Aneri Muni

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FDUCATION

GEORGIA INSTITUTE OF TECHNOLOGY

BS IN ELECTRICAL ENGINEERING MINOR IN ROBOTICS May 2018 | Atlanta, GA Dean's List

STUDY ABROAD: GEORGIA TECH Summer 2014 | Lorraine, France

LINKS

Github:// amuni3 LinkedIn:// aneri-muni

COURSEWORK

UNDERGRADUATE

Intro to Automation and Robotics Feedback Control Control System Design Signals and Systems Electromagnetism Electrical Energy Systems Microelectronic Circuits Computer Communication Data Structures and Algorithms Digital Signal Processing Circuit Analyses

SKILLS

TECHNICAL

Java • Matlab • C++ • CSS • HTML • Assembly • VHDL • RobotC

ROS • Linux • PCL • Movelt! • OpenCV • MySQL

Softwares:

Quartus II • MathCAD •
Multisim • LabVIEW •
LTSpice • AutoDesk Inventor •
Eagle • MS Office

LEADERSHIP

- Undergraduate Research Ambassador
- Women in ECE (WECE)

Newsletter Chair | Publicity co-chair

• ECE Ambassador

EXPERIENCE

AUTONOMOUS SYSTEMS LAB | Visiting Student Researcher

June 2017 - August 2017 | ETH Zurich

- Programmed ABB's YuMi robot to rebuild a block stack after scanning it.
- Developed pick-place pipeline using Movelt! and object-detection pipeline using PCL and ASUS PrimeSense sensor.

GEORGIA TECH RESEARCH INSTITUTE | ROBOTICS AND IMAGE

PROCESSING CO-OP

August 2015 - December 2015 | Georgia Tech

- Programmed agricultural robot to maneuver autonomously in poultry houses.
- Implemented path finding and obstacle avoidance algorithms using Kinect data.

May 2016 - August 2016 | Georgia Tech

• Developed user friendly Windows GUIs in C++ to run a pedestrian tracking software, process the data and access results using MySQL.

SCHOOL OF MATHEMATICS | TEACHING ASSISTANT

January 2016 - May 2016 | Georgia Tech

• Taught **Differential Equations** a class of 30 students by holding recitations.

CENTER FOR ACADEMIC SUCCESS | PEER TUTOR

August 2014 - May 2015 | Georgia Tech

• Taught **Differential Equations** to class of 50 students by holding study sessions.

RESEARCH PROJECTS

DYNAMIC SCENE RECONSTRUCTION

Jan 2017 - Present | Georgia Tech Research Institute

• 3D tracking and reconstruction of dynamic, non-rigid scenes.

QUADRUPED ROBOT

August 2016 - December 2016 | IVALab, Georgia Tech

- Programmed a quadruped robot that emulates the walking gait of quadrupeds.
- Designed 3D model of quadruped with an actuated spine in AutoDesk Inventor.

AUTONOMOUS BLIMPS

May 2015 - December 2016 | Georgia Tech Systems Lab

- Performed system identification and developed PID controllers to control 3D motion of a robotic helium blimp.
- Nano Blimp developed a smaller version of blimp to create a sensor network.

AWARDS

2018, 2016, 2015 President's Undergraduate Research Award ThinkSwiss Research Scholarship

2017 James G. Wohlford Scholarship

2015 IEEE Control System Society Video Contest, 3rd position

PUBLICATIONS

[1] C. T Usher, W. D Daley, B. P Joffe and A. Muni. Robotics for Poultry House Management. **ASABE Annual International Meeting**, 2017.

[2] S. Cho, V. Mishra, Q. Tao, P. Varnell, M. King-Smith, A. Muni, W. Smallwood and F. Zhang. Autopilot Design for a Class of Miniature Autonomous Blimps. *Conference on Control Technology and Applications*, in press.