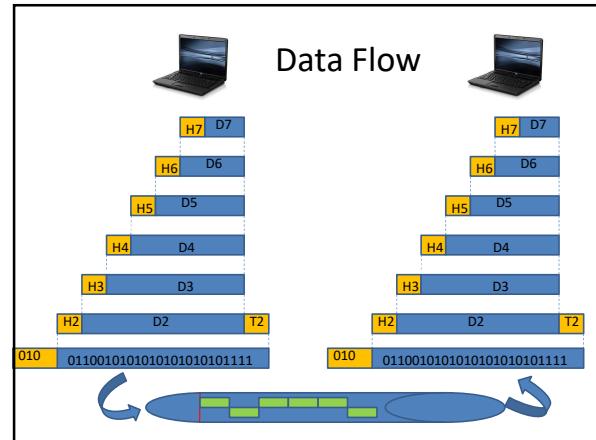


LAYERED MODELS

- Study of layered model means study of their
 - Functions
 - Scope (delivery points)

Delivery points

- Hop to hop (node to node)
- Source to destination (end to end delivery)
- Process to process (port to port)



Physical layer

Physical layer is responsible for transmission of bit stream over the physical medium.

Physical Layer

- Physical layer is the actual interface to the physical transmission medium.
- Implementation varies with the physical medium used. (Twisted pair, coaxial cable, optical fiber or radio waves (wireless).)
- Representation of data (bit-encoding- voltage levels for 0/1 bit transmissions)
- Time-duration of bits (signaling speed).

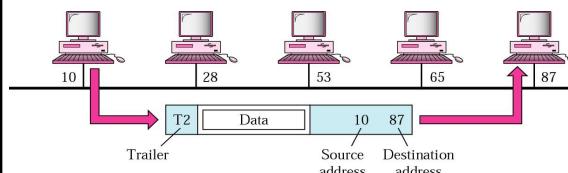
Data link layer

Data link layer is responsible for moving FRAMES from one Hop (Node) to the next. i.e. Hop- to- Hop delivery

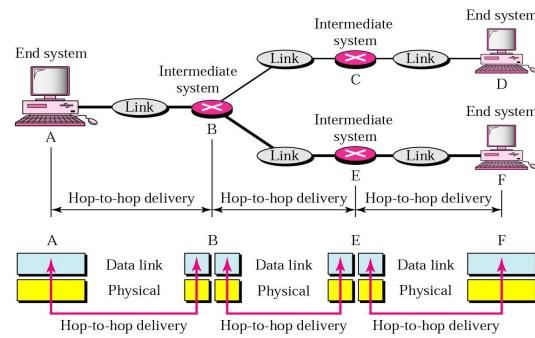
Data link layer

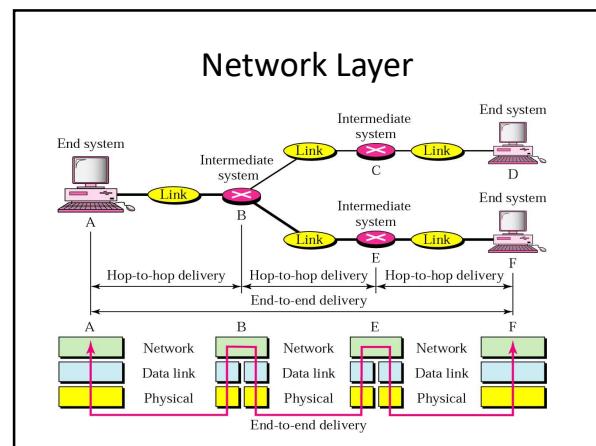
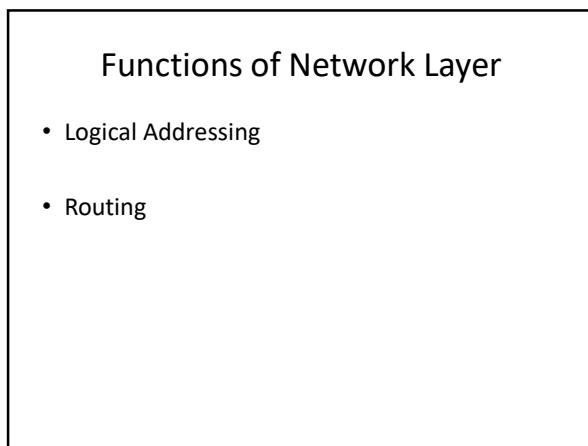
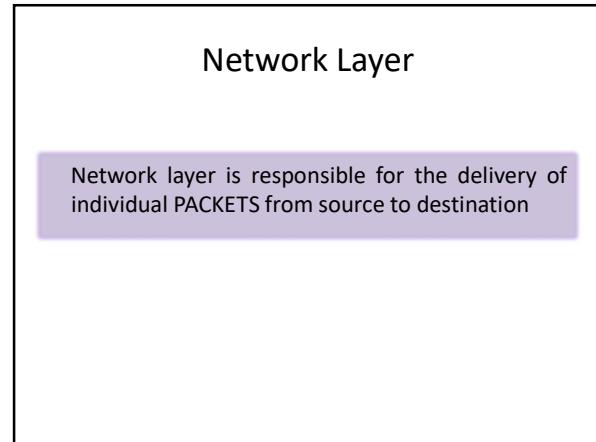
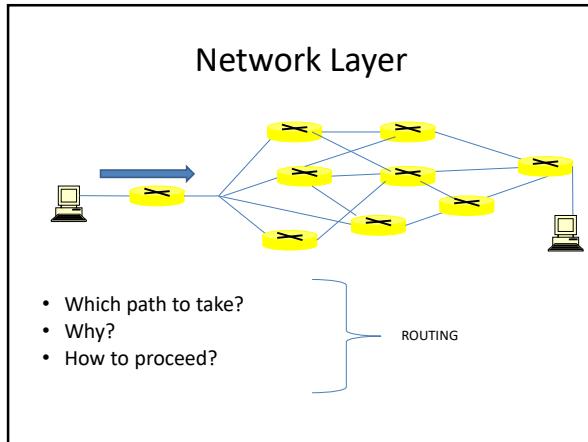
- Framing
- Physical Addressing
- Flow control
- Error control
- Access control

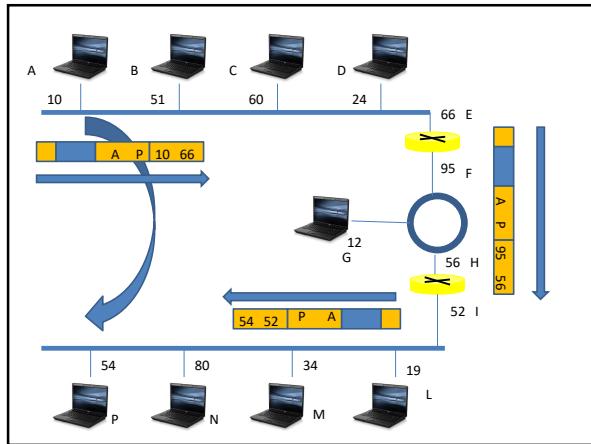
At data link layer...



Hop-to-Hop delivery

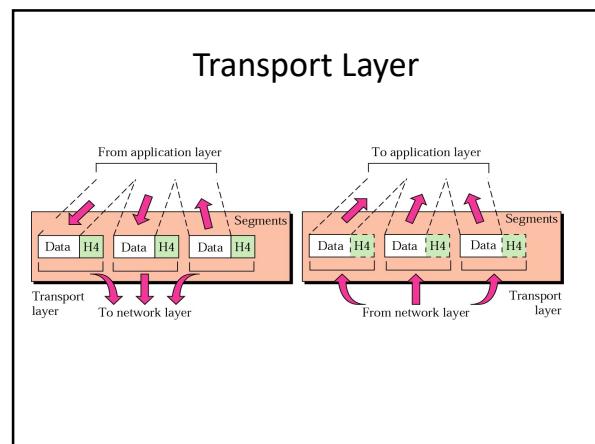
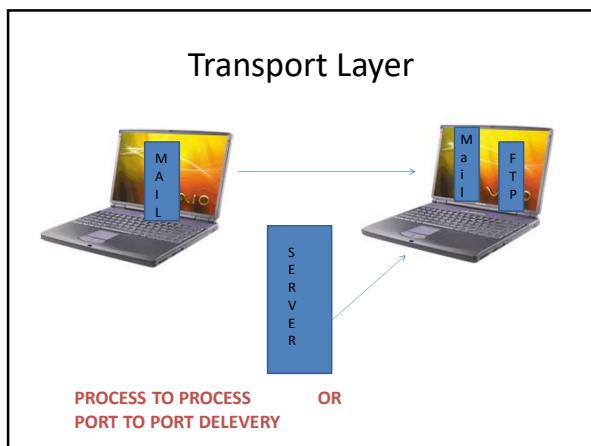


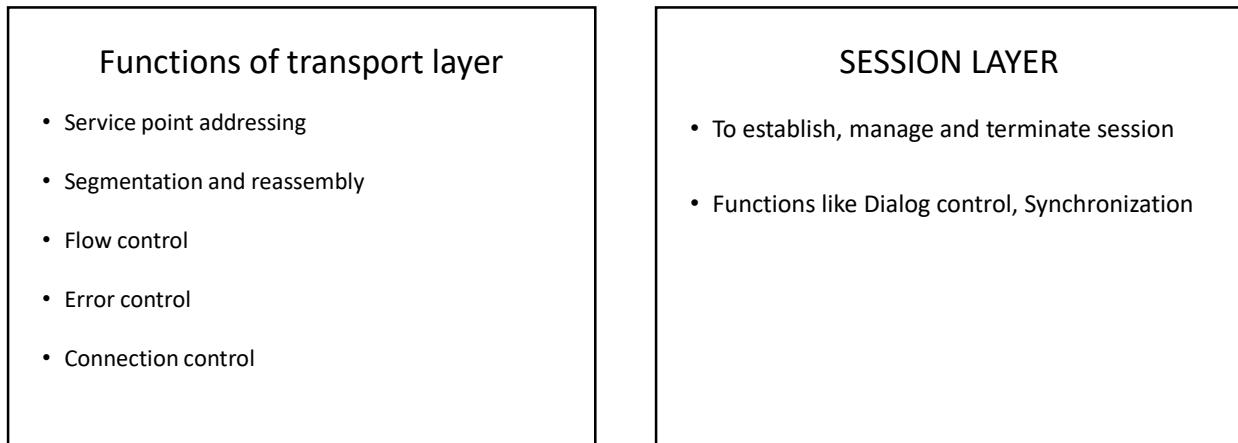
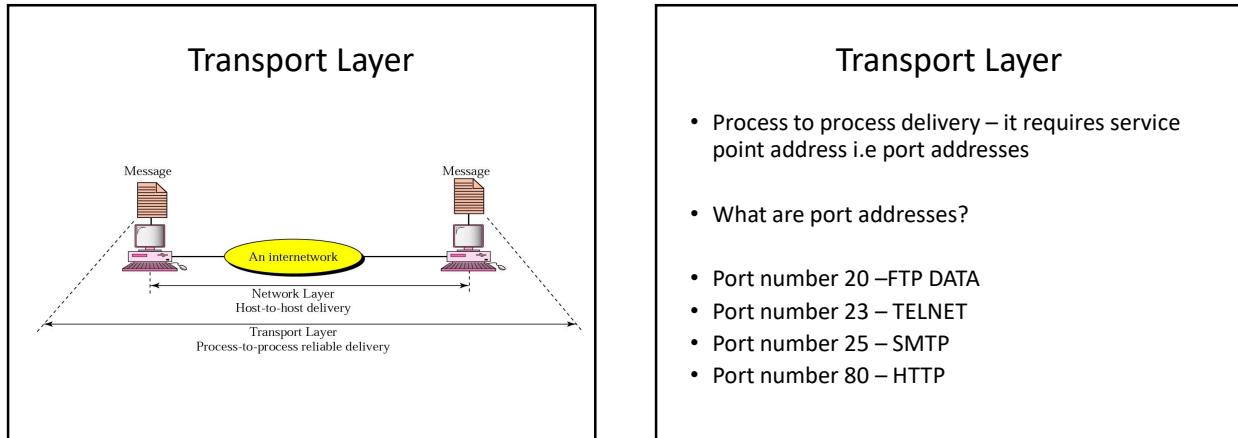




Transport Layer

Transport layer is responsible for delivery of message from one process to another.



