

DSS Prototype Analysis

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Table of contents

1	DSS Prototype Overview	3
1.1	System Context	3
1.2	Container Architecture	3
1.2.1	Applications	3
1.2.2	Tools	5
1.3	Hypothesis	5
2	Load Data Files	6
2.1	Review and Tag MacBook Air (2017) Data	7
2.1.1	Add Source Indicator to MacBook Data	8
2.2	Tag Linux PC (2012) Data	8
2.3	Tag Raspberry Pi 4 (2020) Data	8
2.4	Tag AWS EC2 t2.micro Data	8
2.5	Tag ODU CCI Data	8
2.6	Merge Data Files	9
3	Convert Data into Useable Metrics	9
3.1	Add Additional Column Descriptors	11
3.2	Exploratory Analysis Plots	14
3.3	Remove Macbook Data from Development Platform	15
3.3.1	mclust	19
3.3.2	Mclust Univariate Analysis of Duration	20
3.3.3	Mclust Multivariate Analysis	25
4	Separating Internal from External Data	33
4.1	Internal Data	33
4.2	External Data	37
4.2.1	Data Transformations (Internal Data)	39
4.2.2	Box-Cox Transformation	42

4.3	Normality Testing of the Trasformation	45
4.3.1	Shapiro-Wilk	45
4.3.2	Hypothesis Testing	47
4.4	External Data	48
4.4.1	Q-Q Norm Plot of “Clean” External Span Data	48
4.4.2	Shapiro-Wilk Normality Test	51
4.4.3	Hypothesis Testing	51
5	Observations	52
5.1	General Discussion of Normality	52
5.2	Hypothesis Results	52
5.3	DSS Prototype Environment	53

1 DSS Prototype Overview

1.1 System Context

Figure 1 depicts the context for the DSS. The DSS operator interacts with the DSS Prototype for decision assistance. The DSS relies on a aircraft database to gather real-time flight data to review in decision support algorithms.

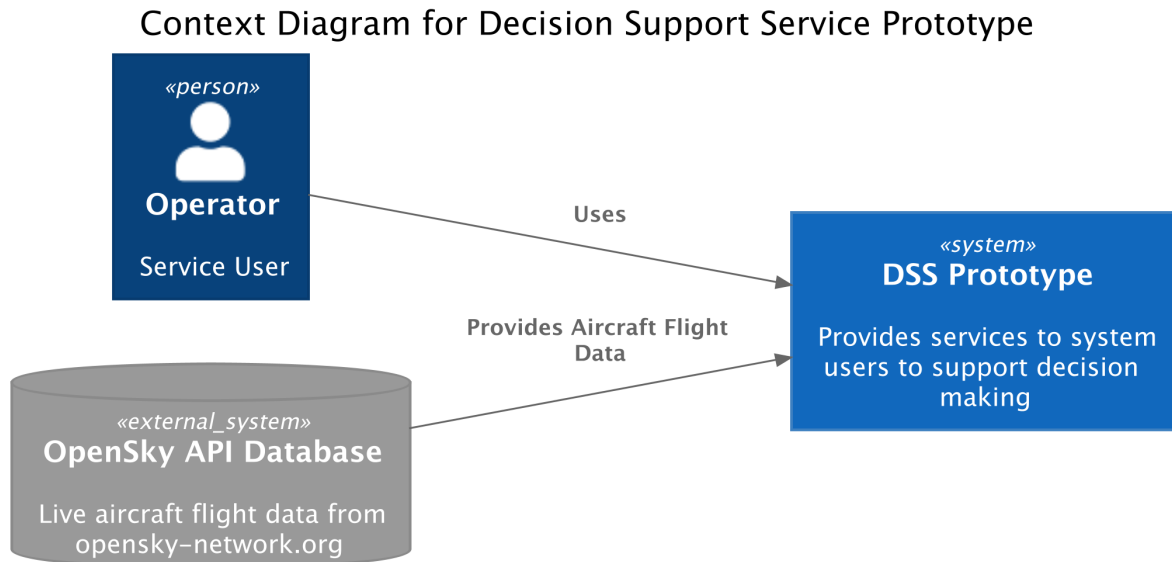


Figure 1: DSS Context Diagram

1.2 Container Architecture

Nine containers are instantiated as part of the DSS architecture (see Figure 2). Six provide the DSS implementation while the additional 3 support collection and calculation of metrics. Each application container was designed around the 12-Factor Application “Single Responsibility Principle”; e.g. each app has one purpose to enable rapid insertion of new capabilities with low cohesion to other functionality. At this time, all responses are canned without underlying calculations to focus on meeting the 500 ms hypothesis prior to burdening the application with calculation latency.

1.2.1 Applications

- **opensky-int**: Provides the OpenSky API for flight data. The app provides data about aircraft within 60 NM of Richmond (RIC) or Dulles (IAD) airports.

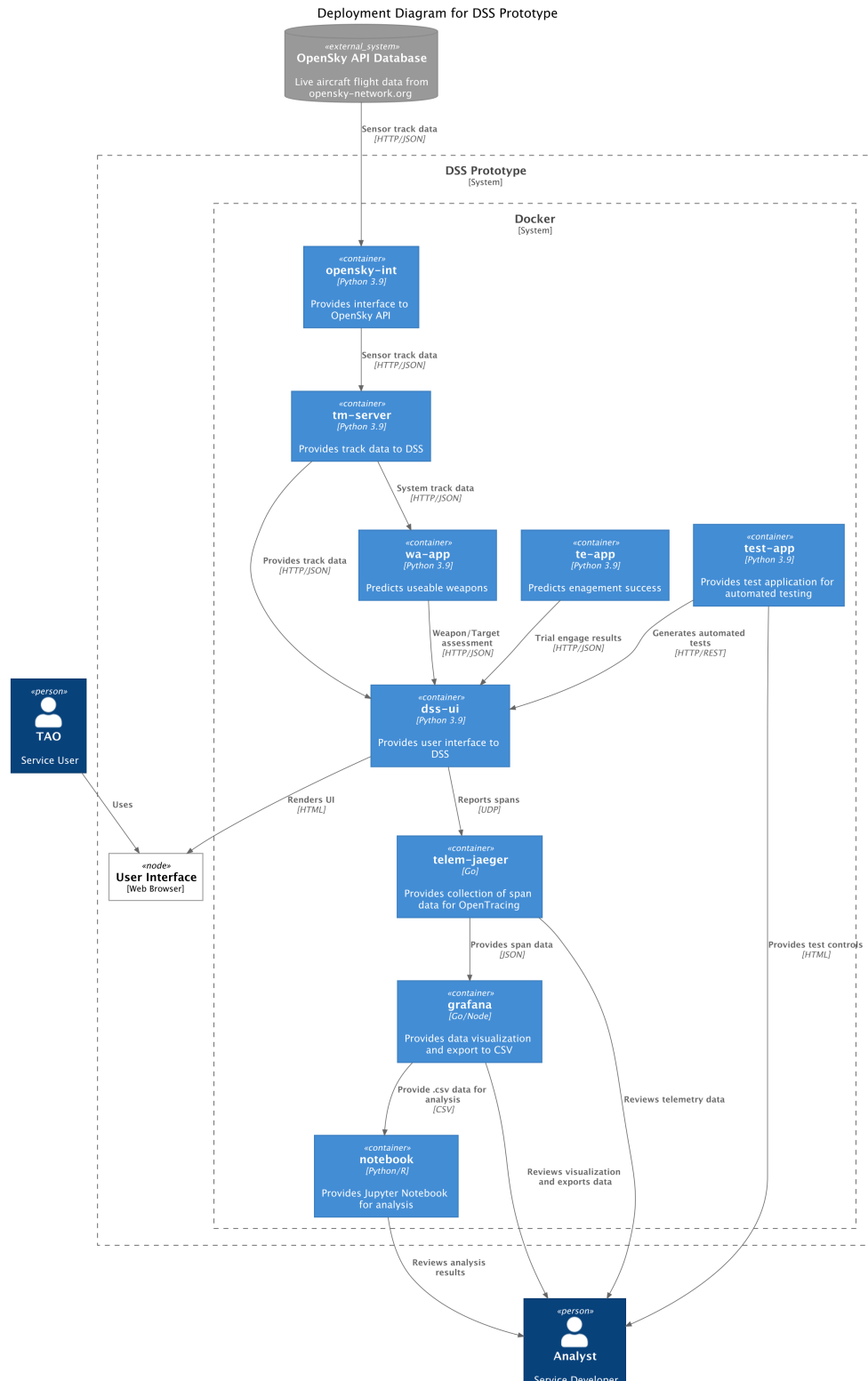


Figure 2: DSS Deployment Diagram

- tm-server: Provides sensor track data (e.g. OpenSky) and system tracks to support DSS services. System tracks represent the system-wide common understanding of track object states used for decision support.
- wa-app: The Weapon Assessment Application determines which weapons are capable to successfully engage a target. The wa-app uses the tm-server api to get track data.
- te-app: The Trail Engage Application predicts the success probability of an engagement with a specific weapon target pairing. The predicted track kinematic data at engagement time is provided; therefore, the current track kinematics from the tm-server are not queried prior to providing a response.
- test-app: Provides an ability to initiate automated tests. the test-app uses the dss-ui to call dss-ui endpoint to replicate operator interactions with the DSS Prototype.
- dss-ui: Provides a simple graphical interface to launch DSS services.

1.2.2 Tools

- telem-jaeger: The open source Jaeger container collects “span” data from the DSS applications. Spans collect duration data for service calls amongst containers; e.g. latency. This the fundamental data that is being analysed here.
- grafana: The open source Grafana container connects to the telem-jaeger container to create visualization dashboards. Also, Grafana facilitates the export of data as a .csv file for analysis.
- notebook: The Jupyter Notebook container supports analysis of the data recorded by Jaeger and exported by Grafana. An embedded R software library is used for analysis.

1.3 Hypothesis

Hypotheses are “innocent until proven guilty.” We’ll assume that SpaceX and others have proven that DevSecOps tech can meet hard-real-time requirements but nothing available in the body of knowledge documents this.

Hypothesis: Modern DevSecOps architectures can be designed to meet hard-real-time latency (μ) requirements using modern computing environments and computing infrastructure.

$H_0 : \mu \leq 500ms$ with jitter within latency bounds

$H_a : \mu > 500ms$ with jitter exceeding latency bounds

Murphy, Alvin C. and Moreland Jr, James D. ‘Integrating AI Microservices into Hard-Real-Time SoS to Ensure Trustworthiness of Digital Enterprise Using Mission Engineering’. 1 Jan. 2021 : 38 – 54.

```
install.packages("stringr")           # Install packages and libraries in R
library(stringr, quietly = TRUE)
```

```

# suppressPackageStartupMessages(library("stringr"))

install.packages("dplyr")
library(dplyr, quietly = TRUE)

install.packages("ggplot2")
install.packages("GGally")
library(ggplot2, quietly = TRUE)
library(GGally, quietly = TRUE)

# Note that loading MASS will cause issues with dplyr select
library("MASS")

install.packages("mclust")
library(mclust, quietly = TRUE)

if(!require(rcompanion)){install.packages("rcompanion")}
library(rcompanion, quietly = TRUE)

# install the package
if(!require(rcompanion)){install.packages("ggstatsplot")}

# Load the package
library(ggstatsplot, quietly = TRUE)

options(warn=-1)

setwd('/home/jovyan/work/data')

```

2 Load Data Files

```
macData <- read.csv('DSS_SpanData-mac-2022-05-02 18_38_26_s10-5-1.csv', header = TRUE)
linpcData <- read.csv('DSS_SpanData-linuxpc-2022-06-06 17_38_29_s10-5-1.csv', header = TRUE)
rpi4Data <- read.csv('DSS_SpanData-rpi4-2022-06-06 17_52_59_s10-5-1.csv', header = TRUE)
awsEC2Data <- read.csv('DSS_SpanData-aws_ec2-2022-06-07 17_44_08_s10-5-1.csv', header = TRUE)
cci_Data <- read.csv('DSS_SpanData-odu_cci-2022-06-28 17_47_20_s10-5-1.csv', header = TRUE)
```

2.1 Review and Tag MacBook Air (2017) Data

```
summary(macData)
```

```

      Trace.ID           Trace.name      Start.time      Duration
Length:100      Length:100      Length:100      Length:100
Class :character Class :character Class :character Class :character
Mode  :character Mode  :character Mode  :character Mode  :character

```

```
head(macData[, c(1,2)])
head(macData[, c(3,4)])
```

A data.frame: 6 × 2

	Trace.ID <chr>	Trace.name <chr>
1	9ee3577fb1b427bc4fc17fecc5154d7d	dss-prototype: /TE
2	f05ddc4dc13aff5c3098011b2a402401	dss-prototype: /tracks
3	2bd901fbbfc9ee8dfa7c9629d93a1567	dss-prototype: /IAD
4	69a48381a14e79da08aaa2353f7db4b2	dss-prototype: /RIC
5	e83037dcb9438c04dc12fba373b5502f	dss-prototype: /WA
6	7e381cd880adb670bb9627ca47020938	dss-prototype: /TE

A data.frame: 6 × 2

	Start.time <chr>	Duration <chr>
1	2022-05-02 10:25:01.366	36.0 ms
2	2022-05-02 10:25:00.309	43.3 ms
3	2022-05-02 10:24:58.818	464 ms
4	2022-05-02 10:24:57.307	494 ms
5	2022-05-02 10:24:56.128	139 ms
6	2022-05-02 10:24:55.081	30.3 ms

2.1.1 Add Source Indicator to MacBook Data

```
macDataPlat <- macData  
  
macDataPlat$platform = "2017-macbook"  
macDataPlat$env = 0
```

2.2 Tag Linux PC (2012) Data

```
linpcDataPlat <- linpcData  
  
linpcDataPlat$platform = "2012-linpc"  
linpcDataPlat$env = 1
```

2.3 Tag Raspberry Pi 4 (2020) Data

```
rpi4DataPlat <- linpcData  
  
rpi4DataPlat$platform = "2020-rpi4"  
rpi4DataPlat$env = 2
```

2.4 Tag AWS EC2 t2.micro Data

```
awsEC2DataPlat <- awsEC2Data  
  
awsEC2DataPlat$platform = "2022-aws-ec2"  
awsEC2DataPlat$env = 3
```

2.5 Tag ODU CCI Data

```
cciDataPlat <- cci_Data  
  
cciDataPlat$platform = "2022-odu-cci"  
cciDataPlat$env = 4
```


2.6 Merge Data Files

Here we merge data from all platforms except for the Macbook. Early plots showed that the **Mac** added latency within the Docker environment. In non-linux based platforms, a Docker desktop running a virtual machine is required to provide that Docker capability that is native to Linux platforms. *Consider removing Mac later after presentation of composite plots.* The Mac is considered to be the development environment and not representative of the integration and production environments.

