Determinants

A general way to compute it is, If If A is an $n \times n$ matrix where n = 1,

$$\det(A) = a_{1,1}$$

If A is an $n \times n$ matrix where n > 1,

$$\det(A) = a_{1,1} \det(A_{1,1}) - a_{1,2} \det(A_{1,2}) + \dots + (-1)^{n+1} a_{1,n} \det(A_{1,n})$$

 $a_{i,j}$ means the element at the $i^{
m th}$ row and the $j^{
m th}$ column.

 $A_{i,j}$ means the Matrix if you drop (get rid of) the $i^{\rm th}$ row and the $j^{\rm th}$ column.

Deriving it for a 2×2

Say we have
$$A = egin{bmatrix} a & b \ c & d \end{bmatrix}$$

$$\det(A) = (a_{1,1})(\det(A_{1,1})) - (a_{1,2})(\det(A_{1,2}))$$

 $\det(A) = (a)(d) - (b)(c)$
 $\det(A) = ad - bc$

Using a **Cofactor**

The determinant of a matrix A can be computed down any row or column of the matrix.

For example, down the $j^{\rm th}$ column the determinant is:

$$\det(A) = a_{1,j} \det(A_{1,j}) - a_{2,j} \det(A_{2,j}) + \dots + (-1)^{n+1} a_{n,j} \det(A_{n,j})$$

This would be useful for a matrix with a few 0's.

$$\mathsf{Say}\: A = egin{bmatrix} 5 & 4 & 3 & 2 \ 0 & 1 & 2 & 0 \ 0 & -1 & 1 & 0 \ 0 & 1 & 1 & 3 \end{bmatrix} \mathsf{find}\: \det(A)$$

We will use the first column due to the 3 zeros.

$$\det(A) = 5C_{1,1} + 0C_{2,1} + 0C_{3,1} + 0C_{4,1} \ = 5 \cdot (-1)^{1+1} \cdot \det \begin{pmatrix} \begin{bmatrix} 1 & 2 & 0 \\ -1 & 1 & 0 \\ 1 & 1 & 3 \end{bmatrix} \end{pmatrix} \ 3^{\mathrm{rd}} \ \mathrm{column} \ = 5 \cdot (0C_{1,3} + 0C_{2,3} + 3C_{3,3}) \ = 5 \cdot \begin{pmatrix} 3 \cdot (-1)^{3+3} \det \begin{pmatrix} \begin{bmatrix} 1 & 2 \\ -1 & 1 \end{bmatrix} \end{pmatrix} \end{pmatrix}$$
Formula $= 5(3(1 \times 1 - 2 \times -1)) \ = \boxed{45}$

Triangular Matrices

The determinant of a triangular matrix is the product of the entries on the main diagonal.

Row Operations

Replacement/Addition

Add a multiple of one row to another.

This does NOT effect the determinant.

$$\det A = \det B$$

Interchange

Interchange two rows to make B.

One swap means, $\det B = -\det A$.

Two One swap means, $\det B = \det A$

We can continue this pattern

Scaling

Multiply a row by a non-zero scalar to make B.

$$\det B = k \det A$$

Invertibility

Important practical implication: if A is reduced to echelon form, by r interchanges of rows and columns, then

$$|A| = \begin{cases} (-1)^r \times \text{(product of pivots)}, & \text{when } A \text{ is invertible} \\ 0, & \text{when } A \text{ is singular} \end{cases}$$

Properties

- 1. $\det A = \det A^T$ (<u>Transpose</u>).
- 2. A is invertible if and only if $\det A \neq 0$.
- 3. $\det(AB) = \det A \cdot \det B$.
- 4. If A is invertible, then $\det A^{-1} = \frac{1}{\det A}$.

Geometric interpretation

Watch 3b1b

TLDR

Area of parallelogram spanned by the columns columns of an $n \times n$ matrix A is $\det \begin{pmatrix} \begin{bmatrix} a & c \\ b & d \end{bmatrix} \end{pmatrix} = ad - bc.$

The volume of the parallelepiped spanned by the columns of an $n \times n$ matrix A is $|\det A|$.

Linear Transformations

If we have $T: \mathbb{R}^n \to \mathbb{R}^n$, and S is a parallelogram in \mathbb{R}^n , then:

$$\operatorname{volume}(T(S)) = |\det A| \cdot \operatorname{volume}(S)$$

This can be extended to higher dimensions.