

University of the Basque Country

FINAL YEAR PROJECT

About Tree Depth

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1 Introduction to Graph Theory

1.1 Definition of a graph

A graph is defined as a pair of sets G = (V, E), such that $E \subseteq V^2$. The members of V are called vertices and the ones of E edges. Take into account, that the vertices can be anything, they can even be sets themselves. The usual way to draw a graph is by representing the vertices as individual points and for each edge, draw a link between both elements of that edge. The shape in which a graph is drawn is irrelevant, it will contain the same information.

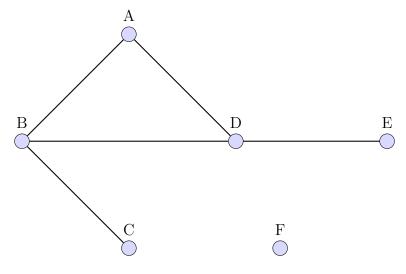


Figure 1: A graph with $V = \{A, B, C, D, E, F\}$ and $E = \{\{A, B\}, \{A, D\}, \{B, D\}, \{B, C\}, \{D, E\}\}$

1.2 Connectivity

An essential concept in graph theory is adjacency. Two vertices $x, y \in V$ are said to be adjacent in G if and only if $\{x, y\} \in E$.

2 Introduction to Tree Depth

2.1 Basic definitions

Vertex x is said to be the ancestor of y in a rooted forest F, if and only if x belongs to the path between y and the root of the component to which x belongs, y included.

The closure of a rooted forest F, expressed as C = clos(F), is defined as follows:

- V(C) = V(F)
- • E(C) = {{x, y} : x is an ancestor of y in F, x \neq y }

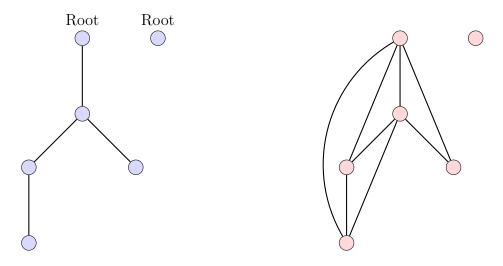
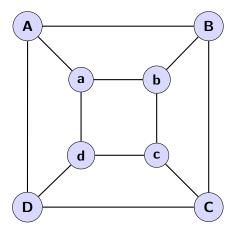


Figure 2: The blue graph at the left is a rooted forest F, the red graph at the right represents clos(F).

2.2 Tree Depth

Definition The tree-depth td(G) of a graph G is the minimum height of a rooted forest F such that $G \subseteq clos(F)$



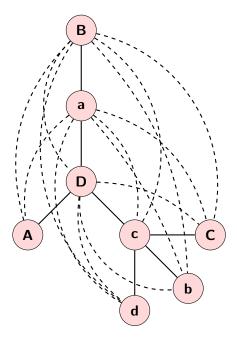


Figure 3: The graph G and tree T are in the left and right respectively. The doted edges in T, represent the clos(T). Because $G \subseteq clos(T)$, height(T) = 4 and the definition of tree depth we just gave, we know that td(G) is at most 4.

The tree depth of a graph G is a numerical invariant of a graph. In other words, the tree depth is a property that depends only on the abstract structure of a graph, not in its representation.

2.3 Elimination tree

An elimination tree Y of a connected graph G is defined recursively as follows:

- If $V(G) = \{x\}$ then Y is just $\{x\}$.
- Otherwise, $r \in V(G)$ is chosen as the root of Y and an elimination tree is created for each component of G r. r will be connected to the root of each of these trees.

The tree T in Figure 3 is an elimination tree for the graph G.

Lemma 2.1. Let G be a graph and T a tree such that $G \subseteq clos(T)$. Then, Y exists, where Y is an elimination tree of G and height(Y) \leq height(T).