<https://dev.to/ericnograles/why-is-docker-on-macos-so-much-worse-than-linux-flh>

<https://collabnix.com/how-docker-for-mac-works-under-the-hood/>

```
# spanData = rbind(macDataPlat)

# spanData = rbind(linpcDataPlat, rpi4DataPlat,
#                  awsEC2DataPlat, cciDataPlat)

spanData = rbind(macDataPlat, linpcDataPlat, rpi4DataPlat,
                  awsEC2DataPlat, cciDataPlat)

# Mclust components
# cci = 1
# mac = 9
# linpc = 1
# rpi4 = 1
# awsEC2 = 9

# summary(spanData)
# head(spanData[, c(1,2,3)])
# head(spanData[, c(4,5,6)])
# spanData
```

3 Convert Data into Useable Metrics

To make the data more usable and easier to understand we apply conversions from text to numeric and add additional columns with supporting information. A **useCase** column is added to identify specific DSS request use cases; e.g. Get Dulles Airport Data. The data also indicates whether the request is managed internally or a connection to an external service is required to provide a response (i.e., <https://opensky-network.org>). A **numContainers** column is added to indicate the number of containers involved in providing a use case response

(e.g. independent variable). An **ext** column is added to indicate whether an API external to the Docker environment is used; e.g., ext = TRUE for OpenSky API calls.

```
## Dictionary for converting data

DSSoperations <- c(
  "dss-prototype: /IAD" = "Get Dulles Airport Data (External)",
  "dss-prototype: /RIC" = "Get Richmond Airport Data (External)",
  "dss-prototype: /tracks" = "Get Stored Local DSS Tracks (Internal)",
  "dss-prototype: /TE" = "Trial Engage (Internal)",
  "dss-prototype: /WA" = "Assess Weapons (Internal)"
)

DSSuseCaseNum <- c(
  "dss-prototype: /IAD" = 4,
  "dss-prototype: /RIC" = 5,
  "dss-prototype: /tracks" = 1,
  "dss-prototype: /TE" = 2,
  "dss-prototype: /WA" = 3
)

DSSexternal <- c(
  "dss-prototype: /IAD" = TRUE,
  "dss-prototype: /RIC" = TRUE,
  "dss-prototype: /tracks" = FALSE,
  "dss-prototype: /TE" = FALSE,
  "dss-prototype: /WA" = FALSE
)

DSStraceShortName <- c(
  "dss-prototype: /IAD" = "/IAD",
  "dss-prototype: /RIC" = "/RIC",
  "dss-prototype: /tracks" = "/tracks",
  "dss-prototype: /TE" = "/TE",
  "dss-prototype: /WA" = "/WA"
)
```

3.1 Add Additional Column Descriptors

```
spanMetrics <- spanData

spanMetrics$useCase <- DSSoperations[spanMetrics$Trace.name]
spanMetrics$useCaseNum <- DSSuseCaseNum[spanMetrics$Trace.name]

spanMetrics$ext = DSSexternal[spanMetrics$Trace.name]
spanMetrics$Trace.name = DSStraceShortName[spanMetrics$Trace.name]

# truncate span ID
# spanMetrics$Trace.ID <- str_sub(spanMetrics$Trace.ID,1,4)

# summary(spanMetrics)
# head(spanMetrics)
# tail(spanMetrics)

# spanMetrics

# Convert character data into numeric metrics

for(index in 1:nrow(spanMetrics)) {      # for-loop over rows

  # Convert span duration

  char = spanMetrics[index,4]
  len = str_length(char)
  duration = str_sub(char,1,(len-3))
  units = str_sub(char,(len-1),len)
  duration = as.numeric(duration)

  # print(duration)
  # print(units)

  if(units == 'ms') {
    duration = duration                      # Keep ms
  } else if (units == 'µs') {
    duration = duration * 0.001             # Convert µs to ms
  } else if (units == 's') {
```

```

        duration = duration * 1000          # Convert s to ms
    } else {
        print ('Unable to find specified units')
        print (units)
    }
    spanMetrics[index,4] = duration

    # Convert time

    # time = spanMetrics[index,3]
    # epoch <- as.POSIXct(time)
    # epoch_int <- as.integer(epoch)
    # spanMetrics[index,3] = epoch_int
}

# spanMetrics

# Convert columns from char to numeric

spanMetrics$Duration = as.numeric(spanMetrics$Duration)
# spanMetrics$Start.time = as.numeric(spanMetrics$Start.time)

# spanMetrics

summary(spanMetrics)

# sort span metrics by use case number
spanMetricsA <- arrange(spanMetrics, useCaseNum)

head(spanMetricsA[, c(2,3,4,5)])
head(spanMetricsA[, c(6,7,8,9)])

# spanMetricsA

```

Trace.ID	Trace.name	Start.time	Duration
Length:500	Length:500	Length:500	Min. : 4.29
Class :character	Class :character	Class :character	1st Qu.: 7.42
Mode :character	Mode :character	Mode :character	Median : 21.65
			Mean : 198.15
			3rd Qu.: 381.00
			Max. : 2000.00

platform	env	useCase	useCaseNum	ext
Length:500	Min. :0	Length:500	Min. :1	Mode :logical
Class :character	1st Qu.:1	Class :character	1st Qu.:2	FALSE:300
Mode :character	Median :2	Mode :character	Median :3	TRUE :200
	Mean :2		Mean :3	
	3rd Qu.:3		3rd Qu.:4	
	Max. :4		Max. :5	

A data.frame: 6 × 4

	Trace.name <chr>	Start.time <chr>	Duration <dbl>	platform <chr>
1	/tracks	2022-05-02 10:25:00.309	43.3	2017-macbook
2	/tracks	2022-05-02 10:24:54.040	30.0	2017-macbook
3	/tracks	2022-05-02 10:24:47.706	126.0	2017-macbook
4	/tracks	2022-05-02 10:24:41.527	20.5	2017-macbook
5	/tracks	2022-05-02 10:24:34.903	27.6	2017-macbook
6	/tracks	2022-05-02 10:24:28.865	15.5	2017-macbook

A data.frame: 6 × 4

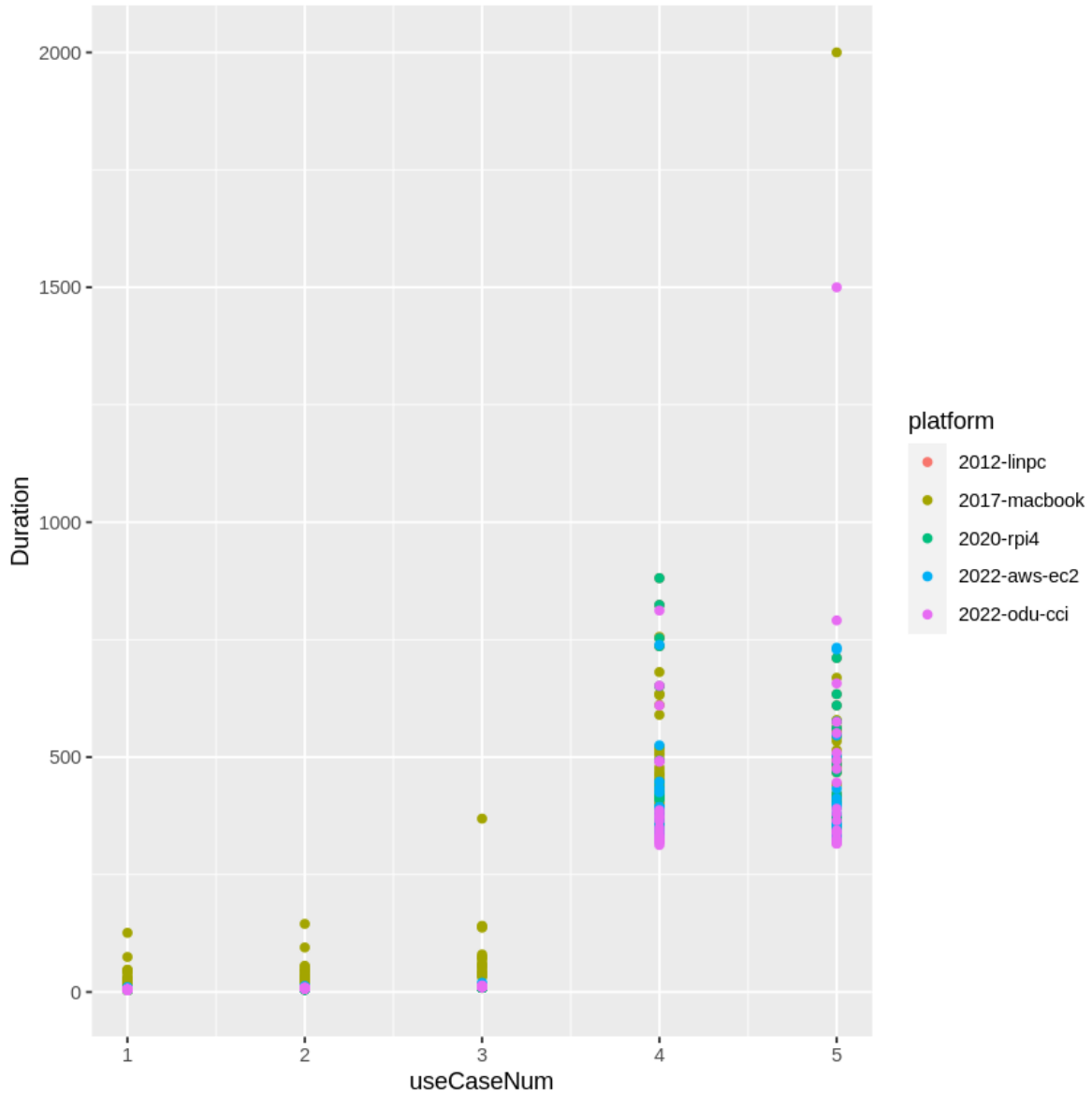
	env <dbl>	useCase <chr>	useCaseNum <dbl>	ext <lgl>
1	0	Get Stored Local DSS Tracks (Internal)	1	FALSE
2	0	Get Stored Local DSS Tracks (Internal)	1	FALSE
3	0	Get Stored Local DSS Tracks (Internal)	1	FALSE

	env <dbl>	useCase <chr>	useCaseNum <dbl>	ext <lgl>
4	0	Get Stored Local DSS Tracks (Internal)	1	FALSE
5	0	Get Stored Local DSS Tracks (Internal)	1	FALSE
6	0	Get Stored Local DSS Tracks (Internal)	1	FALSE

3.2 Exploratory Analysis Plots

```
# spanMetricsNum <- spanMetricsA %>%
#   dplyr::select(useCaseNum, env, ext, Duration)
#   # dplyr::select(Duration, useCaseNum, env)

qplot(useCaseNum, Duration, data = spanMetricsA, colour = platform)
```



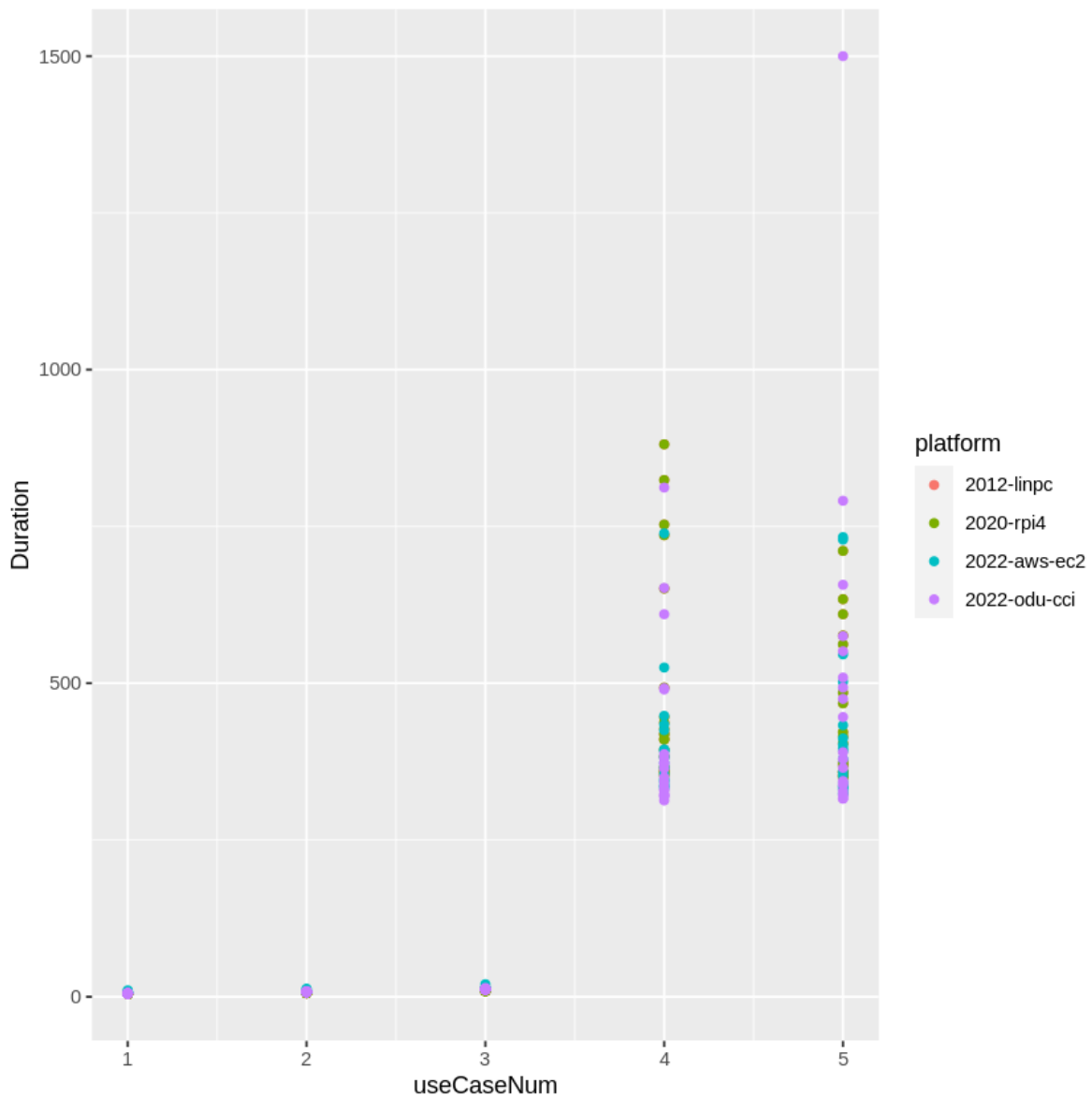
3.3 Remove Macbook Data from Development Platform

Here we remove the data from the Macbook development platform. The qplot shows that the **Mac** added latency within the Docker environment. In non-linux based plaforms, a Docker desktop running a virtual machine is required to provided that Docker capability that is native to Linux platforms. *Consider removing Mac later after presentation of composite plots.* The Mac is considered to be the development environment and not representative of the integration and production environments.

