

Last time: Given  $\sigma \in L(U, V)$ , its dual

$\hat{\sigma} \in L(\hat{V}, \hat{U})$  is given by  $\hat{\sigma}(\phi) = \phi \circ \sigma$ .

If  $A, B$  are bases of  $U, V$ , then

$$\text{Th. 9.3.3} \quad \underset{\hat{A} \leftarrow}{[\hat{\sigma}]}_{\hat{B}} = \left( \underset{B \leftarrow}{[\sigma]}_A \right)^T.$$

## § 9.2 Change of coordinates for linear forms

[?] Given  $A, B$  bases of  $V$ , what is the matrix relating  $\hat{A}$  and  $\hat{B}$  for  $\hat{V}$ ?

i.e. what is  $\underset{\hat{A} \leftarrow}{[\hat{\iota}_V]}_{\hat{B}}$ ?

Note:  $\iota_{\hat{V}} = \hat{\iota}_V \quad \because \quad \hat{\iota}_V(\phi) = \phi \circ \iota_V = \phi$

$\therefore$  From Th 9.3.3:

$$\begin{aligned} \underset{\hat{A} \leftarrow}{[\hat{\iota}_V]}_{\hat{B}} &= \underset{\hat{A} \leftarrow}{[\hat{\iota}_V]}_{\hat{B}} \\ &= \left( \underset{B \leftarrow}{[\iota_V]}_A \right)^T \end{aligned}$$

equivalently

$$\underset{\hat{A} \leftarrow}{[\hat{\iota}_V]}_{\hat{B}} = \left( \underset{A \leftarrow}{[\iota_V]}_B \right)^{T^{-1}}$$

A way to understand this when  
 $\mathcal{A}$  = standard basis of  $\mathbb{F}^n$ ,

$$\mathcal{B} = \{\beta_1, \dots, \beta_n\}$$

$$\text{Let } \widehat{\mathcal{B}} = \{\psi_1, \dots, \psi_n\} \subseteq \widehat{V},$$

$$\text{so } \psi_i: V \rightarrow \mathbb{F}$$

Consider

$$\begin{pmatrix} \text{---} [\psi_1] \text{---} \\ \vdots \\ \text{---} [\psi_n] \text{---} \end{pmatrix} \begin{pmatrix} | & & | \\ \beta_1 & \dots & \beta_n \\ | & & | \end{pmatrix} = \begin{pmatrix} \psi_1(\beta_1) & \psi_1(\beta_2) & \dots & \psi_1(\beta_n) \\ \vdots & & & \vdots \\ \psi_n(\beta_1) & \dots & \dots & \psi_n(\beta_n) \end{pmatrix}$$

↑  
standard matrix of  $\psi_i$   
( $1 \times n$  matrix)

$$i, j \text{ entry of } \uparrow \text{ is } \psi_i(\beta_j) = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

$\therefore$  matrix on RHS is  $I$ .

$$\text{So } \begin{pmatrix} -[\psi_1] - \\ \vdots \\ -[\psi_n] - \end{pmatrix} = \begin{pmatrix} | & & | \\ \beta_1 & \dots & \beta_n \\ | & & | \end{pmatrix}^{-1} = \underbrace{[C_V]}_{\mathcal{A}} B$$

$$\hat{\mathcal{A}} \xleftarrow{[C_V]^T} \hat{B} \quad \because \text{the } i\text{th column of } \begin{pmatrix} -[\psi_1] - \\ \vdots \\ -[\psi_n] - \end{pmatrix}^T$$

is  $[\psi_i]^T = [\psi_i]_{\hat{\mathcal{A}}}$

Ex. 9.2.3 If  $B = \left\{ \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right\} \subseteq \mathbb{R}^3 = V$   
find  $\hat{B}$ .

Method 1 : use change of coordinates matrix:

let  $\mathcal{A} = \{e_1, e_2, e_3\}$ , and let  $\hat{B} = \{\psi_1, \psi_2, \psi_3\}$ .



