AN INTRODUCTION TO SCHUR FUNCTIONS

AMRITANSHU PRASAD

1. **Symmetric Functions.** We consider polynomials in n variables x_1, \ldots, x_n . Given a multiindex $\alpha = (\alpha_1, \ldots, \alpha_n), x^{\alpha}$ denotes the monomial $x_1^{\alpha_1} \cdots x_n^{\alpha_n}$ A symmetric polynomial in n variables x_1, \ldots, x_n is a polynomial of the form

$$f(x_1,\ldots,x_n)=\sum_{\alpha}c_{\alpha}x^{\alpha},$$

where, for any permutation $w \in S_n$,

$$c_{(\alpha_1,\dots,\alpha_n)} = c_{(\alpha_{w(1)},\dots,\alpha_{w(n)})}.$$

We call the integer partition λ obtained by sorting the coordinates of α the shape of α and write $\lambda = \lambda(\alpha)$. The most obvious example of a symmetric polynomial in n variables is the *monomial symmetric function*, defined for each integer partition λ :

$$m_{\lambda} = \sum_{\lambda(\alpha)=\lambda} c_{\alpha} x^{\alpha}.$$

Note that m_{λ} is homogeneous of degree $|\lambda|$ (the sum of the parts of λ).

Exercise 1.1. Take n = 4. Compute the monomial symmetric function $m_{(3)}$, $m_{(2,1)}$, and $m_{(1^3)}$.

Theorem 1.2. The polynomials $m_{\lambda}(x_1, \ldots, x_n)$, as λ runs over all the integer partition of d, form a basis for the space of homogeneous symmetric polynomials of degree d in n variables.

2. Complete and Elementary Symmetric Polynomials. Recall that the coefficients of a polynomial are symmetric polynomials in its roots:

(1)
$$(t-x_1)(t-x_2)\cdots(t-x_n)$$

= $t^n - e_1(x_1,\ldots,x_n)t^{n-1} + \cdots + (-1)^n e_n(x_1,\ldots,x_n),$

where coefficient $e_i(x_1, \ldots, x_n)$ of t^{n-i} is given by:

(2)
$$e_i(x_1, \dots, x_n) = \sum_{\substack{1 \le j_1 < \dots < j_i \le n}} x_{j_1} x_{j_2} \cdots x_{j_i}.$$

The polynomial e_i is called the *i*th elementary symmetric polynomial. By convention, write $e_i(x_1, \ldots, x_n) = 0$, for i > n.

The identity (1) can be written more elegantly as:

$$(1+tx_1)\cdots(1+tx_n) = \sum_{i=0}^n e_i(x_1,\cdots,x_n)t^i.$$

Dually¹, the *complete symmetric polynomials* are defined by the formal identity:

$$\frac{1}{(1-x_1t)\cdots(1-x_nt)} = \sum_{i=0}^{\infty} h_i(x_1,\cdots,x_n)t^i.$$

Example 2.1. In three variables, we have:

$$e_2(x_1, x_2, x_3) = x_1x_2 + x_1x_3 + x_2x_3,$$

 $h_2(x_1, x_2, x_3) = x_1^2 + x_1x_2 + x_1x_3 + x_2^2 + x_2x_3 + x_2^3.$

Exercise 2.2. Show that

$$h_i(x_1, \dots x_n) = \sum_{1 \le j_1 \le \dots \le j_i \le n} x_{j_1} \dots x_{j_i}.$$

More generally, for any integer partition $\lambda = (\lambda_1, \dots, \lambda_l)$, define:

$$h_{\lambda} = h_{\lambda_1} h_{\lambda_2} \cdots h_{\lambda_l},$$

$$e_{\lambda} = e_{\lambda_1} e_{\lambda_2} \cdots e_{\lambda_l}.$$

Theorem 2.3. Given integer partitions $\lambda = (\lambda_1, \dots, \lambda_l)$ and $\mu = (\mu_1, \dots, \mu_m)$ of and integer d, let $M_{\lambda\mu}$ denote the number of integer matrices (a_{ij}) with non-negative entries whose ith row sums to λ_i for each i, and whose jth column sums to μ_j for each j. Then

$$h_{\lambda} = \sum_{\mu} M_{\lambda\mu} m_{\mu}.$$

Dually, let = $N_{\lambda\mu}$ denote the number of integer matrices (a_{ij}) with entries 0 or 1, whose ith row sums to λ_i for each i, and whose jth column sums to μ_i for each j.

$$e_{\lambda} = \sum_{\mu} N_{\lambda\mu} m_{\mu}.$$

The will refer to the replacing of (1+u) by $(1-u)^{-1}$ in a formal identity as dualization.

