

The background features a series of concentric circles in light gray, some solid and some dashed, creating a ripple effect. A large, solid red speech bubble is centered on the page, pointing downwards. The title text is white and located inside the upper part of the speech bubble.

# Mapping Evacuation Routes Using Live Traffic Information

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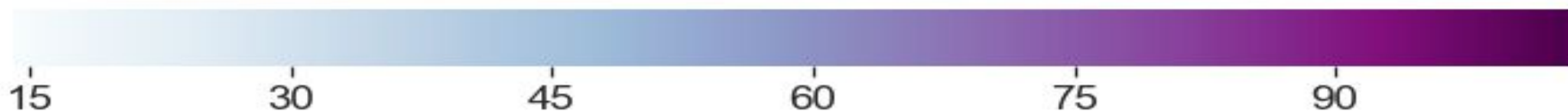
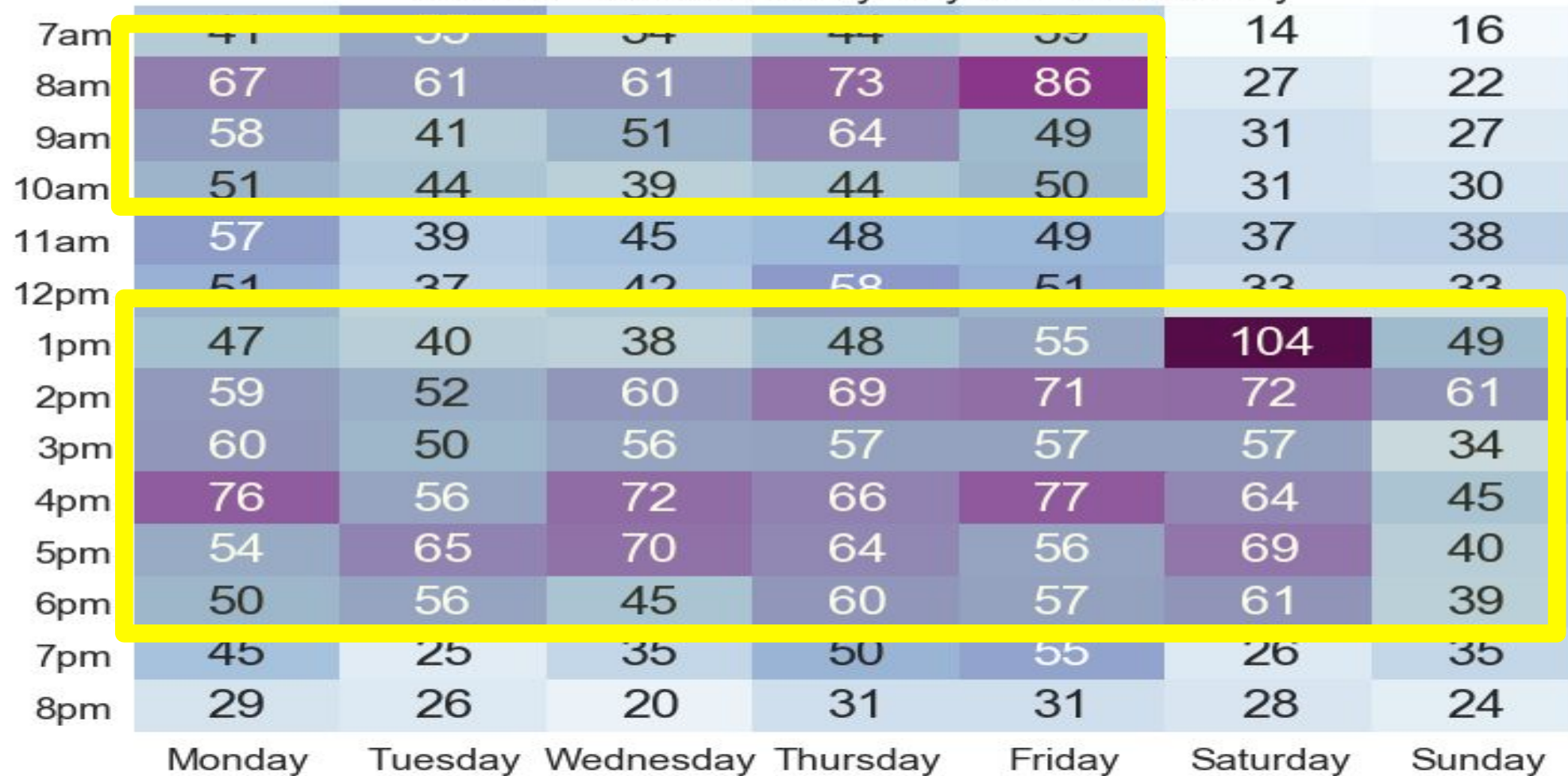
# Problem Statement

- In this project, we were tasked with optimizing the best evacuation route from Central Park to Prospect Park. The ideal output should map the fastest route given live and historical traffic data. Since Tom Tom essentially does this already, we wanted to validate its efficiency. We will test our theory by utilizing DBSCAN to cluster historically dense traffic regions. We then compare the live routing mechanism of Tom Tom to our cluster output. The pseudo-metric used will be silhouette score.

