

Problem 1: Suppose a process $\{x(n)\}$ is characterized by the autocorrelation sequence

$$\gamma_{xx}(0) = \frac{4}{3}, \gamma_{xx}(1) = \frac{2}{3}, \gamma_{xx}(2) = \frac{1}{3}, \gamma_{xx}(3) = \frac{1}{6}.$$

- (a) Use the autocorrelations and calculate an AR(2) model for this process.
- (b) Substituting these results into the Yule-Walker equation for $k=0$ to estimate the white noise variance. Then compute the power spectrum based on the AR(2) model.
- (c) Repeat the above calculation for an AR(3) model. Comment on your results.

a)

$$\gamma_{xx}(0) = \frac{4}{3}, \gamma_{xx}(1) = \frac{2}{3}, \gamma_{xx}(2) = \frac{1}{3}$$

$$Eq1: \frac{4}{3} + a_1 \cdot \frac{2}{3} + a_2 \cdot \frac{1}{3} = \sigma^2 \omega$$

$$-2 - 2a_2 = -2 - 8a_2$$

AR(2) Yule Walker:

$$\begin{bmatrix} \gamma_{xx}(0) & \gamma_{xx}(1) & \gamma_{xx}(2) \\ \gamma_{xx}(1) & \gamma_{xx}(0) & \gamma_{xx}(1) \\ \gamma_{xx}(2) & \gamma_{xx}(1) & \gamma_{xx}(0) \end{bmatrix} \begin{bmatrix} 1 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} \sigma^2 \omega \\ 0 \\ 0 \end{bmatrix}$$

$$Eq2: \frac{2}{3} + a_1 \cdot \frac{4}{3} + a_2 \cdot \frac{2}{3} = 0 \Rightarrow 4a_1 = -2 - 2a_2$$

$$a_2 = 4a_1$$

$$Eq3: \frac{1}{3} + a_1 \cdot \frac{2}{3} + a_2 \cdot \frac{4}{3} = 0 \Rightarrow 2a_1 = -1 - 4a_2$$

$$\therefore a_2 = 0$$

$$\therefore a_1 = -0.5$$

$$AR(2) \text{ model} = H(\omega) = \frac{1}{1 + a_1 e^{-j\omega} + a_2 e^{-2j\omega}}$$

$$H(z) = \frac{1}{A(z)} = \frac{1}{1 + \sum_{k=1}^P a_k z^{-k}}$$

$$b) Eq1: \frac{4}{3} - 0.5 \cdot \frac{2}{3} + 0 \cdot \frac{1}{3} = \sigma^2 \omega$$

$$\frac{4}{3} - \frac{1}{3} + 0 = \sigma^2 \omega = 1$$

$$S_{xx}(\omega) = \sigma^2 \omega |H(\omega)|^2$$

$$= \frac{1}{|1 + a_1 e^{-j\omega} + a_2 e^{-2j\omega}|^2}$$

c) Yule-Walker

$$\begin{bmatrix} \frac{4}{3} & \frac{2}{3} & \frac{1}{3} & \frac{1}{6} \\ \frac{2}{3} & \frac{4}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{2}{3} & \frac{4}{3} & \frac{2}{3} \\ \frac{1}{6} & \frac{1}{3} & \frac{2}{3} & \frac{4}{3} \end{bmatrix} \begin{bmatrix} 1 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} \sigma^2 \omega \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$Eq1: a_1 \cdot \frac{4}{3} + a_2 \cdot \frac{2}{3} + a_3 \cdot \frac{1}{3} = -\frac{2}{3}$$

$$Eq2: a_1 \cdot \frac{2}{3} + a_2 \cdot \frac{4}{3} + a_3 \cdot \frac{2}{3} = -\frac{1}{3}$$

$$Eq3: a_1 \cdot \frac{1}{3} + a_2 \cdot \frac{2}{3} + a_3 \cdot \frac{4}{3} = -\frac{1}{6}$$

