## AN INTRODUCTION TO SCHUR FUNCTIONS

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1. **Symmetric Functions.** We consider polynomials in n variables  $x_1, \ldots, x_n$ . Given a multiindex  $\alpha = (\alpha_1, \ldots, \alpha_n), x^{\alpha}$  denotes the monomial  $x_1^{\alpha_1} \cdots x_n^{\alpha_n}$  A symmetric polynomial in n variables  $x_1, \ldots, x_n$  is a polynomial of the form

$$f(x_1, \dots, x_n) = \sum_{\alpha} c_{\alpha} x^{\alpha},$$

where, for any permutation  $w \in S_n$ ,

$$c_{(\alpha_1,\dots,\alpha_n)} = c_{(\alpha_{w(1)},\dots,\alpha_{w(n)})}.$$

We call the integer partition  $\lambda$  obtained by sorting the coordinates of  $\alpha$  the shape of  $\alpha$  and write  $\lambda = \lambda(\alpha)$ . The most obvious example of a symmetric polynomial in n variables is the *monomial symmetric function*, defined for each integer partition  $\lambda$ :

$$m_{\lambda} = \sum_{\lambda(\alpha) = \lambda} c_{\alpha} x^{\alpha}.$$

Note that  $m_{\lambda}$  is homogeneous of degree  $|\lambda|$  (the sum of the parts of  $\lambda$ ).

**Exercise 1.1.** Take n = 4. Compute the monomial symmetric functions  $m_{(3)}$ ,  $m_{(2,1)}$ , and  $m_{(1^3)}$ .

**Theorem 1.2.** The polynomials  $m_{\lambda}(x_1, \ldots, x_n)$ , as  $\lambda$  runs over all the integer partition of d, form a basis for the space of homogeneous symmetric polynomials of degree d in n variables.

2. Complete and Elementary Symmetric Polynomials. Recall that the coefficients of a polynomial are symmetric polynomials in its roots:

(1) 
$$(t-x_1)(t-x_2)\cdots(t-x_n)$$
  
=  $t^n - e_1(x_1,\ldots,x_n)t^{n-1} + \cdots + (-1)^n e_n(x_1,\ldots,x_n),$ 

where coefficient  $e_i(x_1, \ldots, x_n)$  of  $t^{n-i}$  is given by:

(2) 
$$e_i(x_1, \dots, x_n) = \sum_{\substack{1 \le j_1 < \dots < j_i \le n}} x_{j_1} x_{j_2} \cdots x_{j_i}.$$

The polynomial  $e_i$  is called the *i*th elementary symmetric polynomial. By convention, write  $e_i(x_1, \ldots, x_n) = 0$ , for i > n.

The identity (1) can be written more elegantly as:

$$(1+tx_1)\cdots(1+tx_n) = \sum_{i=0}^n e_i(x_1,\cdots,x_n)t^i.$$

Dually<sup>1</sup>, the *complete symmetric polynomials* are defined by the formal identity:

$$\frac{1}{(1-x_1t)\cdots(1-x_nt)} = \sum_{i=0}^{\infty} h_i(x_1,\cdots,x_n)t^i.$$

**Example 2.1.** In three variables, we have:

$$e_2(x_1, x_2, x_3) = x_1x_2 + x_1x_3 + x_2x_3,$$
  
 $h_2(x_1, x_2, x_3) = x_1^2 + x_1x_2 + x_1x_3 + x_2^2 + x_2x_3 + x_2^3.$ 

Exercise 2.2. Show that

$$h_i(x_1, \dots x_n) = \sum_{1 < j_1 < \dots < j_i < n} x_{j_1} \cdots x_{j_i}.$$

More generally, for any integer partition  $\lambda = (\lambda_1, \dots, \lambda_l)$ , define:

$$h_{\lambda} = h_{\lambda_1} h_{\lambda_2} \cdots h_{\lambda_l},$$
  
$$e_{\lambda} = e_{\lambda_1} e_{\lambda_2} \cdots e_{\lambda_l}.$$

**Theorem 2.3.** Given integer partitions  $\lambda = (\lambda_1, \dots, \lambda_l)$  and  $\mu = (\mu_1, \dots, \mu_m)$  of and integer d, let  $M_{\lambda\mu}$  denote the number of integer matrices  $(a_{ij})$  with non-negative entries whose ith row sums to  $\lambda_i$  for each i, and whose jth column sums to  $\mu_j$  for each j. Then

$$h_{\lambda} = \sum_{\mu} M_{\lambda\mu} m_{\mu}.$$

Dually, let =  $N_{\lambda\mu}$  denote the number of integer matrices  $(a_{ij})$  with entries 0 or 1, whose ith row sums to  $\lambda_i$  for each i, and whose jth column sums to  $\mu_j$  for each j.

$$e_{\lambda} = \sum_{\mu} N_{\lambda\mu} m_{\mu}.$$

<sup>&</sup>lt;sup>1</sup>We will refer to the replacing of (1+u) by  $(1-u)^{-1}$  in a formal identity as dualization.

