

# Bayesian Hierarchical Dynamic Factor Models

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# Contents

# Section 1

# Factor Analysis

- ① **Factor Analysis** is a method that uses the covariances between a set of observed variables to described them in terms of a smaller set of unobservable variables called factors.

# Bayesian Inference

**Bayesian Inference** can be described by three parts:

- 1 Build a model based on data  $\mathbf{X}$  and parameters  $\Theta$ 
  - ▶ Likelihood:  $p(\mathbf{X}|\Theta)$
  - ▶ Prior:  $p(\Theta)$
- 2 Compute the posterior pdf
  - ▶ Posterior:

$$p(\Theta|\mathbf{X}) = \frac{p(\mathbf{X}|\Theta)p(\Theta)}{p(\mathbf{X})}$$

- 3 Report summaries, e.g. posterior expectations

$$\mathbb{E}[h(\Theta)|\mathbf{X}]$$

## Section 2

# Why Variational Bayesian Inference?

- ▶ Consider a model with data  $\mathbf{X}$  and unknowns  $\mathbf{Z}$
- ▶ The goal is to compute the posterior

$$p(\mathbf{Z}|\mathbf{X}) = \frac{p(\mathbf{X}|\mathbf{Z})p(\mathbf{Z})}{p(\mathbf{X})} \quad (1)$$

and report posterior expectations

$$\mathbb{E}[h(\mathbf{Z})|\mathbf{X}] = \int h(\mathbf{Z})p(\mathbf{Z}|\mathbf{X}) d\mathbf{Z} \quad (2)$$

- ▶ The term in the denominator is called the evidence

$$p(\mathbf{X}) = \int p(\mathbf{X}, \mathbf{Z}) d\mathbf{Z} \quad (3)$$

# Why Variational Bayesian Inference?

- ▶ For most interesting models  $\mathbf{Z}$  is high-dimensional
- ▶  $p(\mathbf{z})$  and  $p(\mathbf{z}|\mathbf{y})$  would require high-dimensional integration
- ▶  $p(\mathbf{z})$ ,  $p(\mathbf{z}|\mathbf{y})$ , and  $p(\mathbf{y})$  are typically analytically intractable



# Why Variational Bayesian Inference?

- ① The gold standard has been to use MCMC algorithms
- ② MCMC methods allow sampling from intractable distributions
- ③

# Why Variational Bayes?

, but takes too long to run. VB methods are faster.

# Variational Bayes

VB turns the inference problem into an

## Section 3

# Classical Factor Analysis Model

The Classical (orthogonal) FA model assumes assumes the form

$$\mathbf{X} = \mathbf{\Lambda}\mathbf{F} + \mathbf{e}$$

where

- ①  $\mathbf{X} = (X_1, \dots, X_N)^\top$  denotes the vector of observations
- ②  $\mathbf{\Lambda} = [\lambda_{nk}]_{N \times K}$  denotes the matrix of factor loadings
- ③  $\mathbf{F} = (F_1, \dots, F_K)^\top$  denotes the vector of latent factors
- ④  $\mathbf{e} = (e_1, \dots, e_N)^\top$  denotes the vector of latent error terms

# Normal Theory Assumptions

The Normal Theory Classical FA model assumes the form

$$\mathbf{X} = \mathbf{\Lambda}\mathbf{F} + \mathbf{e}$$

and adds the assumptions that

- ❶  $\mathbf{F} \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_K)$
- ❷  $\mathbf{e} \sim \mathcal{N}(\mathbf{0}, \mathbf{\Sigma})$  where  $\mathbf{\Sigma} = \text{diag}(\sigma_1^2, \dots, \sigma_N^2)$
- ❸  $F_k$  and  $e_n$  are independent for every pair  $k, n$

## Section 4

# Hierarchical Dynamic Factor Model

$$\mathbf{X}_{bst} = \mathbf{\Lambda}_{H.bs}(L)\mathbf{H}_{bst} + \mathbf{e}_{Xbst} \quad (4)$$

$$\mathbf{H}_{bst} = \mathbf{\Lambda}_{G.bs}(L)\mathbf{G}_{bt} + \mathbf{e}_{Hbst} \quad (5)$$

$$\mathbf{G}_{bt} = \mathbf{\Lambda}_{F.b}(L)\mathbf{F}_t + \mathbf{e}_{Gbt} \quad (6)$$

$$\mathbf{\Psi}_F(L)\mathbf{F}_t = \boldsymbol{\epsilon}_{Ft}, \quad (7)$$