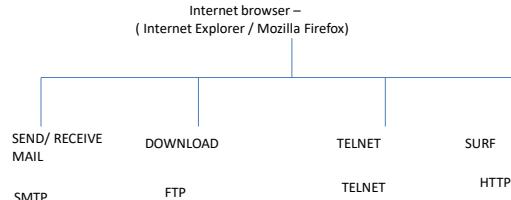


PRESENTATION LAYER

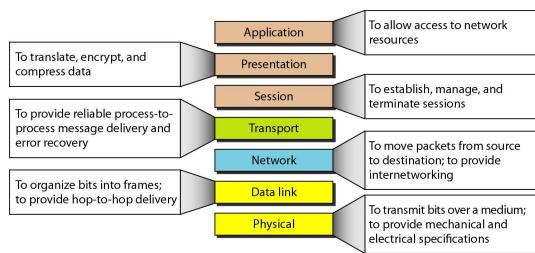
- Sender or receiver may be using different syntax, semantics for information
- Hence, message from above (appl layer) is transferred to common format at sender's side and converted to receiver's required format at his side using corresponding presentation layers.
- So, functions like translation, compression, encryption

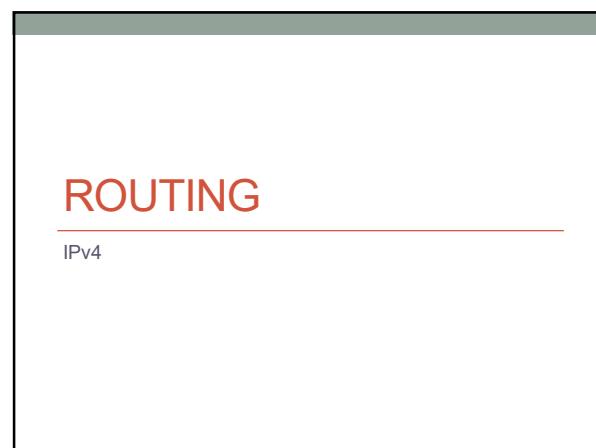
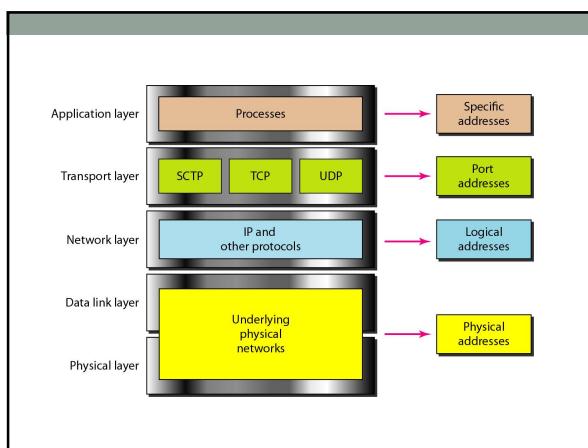
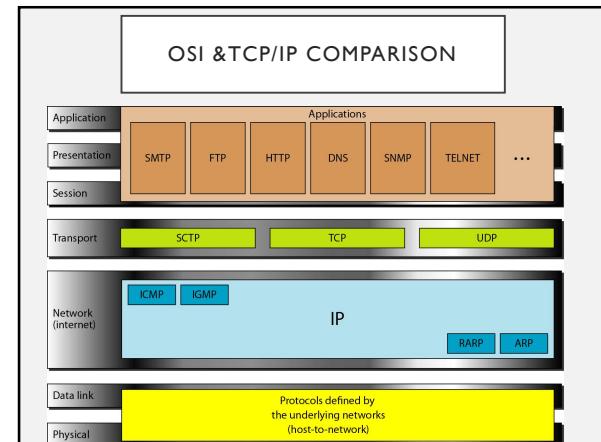
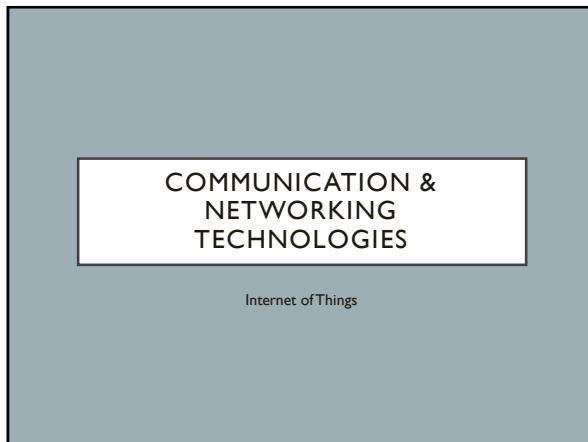
APPLICATION LAYER

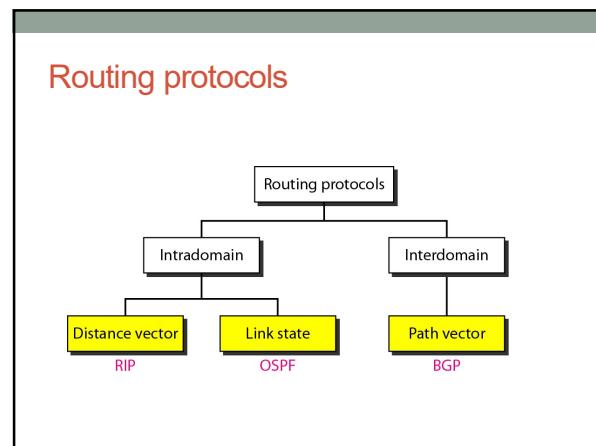
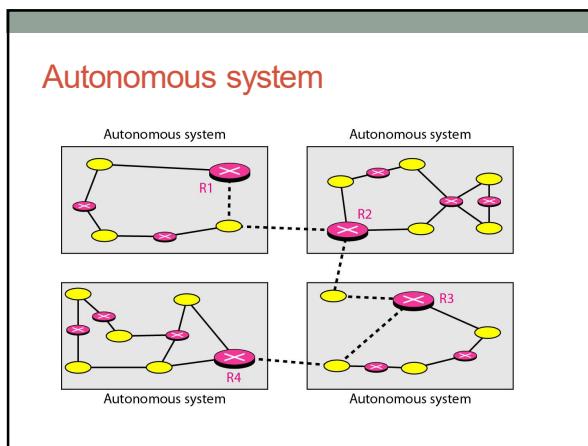
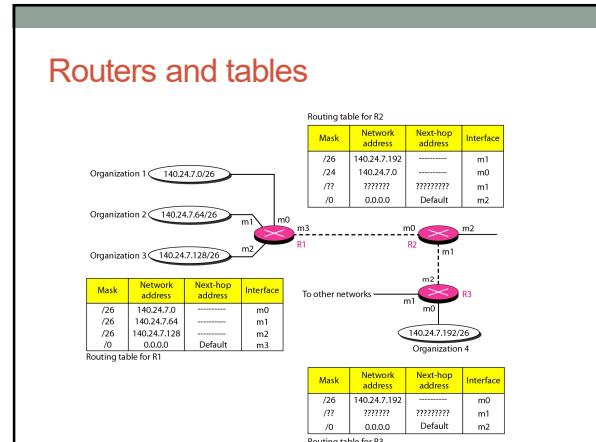
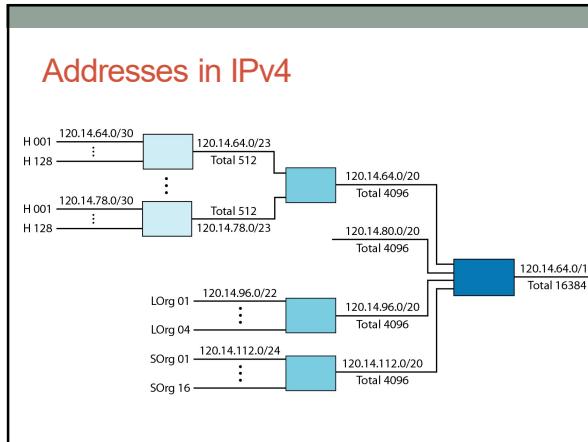
- It enables user/software to access network

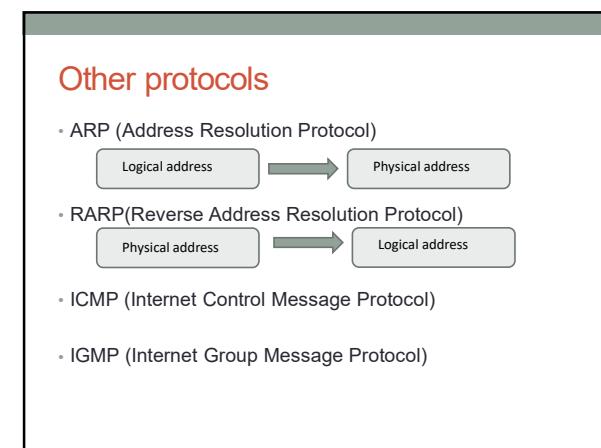
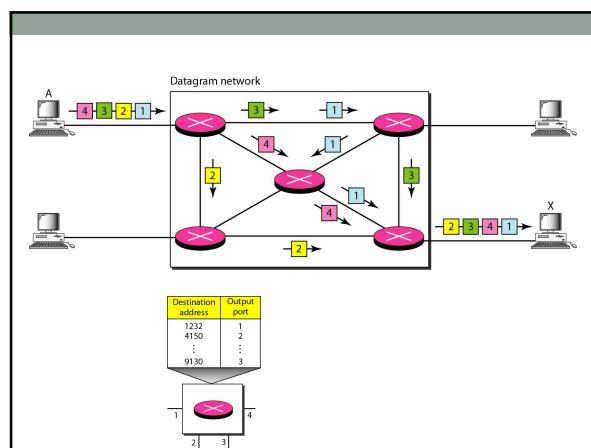
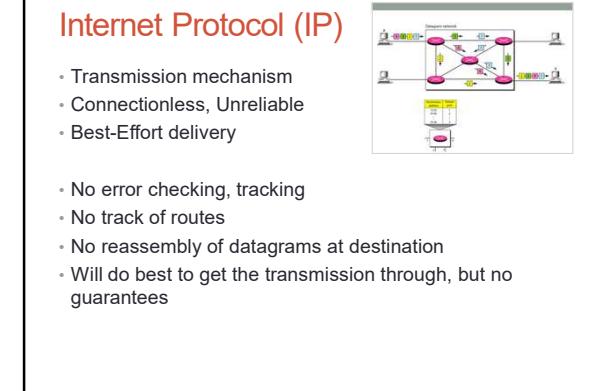
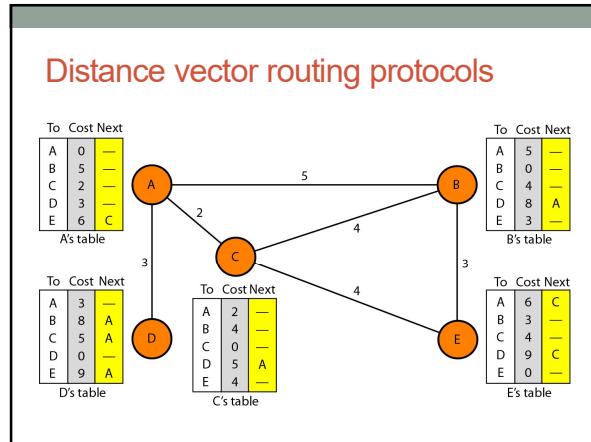