Problem 2: A process $\{x(n)\}$ is characterized by the autocorrelation sequence

$$\gamma_{xx}(0) = \frac{4}{3}, \gamma_{xx}(1) = \frac{2}{3}, \gamma_{xx}(2) = \frac{1}{3}, \gamma_{xx}(3) = \frac{1}{6}.$$

- (a) Consider the one-step forward predictor of order 2. Determine the prediction coefficients.
- (b) Calculate the resulting MMSE (minimum mean-square error) for this 2nd-order predictor.
- (c) Write down the difference equation.

$$\hat{x}(n) = - \sum_{k=1}^P a_p(k) x(n-k)$$

$$a) \hat{x}(n) = - \sum_{k=1}^2 a_2(k) x(n-k) \Rightarrow \gamma_{xx}(l) = - \sum_{k=1}^P a_3(k) \gamma_{xx}(l-k), l=1,2$$

$$X_n = \begin{bmatrix} X(n-1) \\ X(n-2) \end{bmatrix}, h = \begin{bmatrix} -a_2(1) \\ -a_2(2) \end{bmatrix}, Y_d = E[d(n)X_n] = E\left[X(n)\begin{bmatrix} X(n-1) \\ X(n-2) \end{bmatrix}\right]$$

$$\Gamma_2 = E[X_n X_n^T] = \begin{bmatrix} \gamma_{xx}(0) & \gamma_{xx}(1) \\ \gamma_{xx}(1) & \gamma_{xx}(0) \end{bmatrix}$$

$$\begin{bmatrix} \gamma_{xx}(0) & \gamma_{xx}(1) \\ \gamma_{xx}(1) & \gamma_{xx}(0) \end{bmatrix} \begin{bmatrix} -a_2(1) \\ -a_2(2) \end{bmatrix} = \begin{bmatrix} \gamma_{xx}(1) \\ \gamma_{xx}(2) \end{bmatrix}$$

$$h = \Gamma_2^{-1} Y_d$$

$$\begin{bmatrix} a_2(1) \\ a_2(2) \end{bmatrix} = \frac{1}{16 - \frac{4}{9}} \begin{bmatrix} 4/3 & -2/3 \\ -2/3 & 4/3 \end{bmatrix} \cdot \begin{bmatrix} 1/3 \\ 1/3 \end{bmatrix}$$

$$a_2(1) = \left(\frac{8}{3} - \frac{2}{3}\right) \cdot \frac{3}{21} = \frac{6}{4} = 1.5$$

$$a_2(2) = \left(-\frac{4}{3} + \frac{4}{3}\right) \cdot \frac{3}{4} = 0$$

b) MMSE = $\gamma_{dd}(0) - \gamma_d^T h$, $d(n) = X(n)$

$$MMSE = \gamma_{xx}(0) + \sum_{k=1}^2 a_2(k) \gamma_{xx}(k) = \frac{4}{3} + \frac{3}{2} \cdot \frac{2}{3} - 0 \cdot \frac{1}{3} = \frac{7}{3}$$

c) $e(n) = x(n) - \hat{x}(n) = x(n) + \sum_{k=1}^2 a_2(k) x(n-k) = x(n) + 1.5 x(n-1)$

Problem 3: Wiener filter

A zero-mean stationary process $\{s(n)\}$ is characterized by the autocorrelation sequence

$$\gamma_{ss}(0) = 1, \gamma_{ss}(1) = \frac{1}{2}, \gamma_{ss}(2) = \frac{1}{8}, \gamma_{ss}(3) = \frac{1}{64}.$$

- a.) Let us assume that the observed signal $x(n)$ can be expressed as $x(n) = 2s(n) + w(n)$, where $s(n)$ is a process described above, and $\{w(n)\}$ is a white noise sequence with variance $\sigma_w^2 = 1$. Assume that $\{w(n)\}$ is uncorrelated to $\{s(n)\}$. Determine the autocorrelation sequence $\{\gamma_{xx}(m)\}$ of the process $\{x(n)\}$ for $m=0,1,2,3$.

a) $x(n) = 2s(n) + w(n)$

$$\gamma_{xx}(l) = E[X(n)X(n-l)] = E[(2s(n)+w(n))(2s(n-l)+w(n-l))] = 4\gamma_{ss}(l) + 2\gamma_{sw}(l) + 2\gamma_{ww}(l)$$

