

```
In [1]: %matplotlib inline
from tensorscaling import scale, capacity, unit_tensor, random_tensor, marginal, random_unitary, random_orthogonal
import numpy as np
import scipy as scipy
import cvxpy as cp
import matplotlib.pyplot as plt
from numpy import matrix
```

## Tensor scaling

Scale 3x3x3 unit tensor to certain non-uniform marginals:

```
In [ ]: shape = [3, 3, 3]
targets = [(0.5, 0.25, 0.25), (0.4, 0.3, 0.3), (0.7, 0.2, 0.1)]

res = scale(unit_tensor(3, 3), targets, eps=1e-4)
res
```

We can also access the scaling matrices and the final scaled state:

```
In [ ]: print(res.gs[0], "\n")
print(res.gs[1], "\n")
print(res.gs[2])
```

Let's now check that the W tensor *cannot* be scaled to uniform marginals:

```
In [22]: shape = [2, 2, 2, 2]
W = np.zeros(shape)
W[1, 0, 0, 0] = W[0, 1, 0, 0] = W[0, 0, 1, 0] = W[0, 0, 0, 1] = 0.5
targets = [(0.5, 0.5)] * 4
print(targets)

scale(W, targets, eps=1e-4, max_iterations=1000)

[(0.5, 0.5), (0.5, 0.5), (0.5, 0.5), (0.5, 0.5)]
```

Out[22]: Result(success=False, iterations=1000, max\_dist=0.5934653559719874, ...)

To see more clearly what is going on, we can set the `verbose` flag:

```
In [ ]: res = scale(W, targets, eps=1e-4, max_iterations=10, verbose=True)
```

We see that at each point in the algorithm, one of the marginals has Frobenius distance  $\approx 0.59$  to being uniform. Indeed, we know that the entanglement polytope of the W tensor does not include the point corresponding to uniform marginals -- see [here](#) for an interactive visualization!

## Tuples of matrices and tensors

We can just as well only prescribe the desired spectra for subsystems. Note that prescribing two out of three marginals amounts to *operator scaling*.

```
In [ ]: shape = [3, 3, 3]
targets = [(0.4, 0.3, 0.3), (0.7, 0.2, 0.1)]

res = scale(unit_tensor(3, 3), targets, eps=1e-6)
res
```

Indeed, the last two marginals are as prescribed, while the first marginal is arbitrary.

```
In [ ]: print(marginal(res.psi, 0).round(5), "\n")
print(marginal(res.psi, 1).round(5), "\n")
print(marginal(res.psi, 2).round(5))
```

## Duality

**The scaling way:** The below computes  $\frac{1}{t} \inf_{\det L=\det R=1} \langle L \otimes R, e^{C^*} \rangle$  for inputs  $C = \text{uni}(\text{spec})\text{uni}^{\dagger}$ , dimension  $n$ , and weight  $t$ .

```
In [25]: def scalingot(spec, uni, n, weight):
    #marginals p and q are just normalized identities
    targets = [tuple((n*(-1))*np.ones(n)), tuple((n*(-1))*np.ones(n))]

    expcost = uni.copy()
    #make the unitary a list of nxn matrices
    expcost=expcost.reshape([n**2,n,n])

    expspec = np.exp(weight*spec)
    #multiply the i^{th} eigenvector by e^{weight*spec[i]}
    for i in range(0,n**2):
        expcost[i]=expspec[i]
    cap = capacity(expcost, targets, eps=1e-4, max_iterations=400,randomize=False, verbose=False)

    return cap/weight
```

