

Practice Quiz

TOTAL POINTS 11

1.	TD(0) is a solution method for:	1 point
	○ Control	
	O Prediction	
2.	Which of the following methods use bootstrapping? (Select all that apply)	1 point
	Dynamic Programming	
	Monte Carlo	
	TD(0)	
3.	Which of the following is the correct characterization of Dynamic Programming (DP) and Temporal Difference (TD) methods?	1 point
	Both TD and DP methods use <i>expected</i> updates.	
	Both TD and DP methods use sample updates.	
	TD methods use <i>expected</i> updates, DP methods use <i>sample</i> updates.	
	TD methods uses <i>sample</i> updates, DP methods use <i>expected</i> updates.	
4.	Which of the following correctly pairs a prediction algorithm and an update?	1 point
	$oxed{ }$ Monte Carlo: $V(S_t) \leftarrow V(S_t) + lpha[R_{t+1} + \gamma V(S_{t+1}) - V(S_t)]$	
	$oxed{ }$ Monte Carlo: $V(S_t) \leftarrow V(S_t) + lpha[G_t - V(S_t)]$	
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	$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	
5.	Which of the following well-describe Temporal Difference (TD) and Monte-Carlo (MC) methods?	1 point
	TD methods are used in <i>continuing</i> tasks.	
	MC methods are used in <i>continuing</i> tasks.	
	TD methods are used in <i>episodic</i> tasks.	
	MC methods are used in <i>episodic</i> tasks.	

6.	In an episodic setting, we might have different updates depending on whether the next state is terminal or non-terminal. Which of the following TD error calculations are correct?	1 point
	$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	
	$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	
	$oxed{\ } S_{t+1}$ is terminal: $\delta_t = R_{t+1} + \gamma V(S_{t+1}) - V(S_t)$ with $V(S_{t+1}) = 0$	
	$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	
7.	Suppose we have current estimates for the value of two states: V(A) = 1.0, V(B) = 1.0 in an episodic setting. We observe the following trajectory: A, 0, B, 1, B, 0, T where T is a terminal state. Apply TD(0) with step-size, $\alpha=1$, and discount factor, $\gamma=0.5$. What are the value estimates for state A and state B at the end of the episode? Provide your answers to 1 decimal place in the following format, replacing V(A) and V(B) with your answers: (V(A), V(B))	1 point
	Enter answer here	
8.	Which of the following pairs is the correct characterization of the targets used in TD(0) and Monte Carlo?	1 point
	TD(0): High Variance Target, Monte Carlo: High Variance Target	
	TD(0): High Variance Target, Monte Carlo: Low Variance Target	
	TD(0): Low Variance Target, Monte Carlo: High Variance Target TD(0): Low Variance Target, Monte Carlo: Low Variance Target	
9.	Suppose you observe the following episodes of the form (State, Reward,) from a Markov Decision Process with states A and B:	1 point
	Episodes	
	A, 0, B, 0	
	B, 1	
	B, 1	
	B, 1	
	В, 0	
	В, 0	
	B, 1	
	B, 0	
	What would batch Monte Carlo methods give for the estimates V(A) and V(B)? What would batch TD(0) give for the estimates V(A) and V(B)? Use a discount factor, γ , of 1. For Batch MC: compute the average returns observed from each state. For Batch TD: You can start with state B. What is its	
	expected return? Then figure out V(A) using the temporal difference equation: $V(S_t) = E[R_{t+1} + \gamma V(S_{t+1})].$	

Provide your answers to 1 decimal place in the following format: $(V^{\mathrm{batch-MC}}(A), V^{\mathrm{batch-MC}}(B), V^{\mathrm{batch-TD}}(A), V^{\mathrm{batch-TD}}(B))$ and replace

• $V^{\text{batch-MC}}(A)$,

	Note: The second of the second		
•	$V^{\mathrm{batch ext{-}MC}}(B)$,		
•	$V^{ m batch ext{-}TD}(A)$, and		
•	$V^{ m batch-TD}(B)$		
Wİ	th your answers.		
	Enter answer here		
	ue or False: "Both TD(0) and Monte-Carlo (MC) methods converge to the true value function asymptotica e environment is Markovian."	lly, given that	1 point
) True		
0) False		
11. Wi	hich of the following pairs is the correct characterization of the TD(0) and Monte-Carlo (MC) methods?		1 point
	Both TD(0) and MC are offline methods.		
	Both TD(0) and MC are online methods.		
	TD(0) is an online method while MC is an offline method.		
	MC is an online method while TD(0) is an offline method.		
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