<https://dev.to/ericnograles/why-is-docker-on-macos-so-much-worse-than-linux-flh>
<https://collabnix.com/how-docker-for-mac-works-under-the-hood/>

```
noMacSpan <- spanMetricsA[!spanMetricsA$env == 0,]
```

```
qplot(useCaseNum, Duration, data = noMacSpan, colour = platform)
```




```
# par(mfrow=c(2,1))
# hist(spanMetricsA$Duration, counts = 5)

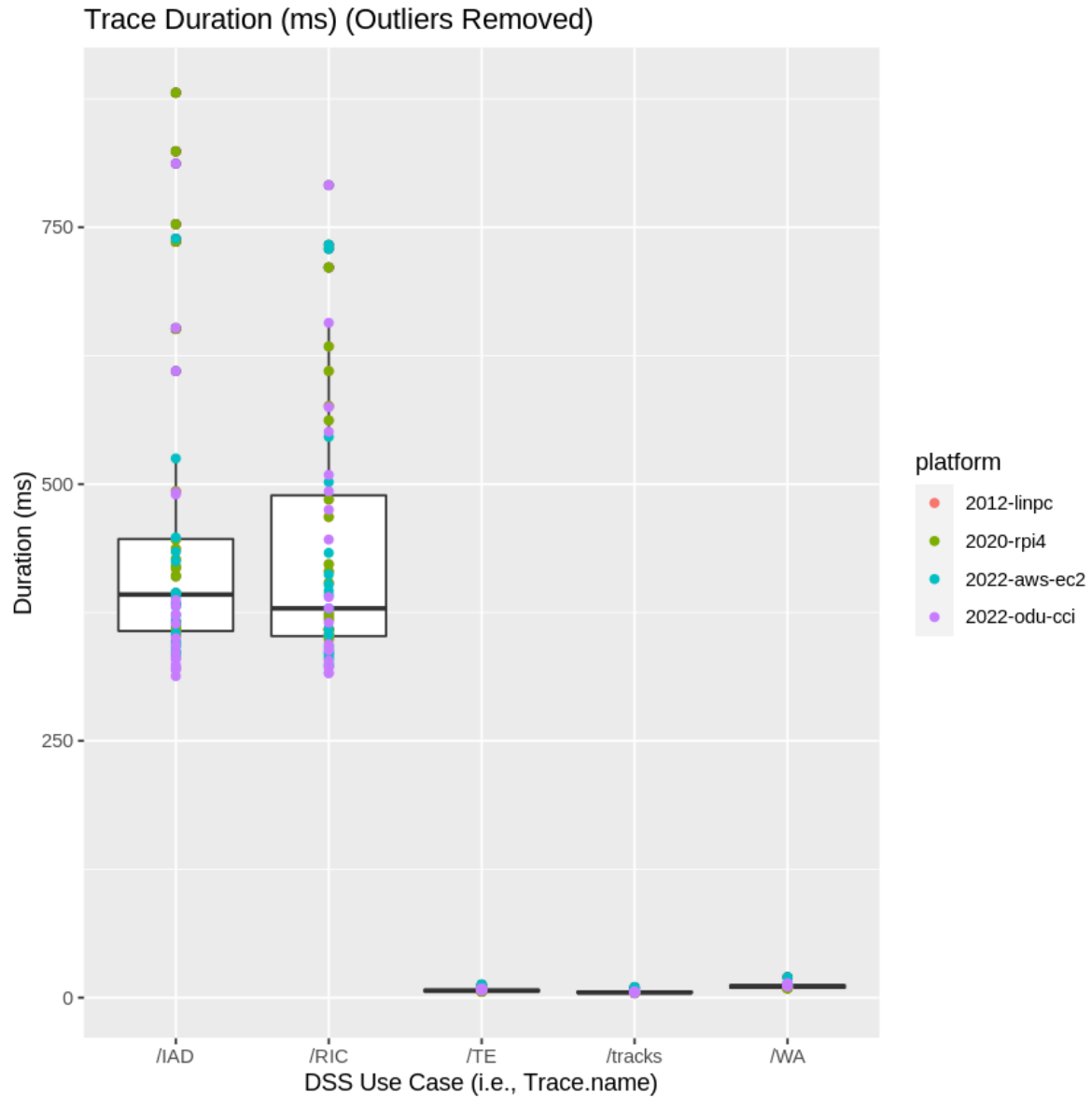
# spanMetricsA %>%
#   ggplot(aes(Trace.name, Duration)) +
#   stat_boxplot(notch="FALSE") + geom_point() +
#   ggtitle("Duration of Endpoint Responses from Trace")
# # notch went outside hinges. Try setting notch=FALSE.
```

```
# Remove outliers
aSpan <- noMacSpan
outliers <- boxplot(aSpan$Duration, plot = FALSE)$out
outliers

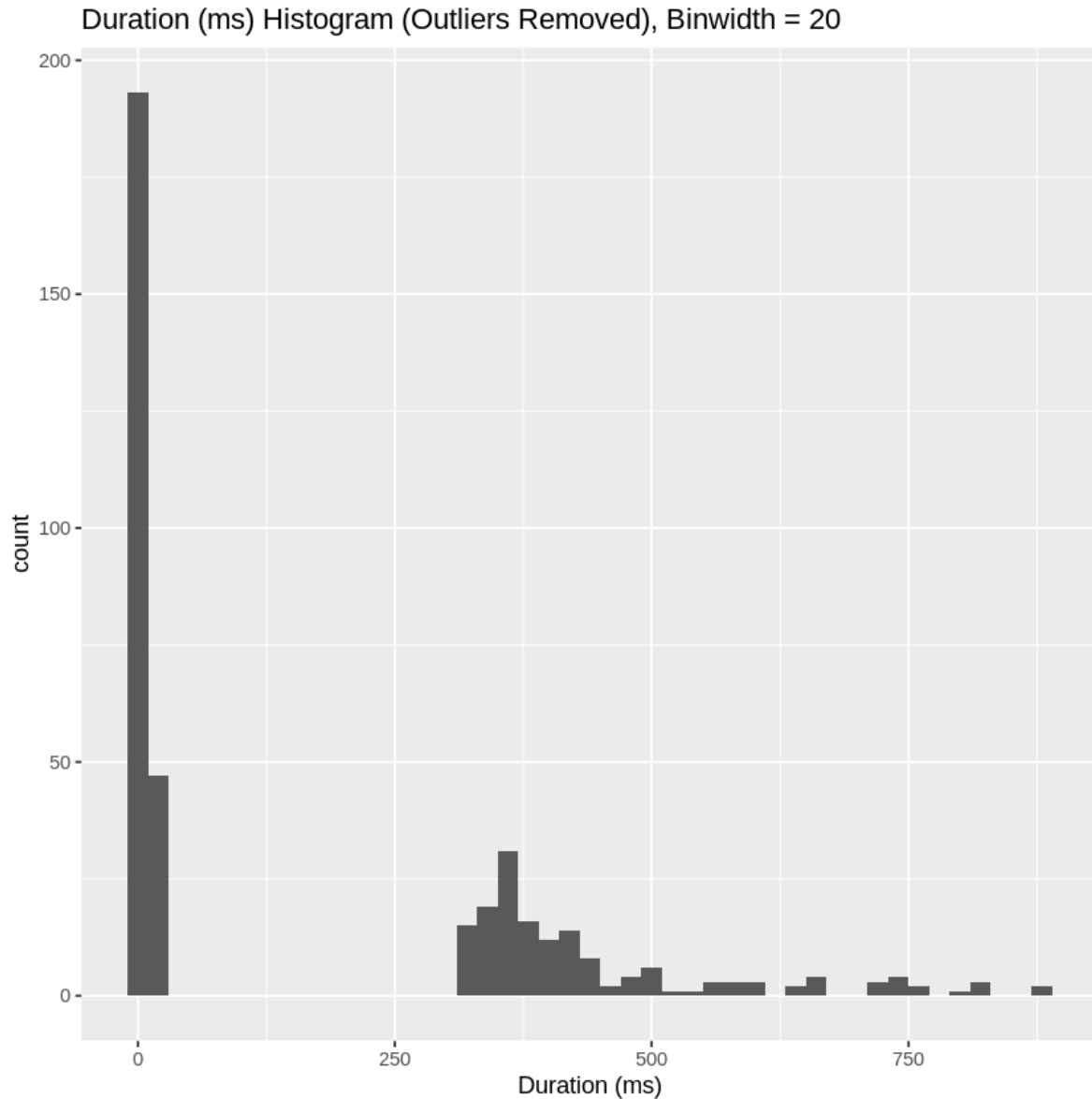
aSpan <- aSpan[-which(aSpan$Duration %in% outliers),]
```

1500

```
aSpan %>%
  ggplot(aes(Trace.name, Duration)) +
  stat_boxplot(notch="FALSE") + geom_point(aes(colour = platform)) +
  ggtitle("Trace Duration (ms) (Outliers Removed)") +
  ylab("Duration (ms)") +
  xlab("DSS Use Case (i.e., Trace.name)")
# notch went outside hinges. Try setting notch=FALSE.
```



```
aSpan %>%
  ggplot(aes(Duration)) + geom_histogram(binwidth = 20) +
  ggtitle("Duration (ms) Histogram (Outliers Removed), Binwidth = 20") +
  xlab("Duration (ms)")
```



```
# ggpairs(spanMetricsNum, title="correlogram with ggpairs()")
```

3.3.1 mclust

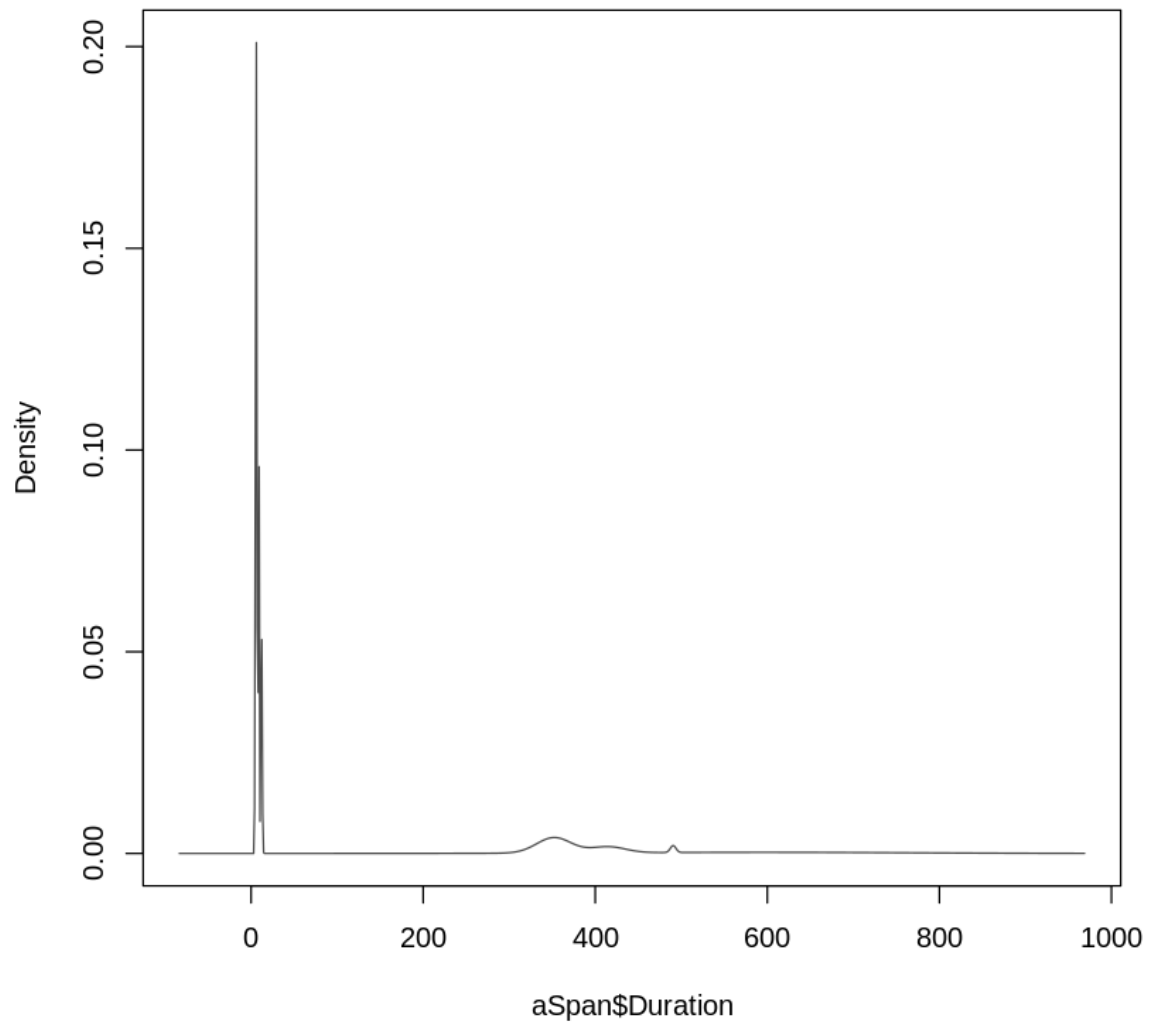
Used mclust to verify the separation of internal and external models as indicated from the useCaseNum vs. Duration plot; i.e. use cases 4 and 5 use an external API.

The library `mclust` is a contributed R package for model-based clustering, classification, and density estimation based on finite normal mixture modelling. It provides functions for parameter estimation via the EM algorithm for normal mixture models with a variety of covariance structures, and functions for simulation from these models.

Scrucca L., Fop M., Murphy T. B. and Raftery A. E. (2016) mclust 5: clustering, classification and density estimation using Gaussian finite mixture models The R Journal 8/1, pp. 289-317

