

view_frames Result
Recorded at time: 1456244466.231

map

base_link

left_0_wheel_link

left_1_wheel_link

left_2_wheel_link

left_3_wheel_link

left_4_wheel_link

left_5_wheel_link

right_0_wheel_link

right_1_wheel_link

right_2_wheel_link

right_3_wheel_link

right_4_wheel_link

right_5_wheel_link

base_footprint

plexiglass_base

camera_mount

flea3

flea3_optical

velodyne_mount

velodyne_mast_top

velodyne_laser_static

velodyne_laser_spin

velodyne

Broadcaster: /laser_scan_matcher_node
Average rate: 10.195 Hz
Most recent transform: 1456244466.183 (0.049 sec old)
Buffer length: 4.904 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1456244466.167 (0.064 sec old)
Buffer length: 4.900 sec

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Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 30.205 Hz
Most recent transform: 1456244466.209 (0.022 sec old)
Buffer length: 4.933 sec

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Average rate: 30.205 Hz
Most recent transform: 1456244466.209 (0.022 sec old)
Buffer length: 4.933 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1456244466.167 (0.064 sec old)
Buffer length: 4.900 sec

Broadcaster: /velodyne_to_velodyneStatic
Average rate: 10.200 Hz
Most recent transform: 1456244466.246 (-0.015 sec old)
Buffer length: 4.804 sec