

Unification

Concepts of Programming Languages

Outline

- » Finish up our discussion of **Hindley–Milner Light** (HM^-)
- » Describe the **unification** algorithm used to determine the "actual" type of our expression, given a collection of constraints

Recap

Recall: Parametric Polymorphism

```
let rec rev = function
| [] -> []
| x :: xs -> rev xs @ [x]
```

Parametric polymorphism allows for functions which are agnostic to the types of its inputs

For example, we can write a single reverse function and use it in multiple contexts

Recall: Quantification

```
let id : 'a . 'a -> 'a = fun x -> x
```

In reality, types variables in OCaml are **quantified**

We read this "**id** has type **t -> t** for any type **t**"

Recall: Hindley-Milner Light

$$e ::= \lambda x . e \mid ee$$
$$\mid \text{let } x = e \text{ in } e$$
$$\mid \text{if } e \text{ then } e \text{ else } e$$
$$\mid e + e \mid e = e$$
$$\mid n \mid x$$
$$\sigma ::= \text{int} \mid \text{bool} \mid \alpha \mid \sigma \rightarrow \sigma$$
$$\tau ::= \sigma \mid \forall \alpha . \tau$$

type quant.

type vars.

Recall: Type Schemes

$$\sigma ::= \text{int} \mid \text{bool} \mid \alpha \mid \sigma \rightarrow \sigma$$
$$\tau ::= \sigma \mid \forall \alpha . \tau$$
$$\alpha \rightarrow \beta$$

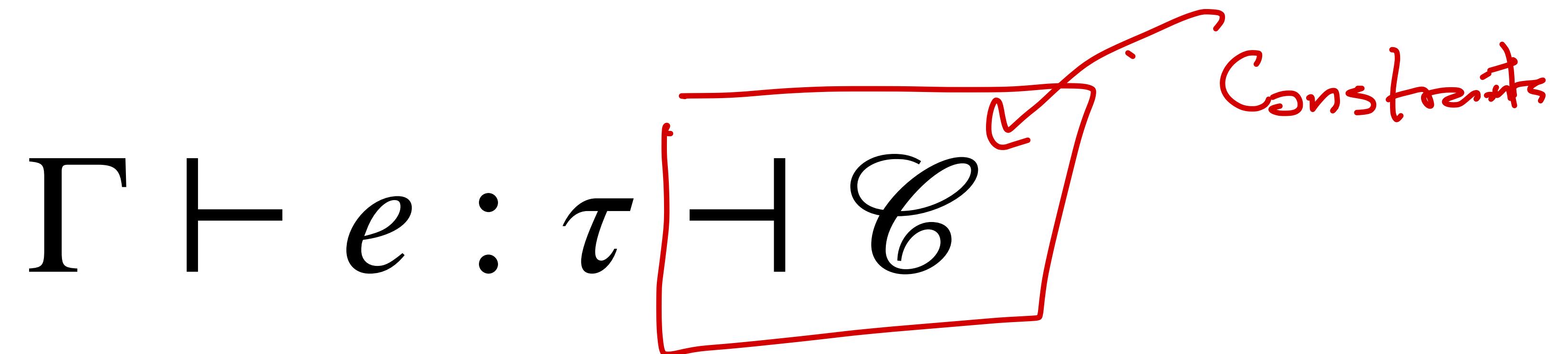
monotype (σ): type with no quantification

monomorphic type: monotype with no type variables

type scheme (τ): type with zero or more quantified type variables

polymorphic type: closed type scheme $\forall \alpha . \alpha \rightarrow \alpha$

Recall: Constraint-Based Inference



Our typing rules well need to keep track of a set of **constraints**, which tell use what must hold for e to be well-typed

The idea: We're formalizing the idea of "collecting together" our constraints, as in our intuitive example

Recall: Constraints

$$\tau_1 \doteq \tau_2$$

" τ_1 should be the same as τ_2 "