3.3.2 Mclust Univariate Analysis of Duration

```
mod4 <- densityMclust(aSpan$Duration)
```



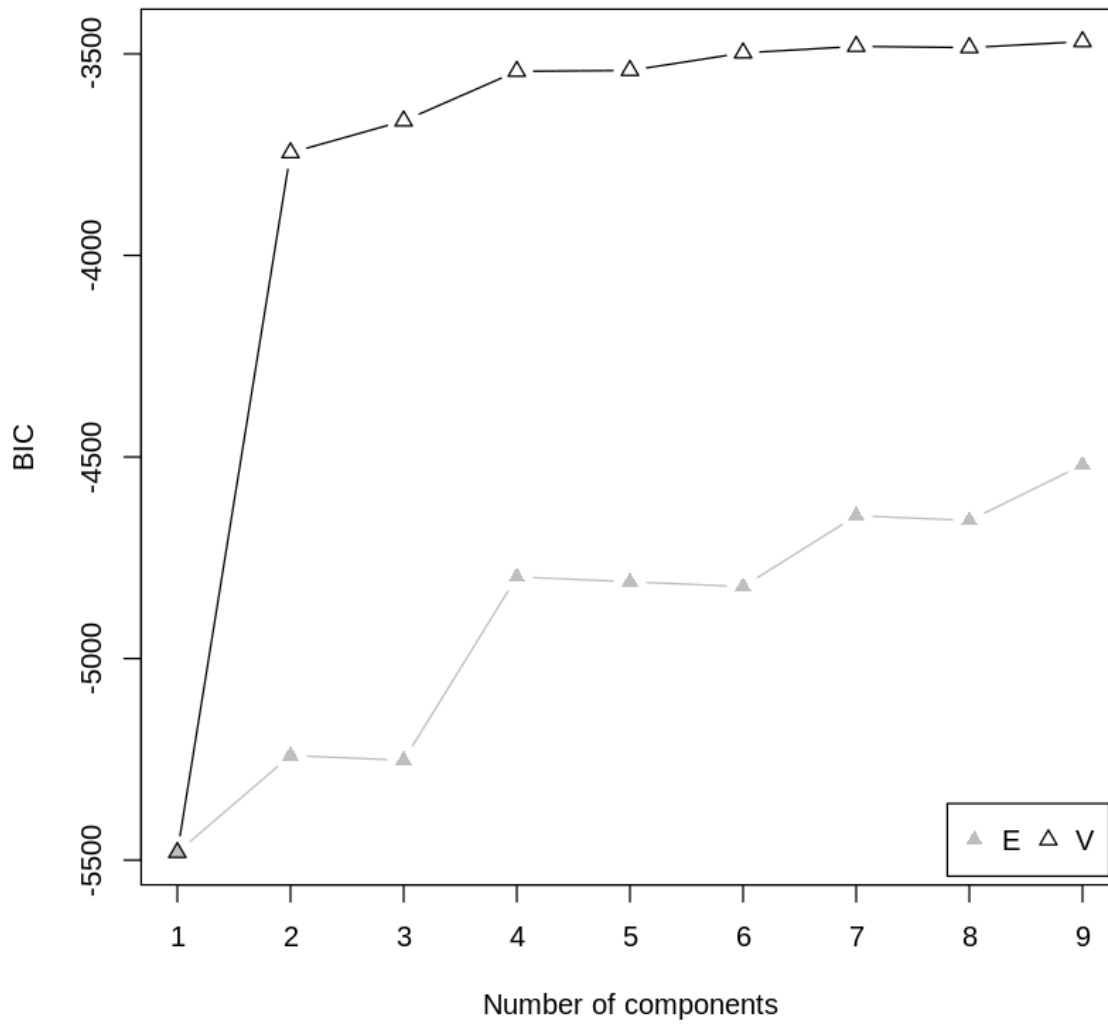
```
summary(mod4)
```

Density estimation via Gaussian finite mixture modeling

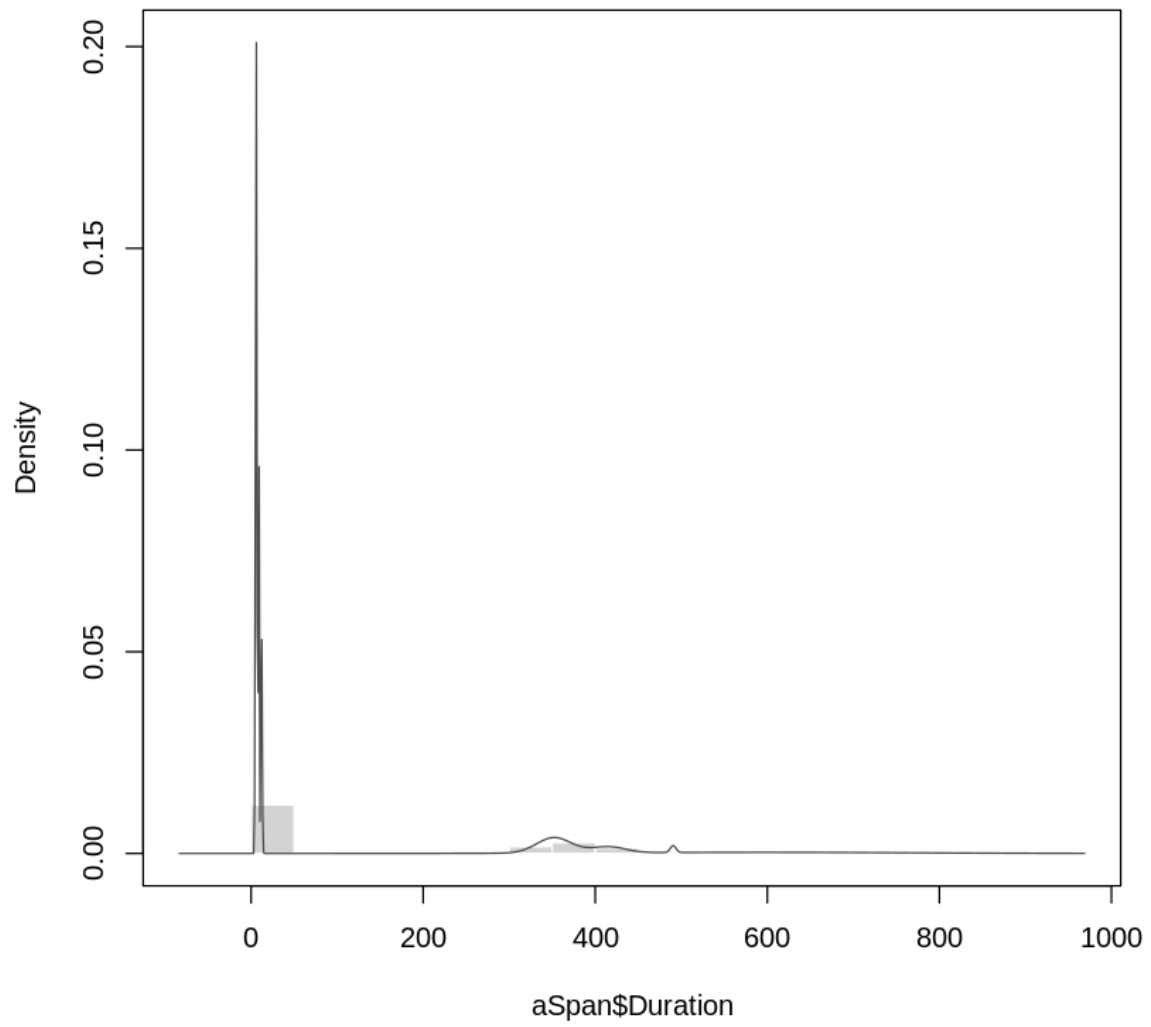
Mclust V (univariate, unequal variance) model with 9 components:

```
log-likelihood  n df      BIC      ICL
-1656.953 399 26 -3469.619 -3511.198
```

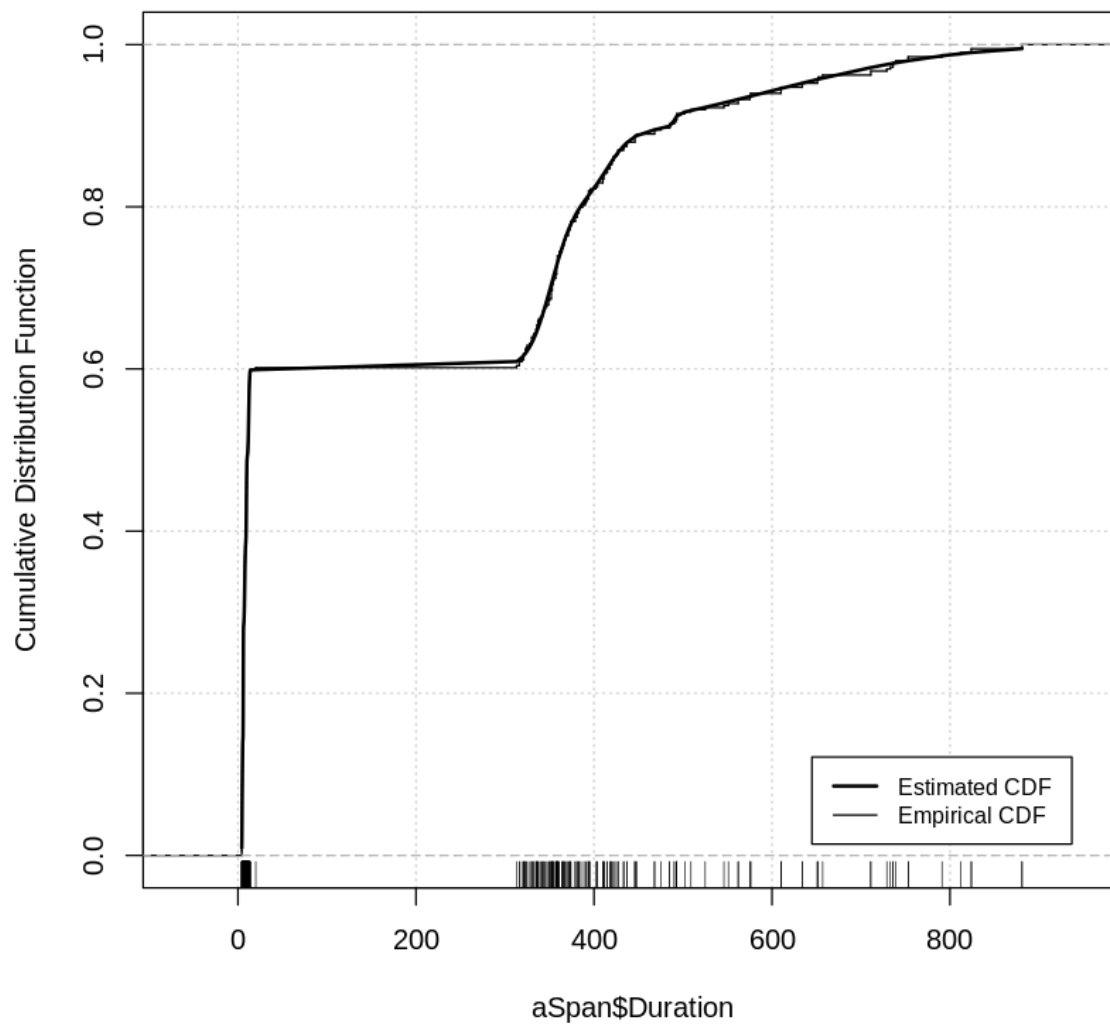
```
plot(mod4, what = "BIC")
```



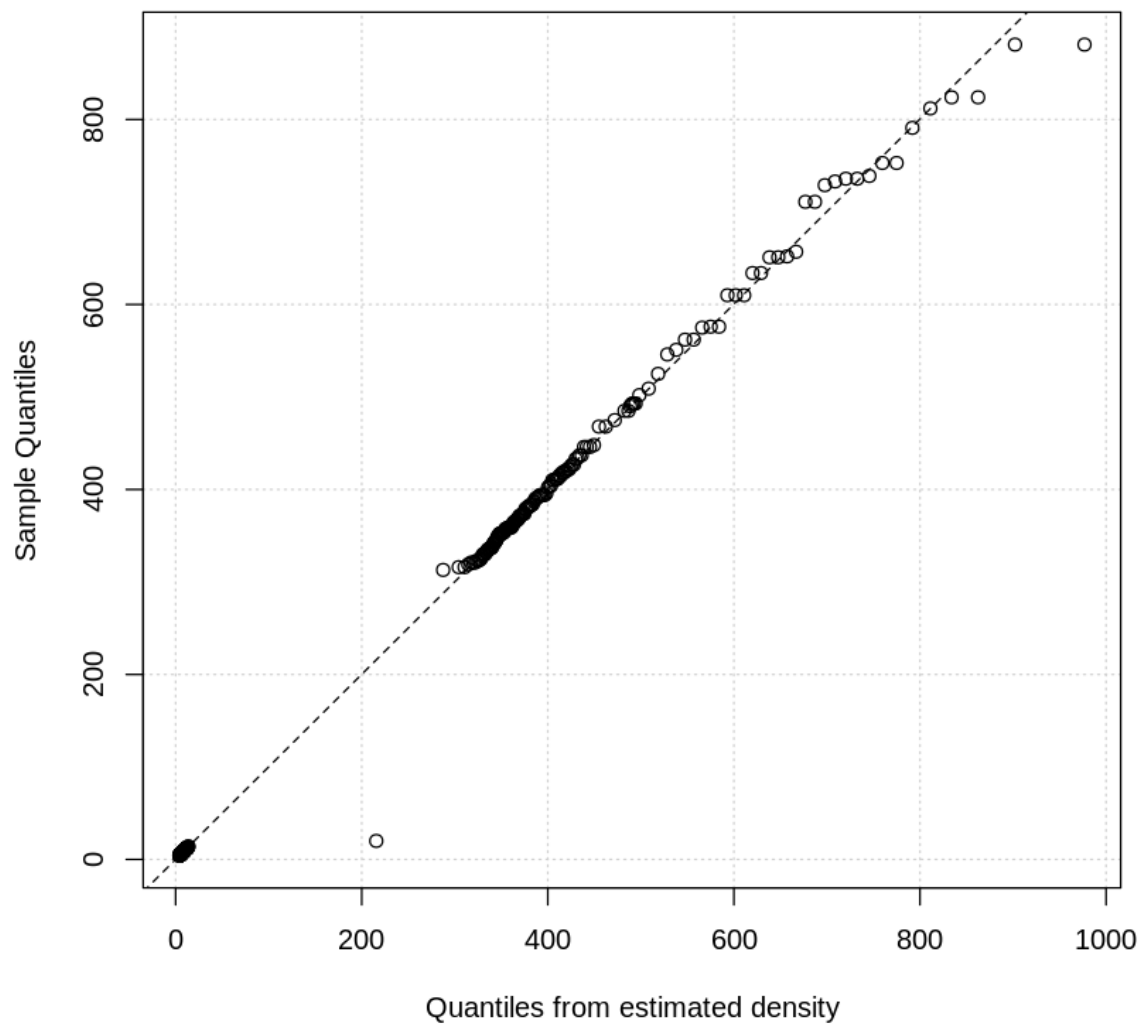
```
plot(mod4, what = "density", data = aSpan$Duration, breaks = 20)
```



```
plot(mod4, what = "diagnostic", type = "cdf")
```



```
plot(mod4, what = "diagnostic", type = "qq")
```

3.3.3 Mclust Multivariate Analysis

```
uc <- aSpan$useCaseNum # Trace.name is char, used uc num conversion

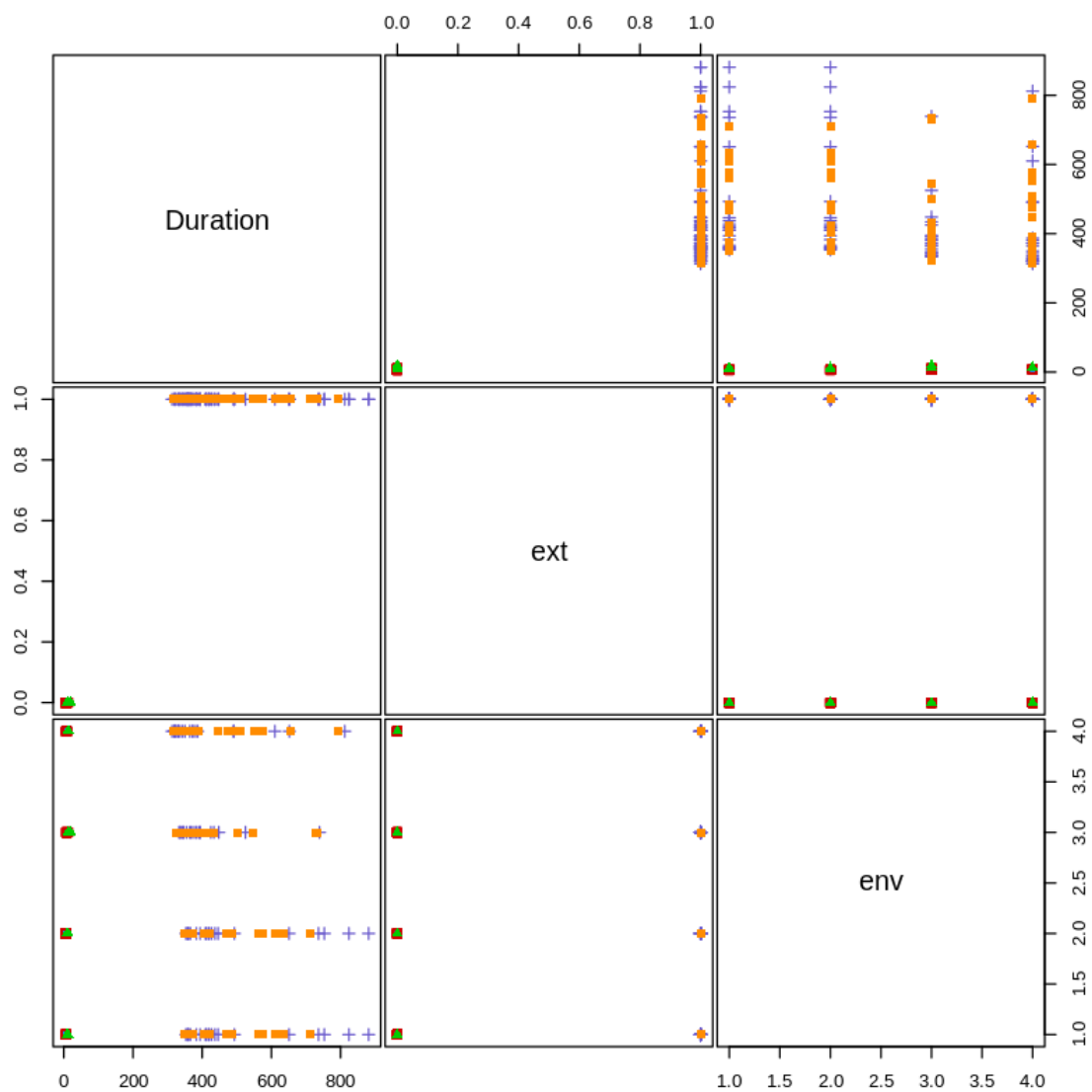
X <- aSpan %>%
  # dplyr::select(useCaseNum, env, ext, Duration)
  dplyr::select(Duration, ext, env)
```

```
# dplyr::select(Duration)

head(X)
clPairs(X, uc)
```

