

video1.mp4

TLF Metadata (tlfd atom)

Type: 360TLF  
Points:  $\langle p - i/2, p + i/2 \rangle$   
Spheres:  $\langle \text{trak0} \rangle$   
Saliency Map: trak1

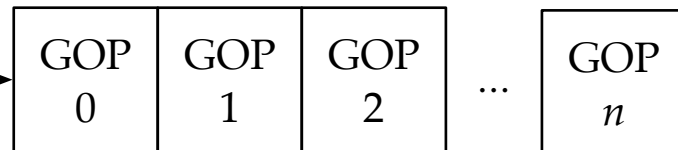
Track 0 (trak atom)

Codec: HEVC (std atom)  
Projection: Equirectangular (sv3d atom)  
Data: stream0.hevc (dref atom)

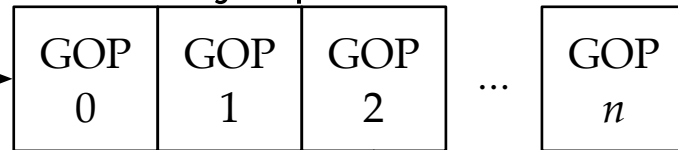
Track 1 (trak atom)

Codec: VignetteCompression (std atom)  
Projection: Equirectangular (sv3d atom)  
Data: saliencymap.bin (dref atom)

stream0.hevc



saliencymap.bin



Tiled Saliency Map bitstream

Tile rows:  $m$   
Tile cols:  $n$   
Row 1: 0x00 0x22 ... 0xD3  
Row 2: 0x01 0x1F ... 0x03  
...  
Row  $m$ : 0x00 0x02 ... 0x00