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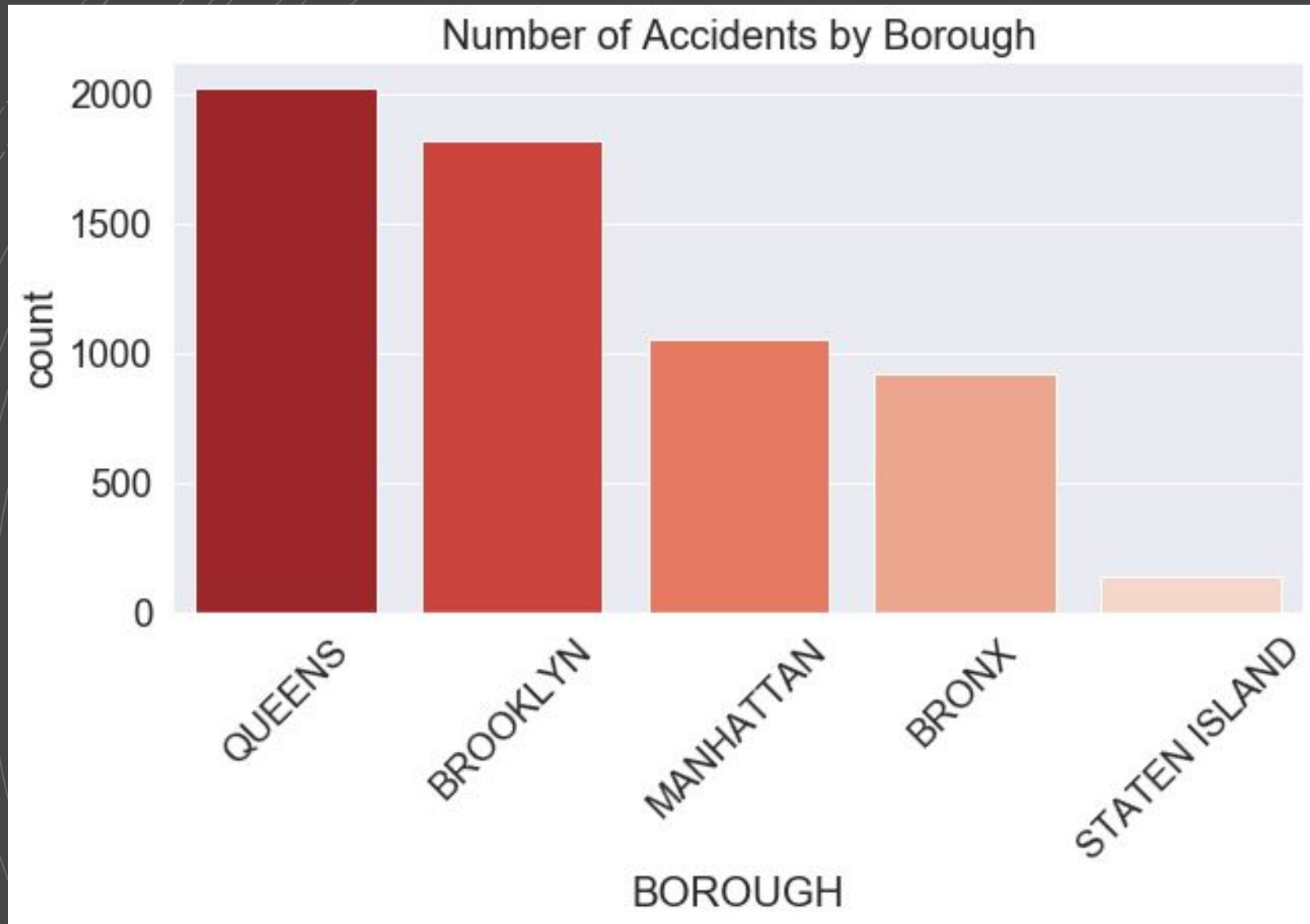
# Exploratory Data Analysis and Outside Research

Number of Accidents by Day and Time of Day



# Observations

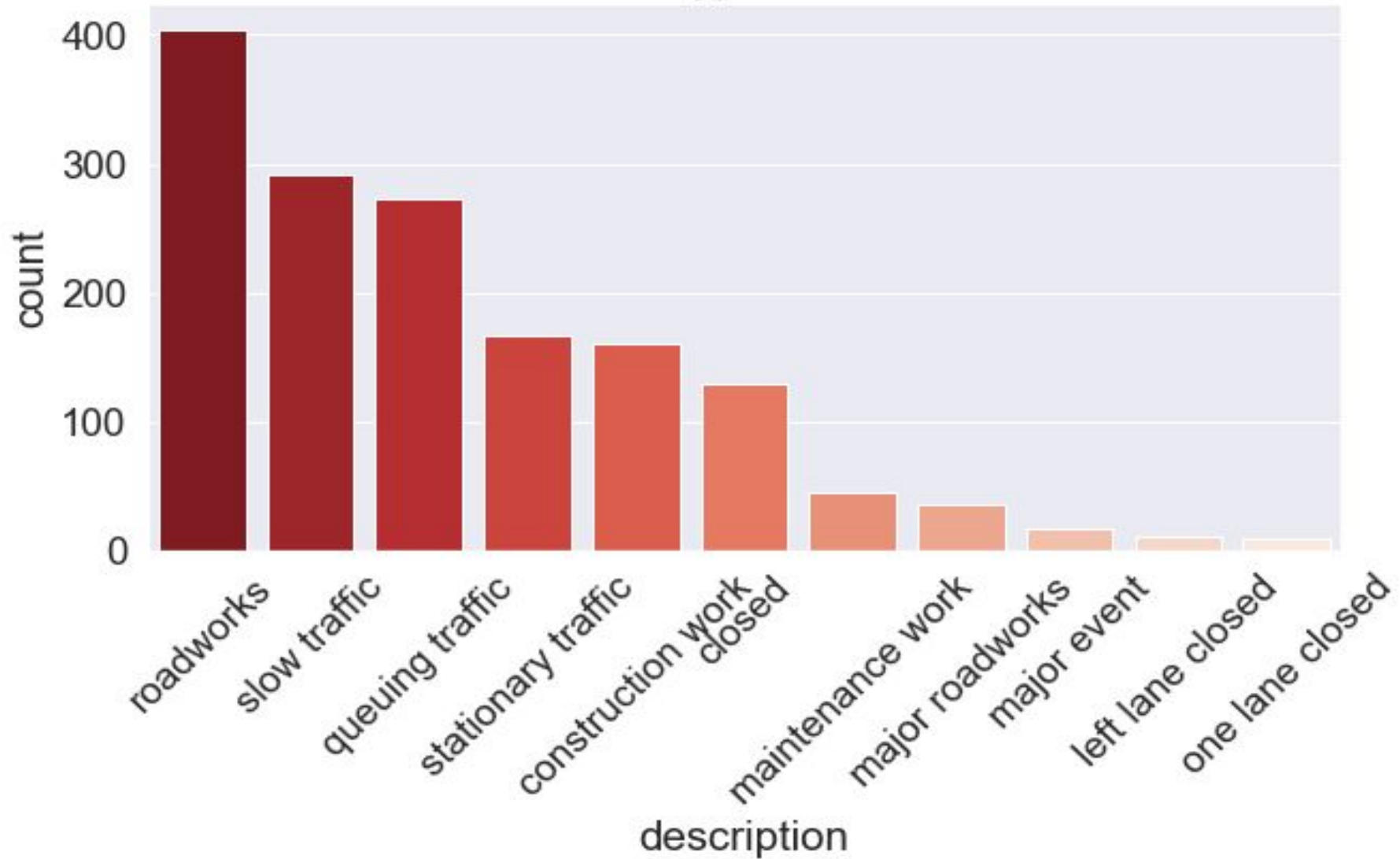
- Monday-Friday: 8-10 AM, 4-6 PM, consistent with typical rush hours
- Afternoon becomes denser from Thursday-Saturday
- Saturday 1 PM and Thursday 8 AM are especially high