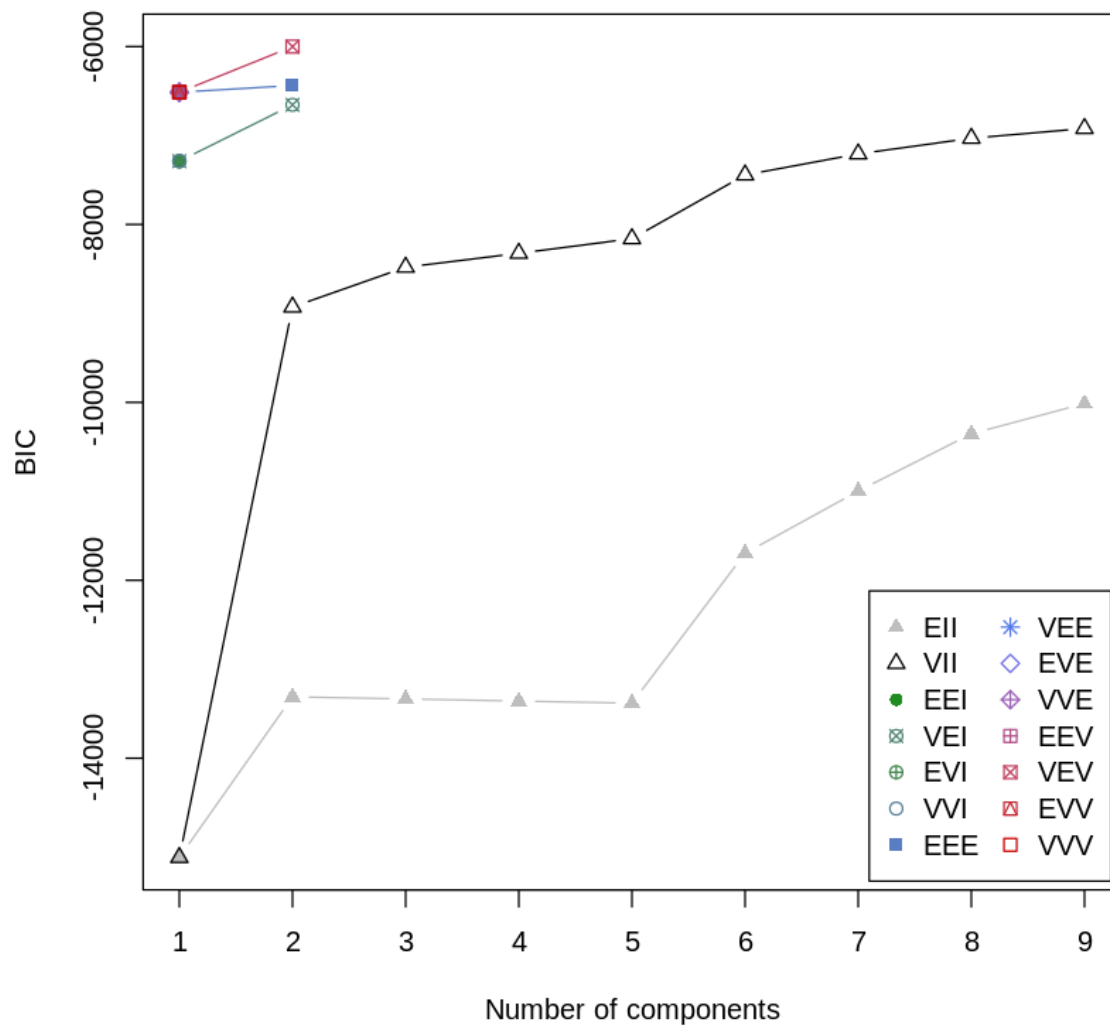
A data.frame: 6 × 3

	Duration <dbl>	ext <lgl>	env <dbl>
21	4.90	FALSE	1
22	4.43	FALSE	1
23	4.67	FALSE	1
24	4.68	FALSE	1
25	4.73	FALSE	1
26	4.89	FALSE	1



```
# spanMclust <- Mclust(aSpan)
# spanMclust <- Mclust(X)
# summary(spanMclust)
# plot(spanMclust, what = c("classification"))
```

```
BIC <- mclustBIC(X)
plot(BIC)
```



`summary(BIC)`

Best BIC values:

	VEV,2	EEE,2	EEE,1
BIC	-6000.192	-6437.9228	-6512.9492
BIC diff	0.000	-437.7311	-512.7575

Note that 2 is included within the list of best Bayesian Information Criterion (BIC) values.

```
# mod1 <- Mclust(X, x = BIC)
# summary(mod1, parameters = TRUE)

# plot(mod1, what = "classification")

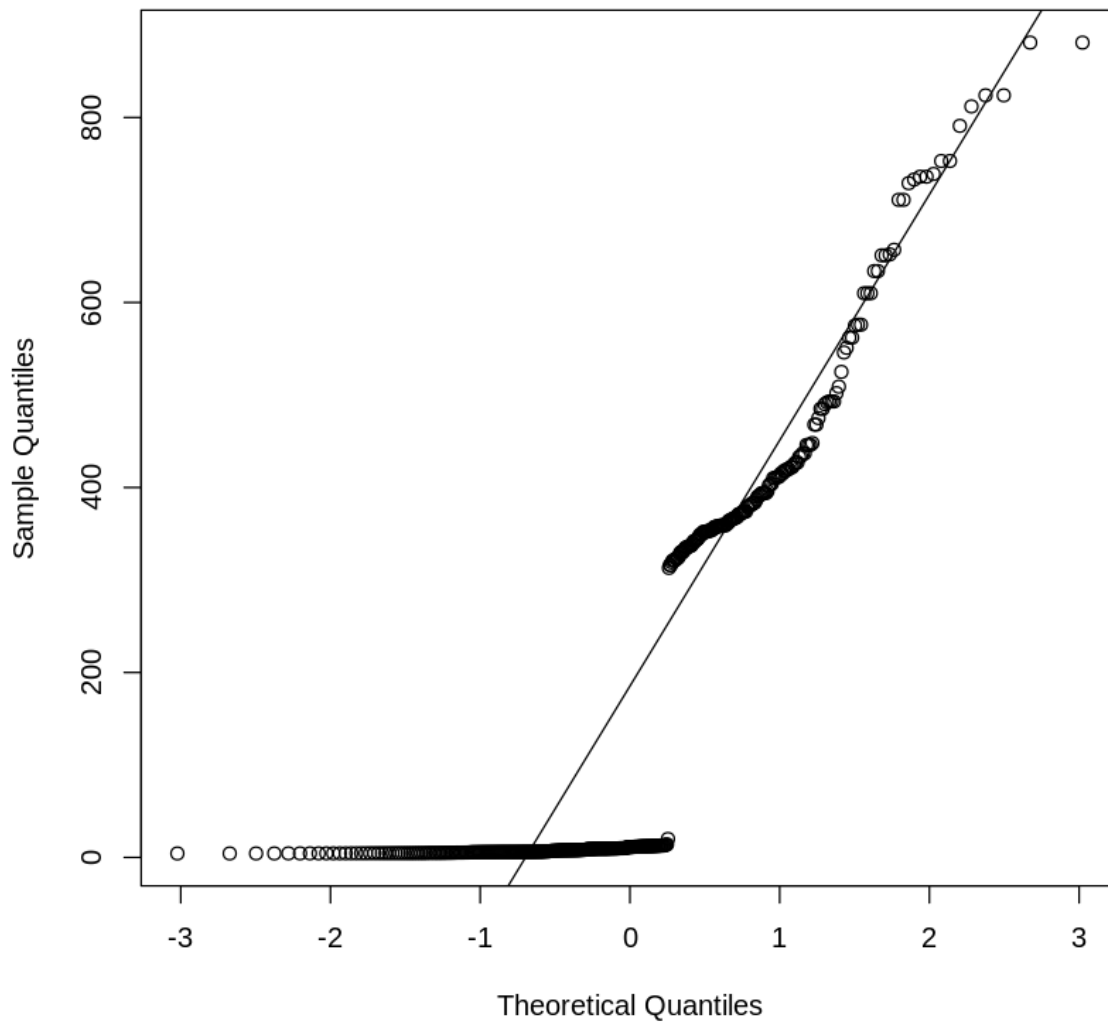
# plot(mod1, what = "uncertainty")

# ICL <- mclustICL(X)
# summary(ICL)
# plot(ICL)

# LRT <- mclustBootstrapLRT(X, modelName = "VEV")
# LRT

qqnorm(aSpan$Duration, main="Span Duration Q-Q Norm Plot")
qqline(aSpan$Duration)
```

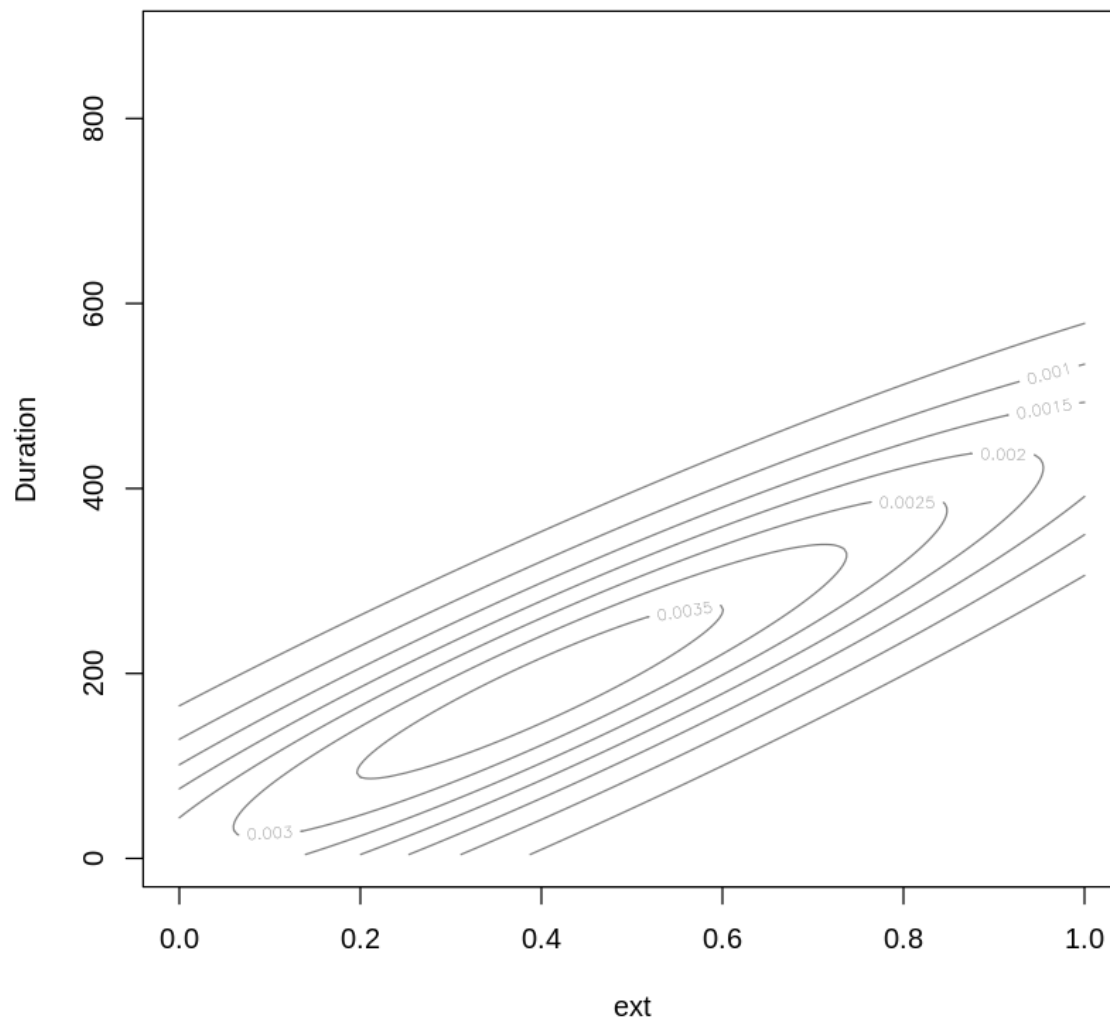
Span Duration Q-Q Norm Plot



```
# head(aSpan)
```

```
aSpan_Density <- aSpan %>%  
  # dplyr::select(useCaseNum, env, ext, Duration)  
  dplyr::select(ext, Duration)  
  # dplyr::select(Duration)
```

```
mod5 <- densityMclust(aSpan_Density)
```



```
# aSpan <- spanMetricsNum
```

```
# sqrt_aSpan <- aSpan
```

```
# sqrt_aSpan$Duration=sqrt(sqrt_aSpan$Duration)
```

```

# log_aSpan <- aSpan
# # log_aSpan$Duration=log(log_aSpan$Duration + 1)
# log_aSpan$Duration=log(log_aSpan$Duration)
# cube_aSpan <- aSpan
# cube_aSpan$Duration=cube_aSpan$Duration^(1/3)

# par(mfrow=c(2,2))
# hist(aSpan$Duration, counts = 5)
# hist(sqrt_aSpan$Duration)
# hist(log_aSpan$Duration)
# hist(cube_aSpan$Duration)

# par(mfrow=c(2,2))
# qqnorm(aSpan$Duration, main="Span Duration Q-Q Norm Plot")
# qqline(aSpan$Duration)

# qqnorm(sqrt_aSpan$Duration, main="Sqrt Span Duration Q-Q Norm Plot")
# qqline(sqrt_aSpan$Duration)

# qqnorm(log_aSpan$Duration, main="Log Span Duration Q-Q Norm Plot")
# qqline(log_aSpan$Duration)

# qqnorm(cube_aSpan$Duration, main="Cube Span Duration Q-Q Norm Plot")
# qqline(cube_aSpan$Duration)

# # y = response (duration/latency)
# # x = use case number

# # #find optimal lambda for Box-Cox transformation
# # bc <- boxcox(y ~ x)
# # (lambda <- bc$x[which.max(bc$y)])

# # #fit new linear regression model using the Box-Cox transformation
# # new_model <- lm(((y^lambda-1)/lambda) ~ x)

# # bcData = aSpan
# # y <- bcData$Duration
# # x <- bcData$useCaseNum

# # bc <- boxcox(y ~ x)