Summary









TRANSPORT LAYER PROTOCOLS

TCP and UDP

Transmission Control Protocol

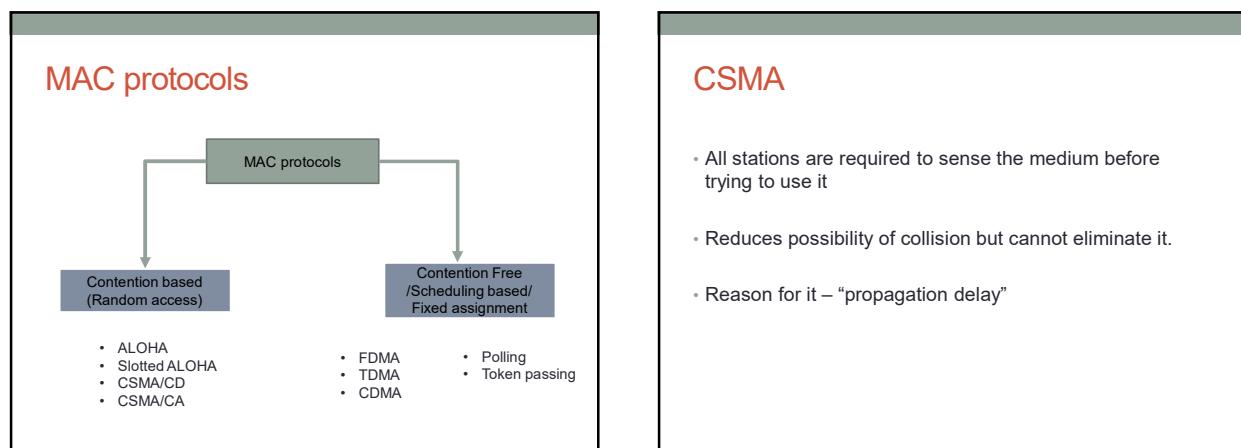
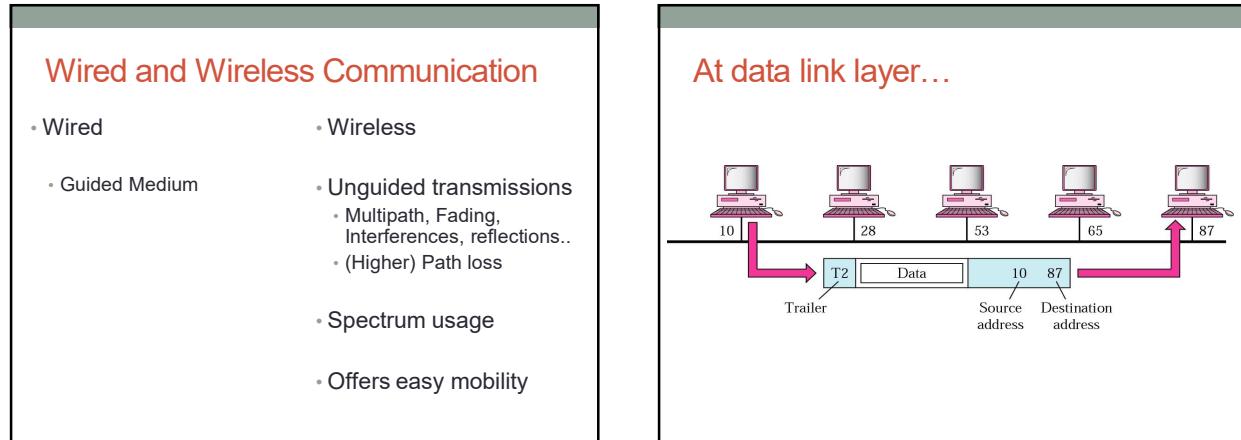
- Full Duplex communication
- Connection-oriented service
 - Creates stream oriented environment in which it accepts the responsibility of delivering bytes in order
- Reliable
 - Uses a mechanism to check safe and sound arrival of data
- Flow control
 - Rx controls amt of data to be sent by the sender
 - Byte oriented flow control
- Error control
 - Byte oriented
- Congestion control
 - Senders data tx is controlled by congestion in n/w

User Datagram Protocol

- Simple protocol with Minimum Overhead
- Connectionless
- Unreliable
- Requires less interaction between sender and Rx

WIRED AND WIRELESS NETWORKS

From Communication and MAC perspective



COMMUNICATION & NETWORKING TECHNOLOGIES

Internet of Things

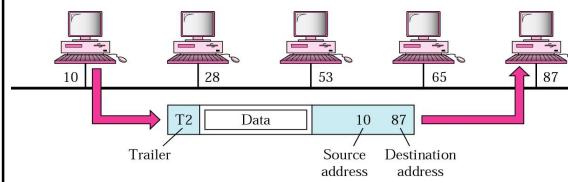
WIRED AND WIRELESS NETWORKS

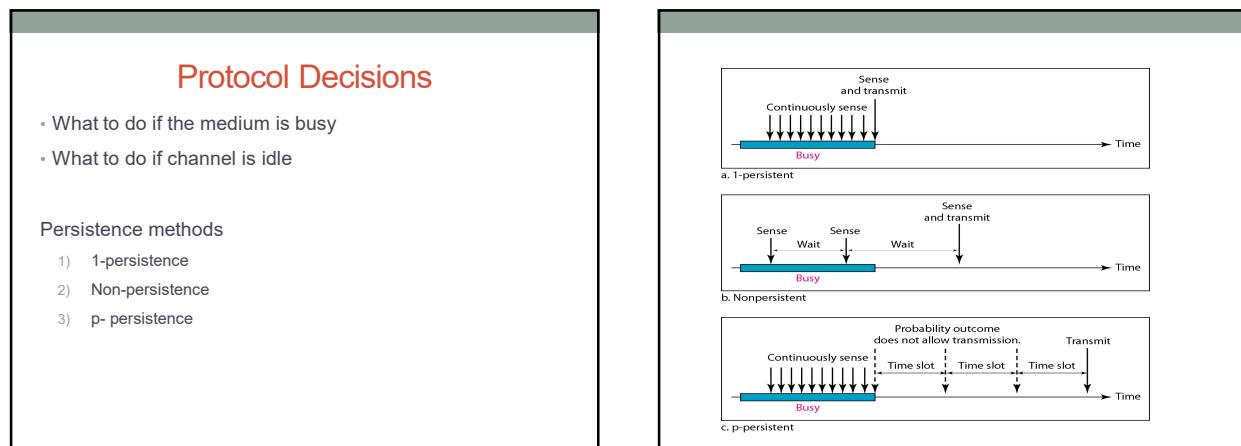
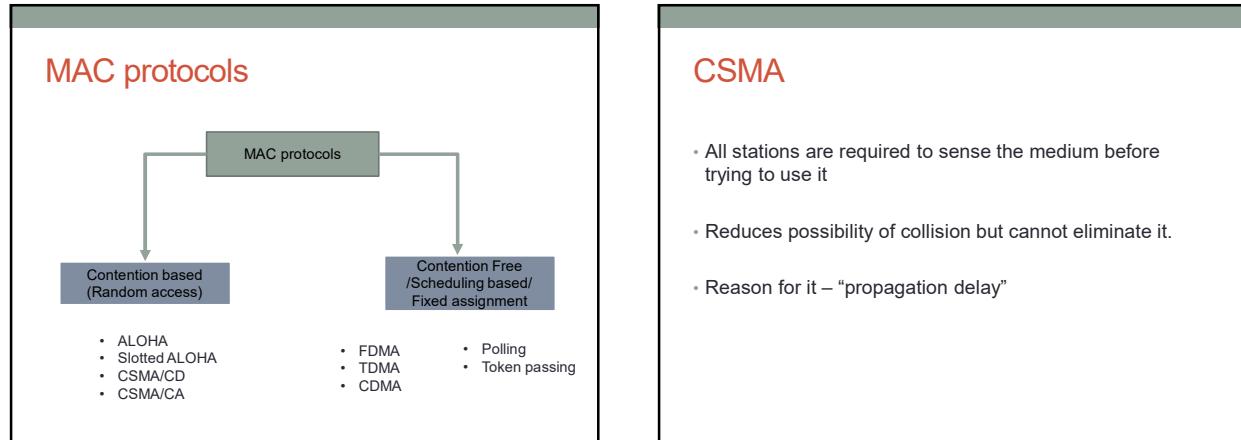
From Communication and MAC perspective

Wired and Wireless Communication

- Wired
 - Guided Medium
 - Unguided transmissions
 - Multipath, Fading, Interferences, reflections..
 - (Higher) Path loss
 - Spectrum usage
 - Offers easy mobility
- Wireless

At data link layer...

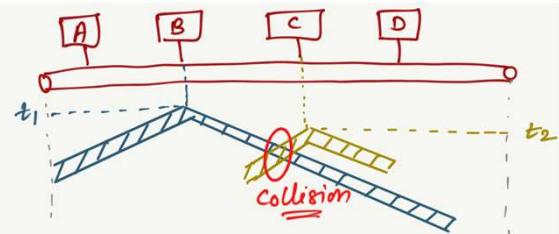




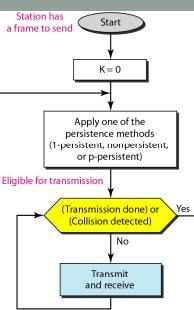
CSMA/CD

- Carrier sense multiple access – collision detection
- Augmentation of algorithm to handle collision
- Monitors medium while sending frame

Collision on shared medium

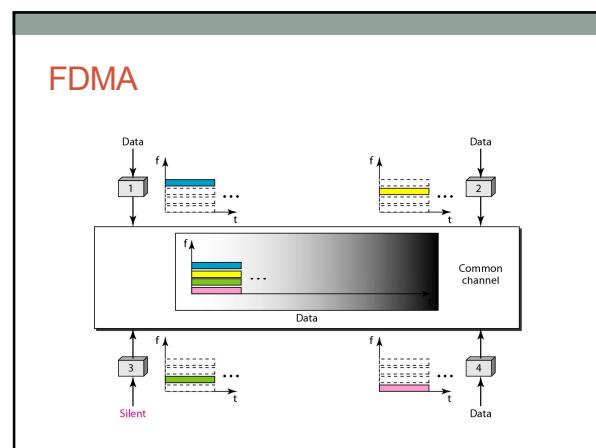
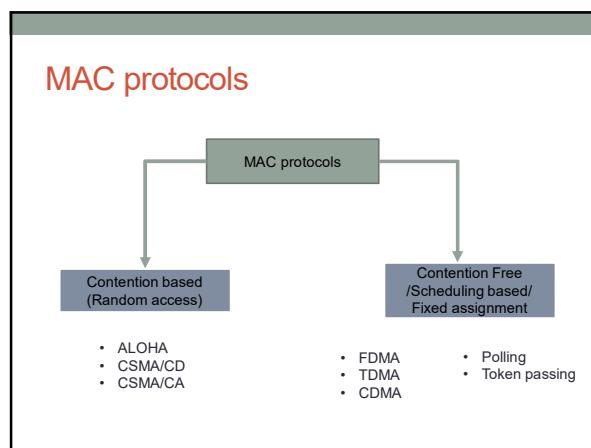
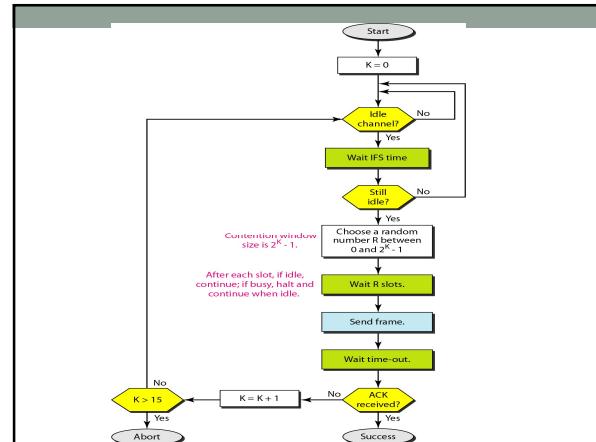
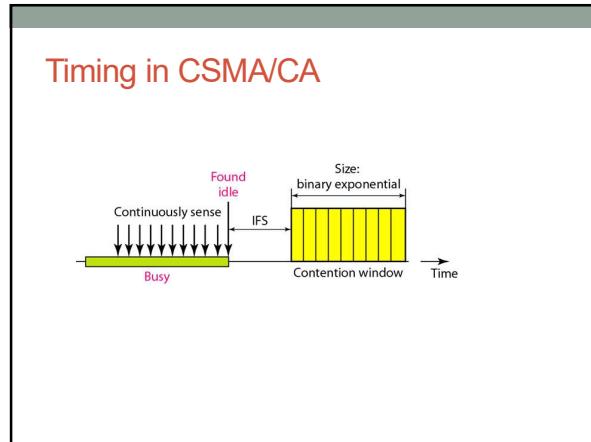


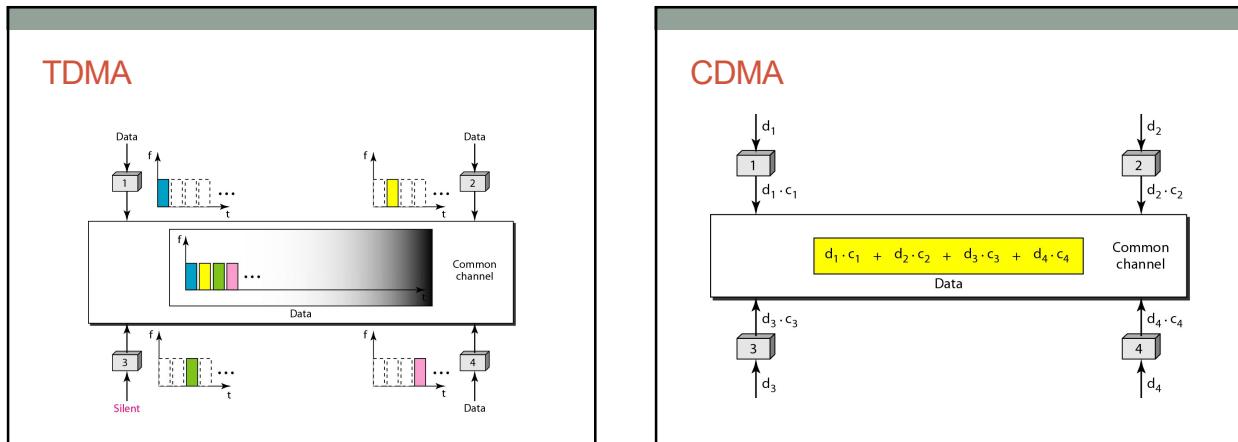
K: Number of attempts
 T_p : Maximum propagation time
 T_f : Average transmission time for a frame
 T_b : Back-off time



Wireless LAN - CSMA/CA

- Carrier Sense Multiple Access – Collision Avoidance
- A mechanism is used to avoid collision rather than detecting it.
- Detecting collision based on energy change might be difficult.





