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In [1]: ## 6 System Identification by ordinary least squares regression, part(a)
        from scipy.io import loadmat
        import numpy as np
        from numpy.linalg import inv
In [2]: a = loadmat('hw01-data/system-identification/a.mat')
        x = np.transpose(a['x'])
        u = np.transpose(a['u'])
        X = np.hstack((x[:29, :], u[:29, :]))
        y = x[1:30, :]
        XT = np.transpose(X)
        w = np.dot(inv(XT @ X) @ XT, y)
        print(w)
        [[ 0.97755214]
         [-0.08775322]]
In [3]: ## 6 System Identification by ordinary least squares regression, part(b)
        b = loadmat('hw01-data/system-identification/b.mat')
        u = b['u']
        x = b['x']
        u = u.reshape(u.shape[0:2])
        x = x.reshape(x.shape[0:2])
        n = u.shape[0]
        Y = x[1:n, :].transpose()
        X = np.vstack((x[0:n-1, :].transpose(), u[0:n-1, :].transpose()))
        XT = X.transpose()
        W = Y @ XT @ inv(X @ XT)
        A = W[:, 0:3]
        B = W[:, 3:6]
        print(A)
        print('\n')
        print(B)
        [[ 0.15207406  0.93480864  -0.00110243]
         [ 0.03893567  0.30958727  0.87436511]
         [-0.52552959
                       0.0540906 - 0.47026217
        [[ 0.04894161  0.20568264 -0.37090438]
         [-0.04524735 -0.92861546 0.12756569]
         [ 0.91096923 -0.47124981 -0.84222314]]
```

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In [4]: ## 6 System Identifcation by ordinary least squares regression, part(c)

train = loadmat('hw01-data/system-identification/train.mat')
x = train['x'].transpose()
xd = train['xd'].transpose()
xdd = train['xdd'].transpose()
xp = train['xp'].transpose()
n = x.shape[0]

X = np.hstack((x, xd, xp, xdp, np.ones((n, 1))))
y = xdd
XT = X.transpose()
w = np.dot(inv(XT @ X) @ XT, y)
print(w)
```

```
[[-0.01152121]
[-0.31779341]
[ 0.01128933]
[ 0.27535824]
[-0.88293502]]
```