3 Game Theoretic approach to Tree-Depth

3.1 Defining the game

The k-step selection-deletion game is played by Alice and Bob on a graph G. The game is played by turns as follows:

- First, Alice selects a connected component of the graph, and the rest of the components are deleted.
- Then, Bob deletes a node from the remaining graph and the next round is played with this graph.

If Bob deletes the last node at the k-th round or earlier, he is said to win the k-step selection-deletion game. Otherwise, Alice wins.

From this definition we can observe that if Bob has a strategy to win in k rounds that strategy will also guaranty a win in any game that lasts more than k rounds. Conversely, if Alice has a winning strategy in k-rounds, that same strategy will also win any game with less than k rounds.

3.2 Bob's winning strategy

Lemma 3.1. Let G be a graph and let F be a rooted forest of height t such that $G \subseteq clos(F)$. Then, Bob has a winning strategy for the (t+1)-step selection-deletion game.

Proof. Because of lemma 2.1 we know an elimination forest Y exists such that $height(Y) \leq height(F)$. Consider h = height(Y), we will proof that Y encodes a winning strategy in h+1 rounds which is also a winning strategy in the t+1-step selection-deletion game because $h \leq t$.

- Base case: If h = 0, then every component of G will have a single vertex, so it's clear that Bob will win the 1-step selection-deletion game.
- Induction: Let $G_i \subseteq G$ be the component Alice chooses, then Y_i exists such that Y_i is an elimination tree belonging to Y, $G_i \subseteq clos(Y_i)$ and obviously $height(Y_i) \leq h$. Bob will delete v, the root of Y_i . This will leave us with $G' = G_i v$ as the new graph. If we consider the children of v the new roots in $Y' = Y_i v$, then $G' \subseteq clos(Y')$ because of how

the elimination trees are built. As $height(Y') \leq h-1$, we can assume by induction that Bob has a winning strategy in h rounds for G', which together with the strategy for the first round we have just defined makes a winning strategy for Bob in the (h+1)-step selection-deletion game on the graph G.

3.3 Alice's winning strategy

Definition A shelter S in a graph G is a partially ordered set with the next properties:

- $\forall H \in S, H \subseteq G \text{ and } H \text{ is connected.}$
- $H \leq M$ if and only if $H \subseteq M$.
- If $H \in S$ and H is not minimal, then $\forall v \in V(H)$, there exists $H' \subseteq H v$ such that H covers H'. In a partially ordered set a covers b means that $a \neq b$, $a \geq b$, and no c exists such that $c \neq a \neq b$ and $a \geq c \geq b$.

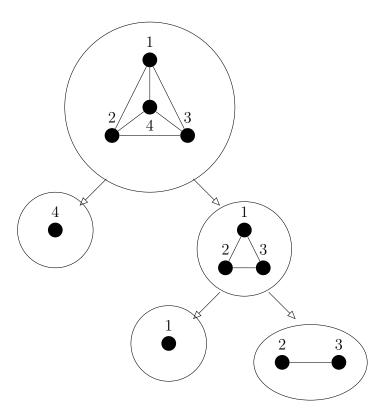


Figure 4: An example of a shelter. The arrows represent the covering relation.

The thickness of a shelter S is the shortest chain from a maximal element in S to a minimal element in S. The length of a chain is defined as the number of elements in it minus one. The thickness of the shelter in figure 4 is 1, because of the chain $\{1, 2, 3, 4\} \ge \{4\}$.

Lemma 3.2. Let G be a graph, S a shelter in G, and t the thickness of S. Then, S encodes a winning strategy for Alice in the t-step selection-deletion game.

Proof. We will proof this by induction over t.