*Proof.* We first prove the second identity involving elementary symmetric functions. A monomial in the expansion:

$$e_{\lambda} = \prod_{i=1}^{l} \sum_{j_1 < \dots < j_{\lambda_j}} x_{j_1} \cdots x_{j_{\lambda_i}}$$

is a product of summands, one chosen from each of the l factors. Construct an  $l \times m$  matrix  $(a_{ij})$  corresponding to such a choice as follows: if the summand  $x_{j_1} \cdots x_{j_{\lambda_i}}$  is chosen from the ith factor, then set the entries  $a_{i,j_1}, \ldots, a_{i,j_{\lambda_j}}$  to be 1 (the remaining entries of the ith row are 0). Clearly the ith row of such a matrix sums to  $\lambda_i$ . The monomial corresponding to this choice is  $x^{\mu}$  if, for each j, the the number of i for which  $x_j$  appears in  $a_{i,j_1}, \ldots, a_{i,j_{\lambda_j}}$ , which is the sum of the jth column of the matrix  $(a_{ij})$ . It follows that the coefficient of  $x^{\mu}$ , and hence the coefficient of  $m_{\mu}$  in the expansion of  $e_{\lambda}$  in the basis of monomial symmetric functions of degree n, is  $N_{\lambda\mu}$ .

A similar proof can be given for the first identity involving complete symmetric functions. The only difference is that a variables are repeated in the monomials that appear in  $h_i$ . Counting the number of repetitions (instead of just recording 0 or 1) gives non-negative integer matrices.

3. Alternating Polynomials. An alternating polynomial in  $x_1, \ldots, x_n$  is of the form:

(3) 
$$f(x_1, \dots, x_n) = \sum_{\alpha} c_{\alpha} x_{\alpha},$$

where,  $c_{w(\alpha)} = \epsilon(w)c_{\alpha}$  for every multiindex  $\alpha$  as in Section 1. Here  $\epsilon: S_n \to \{\pm 1\}$  denotes the sign function. Equivalently, an alternating polynomial is one whose sign is reversed upon the interchange of any two variables.

**Exercise 3.1.** If  $\alpha$  is a multiindex where  $\alpha_i = \alpha_j$  for some  $i \neq j$ , then  $c_{\alpha} = 0$ .

In particular, every monomial in an alternating polynomial must be composed of distinct powers. Moreover, the polynomial is completely determined by the coefficients  $c_{\alpha}$  of strictly decreasing multiindices, namely, multiindices of the form  $\alpha = (\alpha_1, \ldots, \alpha_n)$  with  $\alpha_1 > \cdots > \alpha_n$ .

**Exercise 3.2.** Let  $\delta$  denote the strictly increasing multiindex  $(n-1, n-2, \ldots, 1, 0)$  of lowest degree. Given an integer partition with at most n parts, we will pad it with 0's so that it can be regarded as a weakly decreasing multiindex. Then  $\lambda \mapsto \lambda + \delta$  is a bijection from the set

of integer partitions with at most n onto the set of strictly decreasing multiindices.

**Example 3.3.** Let  $\lambda = (\lambda_1, \dots, \lambda_n)$  be a weakly decreasing multiindex. The polynomial:

$$a_{\lambda+\delta} = \det(x_i^{\lambda_j+n-j})$$

is alternating, with unique strictly decreasing monomial  $x^{\lambda+\delta}$ .

Exercise 3.4. The alternating polynomial of the form (3) is equal to

$$\sum_{\lambda} c_{\lambda} a_{\lambda+\delta},$$

the sum being over all weakly decreasing multiindices.

4. Cauchy's bialternant form of a Schur function. The simplest polynomial of the form  $a_{\lambda+\delta}$  arises when  $\lambda=0$ ;  $a_{\delta}$  is the Vandermonde determinant:

$$a_{\delta} = \prod_{1 \le i < j \le n} (x_i - x_j).$$

**Exercise 4.1.** Show that, for every weakly decreasing multiindex  $\lambda$ ,  $a_{\lambda+\delta}$  is divisible by  $a_{\delta}$  in the ring of polynomials in  $x_1, \ldots, x_n$ .

**Exercise 4.2.** Show that  $f \mapsto fa_{\delta}$  is an isomorphism of the space of symmetric polynomials in  $x_1, \ldots, x_n$  of degree d onto the space of alternating polynomials of degree  $d + \binom{n}{2}$ .

