

# Type Inference

## Concepts of Programming Languages

# Outline

- » Discuss **polymorphism** in general
- » Discuss **type inference** with eye towards **Hindley–Milner typing**
- » Look at a set of typing rules for **constraint-based inference**
- » Walk through some **examples**

# Practice Problem

```
fun f -> fun x -> f (x + 1)
```

```
let rec f x = f (f (x + 1)) in f
```

*What are the types of the above OCaml expressions?*

# Answer

1  $(\text{int} \rightarrow \alpha) \rightarrow \text{int} \rightarrow \alpha$

2  $\text{int} \rightarrow \text{int}$

1  $\text{fun } f \rightarrow \text{fun } x \rightarrow$   $f(x + 1)$   $\text{int} \rightarrow ?$

2  $\text{let rec } f x = f$   $(f(x + 1))$   $\text{in } f$   $\text{int} \rightarrow ?$

# **Polymorphism**

# Explicit Typing

```
let add (x : int) (y : int) : int = x + y
let k (x : int) (y : bool) : int = x
let _ : unit = assert(add 2 3 = k 5 false)
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This is closer to what is done in a PL like **Java**

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We rarely have to specify types in OCaml

Type inference, or type *reconstruction* is the process of determining what type we *could* have annotated our program with

*But what type should we give k?*

# High Level

```
let rec rev_int (l : int list) : int list =
  match l with
  | [] -> []
  | x :: l -> rev l @ [x]
```

```
let rec rev_string (l : string list) : string list =
  match l with
  | [] -> []
  | x :: l -> rev l @ [x]
```

```
let _ = assert (rev_int [1;2;3] = [3;2;1])
let _ = assert (rev_string ["1";"2";"3"] = ["3";"2";"1"] )
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Copy/pasting code is *time consuming* and *error prone*

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**Polymorphism** allows for better code reuse. The *same* function can be applied in multiple contexts

# Basic Example

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let id = fun x -> x
let a = id 0
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Important: We can evaluate this if we *don't* type check

*But if we type-check, what should be the type of **id**?*

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2. **Parametric polymorphism:** The ability to define functions that are *agnostic* to (parts of) the types, giving it more reusability

our focus

# Aside: Ad Hoc Polymorphism

```
let add (x : float) (y : float) = x +. y
let add (x : string) (y : string) = x ^ y
(* This doesn't work in OCaml... *)
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Ad hoc polymorphism is essentially **function overloading**

Functions can be defined and used for different types of inputs

Then we can define code against *interfaces* (this is common in object oriented programming)

# Parametric Polymorphism

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Parametric polymorphism allows for functions which are agnostic to the types of its inputs (this is what OCaml does)

*For example, we can write a single identity function and use it in multiple contexts*

There are many subtleties  
to this...

# Subtlety 1: Type Annotations

```
let rec rev ('a list) : 'a list =
  match l with
  | [] -> []
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let id : 'a -> 'a = fun x -> x
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There are type systems *with* polymorphism that *require* type annotations

# Subtlety 2: Type Inference

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Polymorphism is *not* the same as having type inference

In OCaml, polymorphism is deeply connected with its type inference system, but they are distinct (we can choose to annotate all our OCaml code)

# Subtlety 3: Dispatch

```
let to_string (x : 'a) : string = ...  
(* This is not possible in OCaml *)
```

Parametric polymorphism cannot be used for *dispatch*

We can't write a polymorphic function that "checks the type" to see what to do

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There are a couple approaches to implementing parametric polymorphism:

- » **OCaml (Hindley–Milner)**: Infer the "most general" polymorphic type
- » **System F (2nd-order  $\lambda$ -Calculus)**: take types as arguments!

