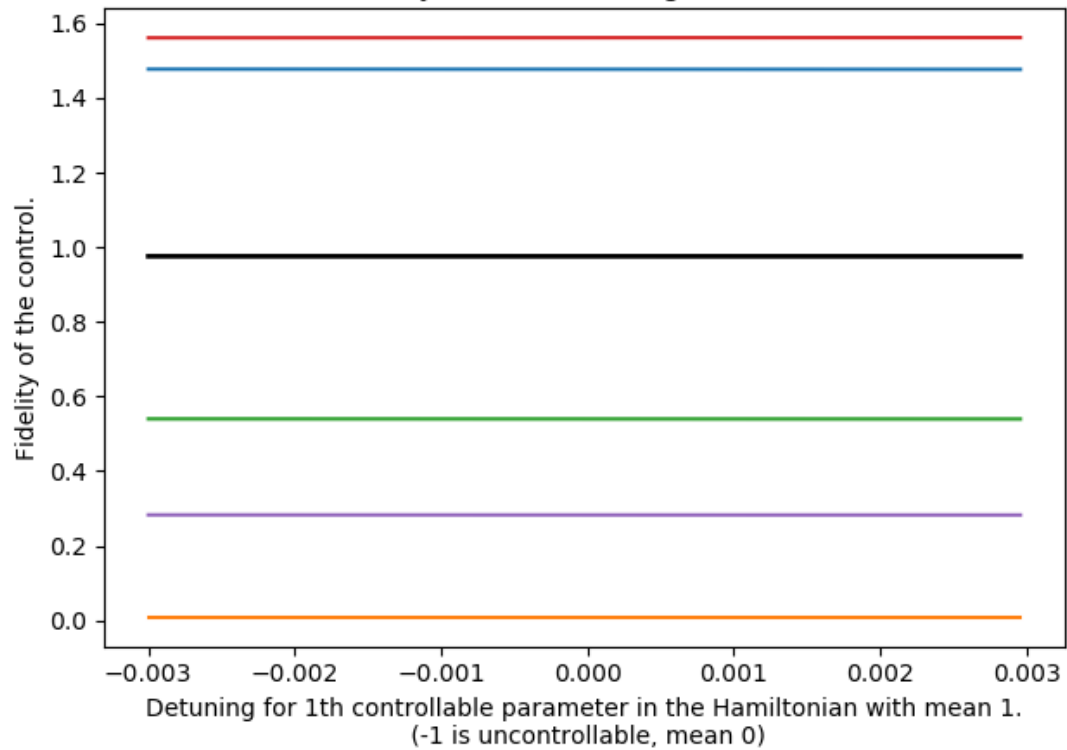
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Control Fidelity versus Detuning for the 0th control

Off diagonal contribution versus detuning for the 0th control

Projection onto off diagonal elements of the PTM

- 6×10^0
- 4×10^0
- 3×10^0
- 2×10^0
- 10^0

— min

Detuning for 0th controllable parameter in the Hamiltonian with mean 1.
(-1 is uncontrollable, mean 0)

−0.003   −0.002   −0.001   0.000   0.001   0.002   0.003

Control Fidelity versus Detuning for the 1th control

Fidelity of the control.

1.6
1.4
1.2
1.0
0.8
0.6
0.4
0.2
0.0

Detuning for 1th controllable parameter in the Hamiltonian with mean 1.
(-1 is uncontrollable, mean 0)