Enforcing this constraint means **unifying** τ_1 and τ_2

Recall II: HM⁻ (Typing)

$$\frac{n \text{ is an integer}}{\Gamma \vdash n : \text{int} \dashv \emptyset} \text{ (int)}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathcal{C}_2 \quad \Gamma \vdash e_3 : \tau_3 \dashv \mathcal{C}_3}{\Gamma \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : \tau_3 \dashv \tau_1 \doteq \text{bool}, \tau_2 \doteq \tau_3, \mathcal{C}_1, \mathcal{C}_2, \mathcal{C}_3} \text{ (if)}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathcal{C}_2}{\Gamma \vdash e_1 = e_2 : \text{bool} \dashv \tau_1 \doteq \tau_2, \mathcal{C}_1, \mathcal{C}_2} \text{ (eq)}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathcal{C}_2}{\Gamma \vdash e_1 + e_2 : \text{int} \dashv \tau_1 \doteq \text{int}, \tau_2 \doteq \text{int}, \mathcal{C}_1, \mathcal{C}_2} \text{ (add)}$$

$$\frac{\alpha \text{ is fresh} \quad \Gamma, x : \alpha \vdash e : \tau \dashv \mathcal{C}}{\Gamma \vdash \lambda x. e : \alpha \rightarrow \tau \dashv \mathcal{C}} \text{ (fun)}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma \vdash e_2 : \tau_2 \dashv \mathcal{C}_2 \quad \alpha \text{ is fresh}}{\Gamma \vdash e_1 e_2 : \alpha \dashv \tau_1 \doteq \tau_2 \rightarrow \alpha, \mathcal{C}_1, \mathcal{C}_2} \text{ (app)}$$

Practice Problem

$$\{f : \alpha \rightarrow \alpha\} \vdash f(f\ 2 = 2) : \tau \dashv \mathcal{C}$$

Determine the type τ and constraints \mathcal{C} such that the above judgment is derivable

$$\frac{n \text{ is an integer}}{\Gamma \vdash n : \text{int} \dashv \emptyset} \text{ (int)}$$

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$\alpha, \beta, \gamma, \delta, \eta, \varepsilon$

Answer

$$\begin{array}{l} \{f : \alpha \rightarrow \alpha\} \vdash f(2 = 2) : \eta \vdash \alpha \rightarrow \alpha \doteq \text{bool} \rightarrow \eta, \alpha \rightarrow \alpha : \text{int} \rightarrow \beta \\ \left[\begin{array}{l} \{f : \alpha \rightarrow \alpha\} \vdash f : \alpha \rightarrow \alpha \vdash \phi \\ \{f : \alpha \rightarrow \alpha\} \vdash f 2 = 2 : \text{bool} \vdash \alpha \rightarrow \alpha \doteq \text{int} \rightarrow \beta, \beta = \text{int} \end{array} \right] \\ \vdash \{f : \alpha \rightarrow \alpha\} \vdash f 2 : \beta \vdash \alpha \rightarrow \alpha \doteq \text{int} \rightarrow \beta \\ \left[\begin{array}{l} \{f : \alpha \rightarrow \alpha\} \vdash f 2 : \beta \vdash \alpha \rightarrow \alpha \doteq \text{int} \rightarrow \beta \\ \{f : \alpha \rightarrow \alpha\} \vdash f : \alpha \rightarrow \alpha \rightarrow \beta \\ \{f : \alpha \rightarrow \alpha\} \vdash f : \alpha \rightarrow \alpha \rightarrow \beta \\ \{f : \alpha \rightarrow \alpha\} \vdash 2 : \text{int} \vdash \phi \\ \{f : \alpha \rightarrow \alpha\} \vdash 2 : \text{int} \rightarrow \phi \end{array} \right] \end{array}$$

C

$$\begin{array}{l} \alpha \rightarrow \alpha \doteq \text{bool} \rightarrow \eta \\ \alpha \rightarrow \alpha \doteq \text{int} \rightarrow \beta \\ \beta = \text{int} \end{array}$$