Either way, we have to introduce the notion of a *type variable*

# Type Variables

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Type **variables** are instantiated at particular types according to the context

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let id : 'a . 'a -> 'a = fun x -> x
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Just like with expression variables, we don't like *unbound* type variables

We read this "**id** has type **t -> t** for any type **t**"

# **Interlude: Compact Derivations**

# The Problem

Derivations take up a lot of horizontal space

We've been careful to choose expressions with short derivations in lecture

*We won't be able to do this moving forward*

# The Problem

$$\frac{}{\{ \} \vdash 2 : \text{int}} \text{ (intLit)} \quad \frac{\{ y : \text{int} \} \vdash y : \text{int}}{\{ y : \text{int} \} \vdash y + y : \text{int}} \text{ (var)} \quad \frac{\{ y : \text{int} \} \vdash y : \text{int}}{\{ y : \text{int} \} \vdash y + y : \text{int}} \text{ (var)} \\ \frac{\{ \} \vdash 2 : \text{int} \quad \{ y : \text{int} \} \vdash y + y : \text{int}}{\{ \} \vdash \text{let } y = 2 \text{ in } y + y : \text{int}} \text{ (intAdd)} \\ \frac{\{ \} \vdash 2 : \text{int} \quad \{ y : \text{int} \} \vdash y + y : \text{int}}{\{ \} \vdash \text{let } y = 2 \text{ in } y + y : \text{int}} \text{ (let)}$$

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# Visualizing Trees

```
•
  └── bin
      └── dune
          └── main.ml
  └── dune-project
  └── interp2.opam
  └── lib
      └── dune
          ├── interp2.ml
          ├── lexer.mll
          ├── parser.mly
          └── utils.ml
  └── spec.pdf
  └── test
      └── dune
          └── test_interp2.ml
```

There are many ways of drawing trees.  
Finding a "good" visualization of  
trees is an art

Moving forward we'll use the *file-tree  
format* for writing derivations (this  
is what is done in the textbook)

*It's more horizontally space-efficient*

# Example

# Example

$\frac{}{\{\} \vdash 2 : \text{int}} \text{(intLit)}$	$\frac{\{y : \text{int}\} \vdash y : \text{int}}{\{y : \text{int}\} \vdash y + y : \text{int}} \text{(var)}$	$\frac{\{y : \text{int}\} \vdash y : \text{int}}{\{y : \text{int}\} \vdash \text{let } y = 2 \text{ in } y + y : \text{int}} \text{(var)}$
$\{\} \vdash \text{let } y = 2 \text{ in } y + y : \text{int} \quad \text{(let)}$		

$\{\} \vdash \text{let } y = 2 \text{ in } y + y : \text{int} \quad \text{(let)}$

  └  $\{\} \vdash 2 : \text{int} \quad \text{(intLit)}$

    └  $\{y : \text{int}\} \vdash y + y : \text{int} \quad \text{(intAdd)}$

      └  $\{y : \text{int}\} \vdash y : \text{int} \quad \text{(var)}$

      └  $\{y : \text{int}\} \vdash y : \text{int} \quad \text{(var)}$

# Hindley-Milner

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They underlie nearly all functional PLs currently in use (e.g., OCaml, Haskell, Elm)

# High Level

$$\lambda^a. \lambda^b. \lambda^a \rightarrow \lambda^b \rightarrow \lambda^a$$

*quantified*

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# High Level

**Hindley–Milner type systems** are typed  $\lambda$ -calculi with parametric polymorphism

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*Type inference is decidable and (fairly) efficient*

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A red circle encloses the symbol  $\dashv$ , with the handwritten word "constraints" written above it in red.

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1. Derive  $\Gamma \vdash e : \tau$  relative to some constraints  $\mathcal{C}$

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2. Use the constraints  $\mathcal{C}$  to determine the "actual" type of  $e$  in  $\Gamma$

