

Dynamic Video Summarization via Bidirectional RNNs and Transformer Architectures

Course Project: Deep Learning (DSAI 308)

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Deep Learning

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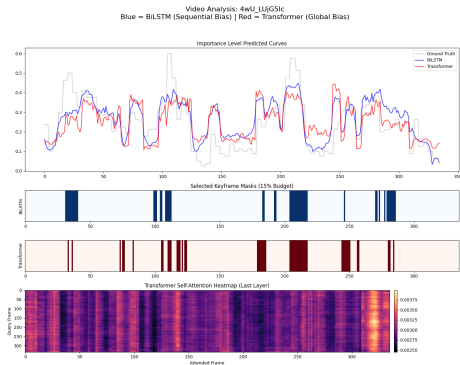
Fall 2025

Outline

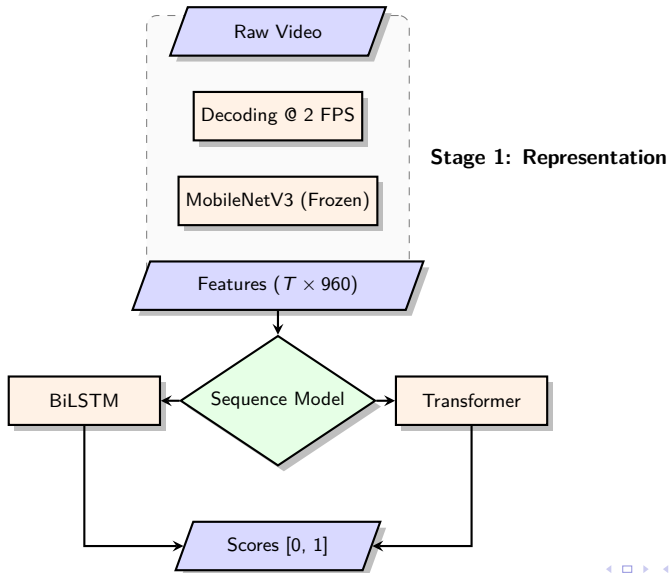
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Motivation & Problem Definition

- **Explosion of Video Content:** Massive growth in platforms requires automated navigation.
- **Video Summarization:** Generating a concise, representative summary (static keyframes).
- **Challenges:**
 - Capturing long-range temporal dependencies.
 - Balancing redundancy vs. information salience.
 - Handling diverse video domains (narratives vs. action).



System Architecture: Two-Stage Pipeline



BiLSTM: Sequential Contextualization

Architecture

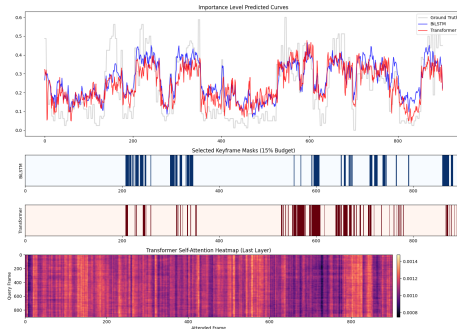
- 512-dim Bottleneck Projection.
- 2-layer Bidirectional LSTM.
- MLP Regression Head.

Intuition

- Models local flow (past/future dependencies).
- Superior for narrative continuity.

$$h_t = [\overrightarrow{f}(x_t, h_{t-1}); \overleftarrow{b}(x_t, h_{t+1})]$$

Video Analysis: Bhxk-01Y7Ho
Blue = BiLSTM (Sequential Bias) | Red = Transformer (Global Bias)



Transformer: Global Dependencies

Architecture

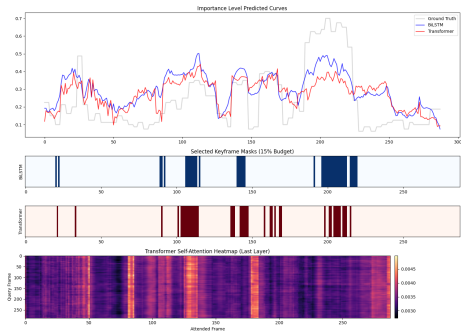
- Sinusoidal Positional Encoding.
- 4-Head Self-Attention.
- Dense Head for Score Regression.

Intuition

- Non-local relationship modeling.
- Correctly identifies sparse climax events.

$$\text{Attn}(Q, K, V) = \text{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right) V$$

Video Analysis: JgHubYSVw3Y
Blue = BiLSTM (Sequential Bias) | Red = Transformer (Global Bias)



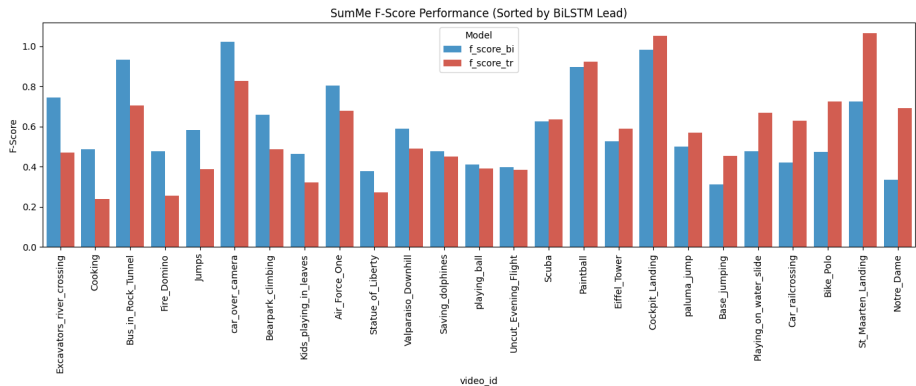
Quantitative Evaluation (TVSum)

Table: Supervised Results on TVSum

Model	Spearman ρ	Kendall τ	MSE	MAE
BiLSTM	0.531	0.362	0.0142	0.092
Transformer	0.418	0.285	0.0191	0.104

- **Key Finding:** BiLSTM excels at sequential tasks (tutorial, vlogs).
- **Observation:** Transformer shows higher robustness in non-linear action sequences.

Transfer Learning on SumMe Dataset



- Successful zero-shot transfer from TVSum \rightarrow SumMe.
- Models successfully identify climax moments even in unseen domains.

Qualitative Results: Sample Demo Keyframes

Cars Demo Video (T=126)



AI Robot Demo Video (T=33)



Conclusion & Future Work

Summary

- Built an E2E pipeline: decoding, features, modeling, selection.
- BiLSTM is the reliable choice for steady temporal flows.
- Transformers offer better global reasoning for sparse highlights.

Future Directions

- **Multimodal Fusion:** Integrating Audio/Text signals.
- **Unsupervised Learning:** Scaling with SUM-GAN/Contrastive learning.

Questions?

Thank You!