```



```

# # (lambda <- bc$x[which.max(bc$y)])
# # new_model <- lm(((y^lambda-1)/lambda) ~ x)

# # https://r-coder.com/box-cox-transformation-r/

# # boxcox(lm(aSpan$Duration ~ 1))

# x <- aSpan$Duration

# b <- boxcox(lm(x ~ 1))

# # Exact lambda
# lambda <- b$x[which.max(b$y)]

# # Transformation
# new_x_bc <- (x ^ lambda - 1) / lambda

# par(mfrow=c(2,2))
# hist(aSpan$Duration)
# hist(new_x_bc)

# qqnorm(aSpan$Duration)
# qqline(aSpan$Duration)

# qqnorm(new_x_bc)
# qqline(new_x_bc)

# shapiro.test(new_x_bc)

```

4 Separating Internal from External Data

4.1 Internal Data

```

# Separate Internal Data
# Could use ext == FALSE

tracksSpanData = subset(aSpan, useCaseNum == 1)
TE_SpanData = subset(aSpan, useCaseNum == 2)

```

```

WA_SpanData = subset(aSpan, useCaseNum == 3)

internalSpanData <- rbind(tracksSpanData, TE_SpanData, WA_SpanData)
dssSpanData <- rbind(TE_SpanData, WA_SpanData)

# tracksSpanData
# TE_SpanData
# WA_SpanData
# internalSpanData
# dssSpanData

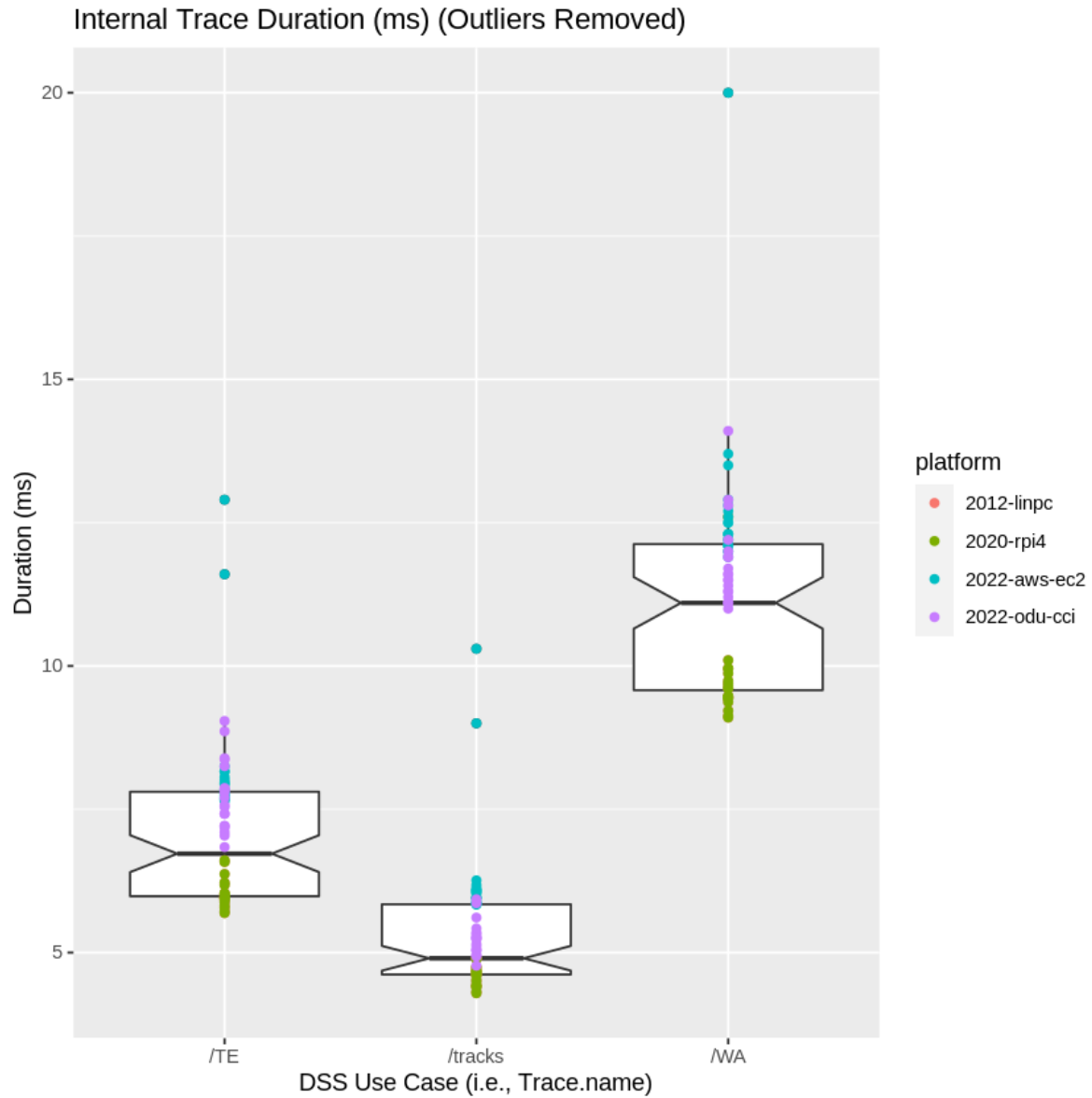
# Remove Outliers
# outliers <- boxplot(internalSpanData$Duration, plot = FALSE)$out
# outliers
# iSpan <- iSpan[-which(iSpan$Duration %in% outliers),]

outliers <- which(internalSpanData$Duration > 50) #outlier rows
outliers
# iSpan <- internalSpanData[!outliers,]
iSpan <- internalSpanData[!internalSpanData$Duration > 50,]
  # Remove if duration is greater than a value

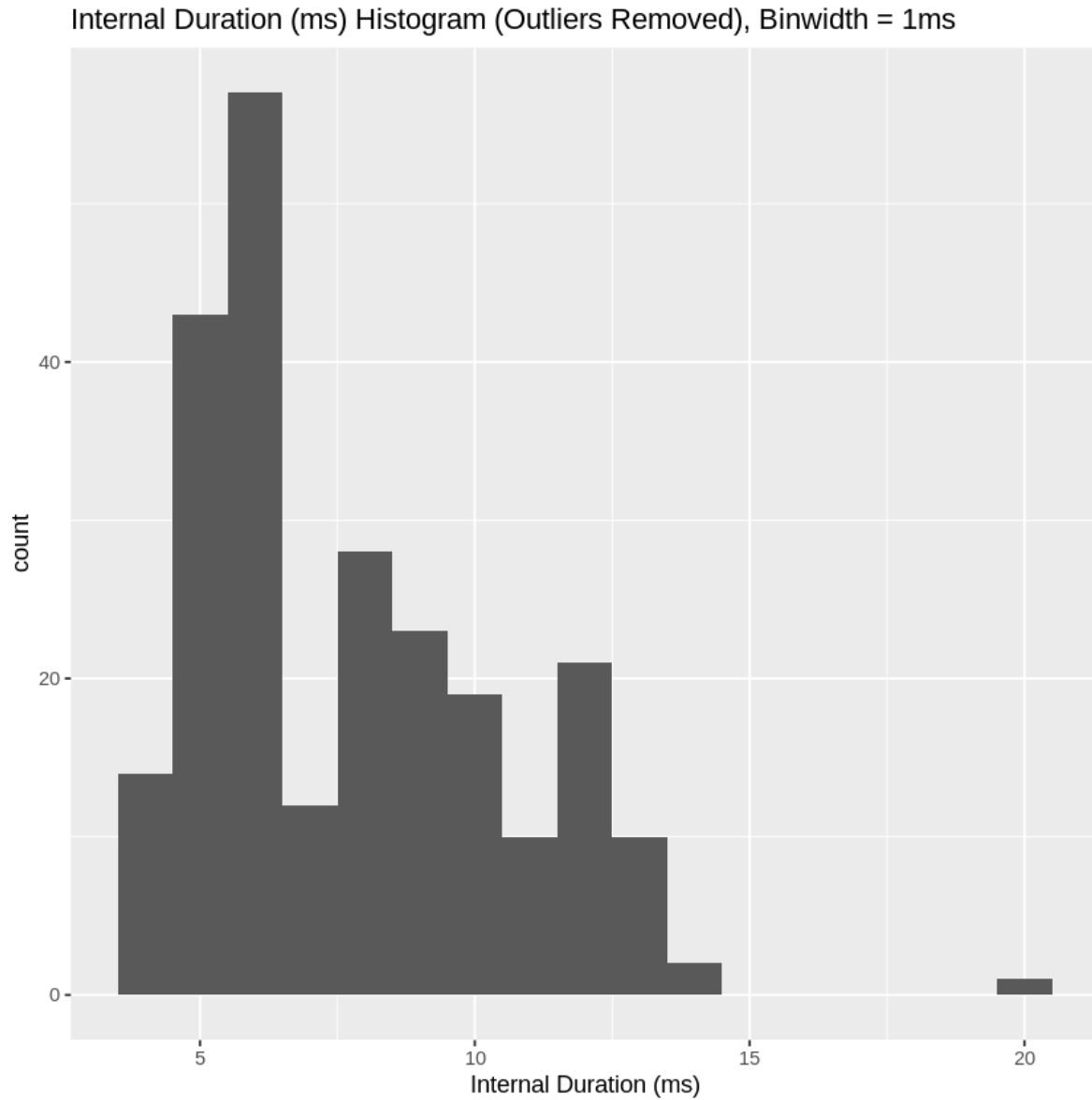
# iSpan

iSpan %>%
  ggplot(aes(Trace.name, Duration)) +
  stat_boxplot(notch="TRUE") + geom_point(aes(colour = platform)) +
  ggtitle("Internal Trace Duration (ms) (Outliers Removed)") +
  ylab("Duration (ms)") +
  xlab("DSS Use Case (i.e., Trace.name)")

```



```
iSpan %>%
  ggplot(aes(Duration)) + geom_histogram(binwidth = 1) +
  ggtitle("Internal Duration (ms) Histogram (Outliers Removed), Binwidth = 1ms") +
  xlab("Internal Duration (ms)")
```



Note that the plot is not normalized and will need a transformation to enable application of statistics.

4.2 External Data

```
RIC_SpanData = subset(aSpan, useCaseNum == 5)
IAD_SpanData = subset(aSpan, useCaseNum == 4)

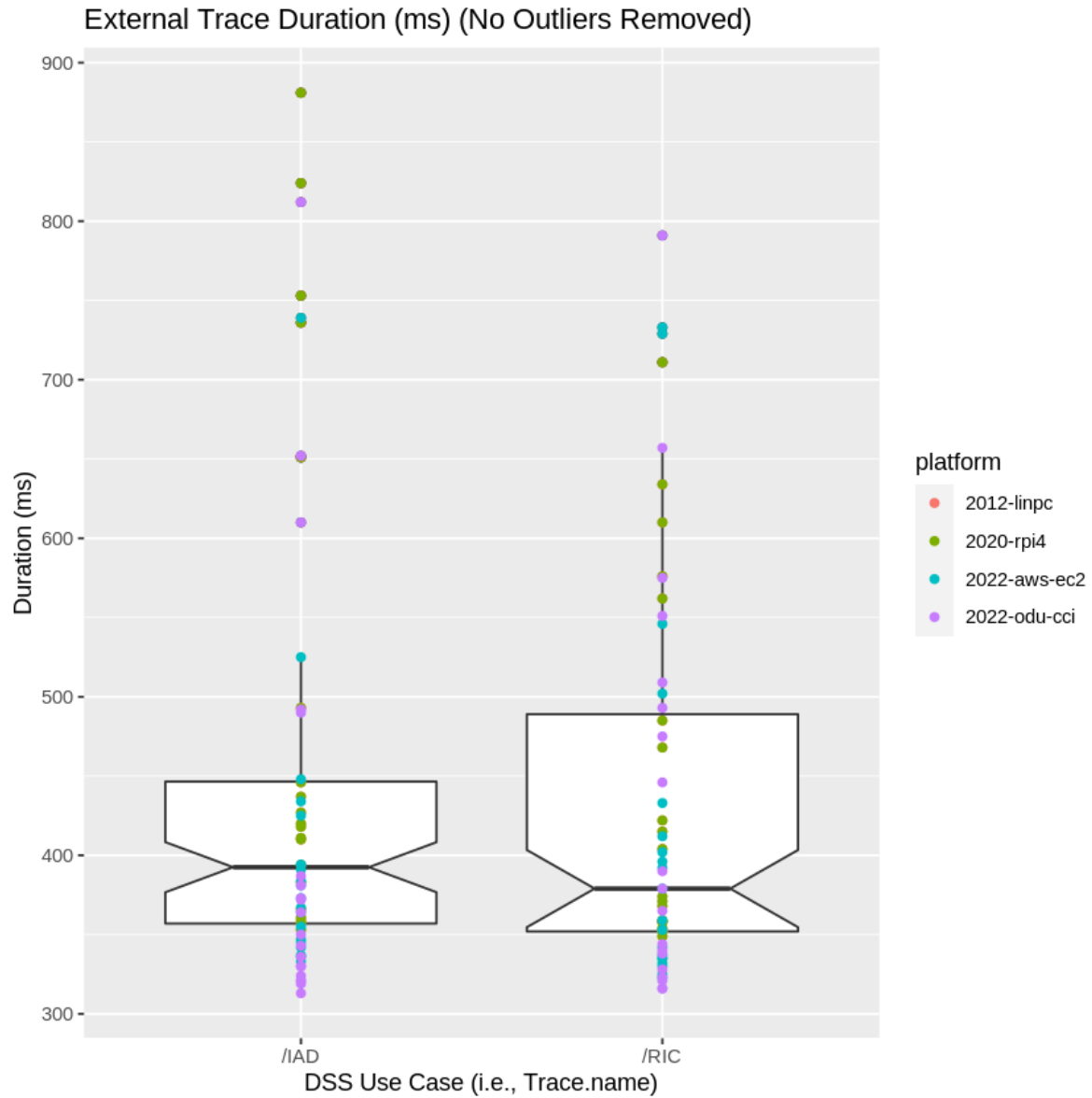
# RIC_SpanData = subset(spanMetricsA, Trace.name == "/RIC")
# IAD_SpanData = subset(spanMetricsA, Trace.name == "/IAD")

externalSpanData <- rbind(RIC_SpanData, IAD_SpanData)

# Remove outliers
# outliers <- boxplot(externalSpanData$Duration, plot = FALSE)$out
# outliers

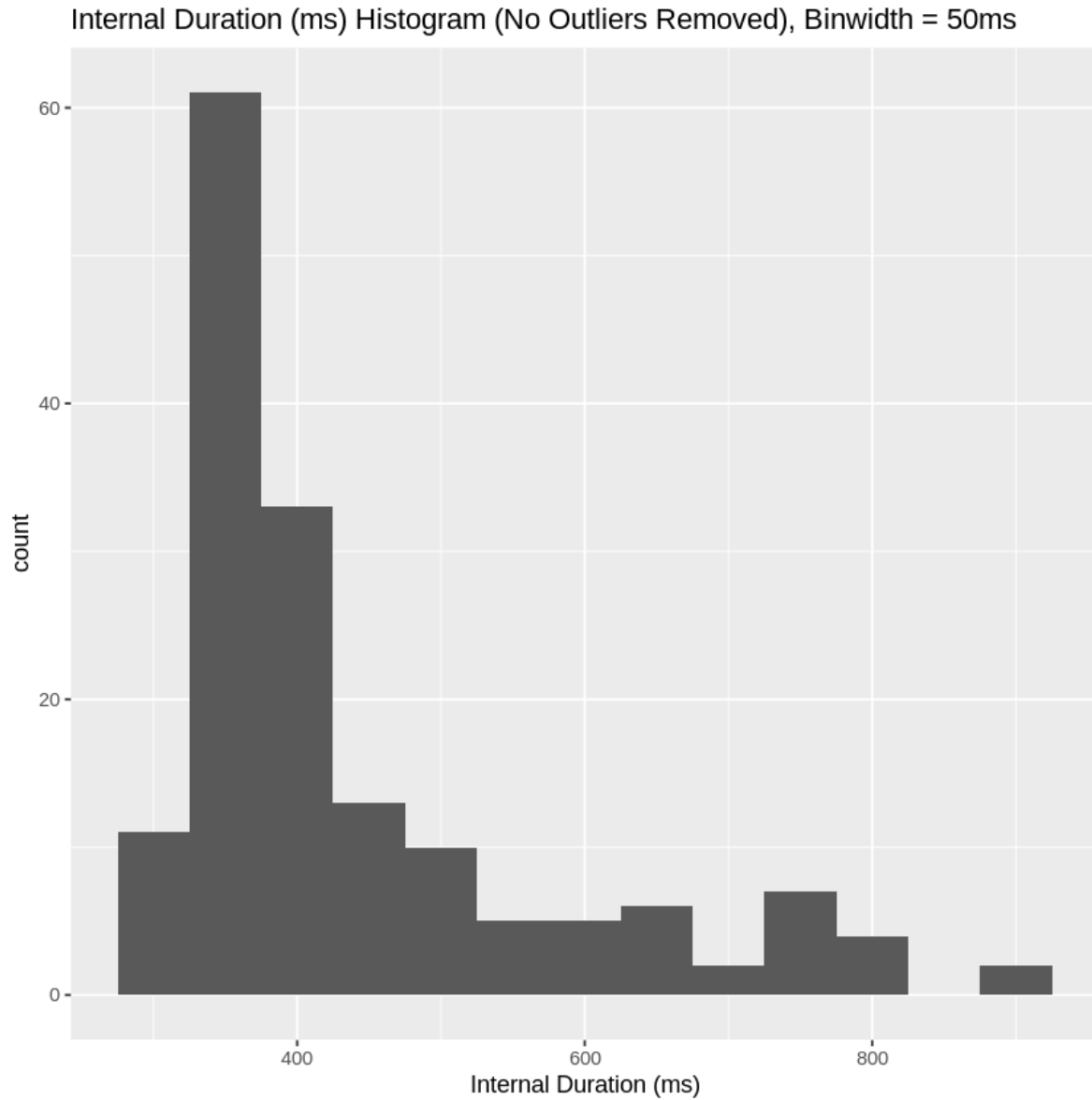
eSpan <- externalSpanData
# eSpan <- eSpan[-which(eSpan$Duration %in% outliers),]

eSpan %>%
  ggplot(aes(Trace.name, Duration)) +
  stat_boxplot(notch="TRUE") + geom_point(aes(colour = platform)) +
  ggtitle("External Trace Duration (ms) (No Outliers Removed)") +
  ylab("Duration (ms)") +
  xlab("DSS Use Case (i.e., Trace.name)")
```