# Type Inference (High Level)

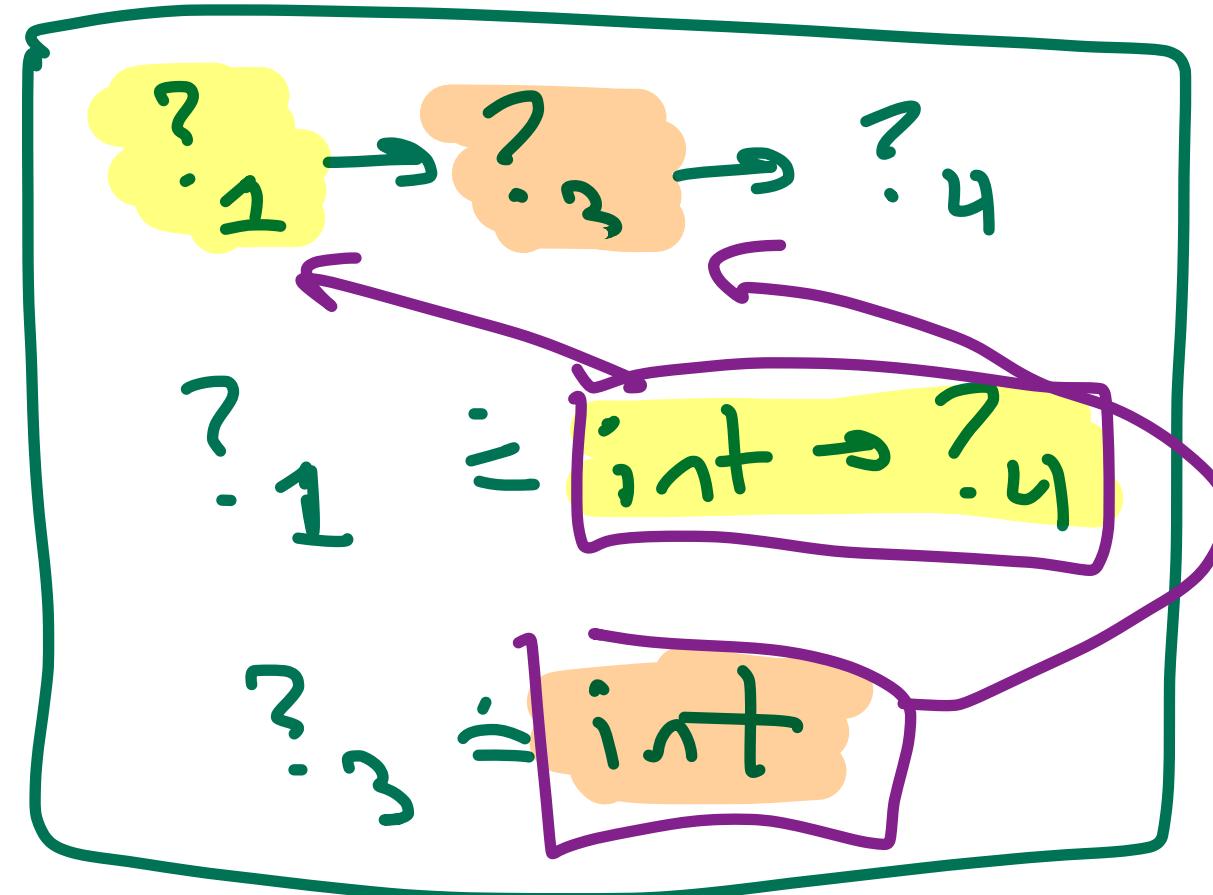
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# Example (by Intuition)

fun f → fun x → f (x + 1)



$\{ \} \vdash \text{fun } f \rightarrow \text{fun } x \rightarrow f (x + 1) : ?_1 \rightarrow ?_3 \rightarrow ?_4 \quad (\text{int} \rightarrow ?_4) \rightarrow \text{int}$

$\vdash \{ f : ?_1 \} \vdash \text{fun } x \rightarrow f (x + 1) : ?_3 \rightarrow ?_4$

$\vdash \{ f : ?_1, x : ?_3 \} \vdash f (x + 1) : ?_4 \quad ?_1 \doteq \text{int} \rightarrow ?_4$

$\vdash \{ f : ?_1, x : ?_3 \} \vdash f : ?_1 \quad (\nu \text{var})$

$\vdash \{ f : ?_1, x : ?_3 \} \vdash x + 1 : \text{int}$

$\vdash \{ f : ?_1, x : ?_3 \} \vdash x : \text{int} \quad ?_3 \doteq \text{int}$

$\vdash \{ \dots \} \vdash 1 : \text{int}$

# Hindley-Milner Light (Syntax)

$\langle \text{expr} \rangle ::= \text{fun } \langle \text{var} \rangle \rightarrow \langle \text{expr} \rangle \mid \langle \text{expr} \rangle \langle \text{expr} \rangle$