# Observations

- Higher count in Brooklyn than Manhattan
- Congestion from Brooklyn-Queens Expressway
- Contradicted by our modeling

Most Common Types of Road Incident

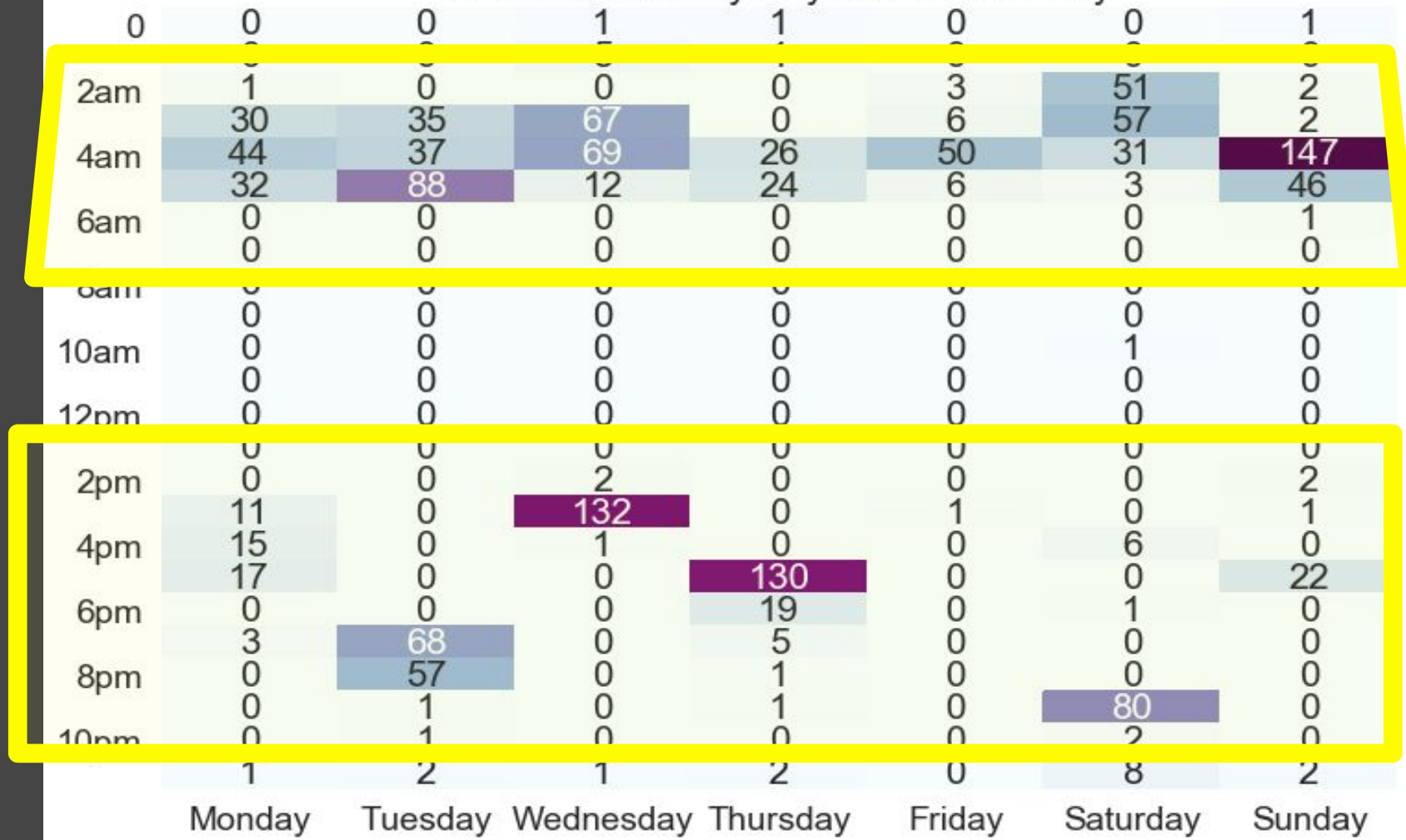




# Observations

- Road works, slow traffic, and gridlock are the most common
- Accidents are a lesser cause of closure
- Consider construction and congestion

# Road Incidents by Day and Time of Day



0 25 50 75 100 125

# Observation

- Monday-Thursday 3-8 PM
- All week 2-5 AM
- Highest: Sunday 4 AM, Wednesday 3 PM, Thursday 5 PM