eSpan %>%

```
ggplot(aes(Duration)) + geom_histogram(binwidth = 50) +
ggtitle("Internal Duration (ms) Histogram (No Outliers Removed), Binwidth = 50ms") +
xlab("Internal Duration (ms)")
```



Note that the plot is not normalized and will need a transformation to enable application of statistics.

4.2.1 Data Transformations (Internal Data)

4.2.1.1 Sqrt-Log-Cube Transformations

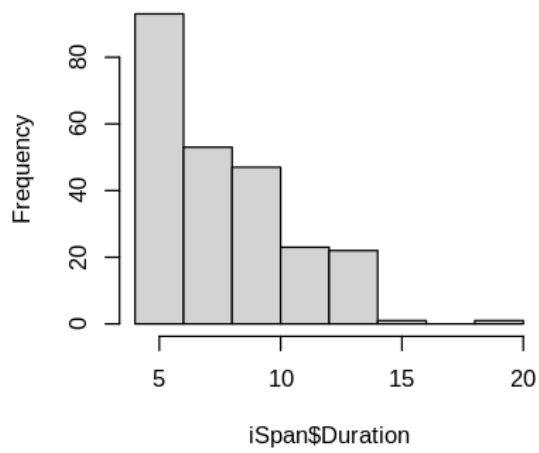
```

sqrt_iSpan <- iSpan
sqrt_iSpan$Duration=sqrt(sqrt_iSpan$Duration)
log_iSpan <- iSpan
log_iSpan$Duration=log(log_iSpan$Duration + 1)
cube_iSpan <- iSpan
cube_iSpan$Duration=cube_iSpan$Duration^(1/3)
# bc_iSpan <- iSpan
# bc_iSpan$Duration=1/sqrt(bc_iSpan$Duration)

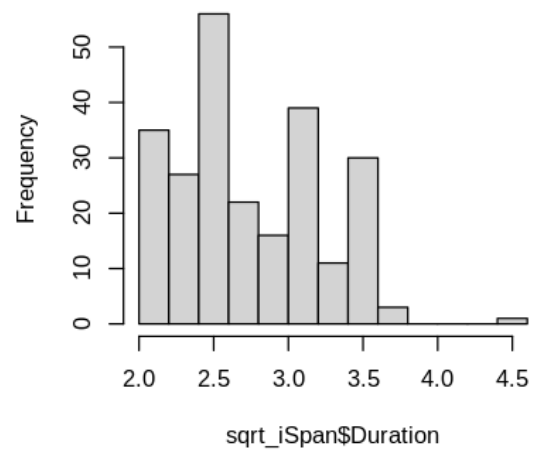
par(mfrow=c(2,2))
hist(iSpan$Duration, counts = 10)
hist(sqrt_iSpan$Duration)
hist(log_iSpan$Duration)
hist(cube_iSpan$Duration)
# hist(bc_iSpan$Duration)

```

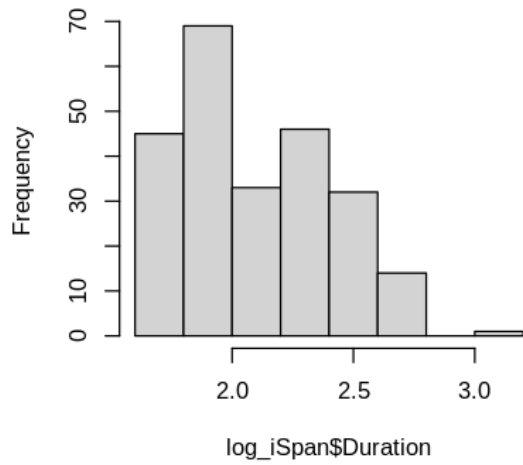

Histogram of iSpan\$Duration



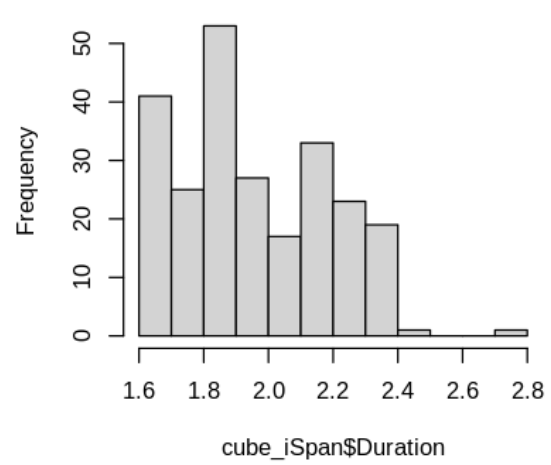
Histogram of sqrt_iSpan\$Duration

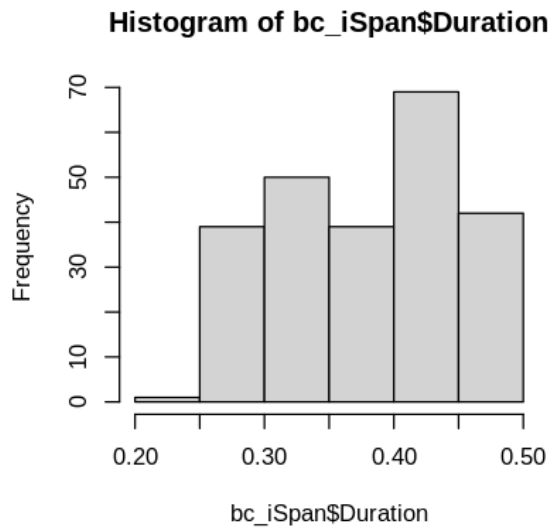


Histogram of log_iSpan\$Duration



Histogram of cube_iSpan\$Duration





4.2.2 Box-Cox Transformation

Box and Cox (1964) developed a family of transformations designed to reduce nonnormality of the errors in a linear model. Applying this transform often reduces non-linearity as well, and heteroscedascity.

The idea is to transform the response variable Y to a replacement response variable $Y_i^{(\lambda)}$, leaving the right-hand side of the regression model unchanged, so that the regression residuals

become normally-distributed. Note that the regression coefficients will also change, because the response variable has changed; therefore, the regression coefficients must be interpreted with respect to the transformed variable. Also, any predictions made with the model have to be back-transformed, to be interpreted in the original units.

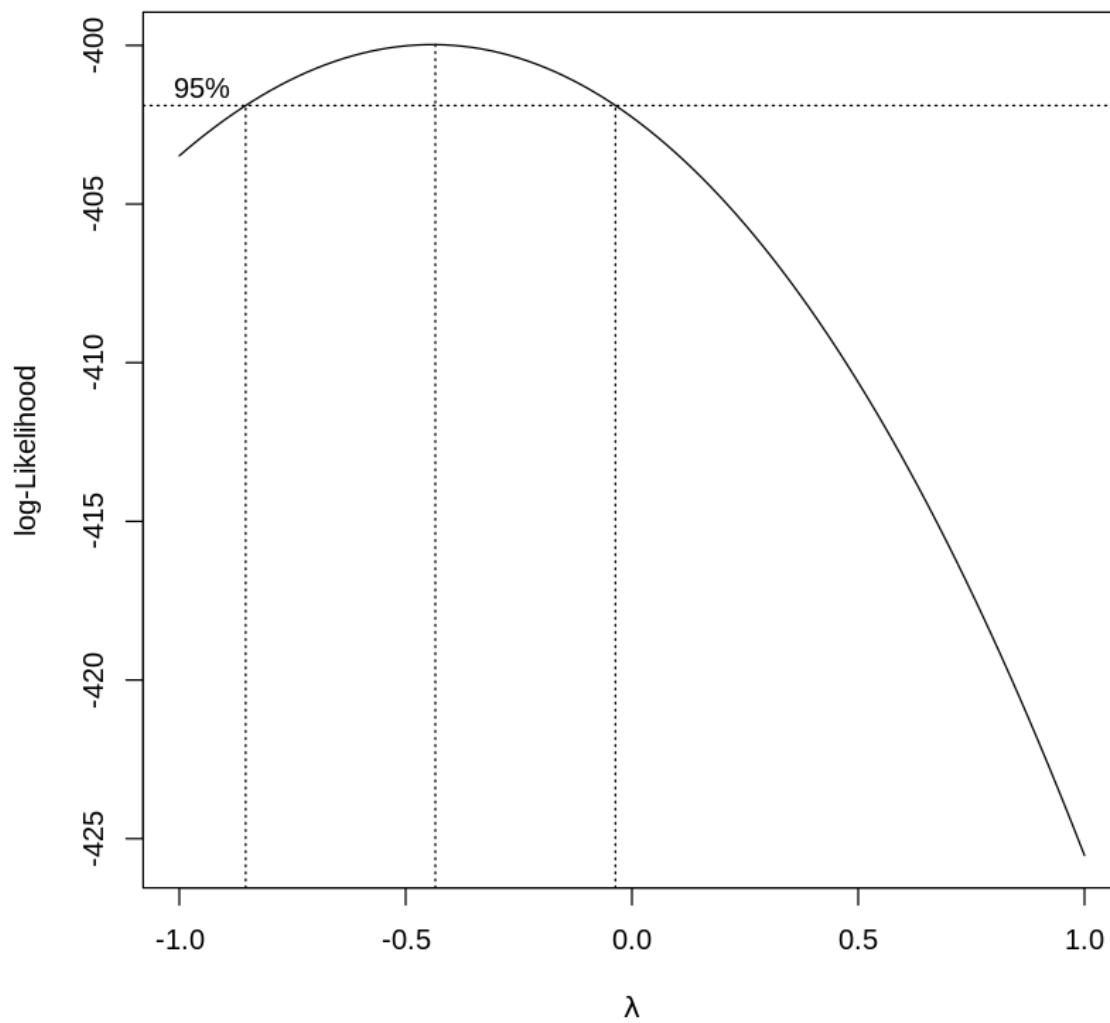
The standard (simple) Box-Cox transform is:

$$Y_i^{(\lambda)} = \begin{cases} \frac{Y_i^\lambda - 1}{\lambda}, & (\lambda \neq 0) \\ \log(Y_i), & (\lambda = 0) \end{cases}$$

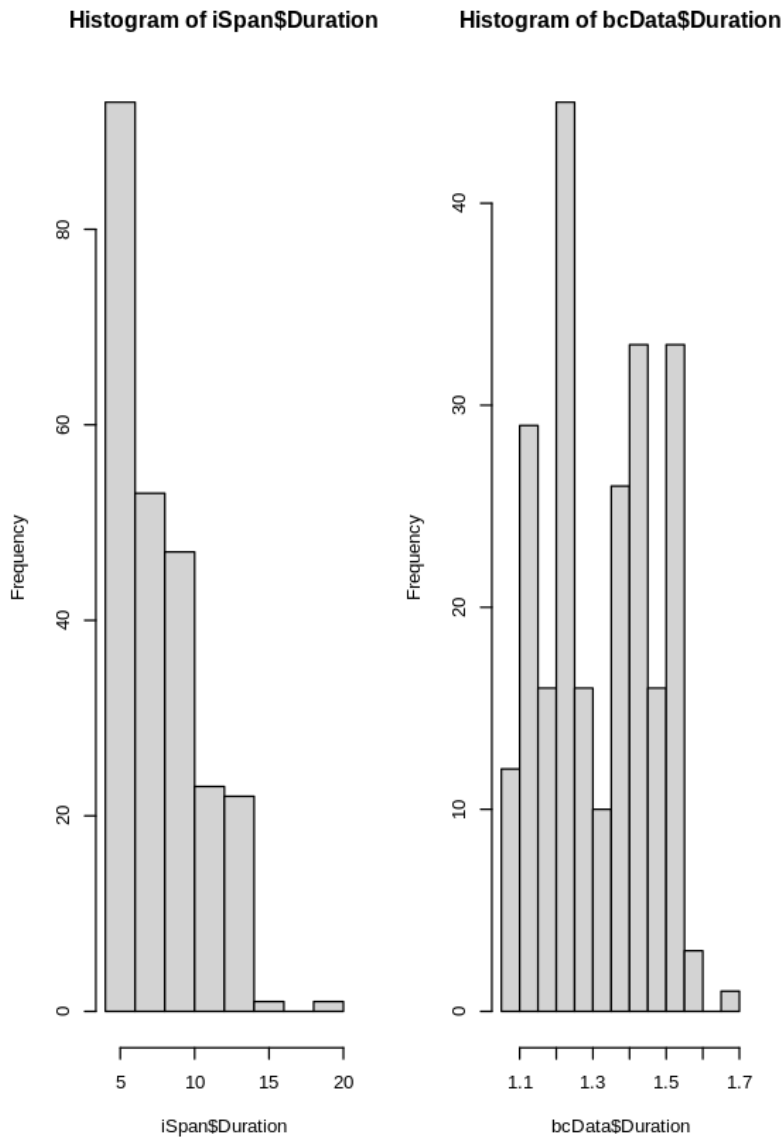
Box, G. E. P., & Cox, D. R. (1964). An Analysis of Transformations. Journal of the Royal Statistical Society, Series B (Methodological), 26(2), 211-252.

http://www.css.cornell.edu/faculty/dgr2/_static/files/R_html/Transformations.html

```
bcData = iSpan
x <- bcData$Duration
bc = boxcox(lm(x ~ 1), seq(-1,1,.1))
# bc = boxcox(lm(x ~ bcData$useCaseNum))
lambda <- bc$x[which.max(bc$y)]
new_x_exact <- (x ^ lambda - 1) / lambda
```



```
bcData$Duration = new_x_exact
par(mfrow=c(1,3))
hist(iSpan$Duration)
hist(bcData$Duration)
```



4.3 Normality Testing of the Trasformation

4.3.1 Shapiro-Wilk

The null-hypothesis of this test is that the population is normally distributed. Thus, if the p value is less than the chosen alpha level, then the null hypothesis is rejected and there is evidence that the data tested are not normally distributed. On the other hand, if the p value is greater than the chosen alpha level, then the null hypothesis (that the data came from a

normally distributed population) can not be rejected (e.g., for an alpha level of .05, a data set with a p value of less than .05 rejects the null hypothesis that the data are from a normally distributed population).

https://en.wikipedia.org/wiki/Shapiro-Wilk_test

```
shapiro.test(bcData$Duration)
```

Shapiro-Wilk normality test

```
data:  bcData$Duration
W = 0.9466, p-value = 1.06e-07
```

With p-value of _____ < 0.05 we reject the null hypothesis that the data are from a normally distributed population. But we'll also do a Q-Q Norm plot to visually see the results.