HM⁻ (Typing Variables)

$$\frac{\text{monotype} \quad (x : \forall \alpha_1 . \forall \alpha_2 \dots \forall \alpha_k . \tau) \in \Gamma \quad \beta_1, \dots, \beta_k \text{ are fresh}}{\Gamma \vdash x : [\beta_1/\alpha_1] \dots [\beta_k/\alpha_k] \tau \dashv \emptyset} (\text{var})$$

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fresh variables can be unified with anything

$\{ f : \forall \alpha. \alpha \rightarrow \alpha \} \vdash f (f 2 = 2) : \Sigma \dashv \beta \rightarrow \beta \doteq \text{bool} \rightarrow \Sigma, \dots$

$\vdash \{ f : \forall \alpha. \alpha \rightarrow \alpha \} \vdash f : \beta \rightarrow \beta \rightarrow \emptyset$

$\vdash \{ f : \dots \} \vdash f 2 = 2 : \text{bool} \dashv \gamma \rightarrow \gamma \doteq \text{int} \rightarrow \delta, \delta \doteq \text{int}$

$\vdash \{ \dots \} \vdash f 2 : \delta \dashv \gamma \rightarrow \gamma \doteq \text{int} \rightarrow \delta$

$\vdash \{ \dots \} \vdash f : \gamma \rightarrow \gamma \rightarrow \emptyset$

$\vdash \{ \dots \} \vdash 2 : \text{int} \rightarrow \emptyset$

$\vdash \{ \dots \} \vdash 2 : \text{int}$

C

$\beta \rightarrow \beta \doteq \text{bool} \rightarrow \Sigma$

$\gamma \rightarrow \gamma \doteq \text{int} \rightarrow \delta$

$\delta \doteq \text{int}$

Example

$\{f : \forall \alpha . \alpha \rightarrow \alpha\} \vdash f(f\ 2 = 2) :$

HM⁻ (Typing Let-Expressions)

$$\frac{\Gamma \vdash e_1 : \tau_1 \dashv \mathcal{C}_1 \quad \Gamma, x : \tau_1 \vdash e_2 : \tau_2 \dashv \mathcal{C}_2}{\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau_2 \dashv \mathcal{C}_1, \mathcal{C}_2} \text{ (let)}$$

The type of a let-expression is the same as the type of its body, relative to the constraints of typing the let-binding and the body (wordy...)

Aside: Let-Polyomorphism

```
let f = fun x -> x in  
let y = f 2 in  
f true
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The Takeaway: We will have to treat typing of top-level let-expressions as *different* from local let-expressions

Unification

High Level

$$a \doteq d \rightarrow e$$
$$c \doteq \text{int} \rightarrow d$$
$$\text{int} \rightarrow \text{int} \rightarrow \text{int} \doteq b \rightarrow c$$

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Unification is the process of solving a system of equations over *symbolic* expressions

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e.g., we could solve a system of equations over *variables* and *ADT constructors*

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$$s_2 \doteq t_2$$

⋮

$$s_k \doteq t_k$$

ADT Unification Problem

A **unification problem** is a collection of equations of the form

$$\begin{aligned}s_1 &\doteq t_1 \\ s_2 &\doteq t_2 \\ &\vdots \\ s_k &\doteq t_k\end{aligned}$$

where s_1, \dots, s_k and t_1, \dots, t_k are element of the ADT possibly with variables

Example