$4 \gamma_{ss}(l) \gamma_{ss}(n-l) + 2 \gamma_{ss}(n) \gamma_{ss}(n-l) + 2 \gamma_{sw}(n) \gamma_{sw}(n-l) + \gamma_{ww}(n) \gamma_{ww}(n-l)$

for $w(n)$ $\gamma_{ww}(l) = \sigma_w^2 \delta(l)$, σ_w^2 given as 1

$\therefore \gamma_{ww}(l) = \delta(l)$, $\gamma_{sw}(l) = 0$ since $s(n)$ and $w(n)$ are uncorrelated.

Since $s(n)$ & $w(n)$ are uncorrelated.

For $w(n)$ $\gamma_{ww}(k) = \sigma_w^2 \delta(k)$, σ_w^2 given as 1

$$\therefore \gamma_{ww}(k) = \delta(k) \rightarrow \{\gamma_{ss}(k)\} \text{ given as } \{1, \frac{1}{2}, \frac{1}{8}, \frac{1}{64}\}$$

$$\therefore \{\gamma_{xx}(k)\} = \{5, 2, 0.5, \frac{1}{16}\}$$

Since $\gamma_{ss}(n) \propto w(n)$
are uncorrelated.

- b.) Consider the signal smoothing application. Based on the signal $\{x(n)\}$, we want to design a FIR Wiener filter of length $M=2$ to estimate $s(n+1)$. Write down the expression of the output $y(n)$ in terms of the FIR filter of length $M=2$ with coefficients $\{h(0), h(1)\}$.
- c.) Calculate the solution for this optimum FIR Wiener filter in b.), and calculate the corresponding minimum MSE (i.e. MMSE₂).
- d.) In the above problem, suppose the observed signal $x(n)$ can be expressed as $x(n) = s(n) + s(n-1) + w(n)$. We want to use $x(n)$ and $x(n+1)$ to estimate $s(n)$. Write down the expression of the output $y(n)$ with coefficients $\{h(0), h(1)\}$. Calculate the solution for this optimum Wiener filter.

b) $d(n) = S(n+1)$

Filter of length M with coefficients $\{h(k)\}$

$$y(n) = \sum_{k=0}^{M-1} h(k) x(n-k) = \vec{x}_n^\top h_m$$

Auto corr Mat: $\Gamma_x = E[\vec{x}_n \vec{x}_n^\top]$

X-corr vec: $\gamma_d = E[d(n) \vec{x}_n^\top]$

MMSE solution: $\Gamma_x h_m = \gamma_d$

MMSE₂ = min $E_m = \sigma_d^2 - \gamma_d^\top \Gamma_x^{-1} \gamma_d$

$h_{opt} = \Gamma_x^{-1} \gamma_d$

$$y(n) = \hat{d}(n) = \hat{S}(n+1) = \sum_{k=0}^1 h(k) x(n-k) = h(0) x(n) + h(1) x(n-1) = \vec{x}_n^\top h, \quad \vec{x}_n^\top = [x(n) \quad x(n-1)], \quad h = \begin{bmatrix} h(0) \\ h(1) \end{bmatrix}$$

c) $\gamma_d = E[d(n) \vec{x}_n] = E\left\{S(n+1) \begin{bmatrix} x(n) \\ x(n-1) \end{bmatrix}\right\} = E\left\{S(n+1) \begin{bmatrix} 2S(n) + w(n) \\ 2S(n-1) + w(n-1) \end{bmatrix}\right\} = \begin{bmatrix} 2\gamma_{ss}(1) \\ 2\gamma_{ss}(2) \end{bmatrix}$

$$\Gamma_x = E[\vec{x}_n \vec{x}_n^\top] = \begin{bmatrix} \gamma_{xx}(0) & \gamma_{xx}(1) \\ \gamma_{xx}(1) & \gamma_{xx}(2) \end{bmatrix} = \begin{bmatrix} 5 & 2 \\ 2 & 5 \end{bmatrix}$$