“if the p value is greater than the chosen alpha level, then the null hypothesis (that the data came from a normally distributed population) can not be rejected”

4.3.1.1 Shapiro-Wilk Testing Sqrt-Log-Cube

```
shapiro.test(sqrt_iSpan$Duration)
shapiro.test(log_iSpan$Duration)
shapiro.test(cube_iSpan$Duration)
# shapiro.test(bc_iSpan$Duration)
```

Shapiro-Wilk normality test

```
data:  sqrt_iSpan$Duration
W = 0.93106, p-value = 3.692e-09
```

Shapiro-Wilk normality test

```
data:  log_iSpan$Duration
W = 0.94087, p-value = 2.892e-08
```

Shapiro-Wilk normality test

```
data:  cube_iSpan$Duration
W = 0.93634, p-value = 1.092e-08
```

Shapiro-Wilk normality test

```
data: bc_iSpan$Duration
W = 0.94652, p-value = 1.039e-07
```

The **cube transformation** seems to provide the best q-q plot fit. With a p-value of _____ > 0.05 we fail to reject the null hypothesis and assume we now have a normal distribution.

“if the p value is greater than the chosen alpha level, then the null hypothesis (that the data came from a normally distributed population) can not be rejected”

4.3.2 Hypothesis Testing

We will use a Student’s t-Test to test the hypothesis on **normal** internal span data. Our mean is 500 ms (e.g. $\mu = 0.5$ seconds) and our null hypothesis is less than 500 ms.

```
mu = 0.5
x = cube_iSpan$Duration
cube_mu = mu^(1/3)
t.test(x=x, mu=cube_mu, alternative = 'greater')
```

One Sample t-test

```
data: x
t = 78.692, df = 239, p-value < 2.2e-16
alternative hypothesis: true mean is greater than 0.7937005
95 percent confidence interval:
 1.927618      Inf
sample estimates:
mean of x
 1.951922
```

```
mu = 0.5
x = iSpan$Duration
t.test(x=x, mu=mu, alternative = 'greater')
```

One Sample t-test

```
data: x
t = 40.422, df = 239, p-value < 2.2e-16
```

```
alternative hypothesis: true mean is greater than 0.5
95 percent confidence interval:
 7.448918      Inf
sample estimates:
mean of x
 7.744875
```

With a original and transformation with a p-value of _____ > 0.05 we fail to reject the null hypothesis, i.e. we assume that latency will be less than 500 ms.

“If the p value is greater than the chosen alpha level, then the null hypothesis (that latency is < 500 ms) can not be rejected”

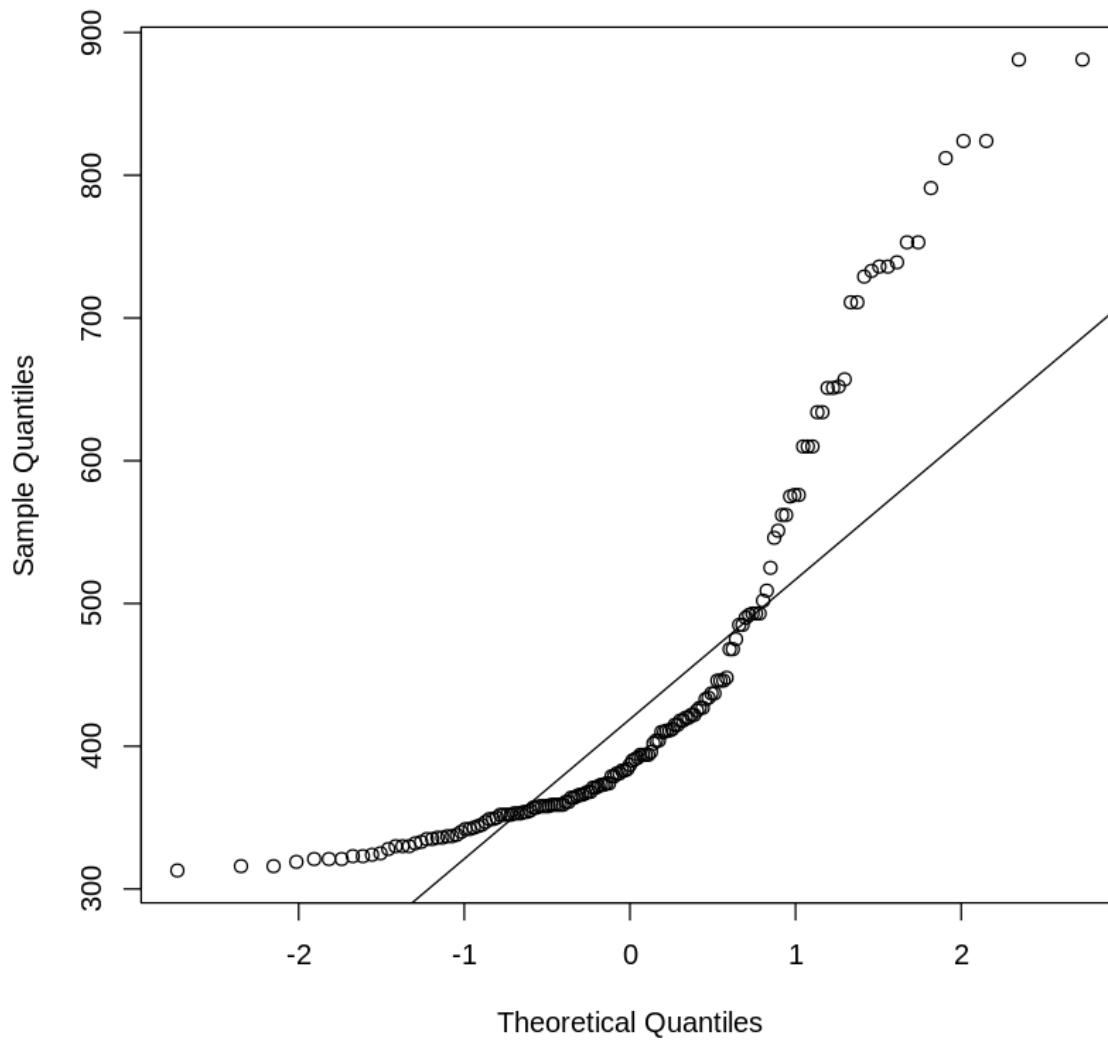
4.4 External Data

4.4.1 Q-Q Norm Plot of “Clean” External Span Data

We’ll look a the Q-Q Norm Plot and Shapiro-Wilk Test

```
qqnorm(eSpan$Duration, main="External Span Duration Q-Q Norm Plot")
qqline(eSpan$Duration)
```


External Span Duration Q-Q Norm Plot



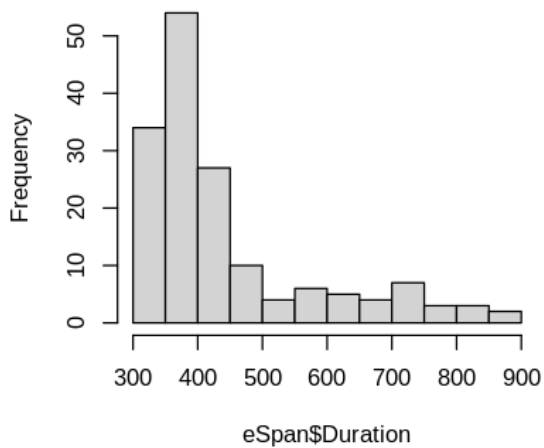
4.4.1.1 Sqrt-Log-Cube Transformations

```
sqrt_eSpan <- eSpan
sqrt_eSpan$Duration=sqrt(sqrt_eSpan$Duration)
log_eSpan <- eSpan
log_eSpan$Duration=log(log_eSpan$Duration + 1)
cube_eSpan <- eSpan
```

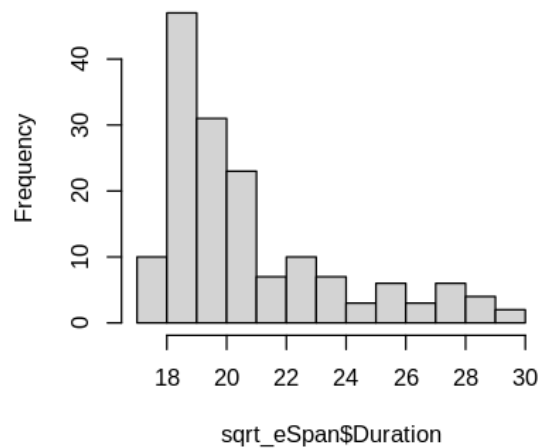
```
cube_eSpan$Duration=cube_eSpan$Duration^(1/3)
```

```
par(mfrow=c(2,2))  
hist(eSpan$Duration, counts = 50)  
hist(sqrt_eSpan$Duration)  
hist(log_eSpan$Duration)  
hist(cube_eSpan$Duration)
```

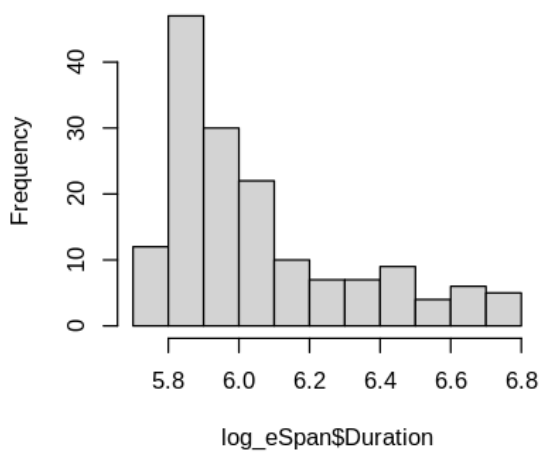
Histogram of eSpan\$Duration



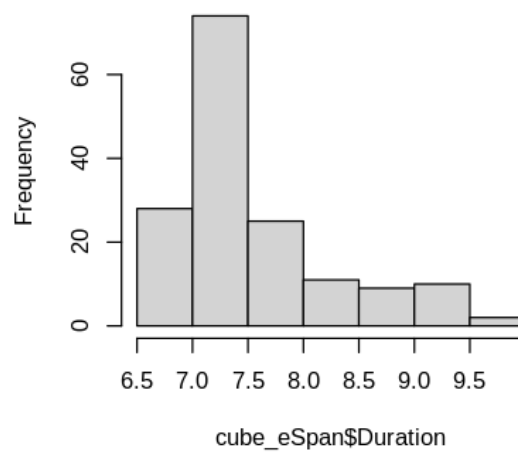
Histogram of sqrt_eSpan\$Duration



Histogram of log_eSpan\$Duration



Histogram of cube_eSpan\$Duration



4.4.2 Shapiro-Wilk Normality Test

```
shapiro.test(sqrt_eSpan$Duration)
shapiro.test(log_eSpan$Duration)
shapiro.test(cube_eSpan$Duration)
shapiro.test(eSpan$Duration)
```

Shapiro-Wilk normality test

```
data:  sqrt_eSpan$Duration
W = 0.81964, p-value = 9.941e-13
```

Shapiro-Wilk normality test

```
data:  log_eSpan$Duration
W = 0.85298, p-value = 2.506e-11
```

Shapiro-Wilk normality test

```
data:  cube_eSpan$Duration
W = 0.83121, p-value = 2.898e-12
```

Shapiro-Wilk normality test

```
data:  eSpan$Duration
W = 0.78293, p-value = 4.439e-14
```

With a p-value of _____ > 0.05 we fail to reject the null hypothesis, i.e. we assume that we have a normal distribution.

“if the p value is greater than the chosen alpha level, then the null hypothesis (that the data came from a normally distributed population) can not be rejected”

4.4.3 Hypothesis Testing

We will use a Student’s t-Test to test the hypothesis on external span data. Our mean is 500 ms (e.g. $\mu = 0.5$ seconds) and our null hypothesis is less than 500 ms.

```
mu = 0.5
```

```
x = eSpan$Duration
t.test(x=x, mu=mu, alternative = 'greater')
```

One Sample t-test

```
data: x
t = 41.115, df = 158, p-value < 2.2e-16
alternative hypothesis: true mean is greater than 0.5
95 percent confidence interval:
 424.4261      Inf
sample estimates:
mean of x
 442.2013
```

With a p-value of _____ > 0.05 we fail to reject the null hypothesis, i.e. we assume that 500 ms can be maintained for external service requests.

“If the p value is greater than the chosen alpha level, then the null hypothesis (that latency is < 500 ms) can not be rejected”

5 Observations

5.1 General Discussion of Normality

It was required to separate external data from internal to establish normality of the data samples. The internal data set required transformation to establish normality, while the external data did not require a transformation.

5.2 Hypothesis Results

Hypothesis testing using the Student's t-Test indicates that latency constraints of 500 ms can be maintained internally and external. However, several external samples were greater than 500 ms. This is most likely due to the non-deterministic nature of internet (e.g. http) requests. Within the internal environment, data is directly routed between microservices within the Docker environment within a private network. The data shows that a container based microservice architecture can meet the requirement; however, care must be taken to manage processing per container that may increase container response times.

5.3 DSS Prototype Environment

The non deterministic nature of the Docker environment on the MacBook laptop significantly affected the ability to assess deterministic behavior. Boxplots of data inclusive of what was sampled from the MacBook clearly depicted this issue. Linux platforms truly run a container as intended; however, non-linux platform require the use of a Linux based Virtual Machine on top of the host OS to implement containers. While the MacBook met the needs for rapid software development, the use of a separate integration and test environment was clearly validated through the collected data.