```
type ty =  
| TInt  
| TBool  
| TFun of ty * ty  
| TVar of string
```

$$x \doteq \text{TFun}(\text{TInt}, \text{TInt})$$

$$y \doteq \text{TFun}(x, \text{TBool})$$

$$y \doteq \text{TFun}(\overline{\text{TInt}}, x)$$

$$x \doteq \text{int} \rightarrow \text{int}$$

$$y \doteq x \rightarrow \text{bool}$$

$$y \doteq \text{int} \rightarrow x$$

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incr i

We write $\mathcal{S}t$ for $[t_i/x_i] \dots [t_1/x_1]t$

; incr i

Unifiers (2)

A solution must have the property that it **satisfies** every equation

$$\mathcal{S}t_1 = \mathcal{S}s_1$$

$$\mathcal{S}s_2 = \mathcal{S}t_2$$

⋮

$$\mathcal{S}s_k = \mathcal{S}t_k$$

Example

$S = \{ c \mapsto \text{int} \rightarrow \text{int}, b \mapsto \text{int}, d \mapsto \text{int}, a \mapsto \text{int} \rightarrow e \}$

$$\begin{array}{c} a \doteq d \rightarrow e \\ \Downarrow \\ \text{int} \rightarrow e = \text{int} \rightarrow e \end{array}$$

$$\begin{array}{l} a \doteq d \rightarrow e \\ c \doteq \text{int} \rightarrow d \\ \text{int} \rightarrow (\text{int} \rightarrow \text{int}) \doteq b \rightarrow c \end{array}$$

exercise: check cst

Unification may Fail

$$\begin{aligned} a &\doteq b \rightarrow c \\ b &\doteq a \rightarrow \text{int} \end{aligned}$$

Not all unification problems have solutions...

