

# Task 6.3

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## 1 Introduction to Path Planning

Path planning is a crucial task in robotics and autonomous systems, where the goal is to find an optimal path from a starting point to a destination. It involves determining a sequence of actions or waypoints that a robot or vehicle should follow to navigate in an environment while avoiding obstacles. Path planning algorithms play a vital role in enabling autonomous navigation and are widely used in various domains, including robotics, self-driving cars, and unmanned aerial vehicles.

## 2 Types of Path Planning Algorithms

There are several types of path planning algorithms available, each with its own characteristics and suitability for different scenarios. Some common types include:

- **Dijkstra's Algorithm:** This algorithm finds the shortest path between two points in a graph by considering the cost associated with each edge or node.
- **A\* Algorithm:** A\* (pronounced "A-star") is a popular heuristic search algorithm that combines the advantages of both Dijkstra's algorithm and greedy best-first search. It efficiently explores the search space and finds the optimal path based on a heuristic function.
- **Probabilistic Roadmap:** Probabilistic roadmap (PRM) is a sampling-based algorithm that builds a graph of feasible paths by randomly sampling the configuration space of the robot. It then connects the samples to create a roadmap that can be used for path planning.
- **Rapidly-exploring Random Trees:** Rapidly-exploring random trees (RRT) is another sampling-based algorithm that incrementally builds a tree structure by randomly exploring the configuration space. It is particularly effective for high-dimensional spaces and dynamic environments.

### 3 Local Planner and Global Planner

Path planning can be divided into two main components: the local planner and the global planner.

- **Local Planner:** The local planner focuses on short-term decisions and is responsible for navigating the robot or vehicle around immediate obstacles. It takes into account the robot's current position, sensor information, and local map to generate a safe and feasible trajectory.
- **Global Planner:** The global planner considers the entire environment and is responsible for determining the optimal path from the start to the goal. It utilizes a path planning algorithm to search the configuration space and generate a high-level plan that the local planner can follow.

### 4 Challenges and Future Trends in Path Planning

Path planning faces several challenges, and researchers are continuously working on developing new techniques to address them. Some of the prominent challenges include:

- **High-dimensional Spaces:** As the complexity of the environment increases, path planning in high-dimensional spaces becomes computationally expensive. Efficient algorithms, such as sampling-based methods, are being developed to tackle this challenge.
- **Dynamic and Uncertain Environments:** Path planning algorithms need to handle dynamic obstacles and uncertain environments, where obstacles can appear or move unpredictably. Techniques like trajectory optimization and online replanning are being explored to deal with these challenges.
- **Real-time Performance:** In many applications, path planning needs to be performed in real-time to ensure the timely response of autonomous systems. Optimizing algorithms and leveraging parallel computing are some of the approaches being pursued for achieving real-time performance.

Future trends in path planning include the integration of machine learning and artificial intelligence techniques, such as reinforcement learning, to improve the adaptability and decision-making capabilities of path planning algorithms.

### 5 Practical Applications of Path Planning

Path planning has numerous practical applications across various domains. Some notable examples include:

- **Autonomous Vehicles:** Self-driving cars rely on path planning algorithms to navigate safely on roads, avoid collisions, and reach their destinations efficiently.
- **Robotics:** Path planning is essential for robots operating in both structured and unstructured environments. It enables them to perform tasks such as pick-and-place operations, exploration, and surveillance.
- **Unmanned Aerial Vehicles (UAVs):** Drones and UAVs utilize path planning to autonomously navigate through airspace, perform surveillance, or deliver goods.
- **Virtual Agents and Video Games:** Path planning algorithms are used in virtual agent systems and video games to create realistic and intelligent movement for characters. This enhances the player's experience and allows for dynamic and interactive gameplay.

## 6 Conclusion and Resources

Path planning is a fundamental aspect of robotics and autonomous systems, enabling them to navigate through complex environments and reach their goals efficiently. In this article, we discussed the introduction to path planning, different types of path planning algorithms, the role of local and global planners, challenges, future trends, and practical applications.

To dive deeper into path planning, here are some recommended resources:

- LaValle, S. M. (2006). *Planning Algorithms*. Cambridge University Press.
- Choset, H., et al. (2005). *Principles of Robot Motion: Theory, Algorithms, and Implementations*. MIT Press.
- Kavraki, L. E., et al. (1996). *Probabilistic Roadmaps for Path Planning in High-Dimensional Configuration Spaces*. IEEE Transactions on Robotics and Automation, 12(4), 566-580.

By understanding path planning algorithms and their applications, we can continue to advance the field and develop more efficient and intelligent autonomous systems.