Build an Artificial Neural Network by implementing the Backpropagation algorithm and test the same using appropriate data sets.

```
import numpy as np
X = np.array(([2, 9], [1, 5], [3, 6]), dtype=float) # X = (hours)
sleeping, hours studying)
y = np.array(([92], [86], [89]), dtype=float) # y = score on
test
# scale units
X = X/np.amax(X, axis=0) # maximum of X array
                             # max test score is 100
y = y/100
class Neural Network(object):
   def init (self):
                          # Parameters
       self.inputSize = 2
       self.outputSize = 1
       self.hiddenSize = 3
                           # Weights
       self.W1 = np.random.randn(self.inputSize,
self.hiddenSize)
                       # (3x2) weight matrix from input to hidden
layer
       self.W2 = np.random.randn(self.hiddenSize,
self.outputSize) # (3x1) weight matrix from hidden to output
layer
   def forward(self, X):
                           #forward propagation through our network
       self.z = np.dot(X, self.W1)
                                         # dot product of X
(input) and first set of 3x2 weights
       self.z2 = self.sigmoid(self.z)
                                               # activation function
       self.z3 = np.dot(self.z2, self.W2) # dot product of
hidden layer (z2) and second set of 3x1 weights
       o = self.sigmoid(self.z3)
                                               # final activation
function
       return o
   def sigmoid(self, s):
       return 1/(1+np.exp(-s)) # activation function
   def sigmoidPrime(self, s):
       return s * (1 - s)
                                 # derivative of sigmoid
```

```
def backward(self, X, y, o):
                                    # backward propgate through the
network
       self.o error = y - o
                                  # error in output
        self.o delta = self.o error*self.sigmoidPrime(o) # applying
derivative of sigmoid to
        self.z2 error = self.o delta.dot(self.W2.T) # z2 error: how
much our hidden layer weights contributed to output error
        self.z2 delta = self.z2 error*self.sigmoidPrime(self.z2) #
applying derivative of sigmoid to z2 error
       self.W1 += X.T.dot(self.z2 delta)
                                           # adjusting first set
(input --> hidden) weights
       self.W2 += self.z2.T.dot(self.o delta) # adjusting second set
(hidden --> output) weights
    def train (self, X, y):
       o = self.forward(X)
       self.backward(X, y, o)
NN = Neural Network()
for i in range(1000): # trains the NN 1,000 times
   print ("\nInput: \n" + str(X))
    print ("\nActual Output: \n" + str(y))
    print ("\nPredicted Output: \n" + str(NN.forward(X)))
    print ("\nLoss: \n" + str(np.mean(np.square(y -
NN.forward(X)))))  # mean sum squared loss)
   NN.train(X, y)
```