Proof. We first prove the second identity involving elementary symmetric functions. A monomial in the expansion:

$$e_{\lambda} = \prod_{i=1}^{l} \sum_{j_1 < \dots < j_{\lambda_j}} x_{j_1} \cdots x_{j_{\lambda_i}}$$

is a product of summands, one chosen from each of the l factors. Construct an $l \times m$ matrix (a_{ij}) corresponding to such a choice as follows: if the summand $x_{j_1} \cdots x_{j_{\lambda_i}}$ is chosen from the ith factor, then set the entries $a_{i,j_1}, \ldots, a_{i,j_{\lambda_j}}$ to be 1 (the remaining entries of the ith row are 0). Clearly the ith row of such a matrix sums to λ_i . The monomial corresponding to this choice is x^{μ} if, for each j, the the number of i for which x_j appears in $a_{i,j_1}, \ldots, a_{i,j_{\lambda_j}}$, which is the sum of the jth column of the matrix (a_{ij}) . It follows that the coefficient of x^{μ} , and hence the coefficient of m_{μ} in the expansion of e_{λ} in the basis of monomial symmetric functions of degree n, is $N_{\lambda\mu}$.

A similar proof can be given for the first identity involving complete symmetric functions. The only difference is that a variables are repeated in the monomials that appear in h_i . Counting the number of repetitions (instead of just recording 0 or 1) gives non-negative integer matrices.

3. Alternating Polynomials. An alternating polynomial in x_1, \ldots, x_n is of the form:

(3)
$$f(x_1, \dots, x_n) = \sum_{\alpha} c_{\alpha} x_{\alpha},$$

where, $c_{w(\alpha)} = \epsilon(w)c_{\alpha}$ for every multiindex α as in Section 1. Here $\epsilon: S_n \to \{\pm 1\}$ denotes the sign function. Equivalently, an alternating polynomial is one whose sign is reversed upon the interchange of any two variables.

Exercise 3.1. If α is a multiindex where $\alpha_i = \alpha_j$ for some $i \neq j$, then $c_{\alpha} = 0$.

In particular, every monomial in an alternating polynomial must be composed of distinct powers. Moreover, the polynomial is completely determined by the coefficients c_{α} of strictly decreasing multiindices, namely, multiindices of the form $\alpha = (\alpha_1, \ldots, \alpha_n)$ with $\alpha_1 > \cdots > \alpha_n$.

Exercise 3.2. Let δ denote the strictly increasing multiindex $(n-1, n-2, \ldots, 1, 0)$ of lowest degree. Given an integer partition with at most n parts, we will pad it with 0's so that it can be regarded as a weakly decreasing multiindex. Then $\lambda \mapsto \lambda + \delta$ is a bijection from the set

of integer partitions with at most n onto the set of strictly decreasing multiindices.

Example 3.3. Let $\lambda = (\lambda_1, \dots, \lambda_n)$ be a weakly decreasing multiindex. The polynomial:

 $a_{\lambda+\delta} = \det(x_i^{\lambda_j + n - j})$

is alternating, with unique strictly decreasing monomial $x^{\lambda+\delta}$.

Exercise 3.4. The alternating polynomial of the form (3) is equal to

$$\sum_{\lambda} c_{\lambda} a_{\lambda+\delta},$$

the sum being over all weakly decreasing multiindices.

4. Cauchy's bialternant form of a Schur function. The simplest polynomial of the form $a_{\lambda+\delta}$ arises when $\lambda=0$; a_{δ} is the Vandermonde determinant:

$$a_{\delta} = \prod_{1 \le i < j \le n} (x_i - x_j).$$

Exercise 4.1. Show that, for every weakly decreasing multiindex λ , $a_{\lambda+\delta}$ is divisible by a_{δ} in the ring of polynomials in x_1, \ldots, x_n .

Exercise 4.2. Show that $f \mapsto fa_{\delta}$ is an isomorphism of the space of symmetric polynomials in x_1, \ldots, x_n of degree d onto the space of alternating polynomials of degree $d + \binom{n}{2}$.

The above exercise allows us to give the historically oldest definition of Schur functions—Cauchy's bialternant formula:

$$(4) s_{\lambda}(x_1, \dots, x_n) = a_{\lambda + \delta}/a_{\delta},$$

for any partition λ with at most n parts. If λ has more than n parts, set $s_{\lambda}(x_1, \ldots, x_n) = 0$. This is clearly a symmetric function of degree $|\lambda|$. When λ has more than n parts, we shall write $s_{\lambda}(x_1, \ldots, x_n) = 0$

Theorem 4.3. As λ runs over all integer partitions of d with at most n parts, the Schur functions $s_{\lambda}(x_1, \ldots, x_n)$ form a basis of the space of all homogeneous symmetric functions in x_1, \ldots, x_n of degree d.

Proof. This follows from Exercises 3.4 and 4.2. \Box

Exercise 4.4. Show that substituting $x_n = 0$ in the Schur function $s_{\lambda}(x_1, \ldots, x_n)$ with n variables gives the corresponding Schur function $s_{\lambda}(x_1, \ldots, x_{n-1})$ with n-1 variables.

Exercise 4.5. From Cauchy's bialternant form (4), deduce that

- (1) $s_{(i)} = h_i$, and
- (2) $s_{(1^i)} = e_i$.