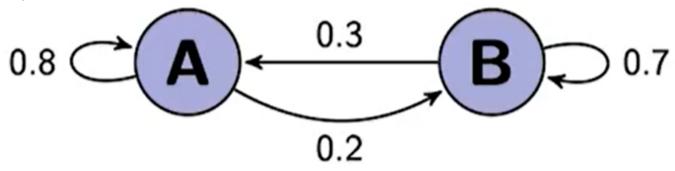
Markov Chains

Say, A and B are libraries with 1000 books.



In the beginning,
$$x_0 = \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix}$$

Now, after 1 month, $x_1 = \begin{bmatrix} 0.8 \cdot 0.5 + 0.3 \cdot 0.5 \\ 0.2 \cdot 0.5 + 0.7 \cdot 0.5 \end{bmatrix} = \begin{bmatrix} 0.8 & 0.3 \\ 0.2 & 0.7 \end{bmatrix} \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix} = Px_1$

$$P = egin{bmatrix} 0.8 & 0.3 \ 0.2 & 0.7 \end{bmatrix}$$

Now, after 2 months, $x_2 = Px_1 = P^2x_0$

Now, after k months, $x_k = P^k x_0$

Steady State

Find the steady state of $P = \begin{bmatrix} 0.8 & 0.3 \\ 0.2 & 0.7 \end{bmatrix}$.

$$Pec{q} = ec{q}$$
 $Pec{q} - ec{q} = 0$
 $Pec{q} - I_n ec{q} = 0$
 $(P - I_n) ec{q} = 0$
 $\left(\begin{bmatrix} 0.8 & 0.3 \\ 0.2 & 0.7 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) ec{q} = 0$
 $\left(\begin{bmatrix} -0.2 & 0.3 \\ 0.2 & -0.3 \end{bmatrix} ec{q} = 0$
 $\left\{ \begin{bmatrix} -2x_1 & +3x_2 & = 0 \\ 2x_1 & -3x_2 & = 0 \end{bmatrix} \right.$
 $\left\{ x_1 = 3, x_2 = 2 \right\}$
 $\left[\frac{1}{3+2} \begin{bmatrix} 3 \\ 2 \end{bmatrix} = ec{q} \right]$
 $ec{q} = \begin{bmatrix} \frac{3}{5} \\ \frac{2}{5} \end{bmatrix}$

Convergence

We have $x_1, x_2, x_3, \dots x_k$. We want to know if while $k \to \infty$ x_k will converge to a <u>steady</u> <u>state</u>.

If P is a regular stochastic matrix (<u>vocabulary</u>), then P has a unique steady-state vector \vec{q} , and $\vec{x}_{k+1} = P\vec{x}_k$ converges to \vec{q} as $k \to \infty$.

Using Eigenvalues to find Convergence

Consider the Markov Chain:

$$\vec{x}_{k+1} = P\vec{x}_k = \begin{pmatrix} 1 & 0.1 \\ 0 & 0.9 \end{pmatrix} \vec{x}_k, \quad k = 0, 1, 2, 3, \dots, \quad \vec{x}_0 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

Use the eigenvalues and eigenvectors of P to determine what \vec{x}_k tends to as $k \to \infty$. The eigenvalues and eigenvectors of P are

$$\lambda_1 = 1, \ \vec{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad \lambda_2 = 0.9, \ \vec{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Say P has 2 eigenvalues (λ_1 and λ_2) and eigenvectors (v_1 and v_2).

$$egin{align*} x_{k+1} &= Px_k \ x_0 &= c_1v_1 + c_2v_2 \ x_1 &= Px_0 \ x_1 &= P(c_1v_1 + c_2v_2) &= c_1Pv_1 + c_2Pv_2 \ x_1 &= c_1\lambda_1v_1 + c_2\lambda_2v_2 \ x_2 &= Px_1 \ x_1 &= P(c_1\lambda_1v_1 + c_2\lambda_2v_2) &= c_1(\lambda_1)^2v_1 + c_2(\lambda_2)^2v_2 \ x_k &= c_1(\lambda_1)^kv_1 + c_2(\lambda_2)^kv_2 \ &= x_0 &= c_1v_1 + c_2v_2 \ egin{bmatrix} 1 \ 0 \ \end{bmatrix} &= c_1 \ egin{bmatrix} 1 \ 0 \ \end{bmatrix} + c_2 \ egin{bmatrix} 1 \ \end{bmatrix} \ c_1 &= 0 \ \hline &= 0 \ \end{bmatrix}$$

 $x_k=v_1$