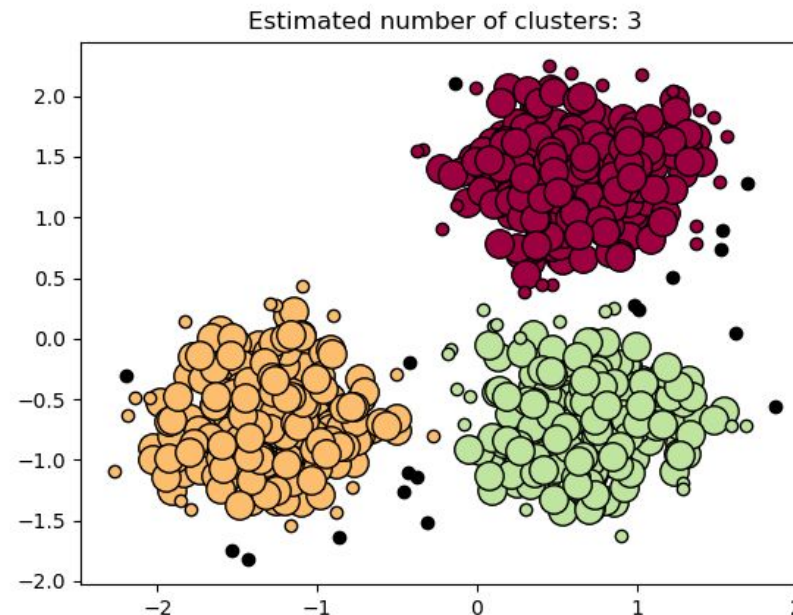
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# Modeling

DBSCAN

# DBSCAN Clustering

The most used models for unsupervised clustering are the KMeans and the DBSCAN. KMeans requires you to specify the number of clusters in advance and it allocates each observation into a cluster with the nearest mean. We chose the DBSCAN because it is a density-based clustering algorithm that groups points that are close to each other according to a radial distance measurement and minimum number of points. It can find clusters with amorphous shapes and mark outliers as points in low-density regions.



## Why did we use DBScan?

We wanted to use a model that clustered historically traffic-dense areas in order to easily visualize evacuation routes and validate the efficiency of TomTom's live routing API.

DBSCAN is an UNSUPERVISED clustering algorithm, so there is no true way to evaluate it. The mechanism for clustering is that the neighborhood of a given radius must contain at least a minimum number of points. Therefore, the parameters of the model are the radius and the number of points included in the cluster. For our modeling, we utilized the coordinates of traffic incidents.

# Model Evaluation

Being that there is no way to really evaluate the model, we still used pseudo-metrics for our evaluation purposes.

- Inertia is the sum of squared error for each cluster. Therefore the smaller the inertia, the denser the cluster.
- The Silhouette Score is from -1 to 1 and shows the proximity and density of clusters.

We chose the Silhouette Score for our model because it showed us the relationship between our clusters.

# Model Evaluation

Percentages of our data in each cluster:

- Cluster 0 : 73.3%
- Cluster 1: 1.4%
- Cluster 2: 2.2%
- Cluster 3: 9.3%
- Cluster 4: 5.8%
- Cluster -1: 7.3%

**Silhouette Score : 0.40**

Being that this is a pseudo-metric and we are utilizing DBSCAN for visual purposes only, we are satisfied with this score.

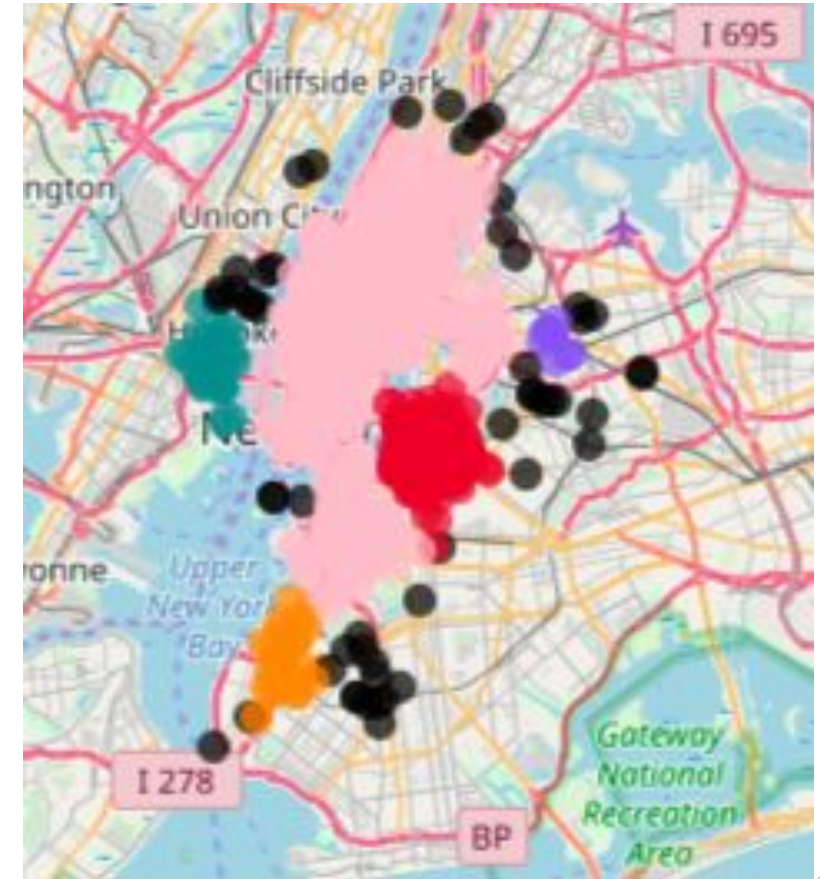


We mapped our Cluster coordinates. As you can see that the biggest cluster (cluster 0) includes most of Manhattan with the smaller clusters in the outer boroughs. Our outliers are the black dots (cluster = -1), they reflect the fact that those coordinates are further away from the city and have fewer traffic incidents.