$\mid \text{let } \langle \text{var} \rangle = \langle \text{expr} \rangle \text{ in } \langle \text{expr} \rangle$

$\mid \text{if } \langle \text{expr} \rangle \text{ then } \langle \text{expr} \rangle \text{ else } \langle \text{expr} \rangle$

$\mid \langle \text{expr} \rangle + \langle \text{expr} \rangle \mid \langle \text{expr} \rangle = \langle \text{expr} \rangle$

$\mid \langle \text{int} \rangle \mid \langle \text{var} \rangle$

$\langle \text{mty} \rangle ::= \text{int} \mid \text{bool} \mid \langle \text{tyvar} \rangle \mid \langle \text{mty} \rangle \rightarrow \langle \text{mty} \rangle$

$\langle \text{ty} \rangle ::= \langle \text{tyvar} \rangle . \langle \text{ty} \rangle \mid \langle \text{mty} \rangle$

$\alpha . \beta . \boxed{\alpha \rightarrow \beta \rightarrow \gamma}$

*type variable*

*type quantification*

*(mty)*

*(mty)*

*(mty)*

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# Hindley-Milner Light (Mathematical)

$$e ::= \lambda x . e \mid ee$$
$$\mid \text{let } x = e \text{ in } e$$
$$\mid \text{if } e \text{ then } e \text{ else } e$$
$$\mid e + e \mid e = e$$
$$\mid n \mid x$$
$$\sigma ::= \text{int} \mid \text{bool} \mid \boxed{\alpha} \mid \sigma \rightarrow \sigma$$
$$\tau ::= \sigma \mid \boxed{\forall \alpha . \tau}$$

*type variable*

*type quantifier*

As usual, we'll often use concise mathematical notation for writing down inference rules and derivations

# Type Variables and Type Schemes

$$\sigma ::= \text{int} \mid \text{bool} \mid \alpha \mid \sigma \rightarrow \sigma$$
$$\tau ::= \sigma \mid \forall \alpha . \tau$$

# Type Variables and Type Schemes

int  $\rightarrow$  bool ✓      bool  $\rightarrow$   $\alpha$  ✗

$\sigma ::= \text{int} \mid \text{bool} \mid \alpha \mid \sigma \rightarrow \sigma$

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$\sigma$  represents **monotypes**, types with *no quantification*. A type is **monomorphic** if it is a monotype with no type variables

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$\tau$  represents **type schemes**, which are types with some number of quantified type variables  $\forall \alpha . \text{int} \rightarrow \beta$

We say a type is **polymorphic** if it is a *closed* type scheme

$$\forall \alpha . \forall \beta . \text{int} \rightarrow \beta$$

# Free Variables (Monotypes)

$$FV(\text{int}) = \emptyset$$

$$FV(\text{bool}) = \emptyset$$

$$FV(\alpha) = \{\alpha\}$$

$$FV(\tau_1 \rightarrow \tau_2) = FV(\tau_1) \cup FV(\tau_2)$$

Once we introduce variables, we have to again talk about free and bound variables

Unlike in System F, we will only need to consider free variables of **monotypes** so there is *no issue with variable capture*

# Understanding Check

Define substitution  $[\tau_1/\alpha]\tau_2$  for monotypes

$$[\text{int} \rightarrow \text{bool}] (\lambda) (\beta \rightarrow [\alpha] \rightarrow [\alpha]) = \beta \rightarrow (\text{int} \rightarrow \alpha) \rightarrow (\text{int} \rightarrow \alpha)$$

①  $[\sigma/\alpha] \text{int} = \text{int}$

②  $[\sigma/\alpha] \text{bool} = \text{bool}$

③  $[\sigma/\alpha] \beta = \begin{cases} \sigma & \alpha = \beta \\ \beta & \text{o.w.} \end{cases}$

④  $[\sigma/\alpha](\tau_1 \rightarrow \tau_2) = [\sigma/\alpha]\tau_1 \rightarrow [\sigma/\alpha]\tau_2$

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The idea: We're formalizing the idea of "collecting together" our constraints, as in our intuitive example

# What is a constraint?

$$\tau_1 \doteq \tau_2$$

In general, a **type constraint** is a predicate on types. The only kind we will consider:

" $\tau_1$  should be the same as  $\tau_2$ "

Enforcing a constraint like this is called **unifying**  $\tau_1$  and  $\tau_2$

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- » What is the *most general* type  $\tau$  we could give  $e$ ?
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- » What must be true of  $\tau$ , i.e., what *constraints*  $\tau$ ?