IEEE special project 802 (Yr. 1985)

- IEEE 802.2 : Logical Link Control (LLC)
- IEEE 802.3 : CSMA/CD (Ethernet)
- IEEE 802.11 : Wireless LAN
- IEEE 802.15 : Wireless PAN

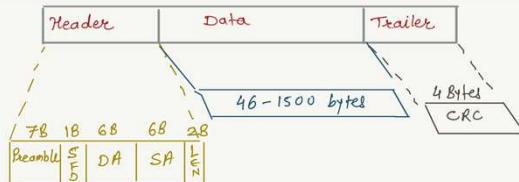
LLC

- Single data link control protocol for all IEEE LAN.
- Provides services to Network layer independent of the physical medium –enables access to different types of physical network.
- Provides interconnectivity between different LANs.
- Functions – flow control, error control, part of framing.

WIRED LAN

ETHERNET

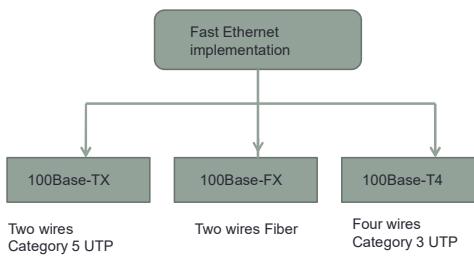
802.3 Frame format

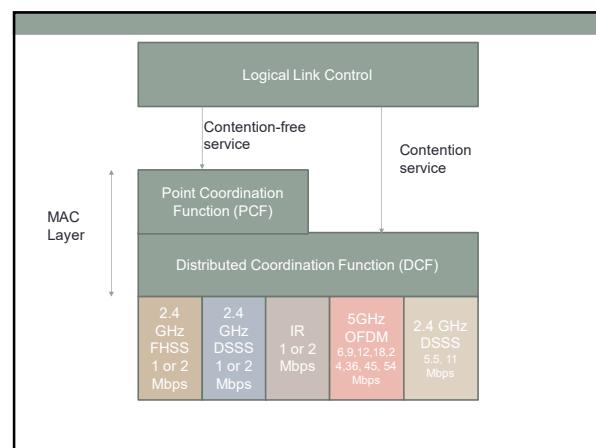
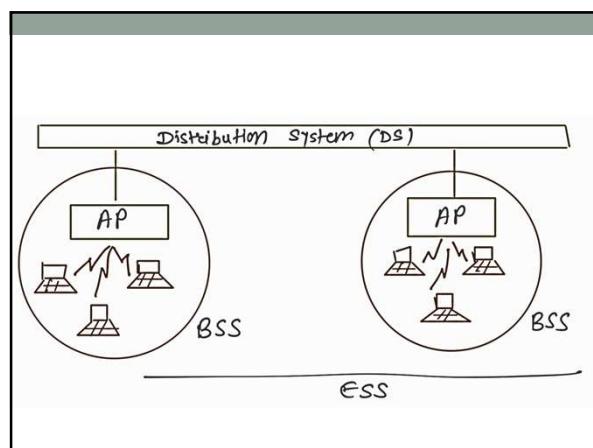
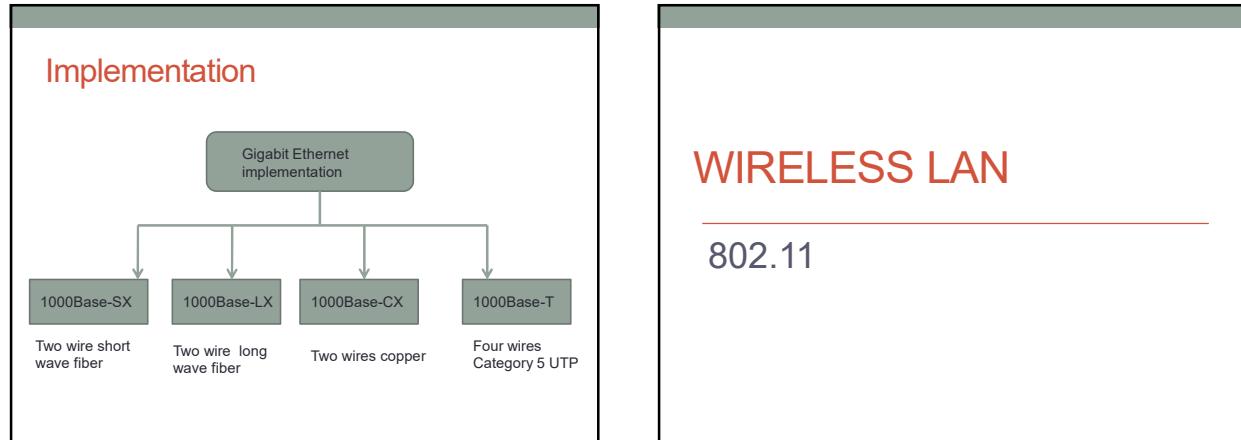


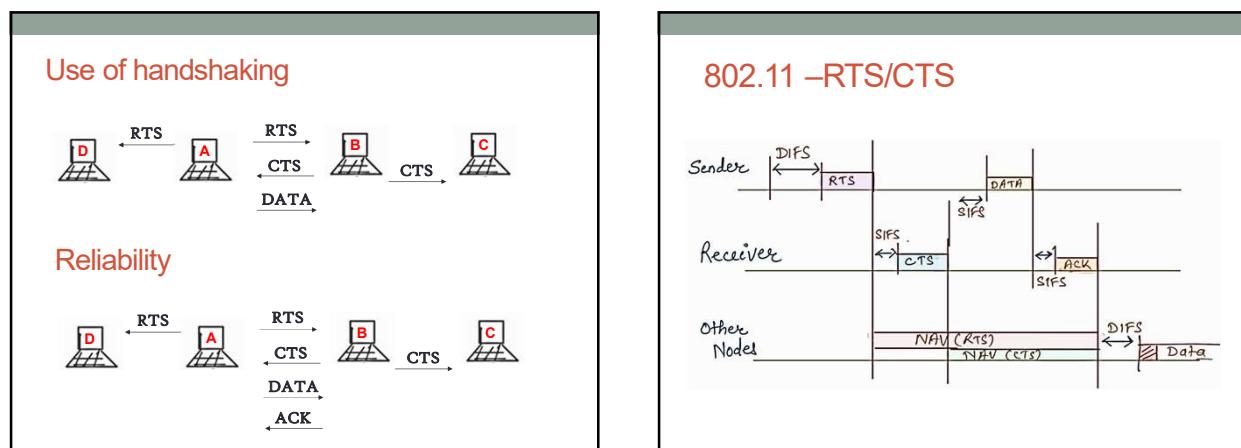
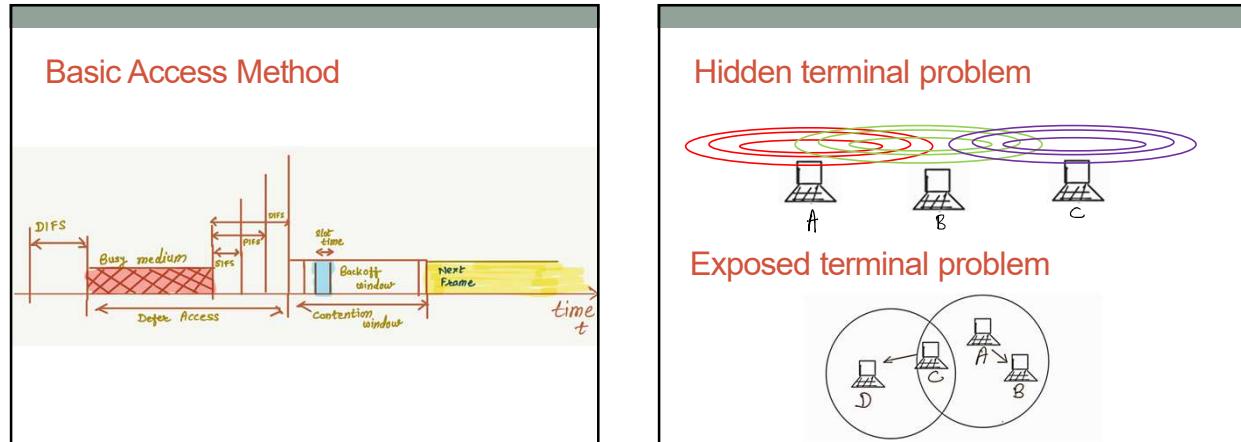
IEEE 802.3 10Mbps physical layer medium alternative