**Legend:**

Cluster -1 = Black  
Cluster 0 = Pink  
Cluster 1 = Dark Cyan  
Cluster 2 = Dark Orange  
Cluster 3 = Crimson  
Cluster 4 = Blue



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# Tom Tom For Developers

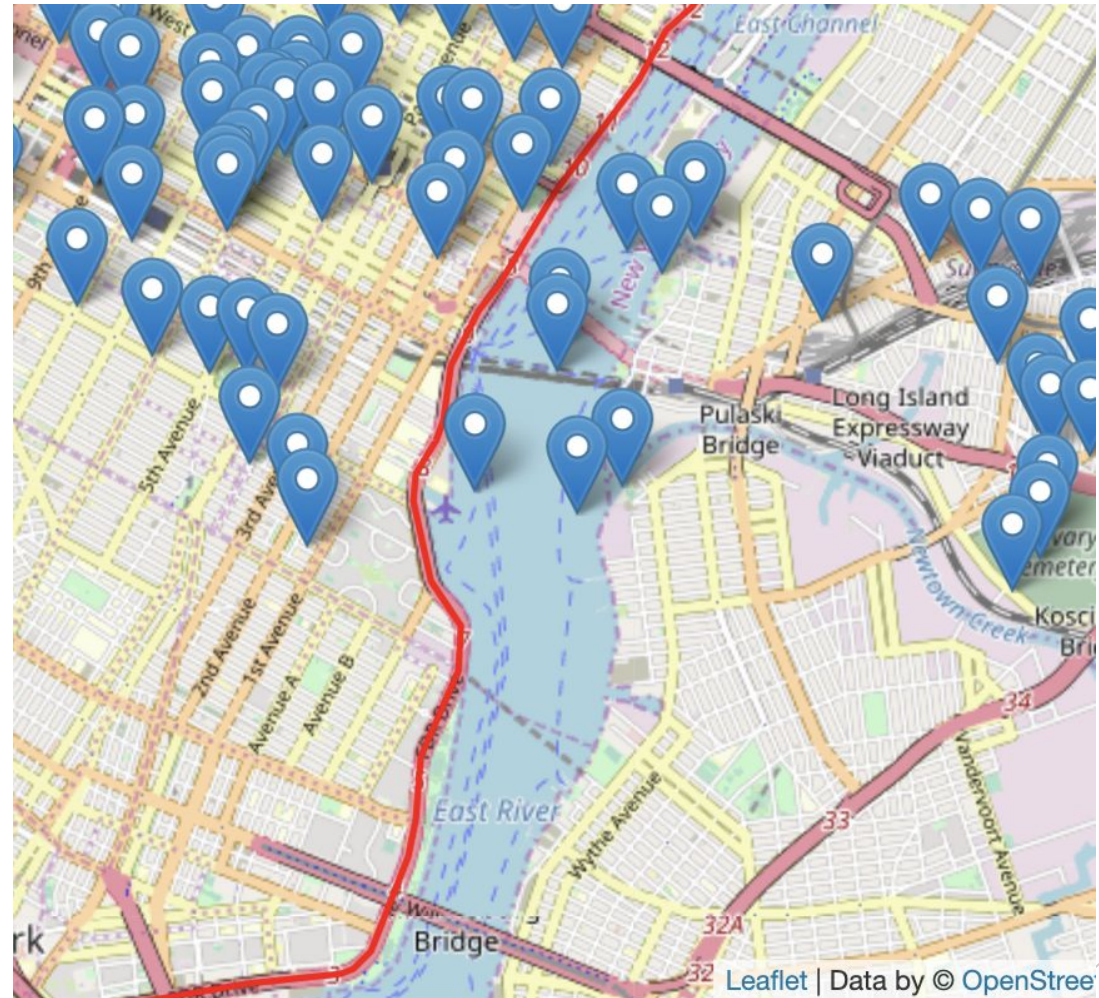
- TomTom is an API that provides real time maps and traffic data, with global coverage.
- We utilized its live routing and traffic incident features for our project.

# Tom Tom Advantages

- Can be utilized globally .
- Comes in multiple languages.
- Pulling live data from the API is free to all!
- It is more up to date than government websites.
- The routing system is already trained on historical traffic data, we will prove this in a second.

# Folium Mapping

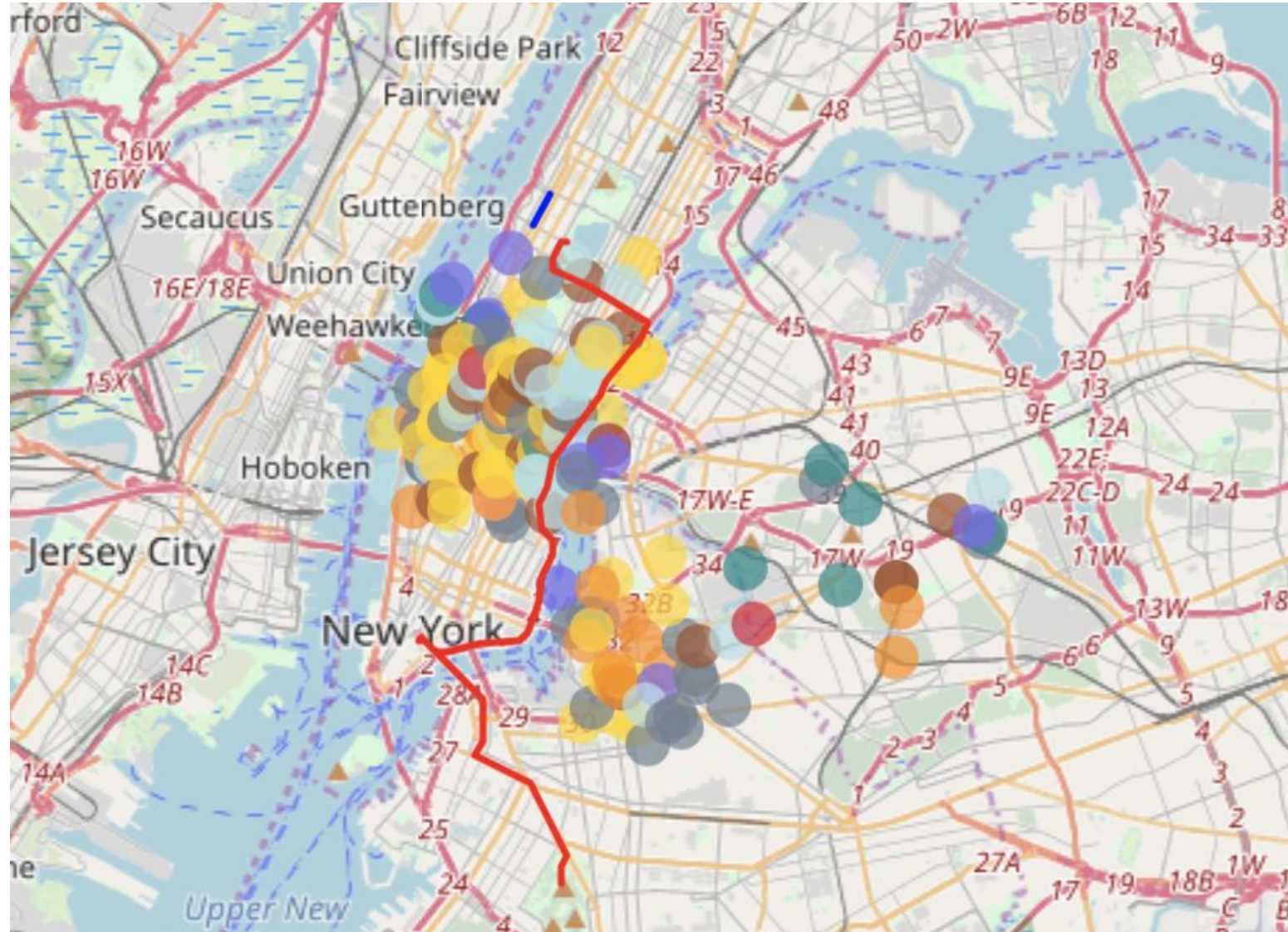
- I chose to use Folium because it had the best interactive map interface for python and is highly customizable.