If we don't know what type something should be, *we create a fresh type variable for it*

Let's see some typing rules...

# HM<sup>-</sup> (Typing Literals)

$$\frac{n \text{ is an integer}}{\Gamma \vdash n : \text{int} \dashv \emptyset} \text{ (int)}$$

$$\frac{}{\{\} \vdash \lambda : \text{int} \dashv \emptyset}$$

Literals have their expected types *without any constraints*

# HM<sup>-</sup> (Typing Operators)

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathcal{C}_2}{\Gamma \vdash e_1 + e_2 : \text{int} \dashv \tau_1 \doteq \text{int}, \tau_2 \doteq \text{int}, \mathcal{C}_1, \mathcal{C}_2} \text{ (add)}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathcal{C}_2}{\Gamma \vdash e_1 = e_2 : \text{bool} \dashv \tau_1 \doteq \tau_2, \mathcal{C}_1, \mathcal{C}_2} \text{ (eq)}$$

$e_1 + e_2$  is an **int** if the types of  $e_1$  and  $e_2$  can be *unified* to **int**

We don't require that  $\tau_i$  is *exactly* **int**, e.g., it may be a type variable!

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv C_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv C_2 \quad \Gamma \vdash e_3 : \tau_3 \dashv C_3 \ (;x)}{\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau_2 \dashv \tau_2 \doteq \tau_3, \tau_1 \doteq \text{bool}, C_1, C_2, C_3}$$

# HM<sup>-</sup> (Typing If-Expressions)

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathcal{C}_2 \quad \Gamma \vdash e_3 : \tau_3 \dashv \mathcal{C}_3}{\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau_3 \dashv \tau_1 \doteq \text{bool}, \tau_2 \doteq \tau_3, \mathcal{C}_1, \mathcal{C}_2, \mathcal{C}_3} \text{ (if)}$$

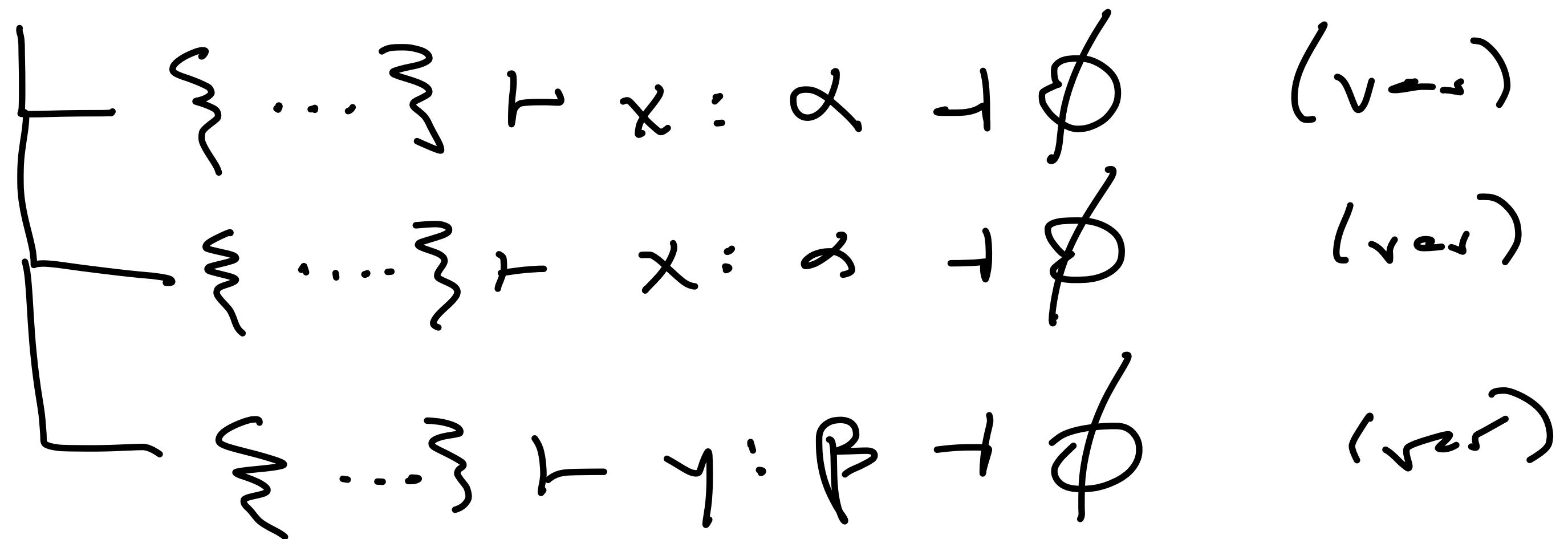
$$\frac{\Gamma \vdash e_1 : \text{bool} \quad \Gamma \vdash e_2 : \tau \quad \Gamma \vdash e_3 : \tau}{\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau}$$