**The SDP way:** Compute the sdp  $\max C \cdot \rho$  subject to  $E_{ij} \otimes I_n \cdot \rho = P_{ij}$  and  $I_n \otimes E_{ij} \cdot \rho = Q_{ij}$  and, of course  $\rho \geq 0$ .

```
In [13]: def sdpot(spec, uni, n):
    #compute the cost matrix C = uni*spec*uni^T
    C = uni.dot(np.diag(spec).dot(np.conj(uni).T))
    #currently the marginals are just the normalized identities
    p = np.eye(n,n)/n
    q = np.eye(n,n)/n

    X = cp.Variable((n**2,n**2), symmetric=True)
    constraintos = [X >= 0]

    #add the partial trace constraints

    for i in range(n):
        for j in range(i+1):
            a = np.kron(np.kron(np.eye(1,n,i), np.eye(n,1,-j)), np.eye(n,n))
            a = (a + a.T)/2

            constraintos += [cp.trace(a @ X) == p[i,j]]

    for i in range(n):
        for j in range(i+1):
            a = np.kron(np.eye(n,n), np.kron(np.eye(1,n,i), np.eye(n,1,-j)))
            a = (a + a.T)/2

            constraintos += [cp.trace(a @ X) == q[i,j]]

    probl = cp.Problem(cp.Maximize(cp.trace(C @ X)),
                        constraintos)

    probl.solve()

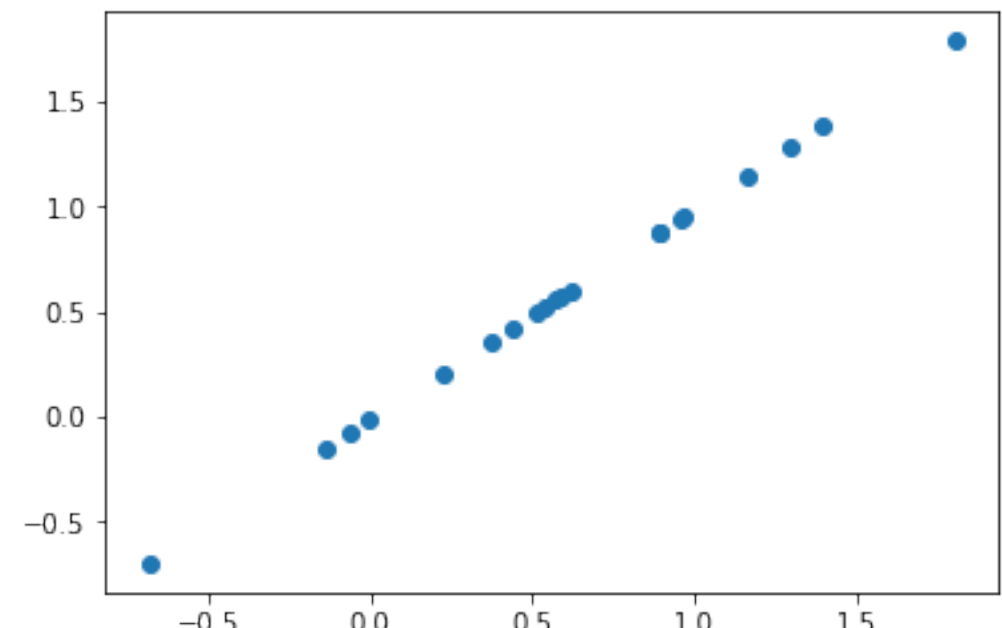
    return probl.value
```

**Sanity check:** when the cost C is diagonal these algorithms should match

```
In [26]: n = 2
scal = []
sdp = []

for i in range(20):
    #choose random spectrum for cost matrix
    spec = np.random.randn(n**2)
    #C will be uni*spec*uni^T, for now we make C diagonal
    uni = np.eye(n**2)
    #compute the mincost using both algorithms
    sc = scalingot(spec,uni,n,20)
    sd = sdpot(spec,uni,n)
    #put them in a list
    scal.append(sc)
    sdp.append(sd)
#scatter plot it
plt.scatter(scal,sdp)
```

Out[26]: <matplotlib.collections.PathCollection at 0x11d59c908>



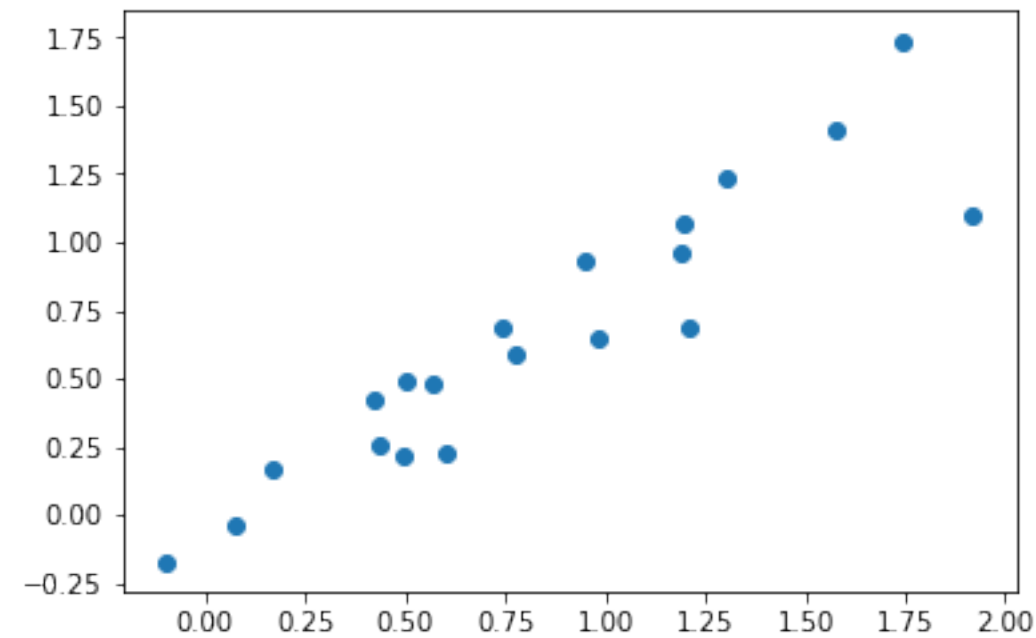
**In general:** we don't know what will happen, but it doesn't look like they are the same.

```
In [27]: n = 2
scal = []
sdp = []

for i in range(20):
    spec = np.random.randn(n**2)
    #same except this time we use random unitary so that C is quite random
    uni = random_orthogonal(n**2)
    sc = scalingot(spec,uni,n,20)
    sd = sdpot(spec,uni,n)
    scal.append(sc)
    sdp.append(sd)

plt.scatter(scal,sdp)
```

Out[27]: <matplotlib.collections.PathCollection at 0x11d6cebe0>



## scratchwork

```
In [ ]: tuple(np.ones(3))
```

```
In [ ]:
```