- Base case: If t = 0, then clearly Alice wins the 0-step selection-deletion game.
- Induction: Let H be a maximal element in S. Then, Alice picks the connected component G_i of G, such that $H \subseteq G_i$. Because t > 0, H is not minimal, so for any vertex v that Bob removes, if $v \in H$ there exists $H' \in S$ that is covered by H and $v \notin H'$. Otherwise, H is still a subgraph of $G_i v$. Let $S' = \{X \mid X \in S \text{ and } X \subseteq G_i v\}$. It is

clear that S' is a shelter for $G_i - v$ and that the thickness of S' is greater than or equal to t-1. By induction we can assume S' encodes a winning strategy in t-1 steps, which together with the strategy for the first round we have just defined is a winning strategy for the t-step selection-deletion game.

3.4 Relation to Tree-Depth

It is clear that if Alice has a winning strategy in the t-step selection deletion game, Bob can't have a winning strategy in that same game. Because of this and lemmas 3.1 and 3.2 we can state the following:

Theorem 3.3. Let G be a graph, S a shelter in G of thickness x and F a rooted forest of height y such that $G \subseteq clos(F)$. Then the following is true.

- 1. Alice has a winning strategy in the t-step selection-deletion game, for any t smaller than or equal to x.
- 2. Bob has a winning strategy in the (t+1)-step selection-deletion game, for any t greater than or equal to y.
- 3. Every rooted forest who's closure contains G has an height higher than or equal to x. Otherwise, Bob would have a winning strategy in the x-step selection-deletion game, which contradicts statement 1.
- 4. Every shelter in G has a thickness smaller than or equal to y. Otherwise, Alice would have a winning strategy in the (y+1)-step selection-deletion game, which contradicts statement 2.
- 5. Because we have F, $td(G) \leq y$. Also, from statement 3 it is clear that $x \leq td(G)$. So we can say that $x \leq td(G) \leq y$.

With this theorem we can now give an upper-bound and a lower-bound to a graphs tree depth.

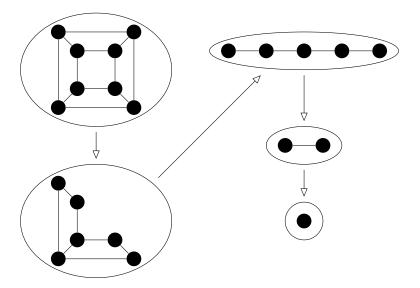


Figure 5: This is a shelter of thickness 4 for the graph in Figure 3. Beware that not all graphs in the shelter are drawn, but every graph in the shelter is isomorphic to these. With this and the rooted forest from Figure 3 we can say that td(G) = 4.

4 Cycle rank

4.1 Defining cycle rank

Cycle rank is a numerical invariant in a directed graph which is closely related to the tree depth of an undirected graph.

Definition The cycle rank of a digraph G, denoted by r(G) is defined as follows:

- If G is acyclic, then r(G) = 0.
- If G is strongly connected and $E \neq \emptyset$, then $r(G) = 1 + \min_{v \in V(G)} \{r(G v)\}.$
- If G is not strongly connected, then r(G) is the maximum cycle rank among all strongly connected components of G.

The $E \neq \emptyset$ condition is necessary because the graph with a single vertex and no edges is both acyclic and strongly connected.

4.2 Directed elimination tree

Similar to the notion of elimination trees in undirected graphs, we have directed elimination trees on digraphs.

Definition A directed elimination tree for a nontrivially strongly connected digraph G = (V, E) is a rooted tree $T = (\nabla, \xi)$. T can be defined recursively as follows:

- (v, V) is the root of T for some $v \in V$.
- For every nontrivially strongly connected component in G v, Y_1, \ldots, Y_j a directed elimination tree for $G[Y_i]$ is created for every $1 \le i \le j$. The roots of these trees are conneced to the root of T.

We can extend the concept of directed elimination trees to directed elimination forests. For a digraph G with $k \geq 0$ nontrivially strongly connected components C_1, \ldots, C_k , a rooted forest is the union of the rooted trees of $G[C_i]$ for $1 \leq i \leq k$.

Lemma 4.1. The minimum height among all directed elimination forests for G equals the cycle rank of G.

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