An if-expression has the same type as its else-case when:

- » the type of the condition can be *unified* with **bool**
- » the types of the then-case and else-case can be *unified to each other*

**Example**  $\{x : \alpha, y : \beta\} \vdash \text{if } x \text{ then } x \text{ else } y : \tau \vdash \mathcal{C}$

$\{x : \alpha, y : \beta\} \vdash \text{if } x \text{ then } x \text{ else } y : \alpha \vdash$   $\alpha \doteq \text{bool}$   
 $\beta \doteq \alpha$



# HM<sup>-</sup> (Typing Functions)

$$\frac{\alpha \text{ is fresh} \quad \Gamma, x : \alpha \vdash e : \tau \dashv \mathcal{C}}{\Gamma \vdash \lambda x. e : \alpha \rightarrow \tau \dashv \mathcal{C}} \text{ (fun)}$$

The input type of a function is some type  $\alpha$  and it's output type is the type of the body

We don't know the input type, so we give it the most general form, i.e., a fresh type variable with no constraints

$\lambda$  is fresh

$$\Gamma \vdash e_1 : \tau_1 \vdash C_1$$

$$\Gamma \vdash e_2 : \tau_2 \vdash C_2$$

---

$$\Gamma \vdash e_1 e_2 : \lambda \vdash \tau_1 \doteq \tau_2 \rightarrow \lambda, C_1, C_2$$

# HM<sup>-</sup> (Typing Application)

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathcal{C}_2 \quad \alpha \text{ is fresh}}{\Gamma \vdash e_2 : \alpha \dashv \tau_1 \doteq \tau_2 \rightarrow \alpha, \mathcal{C}_1, \mathcal{C}_2} \text{ (app)}$$

The type of an application is some type  $\alpha$ , such that the type of the function unifies to a function type with output type  $\alpha$ , and the input type matches the type of the argument (wordy...)

# HM<sup>-</sup> (Typing Variables)

$$\frac{(x : \forall \alpha_1 . \forall \alpha_2 \dots \forall \alpha_k . \tau) \in \Gamma \quad \beta_1, \dots, \beta_k \text{ are fresh}}{\Gamma \vdash x : [\beta_1/\alpha_1] \dots [\beta_k/\alpha_k] \tau \dashv \emptyset} \text{ (var)}$$

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If  $x$  is declared in  $\Gamma$ , then  $x$  can be given the type  $\tau$  with *all free variables replaced by **fresh variables***

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*This is where the polymorphism magic happens*

**fresh variables can be unified with anything**

# Example

```
fun f -> fun x -> f (x + 1)
```

# Up Next

We still need to:

- » introduce a **unification algorithm** to determine the "actual" type given a collection of constraints
- » Discuss **let-expressions** (and top-level let expressions)
- » introduce **type annotations**

We wont:

- » deal with **type errors** (tricker with unification-based inference)

# Summary

By restricting our type quantification, we get a system that has decidable and efficient **type inference**

Hindley–Milner style type inference requires us to figure out a collection of **constraints** that need to be unified