$$\Gamma_x^{-1} h = \gamma_d \therefore h = \Gamma_x^{-1} \gamma_d = \frac{1}{25-4} \begin{bmatrix} 5 & -2 \\ -2 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 1/4 \end{bmatrix} = \begin{bmatrix} \frac{5}{21} - \frac{2}{4 \cdot 21} \\ \frac{-2}{21} + \frac{5}{4 \cdot 21} \end{bmatrix} = \begin{bmatrix} 0.214 \\ -0.036 \end{bmatrix}$$

$$\text{MMSE} = \gamma_{dd}(0) - \gamma_d^\top h = 1 - \begin{bmatrix} 1 & 1/4 \end{bmatrix} \begin{bmatrix} 0.214 \\ -0.036 \end{bmatrix} = 0.795$$

$$\gamma_{dd} = E[S(n+1) S(n+1)] = \gamma_{ss}(0) = 1$$

d) $d(n) = S(n)$ $\vec{x}_n = \begin{bmatrix} x(n) \\ x(n+1) \end{bmatrix}$

$$x(n) = S(n) + S(n-1) + w(n)$$

$$y(n) = \hat{d}(n) = \hat{S}(n) = h(0) x(n) + h(1) x(n+1)$$

$$= \vec{x}_n^\top h, \quad \vec{x}_n = \begin{bmatrix} x(n) \\ x(n+1) \end{bmatrix}, \quad h = \begin{bmatrix} h(0) \\ h(1) \end{bmatrix}$$

$$\gamma_d = E[d(n) \vec{x}_n] = E\left\{S(n) \begin{bmatrix} x(n) \\ x(n+1) \end{bmatrix}\right\} = E\left\{S(n) \begin{bmatrix} S(n) + S(n-1) + w(n) \\ S(n+1) + S(n) + w(n+1) \end{bmatrix}\right\} = \begin{bmatrix} \gamma_{ss}(0) + \gamma_{ss}(1) \\ \gamma_{ss}(1) + \gamma_{ss}(0) \end{bmatrix}$$

$$\gamma_d = E[d(n) x_n] = E\{S(n)\} \begin{bmatrix} x(n) \\ x(n+1) \end{bmatrix} = E\left\{ S(n) \begin{bmatrix} S(n) + S(n-1) + \omega(n) \\ S(n+1) + S(n) + \omega(n+1) \end{bmatrix} \right\} = \begin{bmatrix} \gamma_{ss}(0) + \gamma_{ss}(1) \\ \gamma_{ss}(1) + \gamma_{ss}(0) \end{bmatrix}$$

$$\Gamma_2 = E[x_n x_n^T] = \begin{bmatrix} \gamma_{xx}(0) & \gamma_{xx}(1) \\ \gamma_{xx}(1) & \gamma_{xx}(0) \end{bmatrix} \quad \gamma_{xx}(0) = 2\gamma_{ss}(0) + 2\gamma_{ss}(1) + \gamma_{ww}(0) = 2+1+1=4 \\ \gamma_{xx}(1) = \gamma_{ss}(0) + 2\gamma_{ss}(1) + \gamma_{ss}(2) = 1+1+\frac{1}{8}=2.125$$

$$\gamma_{xx}(1) = (S(n+1) + S(n) + \omega(n+1)) (S(n) + S(n-1) + \omega(n))$$

$$\gamma_{xx}(1) = \gamma_{ss}(1) + \gamma_{ss}(2) + 0 + \gamma_{ss}(0) + \gamma_{ss}(1) + 0 + \gamma_{ww}(1)$$

$$\gamma_{ww}(0) = \sigma_w^2 \delta(0)$$

$$h = \Gamma_2^{-1} \gamma_d = \begin{bmatrix} 4 & 2.125 \\ 2.125 & 4 \end{bmatrix}^{-1} \begin{bmatrix} 1 + \frac{2}{3} \\ 1 - \frac{2}{3} \end{bmatrix} = \begin{bmatrix} 0.272 \\ 0.272 \end{bmatrix}$$