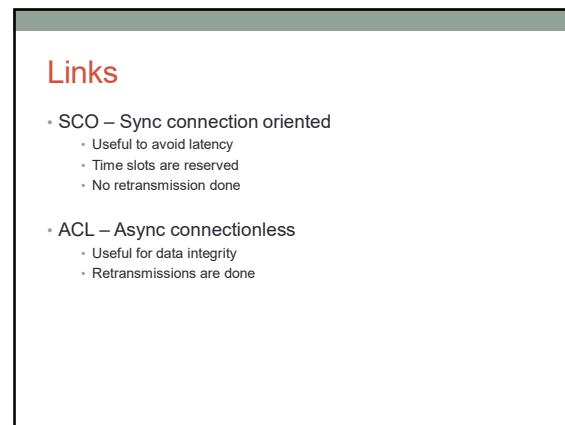
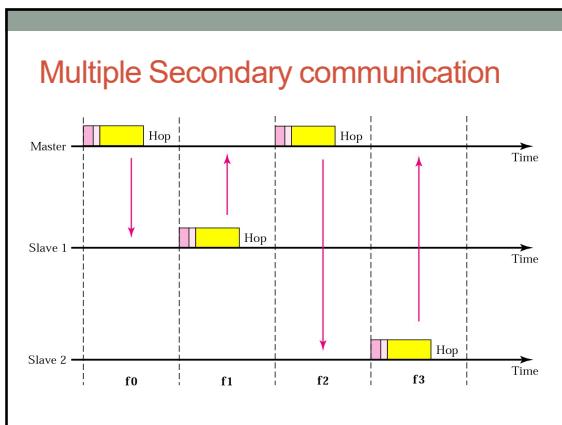
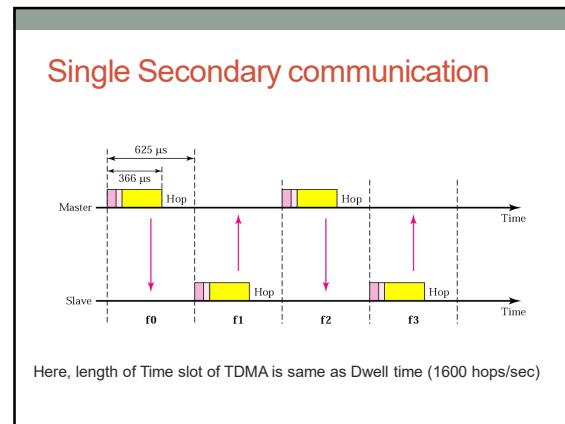
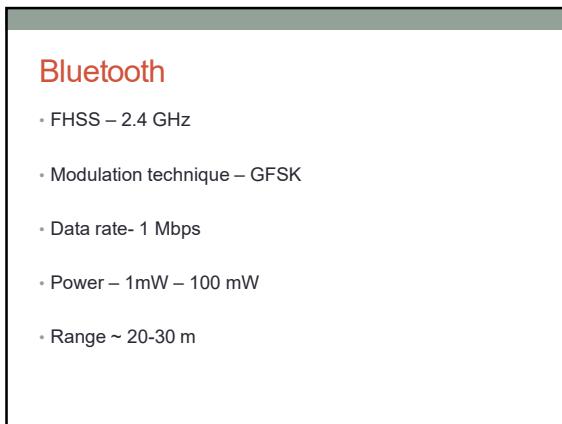
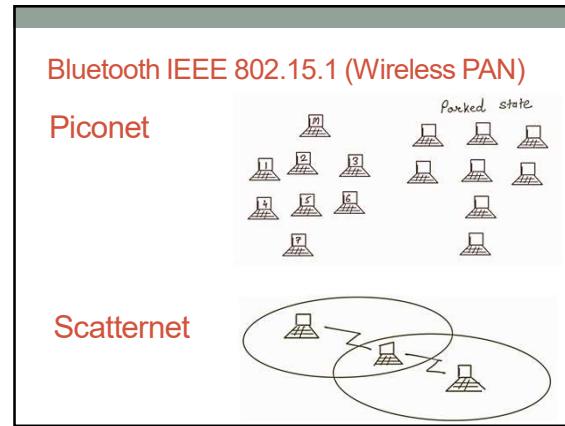
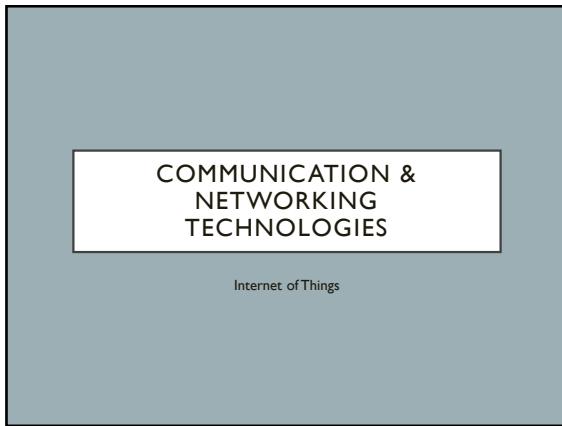
	10 BASE 5	10 BASE 2	10 BASE T	10 BASE-F
Transmission medium	Coaxial cable	Coaxial cable	UTP	850nm optical fiber pair
Signaling Technique	Baseband (Manchester)	Baseband (Manchester)	Baseband (Manchester)	Baseband (Manchester)
Topology	Bus	Bus	Star	Star
Maximum segment length	500 m	185 m	100 m	2000 m
Cable diameter	10 mm	5mm	0.4 to 0.6mm	62.5/125 micrometers

Implementation









IEEE 802.15.4 and Zigbee

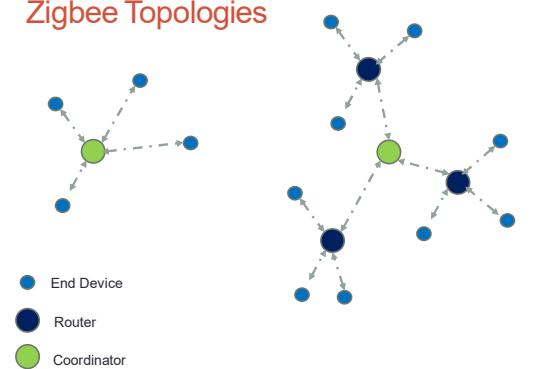
- The IEEE 802.15.4 (LRWPAN) standard defines the physical layer (PHY) and Media Access Control (MAC) layer.
- PHY covers frequency band, power, data-rate, modulation techniques
- Frequency bands -868MHz / 915MHz / 2.4GHz
- Data rate – 20 kbps to 250 kbps
- Range – 10 to 75 m
- MAC –
 - Beaconless mode (uses CSMA/CA, short data messages)
 - Beacon-enabled Mode (mix of contention free and contention based access)

Zigbee

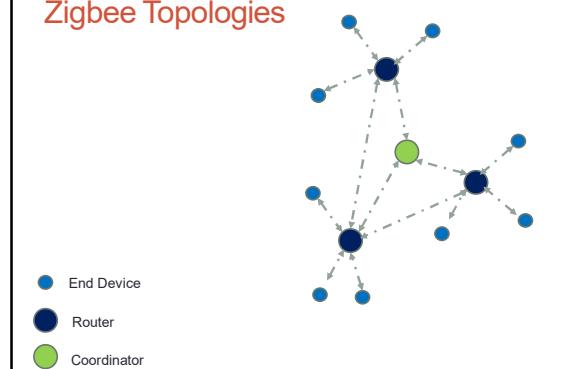
- ZigBee technology is a low data rate, low power consumption.
- Created by a set of companies which form the ZigBee Alliance.
- Defines layer 3 and above.
- Provides more flexible network topologies, intelligent message routing and enhanced security measures.
- Topologies – Star, mesh, cluster-tree.

<https://zigbeealliance.org/>

Zigbee Topologies



Zigbee Topologies



Mesh Network

- Nodes may be connected to each other via multiple connections.
- In routing tables, connections are dynamically updated and optimized.
- Re-configuration of routing paths is possible (in case of nodes appearing, disappearing and re-appearing in the network).
- Self-healing and stability of the network.

Near Field Communication (NFC)

- Short range wireless communication (radio waves -13.56 MHz)
- Applications –
 - Mobile (cashless) payments
 - Smart ticketing system
 - Data sharing
 - Information exchange (ex. Smart Business cards)
 - Targeted marketing (Smart Adv. Posters)
 - Access control



<https://nfc-forum.org/>

Mode of operation

- Peer-to-peer communication mode
- Reader/Writer mode
- Card-Emulation mode
- Standards- NFC-A, NFC-B, NFC-F, and NFC-V
- Defines the coding scheme, modulation tech & data rate
- Low data rate (~ 200 kbps)

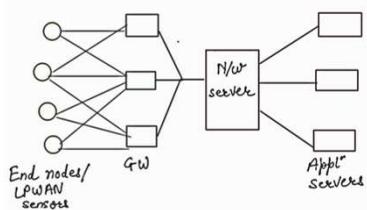
LoRa and LoRaWAN

- LoRa – Covers Physical layer
- Enables the low-power, long-range communication link
- Utilizes Chirp Spread Spectrum modulation technique
- License free band - 865 MHz to 867 MHz (India)
- Data rate – 290 bps – 50 kbps
- Range ~ 10 KM+
- Very high power efficiency Battery lifetime – 105 months (2000 mAh)
- Low cost, high capacity
- Interference immunity

<https://lora-alliance.org/>

LoRaWAN

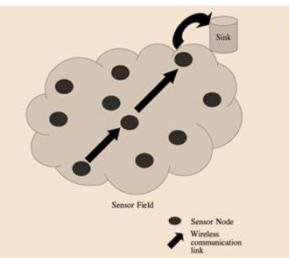
- LoRaWAN defines the communication protocol and system architecture for the network.



WIRELESS SENSOR NETWORK

WSN

Wireless Sensor Networks



Sensor networks are built using a large number of densely deployed sensor nodes

Wireless Sensor Networks

Deployments

- On the ground
- Underground
- Air
- Underwater
- On human bodies
- In vehicles
- Inside building structures

Collection of data

- Periodic
- Threshold based
- Query based
- Event triggered
- Combination of above

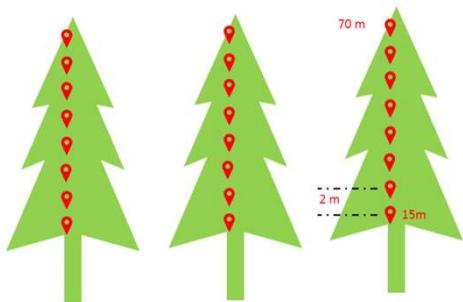
WSN applications

- Monitoring Space
- Monitoring Objects
- Monitoring Interaction between Space & Objects

Monitoring Space

- Environmental and Habitat Monitoring
- Precision Agriculture
- Indoor Climate Control
- Military Surveillance
- Intelligent Alarms

Redwood climate monitoring

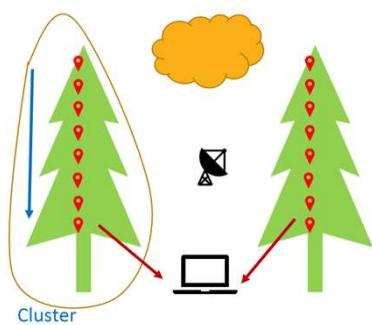


Parameters Monitored

- Temperature
- Humidity
- Solar Radiation
- Light Levels
- Photosynthetically active radiation

Interval of 5 mins

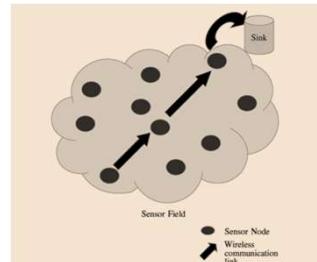
Network structure



WIRELESS SENSOR NETWORK

WSN

Wireless Sensor Networks



- Sensor Node
 - Sensing
 - Processing/Computation
 - Comm/networking

Sensor networks are built using a large number of densely deployed sensor nodes.

Wireless Sensor Networks

Deployments

- On the ground
- Underground
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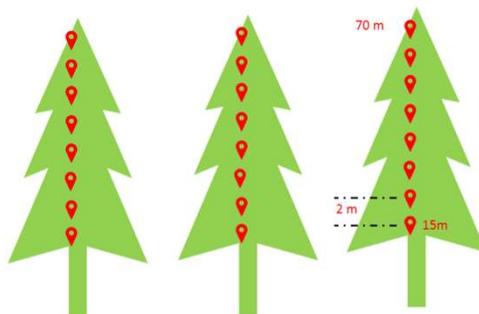
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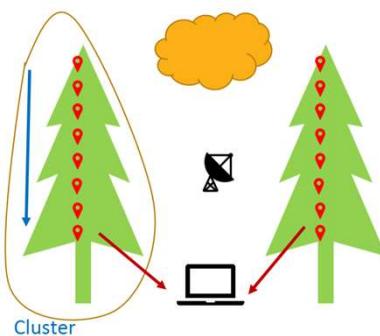


Parameters Monitored

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Interval of 5 mins

Network structure



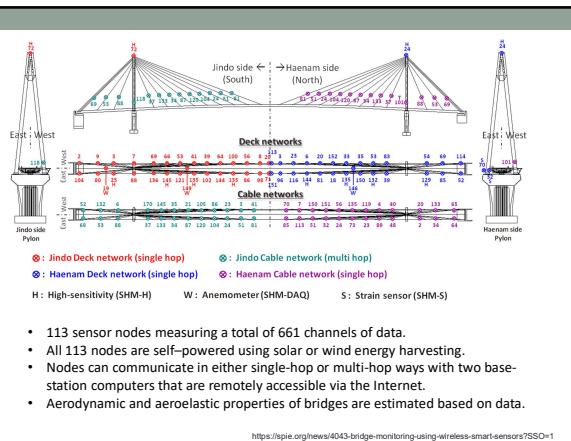
Monitoring objects

- Structural monitoring
- Condition based maintenance
- Medical Diagnostics

Bridge monitoring system



Jindo Bridge in South Korea



Monitoring Interaction between Space & Objects

- Wildlife Habitats
- Disaster Management
- Asset Tracking
- Manufacturing Process Flows

Zebranet (Kenya)

- GPS position samples every 3 minutes
- Wide range – hundred's or thousands of kms
- Parameters
 - Moving (Mobility patterns)
 - Sleep patterns
 - Drinking habits