Traffic Incidents are colored coded according to type.

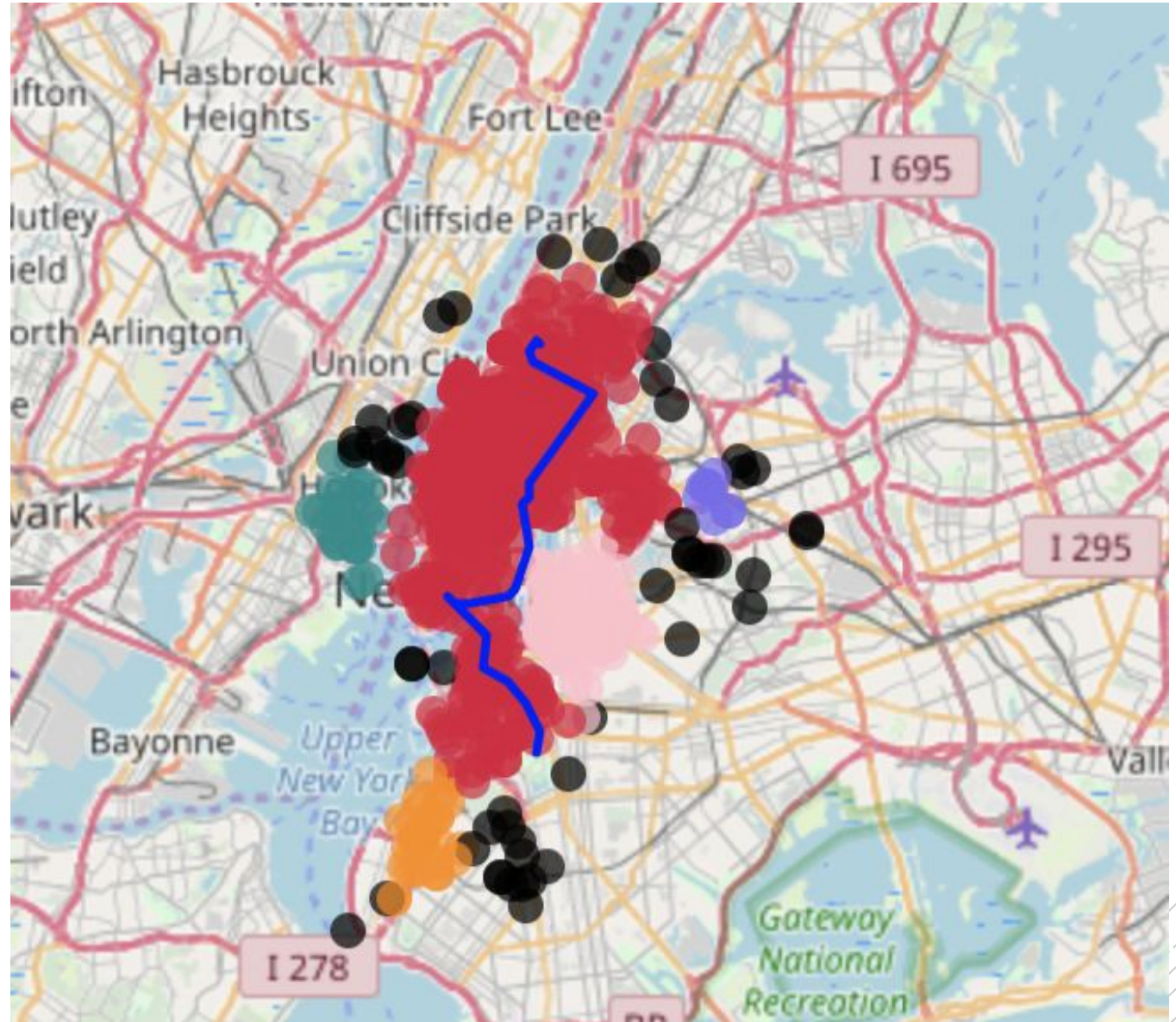
# Folium Mapping Live Traffic & Routing



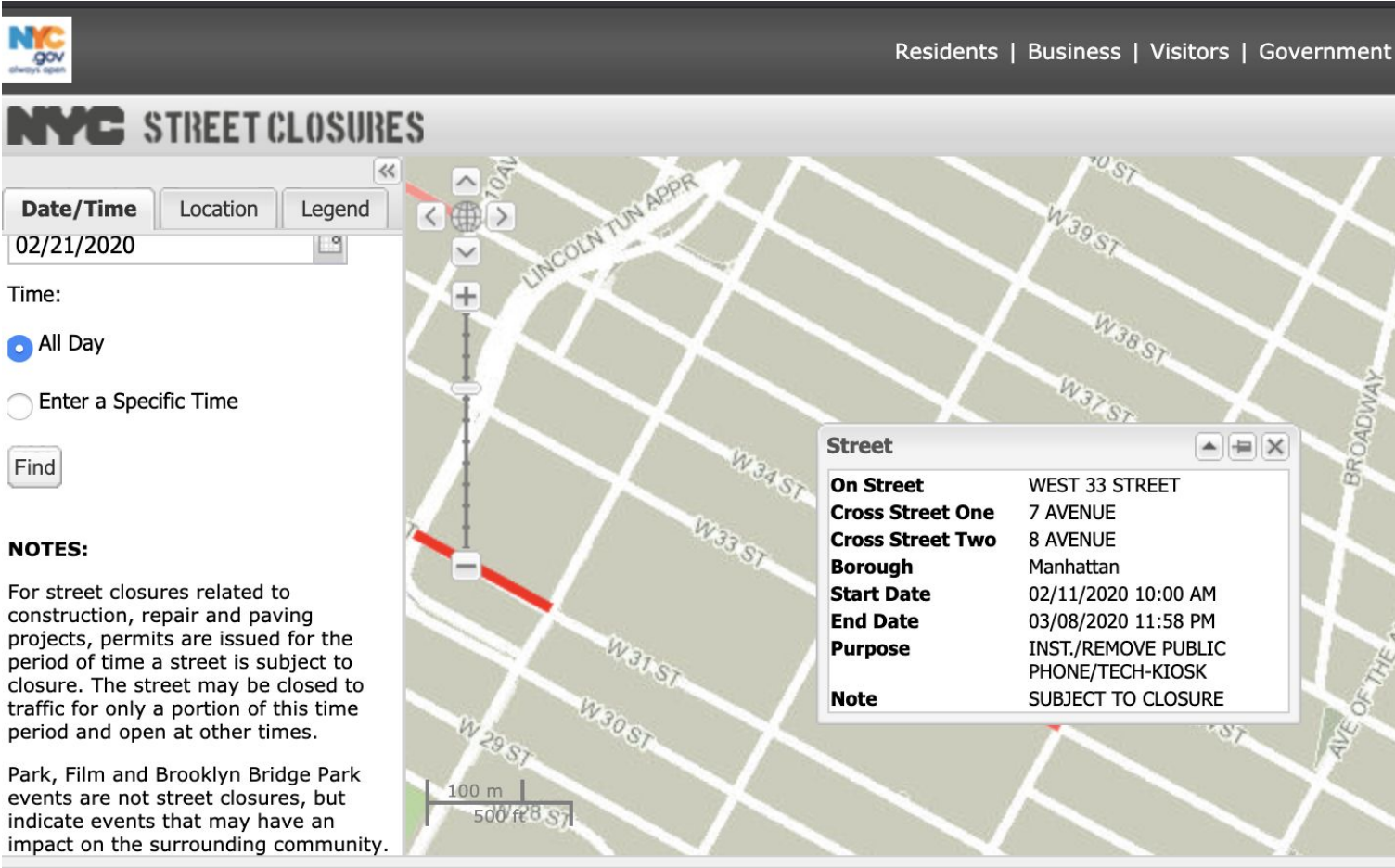


