§8.1: Diagonal and Triangular form: Review/Update: Let och(V,V), A=[o](=[o])

Def: A is similar to B if I invertible P such that $A = PBP^{-1}$ i.e. I basis B such that $[\sigma]_B = B$

Def: A is diagonalisable if 3 invertible P, diagonal D with A=PDP". Def 8.1.2: (if dim $V < \infty$) σ is diagonalisable if \exists basis B such that $[\sigma]_B = D$, a diagonal matrix

i.e. Let
$$B = \{\beta_1, \dots, \beta_n\}$$
, then $[\sigma]_B = (\sigma(\beta_1))_B \dots [\sigma(\beta_n)]_B = (\lambda_1, \lambda_n)$

first column: $[\sigma(\beta_1)]_B = (\lambda_1, \lambda_1)_B = (\lambda_1, \lambda_2)_B = (\lambda_1, \lambda_2)_B$

Similar in other columns:

 $\sigma(\beta_1) = \lambda_1 \beta_1 + O(\beta_2 + \dots + O(\beta_n))_B = (\lambda_1, \lambda_2)_B$

: σ is diagonalisable if and only if $\exists basis B = \{\beta_1, \dots, \beta_n\}$ such that

o(Bi)=liBi for some liEF.

of is a A-eigenvector of A if Ax=>x and x+3.

 $\mathcal{E}_{\lambda} = Nul(A-\lambda I)$ is the λ -eigenspace of A.

Def 8.1.2 B is 2-eigenvector of or if o(p)=2p and p+0 Ex = ker (o-21) is the 2-eigenspace of o. Note: B is a X-eigenvector of o = [B] is a X-eigenvector of A=[o]A if B is an eigenvector, then or (Spon (B)) = Spon (B).

To find eigenvectors, first find eigenvalues: solve the characteristic polynomial $X_A(x) = det(A-xI)$

Def 8.1.1: The characteristic polynomial of o is $\chi_{\sigma}(x) = dt([\sigma]_{A} - xI)$ for any basis of (it does not depend on A: see 2207 week 10 p31)

Def: A is triangularisable if I invotible P such that P'AP is upper_triangular or is triangularisable if I basis B such that [0] B is upper-triangular. i.e. $[\sigma(\beta_n)]_{\mathcal{B}} \dots [\sigma(\beta_n)]_{\mathcal{B}} = \begin{pmatrix} \lambda_1 & \lambda_2 & \lambda_1 \\ \lambda_2 & \lambda_2 \end{pmatrix}$ first column: $\sigma(\beta_i) = \lambda, \beta, + 0\beta_2 + \cdots + 0\beta_n \in Span \{\beta_i\}.$ Second column: $\sigma(\beta_2) = *\beta_1 + \lambda_2 \beta_2 + 0 \beta_3 + \cdots 0 \beta_n \in Span \{\beta_1, \beta_2\}$ Similarly: $O(\beta_K) = *\beta_1 + \dots + *\beta_{k-1} + \lambda_k \beta_k + O\beta_{k+1} + \dots + O\beta_n \in Span \{\beta_1, \beta_2, \dots, \beta_k\}$ $(Span \{\beta_1,...,\beta_k\}) = Span \{\sigma(\beta_1),...,\sigma(\beta_k)\} \subseteq Span \{\beta_1,...,\beta_k\} \quad (:each \sigma(\beta_i) \in Span \{\beta_1,...,\beta_k\} \text{ for } i \in k\}$ $i.e. Span \{\beta_1,...,\beta_k\} \text{ is an invariant subspace.}$ Def 8.1.4. A subspace W=V is invariant under of if $\sigma(W) \subseteq W$. Advantages over diagonalisation: . The eigenvalues are on the diagonal. · Schur Theorem: every linear transformation over (is triangularisable (orthogonally, see \$10.4).

(for other fields, e.g. {0,1} = Z2 - use a bigger field where all polynomials have solutions. — find an eigenvector,

· Triangularisation is more stable on computers