Node structure

```

graph TD
    subgraph Node [Node structure]
        direction TB
        subgraph SU [Sensing Unit]
            SU_Sensor[Sensor, ADCs etc]
            SU_ADC[ADCs etc]
        end
        subgraph PU [Processing Unit]
            PU_Processor[Processor, Memory, etc]
        end
        subgraph CU [Comm Unit]
            CU_Transceivers[Transceivers]
        end
        subgraph LFS [Location finding system]
            LFS_BT[zeero BT]
            LFS_I mote[Intel IMOTE2]
            LFS_BTnodeEyes[BTNode Eyes]
            LFS_Nokia[NOKIA]
            LFS_Hp[HP]
            LFS_Trio[Trio]
            LFS_Motorola[MOTOROLA]
            LFS_Shockfish[shockfish]
            LFS_Motevo[motevo]
            LFS_Crossbow[crossbow]
            LFS_Telos[Telos]
            LFS_Luxoft[Luxoft Lab]
            LFS_Ultimote[Ultimote]
            LFS_DigitalSun[digital sun]
            LFS_RainMica[rain-mica]
            LFS_MoteC2dot[mote c2dot]
            LFS_Xbow[XBOW]
            LFS_Mica2[Xbow mica2]
            LFS_MicaZ[Xbow micaZ]
            LFS_Bosch[Bosch]
            LFS_Sensicast[Sensicast]
            LFS_Dust[DUST]
            LFS_Huawei[Huawei]
            LFS_RenewablePower[Renewable Power]
            LFS_Leap[LEAP]
        end
        subgraph M [Mobilizer]
            M_BT[zeero BT]
            M_I mote[Intel IMOTE2]
            M_BTnodeEyes[BTNode Eyes]
            M_Nokia[NOKIA]
            M_Hp[HP]
            M_Trio[Trio]
            M_Motorola[MOTOROLA]
            M_Shockfish[shockfish]
            M_Motevo[motevo]
            M_Crossbow[crossbow]
            M_Telos[Telos]
            M_Luxoft[Luxoft Lab]
            M_Ultimote[Ultimote]
            M_DigitalSun[digital sun]
            M_RainMica[rain-mica]
            M_MoteC2dot[mote c2dot]
            M_Xbow[XBOW]
            M_Mica2[Xbow mica2]
            M_MicaZ[Xbow micaZ]
            M_Bosch[Bosch]
            M_Sensicast[Sensicast]
            M_Dust[DUST]
            M_Huawei[Huawei]
            M_RenewablePower[Renewable Power]
            M_Leap[LEAP]
        end
        subgraph P [Battery (Power Unit)]
            P_GEH[Power Generation/Energy Harvesting unit]
        end
    end
    SU_Sensor <--> PU_Processor
    PU_Processor <--> CU_Transceivers
    CU_Transceivers <--> P_GEH
    P_GEH <--> LFS_BT
    P_GEH <--> M_BT
    P_GEH <--> LFS_BTnodeEyes
    P_GEH <--> M_BTnodeEyes
    P_GEH <--> LFS_Nokia
    P_GEH <--> M_Nokia
    P_GEH <--> LFS_Hp
    P_GEH <--> M_Hp
    P_GEH <--> LFS_Trio
    P_GEH <--> M_Trio
    P_GEH <--> LFS_Motorola
    P_GEH <--> M_Motorola
    P_GEH <--> LFS_Shockfish
    P_GEH <--> M_Shockfish
    P_GEH <--> LFS_Motevo
    P_GEH <--> M_Motevo
    P_GEH <--> LFS_Crossbow
    P_GEH <--> M_Crossbow
    P_GEH <--> LFS_Telos
    P_GEH <--> M_Telos
    P_GEH <--> LFS_Luxoft
    P_GEH <--> M_Luxoft
    P_GEH <--> LFS_Ultimote
    P_GEH <--> M_Ultimote
    P_GEH <--> LFS_DigitalSun
    P_GEH <--> M_DigitalSun
    P_GEH <--> LFS_RainMica
    P_GEH <--> M_RainMica
    P_GEH <--> LFS_MoteC2dot
    P_GEH <--> M_MoteC2dot
    P_GEH <--> LFS_Xbow
    P_GEH <--> M_Xbow
    P_GEH <--> LFS_Mica2
    P_GEH <--> M_Mica2
    P_GEH <--> LFS_MicaZ
    P_GEH <--> M_MicaZ
    P_GEH <--> LFS_Bosch
    P_GEH <--> M_Bosch
    P_GEH <--> LFS_Sensicast
    P_GEH <--> M_Sensicast
    P_GEH <--> LFS_Dust
    P_GEH <--> M_Dust
    P_GEH <--> LFS_Huawei
    P_GEH <--> M_Huawei
    P_GEH <--> LFS_RenewablePower
    P_GEH <--> M_RenewablePower
    P_GEH <--> LFS_Leap
    P_GEH <--> M_Leap
  
```

- Limited Battery power
Ex. 2 AA batteries
- Limited storage capacity
Ex. 128KB-1MB
- Limited processing powers
Ex. 8/16 bit processors
- Low data rate/bandwidth
Ex. 1Kbps - 1Mbps, 3-100 Meters

Glimpse at available motes

The timeline shows the progression of mote technology from 1997 to 2007, with each year marked by a different mote model:

- 1997: LWIM-III (UCLA)
- 1998: WINS (UCLA/Rockwell)
- 1999: Intel rene'
- 2000: Intel/UCB dot
- 2001: intel cf-mica
- 2002: zeevo BT, Intel IMOTE2, BTNode Eyes, Nokia, HP, Trio, Motorola, shockfish, motevo, crossbow, Telos, Luxoft Lab, Ultimote, digital sun, rain-mica, mote c2dot, XBOW, mica2, micaZ, Bosch, sensicast, DUST, Huawei, Renewable Power, Leap
- 2003: XBOW, mica2, c2dot, XBOW mica2, XBOW micaZ
- 2004: XBOW, mica2, XBOW micaZ
- 2005: XBOW, mica2, XBOW micaZ
- 2006: XBOW, mica2, XBOW micaZ
- 2007: XBOW, mica2, XBOW micaZ

• Node's characteristics	• System's characteristics
<ul style="list-style-type: none"> Power Range Timing mechanism Size Cost Flexibilities Processing capacity 	<ul style="list-style-type: none"> Lifetime Coverage Response time Temporal accuracy Effective sampling rate Ease of deployment Overall cost
• Mote should have Individual Chars that satisfy a Distributed Environment	• Map overall design requirement to Individual Device Capability

4

Challenges of Sensor Networks

- Random deployment – self configuring and maintaining networks required.
- Heterogeneity (of nodes)
- Different types of sensors and interfacing
- Mobility of nodes
- Wireless communication channel (temporally and spatially varying, Unreliable)
- Large scale coordination
- Distributed processing
- Real-time computation

Challenges of Sensor Networks

- Limited Resources –Energy, processing power, bandwidth, storage
- Harsh environment – not easily accessible
- Failure of nodes (Extreme environment and limited battery) - redundancy and fault tolerance required
- Applications requirements –
 - Varying latency bounds
 - Duration of deployment
 - Resolution (density of deployment)
 - Cost

Types of deployments

- Simpler – ex. of indoor –warehouse monitoring
 - Power supply available
 - Nodes are accessible
- Outdoor – Glacier monitoring
 - Energy consumption -Several months to years
 - Need redundancy – no accessibility
- Large scale – Habitat monitoring, ocean
 - Large no of nodes
 - Mobility - more frequent reconfiguration
 - Long duration - Energy optimization required

Deployment objectives

- Coverage
 - Sensing range, sampling rate
 - Resolution required
- Connectivity
 - Communication range
 - Partitioning or voids formations
- Topology
 - Direct comm -Star
 - Multi-hop
 - Hierarchy –Cluster formation

PROTOCOL STACK FOR WSN

Considerations of Protocol stack

- WSN design has to consider -
 - Environmental conditions
 - Application's requirements
 - Limited available resources
- Network architecture and entire protocol stack needs to be critically examined and modified for optimization.
- Ideally, the network protocol stack is expected to be channel-aware and application-aware leading to optimal network performance with efficient use of resources.

Physical Layer

- Need **simpler** radio technology with
 - High-spectral efficiency
 - Min energy consumption
 - Low cost and size
- Immunity from interference and noise
- Reliability/R robustness from multipath and fading effects
- Licensed and unlicensed bands of operation
- Options- Narrowband, Spread-spectrum, UWB

It is more efficient to transmit a signal using multi-hop network composed of short-range radios rather than using a long-range link.

Data Link Layer

- Energy efficient
- Avoid collisions, Idle listening, overhearing, over-emitting
- Small code size and memory requirements
- Scalability
- Adaptability to changes in topology
- Other issues – Throughput/channel utilization, Latency, fairness etc.

Sensor nodes can follow sleep/Wake patterns

Network layer

- Energy efficient operations
- End-to-end delay bounds
- Void/disconnections happening due to
 - Node failure
 - Depletion of battery
 - Unforeseen mobility
 - Obstacles
 - Nodes may follow sleep/wake patterns
- Routing decisions based on geographic co-ordinates and/or data semantics instead of node IDs.

Data aggregation can be used to avoid traffic of redundant data on the network.

Upper layers

- **Transport Layer** – would be needed (at gateway) when WSN is connected to Internet.
- In a WSN environment, hop-by-hop reliability of data transfer is a preferable approach than the conventional end-to-end reliability.
- **Application Layer** - WSN technologies are designed to realize a particular application.

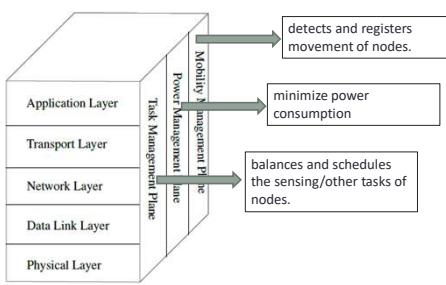
WIRELESS SENSOR NETWORK

WSN

Approaches of protocol stack design

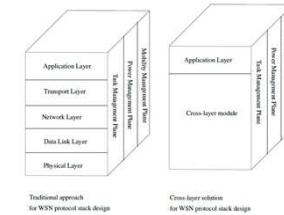
- WSN's provide functionalities which are not present in the traditional networks.
- Various approaches of protocol stack design have been proposed.
- Blocks needed to build WSN might span several layers of OSI model.
- For ex. Localization

Management planes in WSN



Cross-layer approach

- Joint optimization and design of networking layers.
- Functionalities of two or more layers can be combined to form a single coherent framework.
- Results in significant improvement in terms of energy conservation.



TIME SYNCHRONIZATION

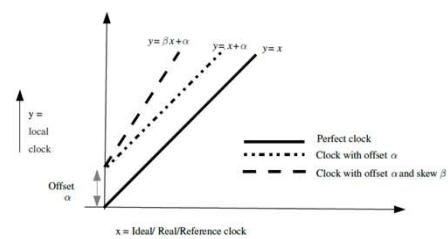
Time Synchronization

- The process of achieving and maintaining a common time-base throughout the network is called as time synchronization.
- Correct timing information is required in situations such as
 - Absolute time stamp - Event monitoring application
 - Right chronology of the events - Target Tracking applications
 - TDMA MAC protocols, Localization, sleep/wake scheduling, task scheduling

Issues

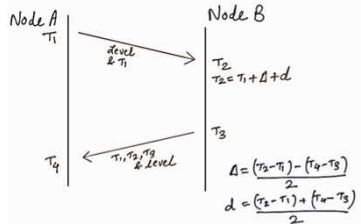
- Timing information available to node from the local clock.
- Most common clock hardware on nodes is not very accurate because the frequency (that makes time increase) is never exactly right.
- Accuracies are affected by temperature, supply voltage fluctuations, aging and so on.
- For TelosB motes, the upper bound on clock drift is 40 ppm. This means a clock in mote can lose up to 40 microseconds in a second.

Characteristics of clock



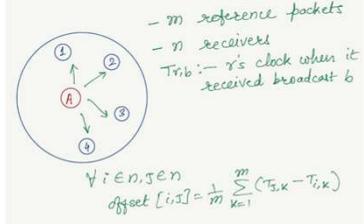
Timing-sync Protocol for Sensor Networks

- TPSN Protocol – Ganeriwal et.al., UCLA, 2003



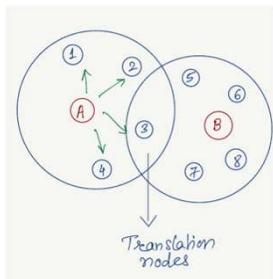
Time Synchronization using Reference Broadcasts

- RBS Protocol – Elson et.al., UCLA, 2002



RBS broadcast is always used as a *relative* time reference, never to communicate an absolute time value.

