

2. (1) if  $\hat{S} = \begin{pmatrix} S_1 \\ S_2 \\ S_3 \end{pmatrix}$  then  $S = \begin{pmatrix} 0 & -S_3 & S_2 \\ S_3 & 0 & -S_1 \\ -S_2 & S_1 & 0 \end{pmatrix}$

Proof:  $\vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$   $\begin{matrix} S_1 & S_2 & S_3 & S_1 & S_2 & S_3 \\ b_1 & b_2 & b_3 & b_1 & b_2 & b_3 \end{matrix}$

$$\hat{S} \times \vec{b} = \begin{pmatrix} S_2 b_3 - b_2 S_3 \\ S_3 b_1 - b_3 S_1 \\ S_1 b_2 - b_1 S_2 \end{pmatrix}$$

$$S \vec{b} = \begin{pmatrix} 0 & -S_3 & S_2 \\ S_3 & 0 & -S_1 \\ -S_2 & S_1 & 0 \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \begin{pmatrix} -b_2 S_3 + S_2 b_3 \\ b_1 S_3 - b_3 S_1 \\ -b_1 S_2 + b_2 S_1 \end{pmatrix}$$

(2)  $R = \exp(\phi S)$

$$= 1 + \phi S + \frac{1}{2!} (\phi S)^2 + \frac{1}{3!} (\phi S)^3 + \dots$$

$$= 1 + \phi S + \frac{1}{2!} \phi^2 S^2 - \frac{1}{3!} \phi^3 S + \frac{1}{4!} \phi^4 S^2 + \frac{1}{5!} \phi^5 S + \dots$$

$$= 1 + (\phi S - \frac{1}{3!} \phi^3 S + \frac{1}{5!} \phi^5 S) + (\frac{1}{2!} \phi^2 S^2 - \frac{1}{4!} \phi^4 S^2 + \dots)$$

$$= 1 + \sin \phi S + (1 - \cos \phi) S^2$$

$$S^2 = \begin{pmatrix} 0 & -S_3 & S_2 \\ S_3 & 0 & -S_1 \\ -S_2 & S_1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -S_3 & S_2 \\ S_3 & 0 & -S_1 \\ -S_2 & S_1 & 0 \end{pmatrix} = \begin{pmatrix} -S_3^2 - S_2^2 & S_1 S_2 & S_1 S_3 \\ S_1 S_2 & -S_3^2 - S_1^2 & S_2 S_3 \\ S_1 S_3 & S_2 S_3 & -S_1^2 - S_2^2 \end{pmatrix}$$

$$= \begin{pmatrix} S_1^2 - 1 & S_1 S_2 & S_1 S_3 \\ S_1 S_2 & S_2^2 - 1 & S_2 S_3 \\ S_1 S_3 & S_2 S_3 & S_3^2 - 1 \end{pmatrix}$$

$$S^3 = \begin{pmatrix} 0 & -S_3 & S_2 \\ S_3 & 0 & -S_1 \\ -S_2 & S_1 & 0 \end{pmatrix} \begin{pmatrix} S_1^2 - 1 & S_1 S_2 & S_1 S_3 \\ S_1 S_2 & S_2^2 - 1 & S_2 S_3 \\ S_1 S_3 & S_2 S_3 & S_3^2 - 1 \end{pmatrix} = \begin{pmatrix} 0 & S_3 & -S_2 \\ -S_3 & 0 & S_1 \\ S_2 & -S_1 & 0 \end{pmatrix} = -S$$

$$S^4 = S^3 \cdot S = -S \cdot S = -S^2 \quad S^5 = S^3 \cdot S^2 = -S \cdot S^2 = -S^3 = S$$