The above exercise allows us to give the historically oldest definition of Schur functions—Cauchy's bialternant formula:

$$(4) s_{\lambda}(x_1, \dots, x_n) = a_{\lambda + \delta}/a_{\delta},$$

for any partition  $\lambda$  with at most n parts. If  $\lambda$  has more than n parts, set  $s_{\lambda}(x_1, \ldots, x_n) = 0$ . This is clearly a symmetric function of degree  $|\lambda|$ . When  $\lambda$  has more than n parts, we shall write  $s_{\lambda}(x_1, \ldots, x_n) = 0$ 

**Theorem 4.3.** As  $\lambda$  runs over all integer partitions of d with at most n parts, the Schur functions  $s_{\lambda}(x_1, \ldots, x_n)$  form a basis of the space of all homogeneous symmetric functions in  $x_1, \ldots, x_n$  of degree d.

*Proof.* This follows from Exercises 3.4 and 4.2.

**Exercise 4.4** (Stability of Schur functions). Show that substituting  $x_n = 0$  in the Schur function  $s_{\lambda}(x_1, \ldots, x_n)$  with n variables gives the corresponding Schur function  $s_{\lambda}(x_1, \ldots, x_{n-1})$  with n-1 variables.

Exercise 4.5. From Cauchy's bialternant form (4), deduce that

- (1)  $s_{(i)} = h_i$ , and
- (2)  $s_{(1^i)} = e_i$ .

5. The Lindström-Gessel-Viennot Lemma. Let R be a commutative ring. Let S be any set of points, and  $v: S \times S \to R$  be any function (we think of w as a weight function. Given  $s, t \in S$ , a path in S from s to t is is a sequence  $\omega = (s = s_0, s_1, \ldots, s_k = t)$  of distinct points in S. We denote this by  $\omega: s \to t$ . The weight of the path  $\omega$  is defined to be:

$$v(\omega) = v(s_0, s_1)v(s_1, s_2)\cdots v(s_{k-1}, s_k).$$

**Definition 5.1** (non-crossing paths). Two paths  $\omega = (s_0, \ldots, s_k)$  and  $\eta = (t_0, \ldots, t_l)$  are said to be non-crossing if  $s_i \neq t_j$  for all  $0 \leq i \leq k$  and  $0 \leq i \leq l$ .

Fix points  $A_1, \ldots, A_n$  and  $B_1, \ldots, B_n$  in S, and define an  $n \times n$  matrix  $(a_{ij})$  by:

$$a_{ij} = \sum_{\omega: A_i \to B_j} v(\omega).$$

**Theorem 5.2** (Lindström-Gessel-Viennot Lemma). The determinant of the matrix  $(a_{ij})$  defined above is given by:

$$\det(a_{ij}) = \sum_{\omega_i: A_i \to B_i} v(\omega_1) \cdots v(\omega_n),$$

where the sum is over all n-tuples  $(\omega_1, \ldots, \omega_n)$  of pairwise non-crossing paths.

6. The Jacobi-Trudi Identities.

$$s_{\lambda} = \det(h_{\lambda_i - i + j}), \quad s_{\lambda'} = \det(e_{\lambda_i - i + j}).$$

For the first Jacobi-Trudi identity take S to be the positive cone in the the integer lattice:

$$S = \{(i, j) \mid i \ge 0, j > 0 \text{ are integers}\}.$$

Set the weight v((i,j),(i+1,j)) of each rightward horizontal edge to be  $x_j$  for  $j=1,\ldots,n$ , the weight of each downward vertical edge v((i,j),(i,j-1)) to be 1 for all  $j=2,\ldots,n$ . The remaining weights are all zero.

**Lemma 6.1.** For all integers i > 0 and  $j \ge 0$ , we have:

$$\sum_{\omega:(i,n)\to(i+j,1)}v(\omega)=h_j(x_1,\ldots,x_n).$$

*Proof.* Only rightward or downward steps have non-zero weights. So every path with non-zero weight is composed of unit downward and rightward steps. A path with non-zero weight from (i, n) to (i + j, 1) must have exactly j rightward steps, say in rows  $n \ge i_1 \ge i_2 \cdots \ge i_j \ge i_j$ 

1. The weight of such a path is  $x_{i_1} \cdots x_{i_j}$ , and hence, the sum of the weights of all such paths is  $h_j(x_1, \ldots, x_n)$ .

Let  $A_i = (n-i, n)$  and  $B_j = (\lambda_j + n - j, 1)$  for  $i = 1, \dots, n$ . Then by Lemma 6.1,

$$\sum_{\omega: A_i \to B_j} = h_{\lambda_j + i - j}.$$