−0.003   −0.002   −0.001   0.000   0.001   0.002   0.003
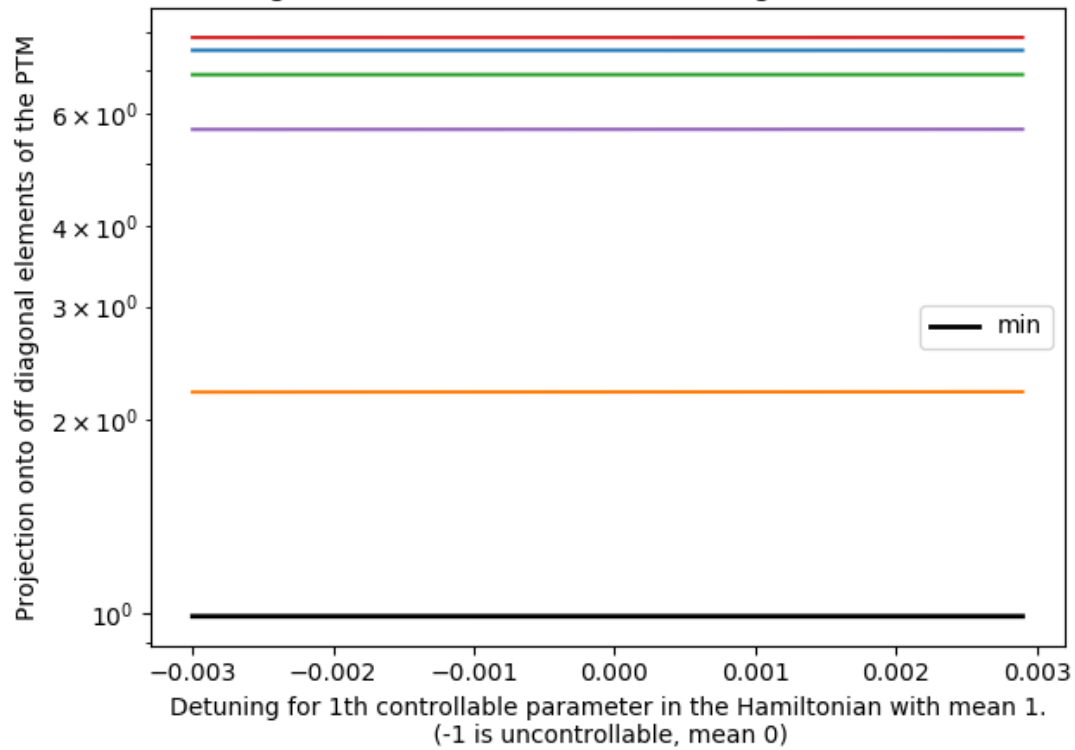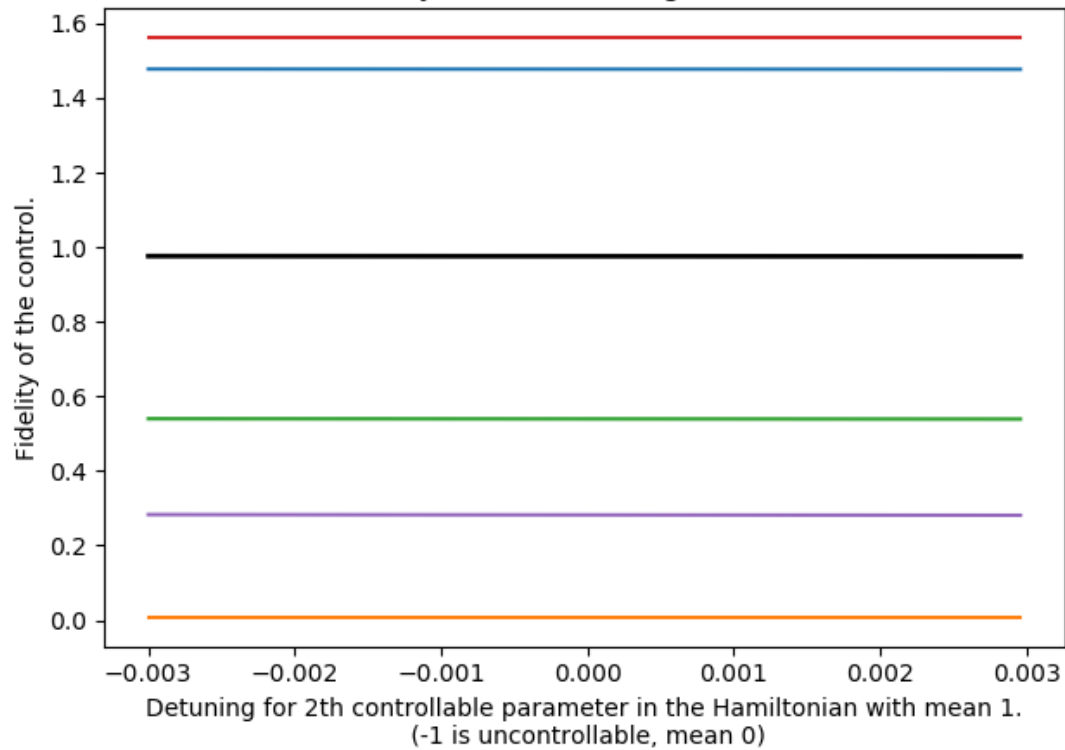
Off diagonal contribution versus detuning for the 1th control

Control Fidelity versus Detuning for the 2th control

Off diagonal contribution versus detuning for the 2th control