Clusters are color coded

Folium  
Mapping  
Historical Traffic  
Clusters & Live  
Routing



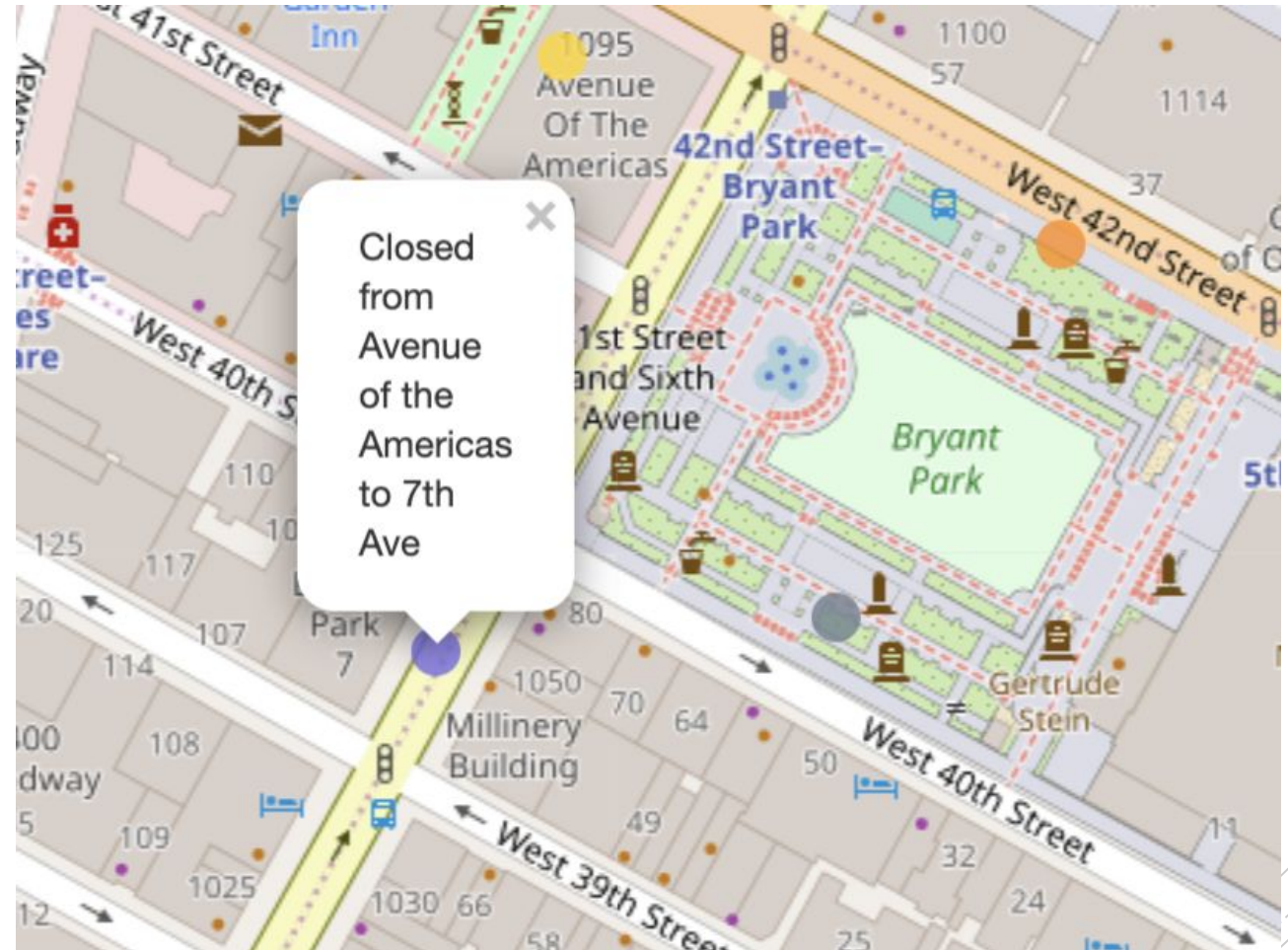
# Proving Tom Tom's Efficiency & Accuracy