$$\begin{aligned} a &\doteq (a \rightarrow \text{int}) \rightarrow c \\ a &\doteq ((a \rightarrow \text{int} \rightarrow c) \rightarrow \text{int}) \rightarrow c \end{aligned}$$

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Ex.

$$\begin{aligned} a &\doteq d \rightarrow e \\ c &\doteq \text{int} \rightarrow d \\ \text{int} \rightarrow \text{int} \rightarrow \text{int} &\doteq b \rightarrow c \end{aligned}$$

$$\begin{aligned} S = \{ & b \mapsto \text{int} \rightarrow \text{int}, \\ & c \mapsto \text{int}, \\ & d \mapsto \text{int}, \\ & a \mapsto \text{int} \rightarrow e \} \end{aligned}$$

$$\begin{aligned} S' = \{ & b \mapsto \text{int} \rightarrow \text{int}, \\ & c \mapsto \text{int}, \\ & d \mapsto \text{int}, \\ & a \mapsto \text{int} \rightarrow e \\ S'' = \{ & e \mapsto \text{bad} \} \end{aligned}$$

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And we're guaranteed to get a most general unifier

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$\mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\}$

perform the substitution $\alpha \mapsto t$ to every equation in \mathcal{U}

OTHERWISE \implies FAIL

An Algorithm (Pseudocode)

input: type unification problem \mathcal{U}

output: most general unifier to \mathcal{U}

$\mathcal{S} \leftarrow$ empty solution

WHILE $eq \in \mathcal{U}$: // \mathcal{U} is not empty

MATCH eq :