The columns of  $\underset{\hat{A} \leftarrow \hat{B}}{\hat{A}} [\hat{v}]_{\hat{B}}$  are  $[\psi_1]_{\hat{A}}, [\psi_2]_{\hat{A}}, [\psi_3]_{\hat{A}}$ .

$$\underset{\hat{A} \leftarrow \hat{B}}{\hat{A}} [\hat{v}]_{\hat{B}} = \underset{\hat{B} \leftarrow \hat{A}}{[v]_{\hat{A}}}^T \leftarrow \text{columns of this are } [e_i]_{\hat{B}}.$$

$$= \left( \underset{\hat{A} \leftarrow \hat{B}}{[v]_{\hat{A}}}^{-1} \right)^T$$

$$= \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 1 \\ -1 & 0 & 1 \end{pmatrix}^{-1 T}$$

$$= \frac{1}{2} \begin{pmatrix} 1 & 1 & -1 \\ -1 & 1 & -1 \\ 1 & 1 & 1 \end{pmatrix}^T$$

$$= \frac{1}{2} \begin{pmatrix} 1 & -1 & 1 \\ 1 & 1 & 1 \\ -1 & -1 & 1 \end{pmatrix}$$

row reduction to find inverse

read the columns:

$$[\psi_1]_{\hat{A}} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}. \text{ i.e. } \psi_1 \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \frac{1}{2}x + \frac{1}{2}y - \frac{1}{2}z$$

$$\psi_1 = \frac{1}{2}\phi_1 + \frac{1}{2}\phi_2 - \frac{1}{2}\phi_3 \text{ if } \hat{A} = \{\phi_1, \phi_2, \phi_3\}$$

$$\psi_2 \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -\frac{1}{2}x + \frac{1}{2}y - \frac{1}{2}z$$

$$\psi_3 \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \frac{1}{2}x + \frac{1}{2}y + \frac{1}{2}z.$$

Check:  $\psi_i(\beta_i) = 1$  and  $\psi_i(\beta_j) = 0$  if  $i \neq j$ .

$$\text{e.g. } \psi_1(\beta_1) = \psi_1 \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \frac{1}{2}1 + \frac{1}{2}0 - \frac{1}{2}(-1) = 1 \checkmark$$

$$\psi_2(\beta_3) = \psi_2 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = -\frac{1}{2}0 + \frac{1}{2}1 - \frac{1}{2}1 = 0 \checkmark$$

Method 2: use definition of  $\hat{B}$ .

$$\text{let } \psi_1\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = ax + by + cz.$$

We need  $\psi_1(\beta_1) = 1$ ,  $\psi_1(\beta_2) = 0$ ,  $\psi_1(\beta_3) = 0$ .

$$\psi_1(\beta_1) = \psi_1\left(\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}\right) = a \cdot 1 + b \cdot 0 + c(-1) = 1$$
$$\underline{a - c = 1}$$

$$\psi_1(\beta_2) = \psi_1\left(\begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}\right) = -a + b = 0$$

$$\psi_1(\beta_3) = \psi_1\left(\begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}\right) = b + c = 0$$

$$a = b = -c = \frac{1}{2}.$$

$$\text{so } \psi_1\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = \frac{1}{2}x + \frac{1}{2}y - \frac{1}{2}z$$

similarly solve for  $\psi_2, \psi_3$ .



## The double dual:

Recall  $\hat{V} = L(V, \mathbb{F})$ , so  $\hat{\hat{V}} = L(\hat{V}, \mathbb{F})$

i.e. each  $f \in \hat{\hat{V}}$  is a function  $\phi \mapsto \text{number}$ ,

where the input  $\phi$  is a function on  $V$ .

One example:  $f = \text{evaluation at some fixed } \alpha \in V$ .

i.e.  $f$  is  $\phi \mapsto \phi(\alpha)$  i.e.  $f(\phi) = \phi(\alpha)$ .

Exercise: check this  $f$  is in  $\hat{\hat{V}}$ , i.e.  $f$  is linear (in its input in  $\hat{V}$ ).

So, to every  $\alpha \in V$ , we can associate such an  $f \in \hat{\hat{V}}$ .

Th. 9.2.1: The function  $J: V \rightarrow \hat{\hat{V}}$  given by  $J(\alpha) = \text{evaluation at } \alpha$ , i.e.

$[J(\alpha)](\phi) = \phi(\alpha)$  is an injective linear transformation.