## Live Traffic Incidents at Bryant Park

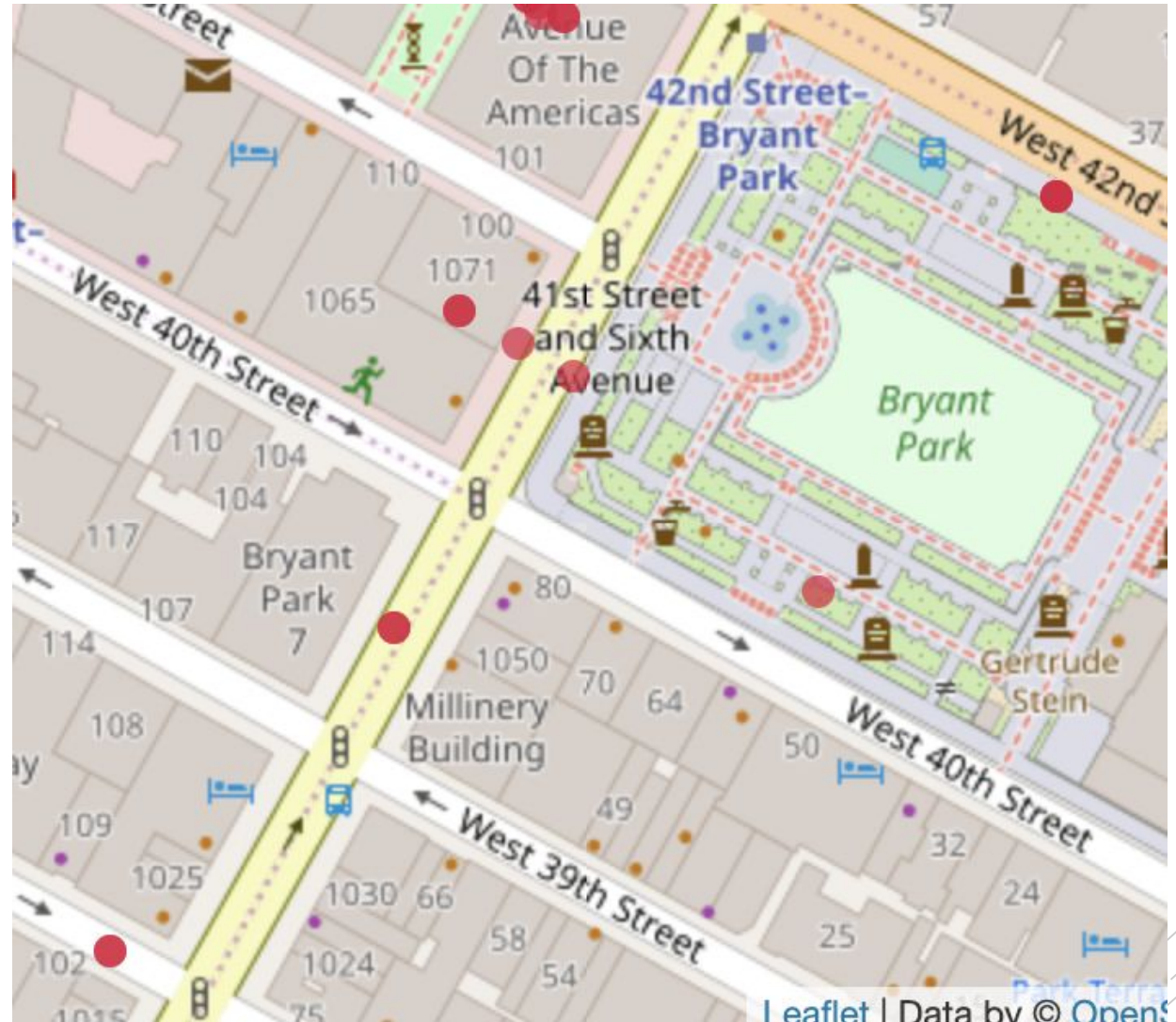
Proving Tom  
Tom's  
Efficiency &  
Accuracy





Proving Tom  
Tom's  
Efficiency &  
Accuracy

## Historical Traffic Incidents at Bryant Park



# Conclusions

- The DBSCAN clustering algorithm does a decent job of clustering the traffic incident areas. Since it is an unsupervised model and it is being utilized for visual purposes only, a Silhouette score of 0.40 will suffice. Therefore, we are satisfied with our final model.
- TomTom API is a reliable source for live traffic data. It is able to be utilized globally.

## Next Steps

- Geocoding to use physical addresses
- Overlay traffic polylines
- Additional research on causes of traffic-dense hours
- Apply to other regions of the world