

main

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1 contributor



198 lines (165 sloc) | 6.62 KB



# Lab 1: Samuel Kosik

Link to your `Digital-electronics-2` GitHub repository:

[GitHub Link](#)

## Blink example

1. What is the meaning of the following binary operators in C?

- `|` = OR, sum
- `&` = AND, product
- `^` = XOR
- `~` = NOT, flipping bits
- `<<` = LEFT Shift
- `>>` = RIGHT Shift

2. Complete truth table with operators: `|`, `&`, `^`, `~`

b	a	b or a	b and a	b xor a	not b
0	0	0	0	1	1
0	1	1	0	0	1
1	0	1	0	0	0

b	a	b or a	b and a	b xor a	not b
1	1	0	1	1	0

## Morse code

1. Listing of C code with syntax highlighting which repeats one "dot" and one "comma" on a LED:

```
#define LED_GREEN    PB5 // AVR pin where green LED is connected
#define LINE_DELAY   500 // LINE
#define SHORT_DELAY  150 // VERY SHORT DELAY (in ONE letter)
#define DOT_DELAY     250 // DOT
#define LONG_DELAY    800 // NEW Letter
#ifndef F_CPU         // Preprocessor directive allows for conditional
                      // compilation. The #ifndef means "if not defined".
# define F_CPU 16000000 // CPU frequency in Hz required for delay
#endif               // The #ifndef directive must be closed by #endif

/* Includes -----*/
/* Include another C language file into the current file at the location
 * of the #include statement prior to compiling the source code.
 */
#include <util/delay.h> // Functions for busy-wait delay loops
#include <avr/io.h>     // AVR device-specific IO definitions

/* Function definitions -----*/
/*****
 * Function: Main function where the program execution begins
 * Purpose:  Toggle one LED and use delay library.
 * Returns:  none
 *****/
int main(void)        //funkcia
{
    // Set pin as output in Data Direction Register
    // DDRB = DDRB or 0010 0000
    DDRB = DDRB | (1<<LED_GREEN);

    // Set pin LOW in Data Register (LED off)
    // PORTB = PORTB and 1101 1111
    PORTB = PORTB & ~(1<<LED_GREEN);           // << je bit shift

    // Infinite loop
    while (1)
    {

        //WORD "MORSE CODE":

        _delay_ms(LONG_DELAY);
        _delay_ms(LONG_DELAY);

        //M --
    }
}
```

```

PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(LONG_DELAY);

//O ---
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(LONG_DELAY);

//R .-.
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(LONG_DELAY);

//S ---
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF
_delay_ms(LONG_DELAY);

//E .
PORTB = PORTB ^ (1<<LED_GREEN);    //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN);    //LED OFF

```

```

_delay_ms(LONG_DELAY);

//
//C -.-.
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(LONG_DELAY);

//O ---
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
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PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(LONG_DELAY);

//D -..
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(LINE_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(SHORT_DELAY);
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(LONG_DELAY);

//E .
PORTB = PORTB ^ (1<<LED_GREEN); //LED ON
_delay_ms(DOT_DELAY);
PORTB = PORTB & ~(1<<LED_GREEN); //LED OFF
_delay_ms(LONG_DELAY);

```

```

}

// Will never reach this
return 0;
}

```

2. Scheme of Morse code application, i.e. connection of AVR device, LED, resistor, and supply voltage. The image can be drawn on a computer or by hand. Always name all components and their values!