RBS - Multi-Hop Time Synchronization



LOCALIZATION PROTOCOLS

Need?

- Sensed data need a geo-stamp
- Certain applications – Target tracking, speed estimation
- Geographical routing depends on location information
- Aids in self-organization and self-healing of the WSN
- GPS is expensive (cost, size and energy required)
- GPS systems may not be available in some cases

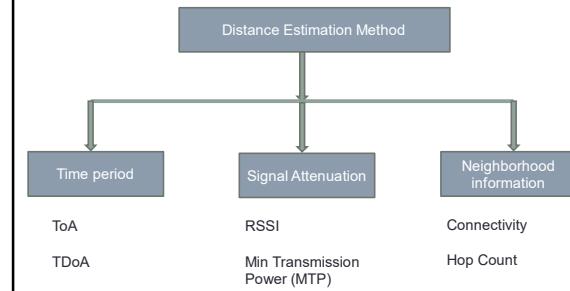
Requirements of localization

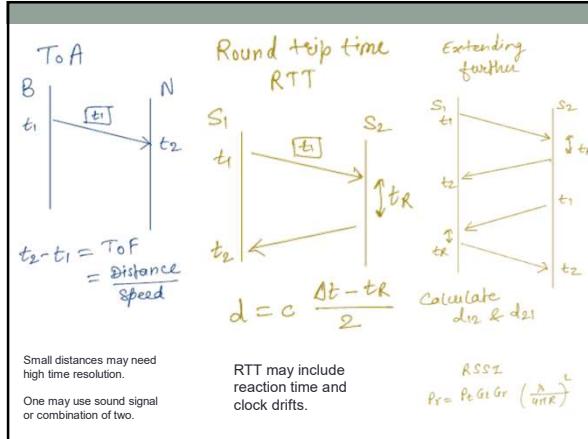
- Precision as per the application.
- Efficient in utilizing resources – If beacon hardware is required- should be minimal.
- Distributed algorithm (processing).
- Adaptive to the changing environment.
- Fast – Localization is needed immediately after deployment of network, many other protocols depend on it.
- Mobile networks might need repetitive process.

Classification of algorithm

- Approximate Vs Precise
- Central Vs Distributed
- Range based Vs Range Free
- Relative Vs Absolute
- Indoor Vs Outdoor
- Beacon-Free Vs Beacon based

Distance estimation methods



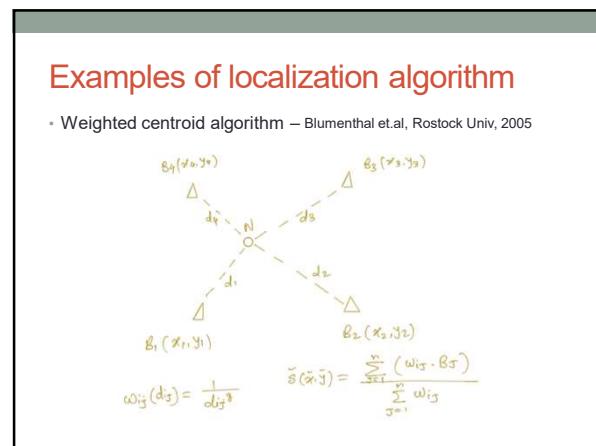
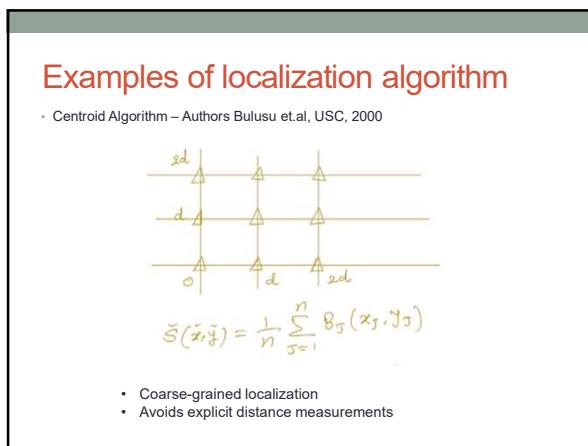


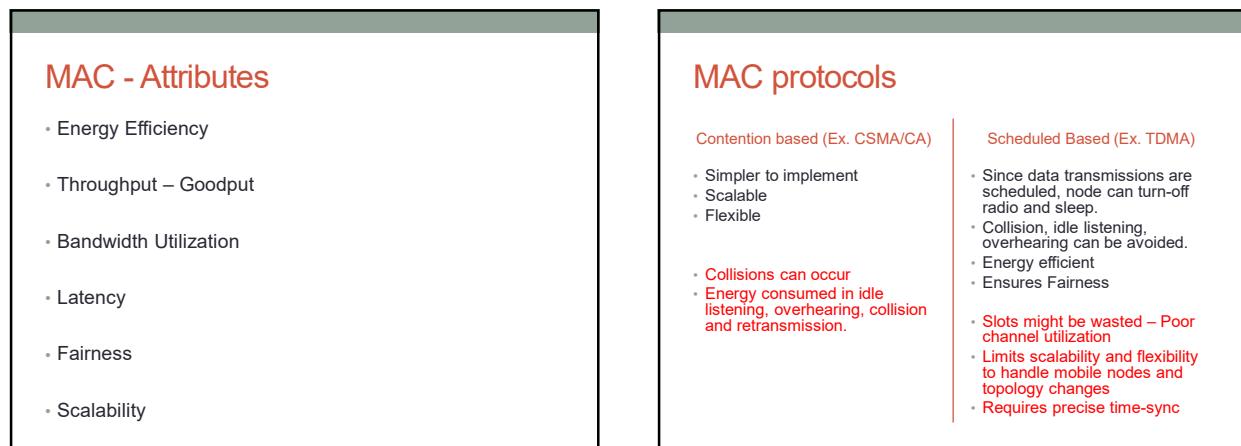
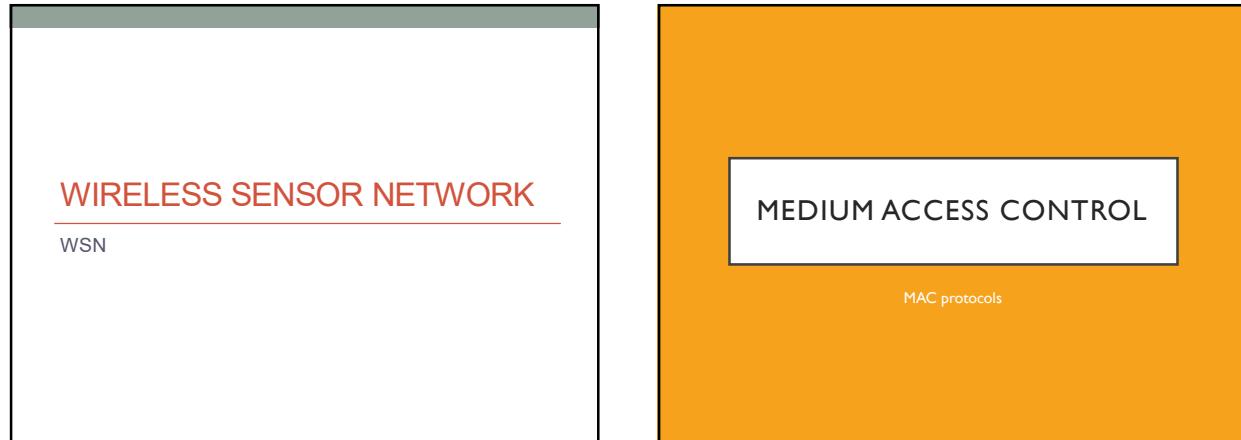
The diagram illustrates TDoA using two beacons, B_1 and B_2 , with start times t_1 and end times t_2 . The distance to each beacon is d_1 and d_2 respectively. The time difference is $\Delta t = t_2 - t_1$. The formula for distance is:

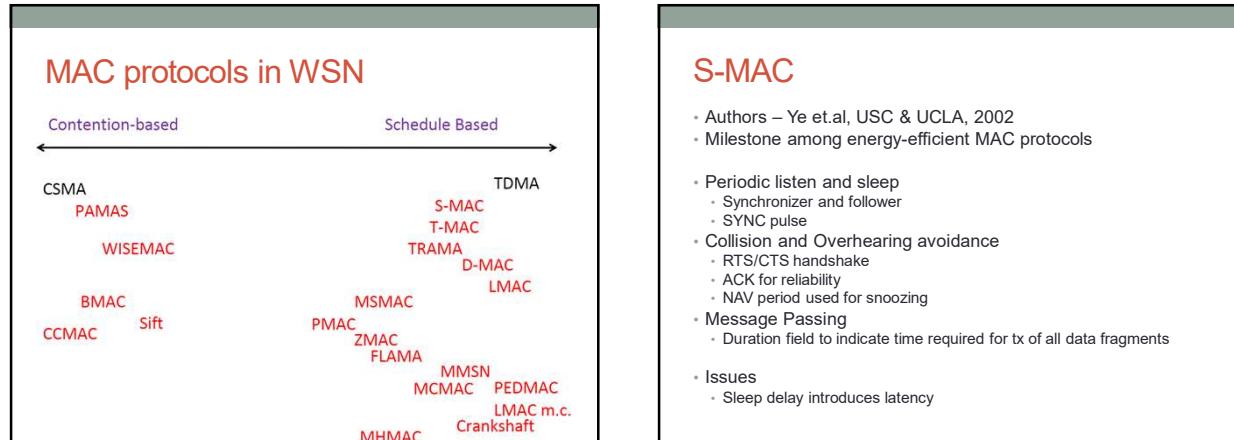
$$d = \frac{\sqrt{(x-x_1)^2 + (y-y_1)^2}}{\Delta t} - \frac{\sqrt{(x-x_2)^2 + (y-y_2)^2}}{\Delta t}$$

Definitions:

- 1st Beacon - start time
- 2nd Beacon - end time
- Δt = end - start
- Δd = $\Delta t \cdot C = d_1 - d_2$
- $\frac{\Delta d}{\Delta t} = \frac{d_1}{\Delta t} - \frac{d_2}{\Delta t}$







S-MAC

- Authors – Ye et.al, USC & UCLA, 2002
- Milestone among energy-efficient MAC protocols
- Periodic listen and sleep
 - Synchronizer and follower
 - SYNC pulse
- Collision and Overhearing avoidance
 - RTS/CTS handshake
 - ACK for reliability
 - NAV period used for snoozing
- Message Passing
 - Duration field to indicate time required for tx of all data fragments
- Issues
 - Sleep delay introduces latency

ROUTING PROTOCOLS

Simple approaches of relaying data

- Flooding
 - Each packet received by sensor node is broadcast to all its neighbors, until the destination is reached.
 - Large number of duplicate packets will be generated on network.
 - Multiple nodes may send same data to the same destination node.
- Gossiping
 - Select a random neighbor (other than the source of packet), at every hop, until the packet reaches the destination.
 - May have large end-to-end delays in data delivery.
- Both approaches do not consider power consumption criteria.

Design aspects for routing protocols

- Data delivery models
 - Periodic data transmission to the Base-station
 - Query-response or event triggered transmissions
- Direct or multi-hop routing
- Performance matrices
 - Packet delivery ratio
 - Avg delay per packet
 - Energy consumption
 - Product of Energy* delay as Criteria
- Network lifetime
 - First node dies
 - Half of nodes dies
 - Last node dies

Topology management protocols

- Topology management protocols select which nodes can turn off the radios without compromising network capacity.
- Co-ordinate the sleep transitions of all nodes while ensuring adequate network connections.