$t_1 \doteq t_2$ when $t_1 = t_2 \implies \mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\}$ // t_1 and t_2 are *syntactically* equal, remove eq

$s_1 \rightarrow t_1 \doteq s_2 \rightarrow t_2 \implies \mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\} \cup \{s_1 \doteq s_2, t_1 \doteq t_2\}$ // remove eq and add $s_1 \doteq s_2$ and $t_1 \doteq t_2$

$\alpha \doteq t$ or $t \doteq \alpha$ where $\alpha \notin FV(t) \implies$ // type variable α does not appear free in t

$\mathcal{S} \leftarrow \mathcal{S} \cup \{\alpha \mapsto t\}$ // add $\alpha \mapsto t$ to \mathcal{S}

$\mathcal{U} \leftarrow \mathcal{U} \setminus \{eq\}$

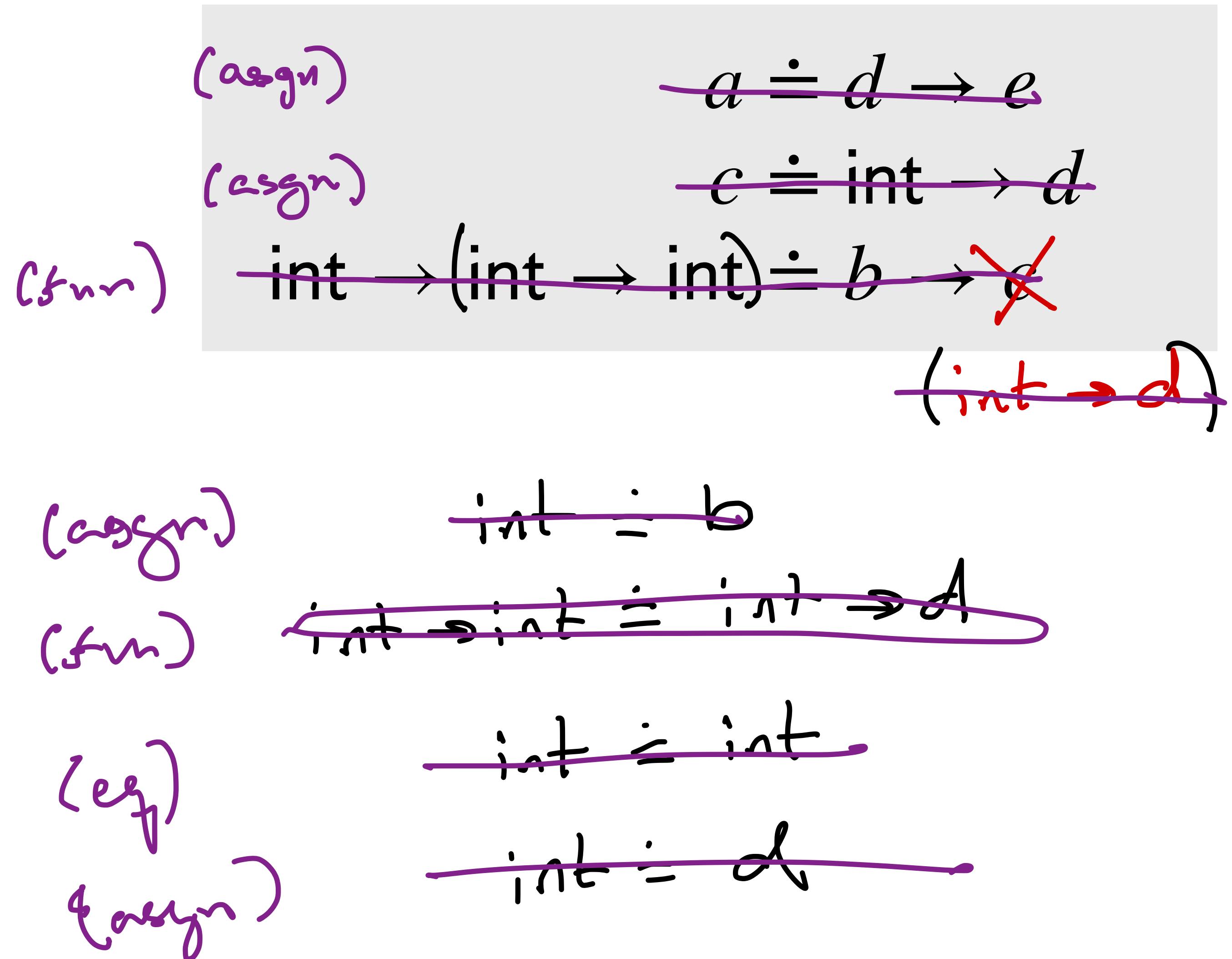
perform the substitution $\alpha \mapsto t$ to every equation in \mathcal{U}

OTHERWISE \implies **FAIL**

RETURN \mathcal{S}

Example

$S = \{ a \mapsto d \rightarrow e ,$
 $c \mapsto \text{int} \rightarrow d ,$
 $b \mapsto \text{int} ,$
 $d \mapsto \text{int} \}$

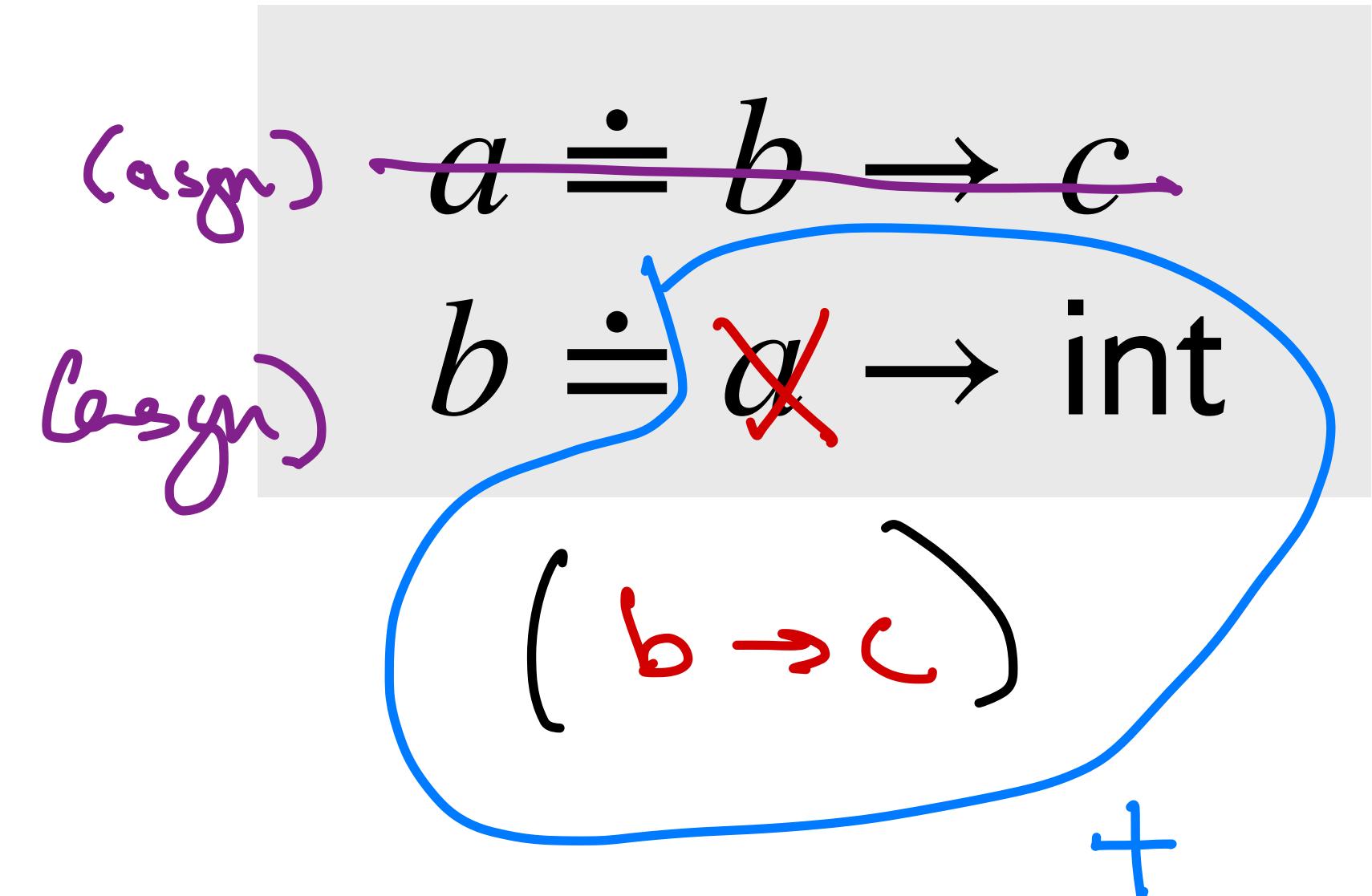


$S a \rightarrow d \rightarrow e \rightarrow \text{int} \rightarrow \text{P}$

Example

$$S = \{ a \mapsto b \rightarrow c$$

~~F A \wedge~~



$$b \in F \vee (+)$$

$$= F \vee ((b \rightarrow c) \rightarrow \text{int})$$

Summary

Unification is used to solve a collection of constraints generated by constraint-based inference

Not all unification problems have solutions. In the type unification problem, this indicates a type error