Categories of Routing protocols in WSN

- Optimization-based Routing protocols
 - Use optimization techniques to find minimum cost path
 - “Optimal” routes that avoid low-energy nodes and balances traffic
 - Optimal paths may get depleted sooner – choose set of “good” routes (sub-optimal) paths in probabilistic manner
 - Maintain network connectivity as long as possible
- Data centric based Routing protocols
 - Reduce data redundancy by performing data aggregation
 - Use signal processing techniques to perform data fusion

Categories of Routing protocols in WSN

- Cluster-based Routing protocols
 - Introduces hierarchy in the network
 - Special nodes termed as “Cluster-head” nodes form a wireless backbone to the sink
 - Energy optimization can be done at time of cluster formation, cluster-head election, data aggregation at CH etc.
- Location-based routing protocols
 - Uses position information for data relaying
 - Query can be sent to particular region
 - Offers significant reduction in number of transmissions
- QoS enabled Routing protocols
 - QoS in terms of end-to-end average delay, Deadline-miss ratio

Low Energy Adaptive Cluster Hierarchy protocol (LEACH)

- LEACH, Heinzelman et.al, MIT, 2000
- Milestone for cluster-based protocols in WSNs
- Designed for WSNs where BS is fixed and distant from sensor nodes.
- Design principles
 - Localized co-ordination and control for both set-up and operational phases
 - Random rotation of Cluster-Heads
 - Data aggregation to reduce communication cost

LEACH

- Cluster-head election mechanism is totally distributed – Knowledge of topology not required.
- Cluster-head election is performed at defined time intervals.
- Time between two elections is fixed – Round
- In each round, not only does cluster-head change, but also clusters are totally rebuilt.
- Each round consists of set-up phase and data transmission phase.
- Data transmission phase is longer than set-up phase.

LEACH

- Advertisement phase
- Cluster set-up phase
- Schedule creation
- Data transmission

LEACH – Advertisement phase

- Node n decides whether or not to become cluster-head, by generating a random number in the interval [0-1] and comparing it with the threshold T(n) as follows –

$$T(n) = \begin{cases} p & \text{if } n \in G \\ 1 - p(r \bmod \frac{1}{p}) & \text{Otherwise} \\ 0 & \end{cases}$$

- Here,
 - p is the desired percentage of CH nodes in network
 - r – current round number
 - G – Set of nodes that were not CH nodes during last 1/p rounds
- Using this, each node can be a cluster-head approximately once every 1/p rounds.
- Self-elected CH node sends ADV message to other nodes using fixed transmission power and CSMA MAC
- Non-CH nodes collect all ADV messages and select CH with best signal strength.

LEACH

- Cluster set-up phase
 - Nodes have chosen the cluster to join in earlier phase.
 - Nodes communicate the choice to the relative CH node using CSMA MAC protocol.
- Schedule Creation
 - CH calculates TDMA schedule for all nodes for communication inside cluster and broadcasts it to nodes
 - CH also gives CDMA code to be used by nodes to avoid interference with adjacent clusters.
- Data transmission
 - Nodes transmit to CH only during allotted time slots with appropriate transmission power
 - Nodes can sleep at other times
 - CH is active during whole round. CH does data aggregation and sends data to BS directly.

LEACH

- Reduces average energy consumption of nodes.
- Because of CH rotation, energy usage is fairly distributed.
- Issues
 - Periodic rebuild of clusters
 - Single hop transmission strategy of CH nodes.

MANET

Mobile Ad-hoc Networks

MANET

- Distributed, Dynamic, Self Configurable Wireless Network.
- No Infrastructure support.
- Network's wireless topology may dynamically change in an unpredictable manner since nodes are free to move.
- Information is transmitted in a store-and forward manner using multi hop routing.

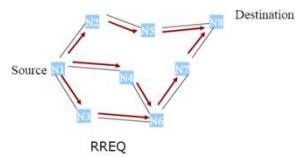
Protocol Stack

- Needs to be mobility-aware.
- Protocols should be able to adapt to the frequent change of topology.
- For ex. Routing – Needs to be dynamic routing with minimal overhead.
- Mobile nodes in MANET might be slightly more powerful compared to WSN nodes.
- Deployment may not always be dense.

Types of Routing protocols

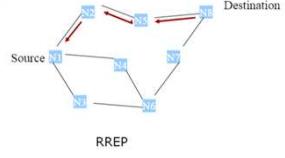
- **Proactive protocols**
 - Traditional distributed shortest-path protocols
 - Maintain routes between every host pair at all times
 - Based on periodic updates; High routing overhead
 - Example: DSDV (Destination Sequenced Distance Vector)
- **Reactive protocols**
 - Determine route if and when needed
 - Source initiates route discovery
 - Example:
 - AODV (Ad-hoc On-demand Distance Vector)
 - DSR (Dynamic Source Routing)
- **Hybrid protocols**
 - Adaptive; Combination of proactive and reactive
 - Example : ZRP (Zone Routing Protocol)

AODV



- Source node floods the RREQ (Route request) packet in the network if the route to destination is not available.
- RREQ contains – SrcID, DestID, SrcSeqNum, DestSeqNum, BcastID and TTL.
- DestSeqNum indicates freshness of the route (up-to-date path).
- Intermediate node either forwards the RREQ or replies with RREP.
- Path info is updated if DestSeqNum of received packet > DestSeqNum stored at the Node.
- Duplicate packets are identified by SrcID-BcastID pair and can be discarded.

AODV



- Every intermediate node enters the previous node address and its Bcast ID while forwarding the RREQ.
- If the RREP not received, timer (TTL) is used to delete the entry.
- In AODV, source node and intermediate nodes store the next-hop information corresponding to each flow for data packet transmission.
- If any link breaks, route error messages are sent to end nodes. Nodes re-initiates the path finding process.

VANET

Vehicular Ad-hoc Networks

VANETS

- Intra-Vehicular communication
- V2I/V2R
- V2V



Applications

- Navigation safety applications
 - crash prevention,
 - road problem warnings,
 - conditions of the driver,
- Navigation efficiency
 - Intelligent Transport Sys,
 - Road congestion avoidance,
 - personalized navigator,
 - pollution mitigation
- Vehicle monitoring
 - Carbon emission level,
- Emergency
 - Evacuations in case of disasters
- urban sensing
 - congestion, pollution sensing
- Entertainment:
 - download multimedia;
 - multiuser games
- Social networking:
 - proximity and correlated motion driven acquisition of friends/peers;
 - blog uploading
- Traffic management
 - Automated toll payment
 - Location-based services

VANET Vs MANET

- High speed mobility – but regular and predictable
- Topology is very dynamic
- No significant power constraints
- Localization information might be available

Types of Traffic

- Inter vehicle Communication
 - Multicast/Broadcast to transmit traffic related information over multiple hops to a group of receivers.
 - Emergency message dissemination.
- Vehicle to roadside
 - Single hop broadcast from RSU to all equipped vehicles in the vicinity.
 - High bandwidth link.
- Routing-based communications
 - Unicast multi-hop communication between vehicles.

MAC protocol

- Dedicated Short Range Communications (DSRC) is a short to medium range communications service that was developed to support vehicle-to-vehicle and vehicle-to-roadside communications.
- Wireless connectivity between moving vehicles can be provided by existing 802.11a compliant devices – but it has high overhead and complexity.
- In vehicular network, timely communication is essential.
- DSRC effort was migrated to the IEEE 802.11 standard group which renamed the DSRC to IEEE 802.11p –WAVE.
- Wireless Access in Vehicular Environments (WAVE) can be used for both Safety & Non- Safety Applications.

802.11p - Physical Layer

- IEEE802.11P adopts the OFDM PHY on 10-MHz channels in the 5.9 GHz frequency band.
- Wi-Fi industry normally implements the OFDM PHY on the 20-MHz channels, even though 5/10/20 MHz channels have been specified in IEEE802.11-2007 (2.4/5 GHz band).
- Modulation, channel coding etc. remains same.
- Supported Data rate -3, 4.5, 6, 9, 12, 18, 24, and 27 Mbps
- Seven channels of 10 MHz bandwidth with various purposes -
 - Critical safety of life
 - High Power public safety
 - Control Channel (CCH) - safety communications only
 - Service Channel (SCH) -available for both safety and non-safety usage

802.11p

- V2I links –active only for short amount of time.
- Exchange data without the need to establish a basic service set (BSS).
- No need to wait for the association and authentication procedures to complete before exchanging data.
- Uses the wildcard BSSID (a value of all 1s) in the header of the frame.
- Start sending and receiving data frames as soon as they arrive on the communication channel.

Routing protocol - peculiarities

- Network topology.
- Mobility patterns.
- Density of vehicles at different times of the day.
- Rapid changes in vehicles arriving and leaving the VANET

Position based routing

- Position-based routing protocols require info about the physical position of the participating nodes.
- This position is made available to the direct neighbors in the form of periodically transmitted beacons.
- A sender can request the position of a receiver by means of a location service.
- The routing decision at each node - based on destination's position contained in the packet & position of forwarding node's neighbors.
- Position-based routing does not require the establishment / maintenance of routes.

Why PBR is suitable?

- Frequent topology changes.
- Short connectivity time.
- Availability of positioning systems.
- Use GPS technology enables forwarding to be decoupled from a node's identity and therefore the position of the destination node is used rather than a route to it.
- Position-based routing provides a more scalable and efficient forwarding mechanism appropriate for highly volatile ad hoc networks.

PBR - Mechanism

- Beaconing
- Location service
- Forwarding
 - geographic unicast
 - geographic broadcast

PBR- Beaconing

- Nodes periodically broadcast short packets with their ID and current geographic position.
- On reception of a beacon, a node stores the information in its location table.

PBR – Location service

- When a node needs to know the position of another node currently not available in its location table, it issues a location query message with the sought node ID, sequence number and hop limit.
- Neighboring nodes rebroadcast this message until it reaches the sought node (or the hop limit).
- sought node answers with a location reply message carrying its current position and timestamp.
- On reception of the location reply, the originating node updates its location table.

Geographic Unicast

- It provides packet transport between two nodes via multiple wireless hops.
- When a node wishes to send a unicast packet, it first determines the destination position (by location table look-up or the location service).
- Then, it executes a greedy forwarding algorithm, sending the packet to its neighbor with the minimum remaining distance to the destination.
- The algorithm is executed at every node along the forwarding path until the packet reaches the destination.

Geographic Broadcast

- It distributes data packets by flooding, where nodes re-broadcast the packets if they are located in the geographic area determined by the packet.
- Also, advanced broadcasting algorithms ensure avoidance of the so-called 'broadcast storms' minimize overhead.

Types

- Position based
 - DTN
 - Non-DTN
- Cluster-Based
- Geocast based
- Mobicast based
- Topology based
 - Proactive
 - Reactive
 - Hybrid
- Broadcast based

Broadcast protocols in VANET

- Highway scenario
 - BROADCOMM –Broadcast communication
- Urban Scenario
 - UMB - Urban multi-hop broadcast protocol
- Hybrid
 - RBLSM -Reliable Broadcasting of Life Safety Messages

Urban Multi-hop Broadcast

- Korkmaz et.al, Ohio State Univ, 2004
- IEEE 802.11 based multi-hop broadcast protocol (UMB) which is designed to address the broadcast storm, hidden node, and reliability problems of multi-hop broadcast in urban areas.
- Message dissemination to locations beyond the transmission range requires multi-hopping.
- Interference, packet collisions, and hidden nodes can stop the message dissemination during multi-hop broadcast.
- Multi-hop broadcast can consume significant amount of wireless resources because of unnecessary retransmissions.
- Message dissemination to different road segments at intersections.

Mechanism

- Sender nodes try to select the furthest node in the broadcast direction to assign the duty of forwarding and acknowledging the packet.
- Protocol divides the road portion inside the transmission range into segment (in the direction of broadcast).
- RTB/CTB handshake is performed with the selected node – Includes transmission duration, source node position, intended direction of broadcast.

Detection of farthest node

- Length of the black-burst signal in the 1st iteration.

$$L_1 = \left\lfloor \frac{d}{Range} * N_{max} \right\rfloor * SlotTime$$
 - L1 is the black-burst length in the 1st iteration,
 - D is the distance between the source and the vehicle,
 - Range is the transmission range,
 - Nmax is the number of segments created, and
 - SlotTime is the length of one slot.
- As a result of this computation, the furthest node sends the longest black-burst.

Data transmission and ACK

- After receiving a successful CTB, the source node sends its broadcast packet – ID of the selected node is included in packet.
- This corresponding node is now responsible for forwarding the broadcast packet and sending an ACK to the source.
- Although all other nodes between the source and the ACK sender receive the broadcast packet, they do not rebroadcast or acknowledge it.

Intersection broadcast

- At intersection, new directional broadcasts should be initiated to all road directions.
- Protocol assumes that there is repeater available at intersection to perform intersection broadcast.