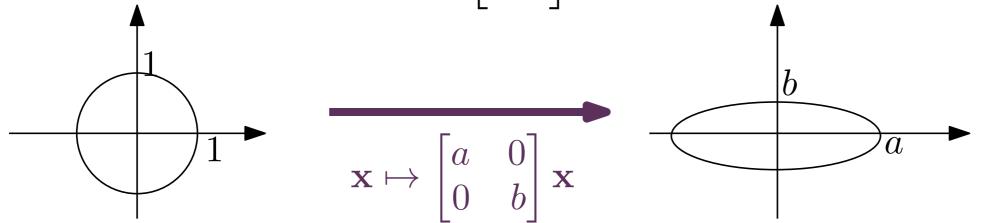
## §3.1-3.3: Determinants

Conceptually, the determinant  $\det A$  of a square  $n \times n$  matrix A is the signed area/volume scaling factor of the linear transformation  $T(\mathbf{x}) = A\mathbf{x}$ , i.e.:

- For any region S in  $\mathbb{R}^n$ , the volume of its image T(S) is  $|\det A|$  multiplied by the original volume of S,
- If  $\det A>0$ , then T does not change "orientation". If  $\det A<0$ , then T changes "orientation".

**Example**: Area of ellipse  $= \det \begin{vmatrix} a & 0 \\ 0 & b \end{vmatrix} \times \text{ area of unit circle} = ab\pi.$ 

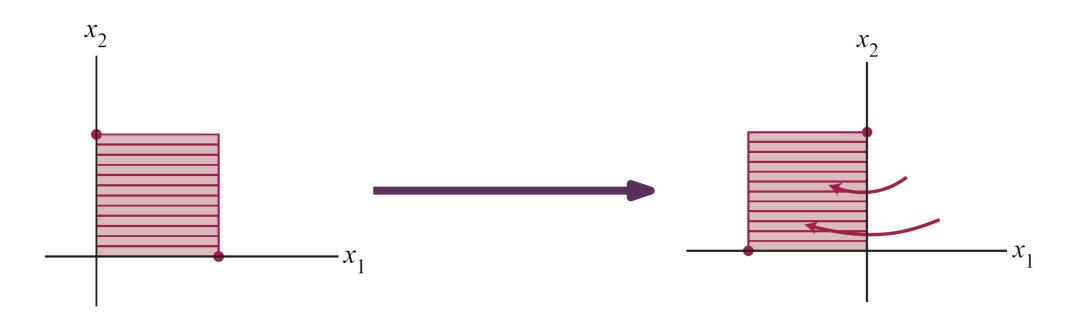


This idea is useful in multivariate calculus.

Formula for 
$$2 \times 2$$
 matrix:  $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$ .

**Example**: The standard matrix for reflection through the  $x_2$ -axis is  $\begin{bmatrix} -1 & 0 \ 0 & 1 \end{bmatrix}$ . Its determinant is  $-1 \cdot 1 - 0 \cdot 0 = -1$ : reflection does not change area, but

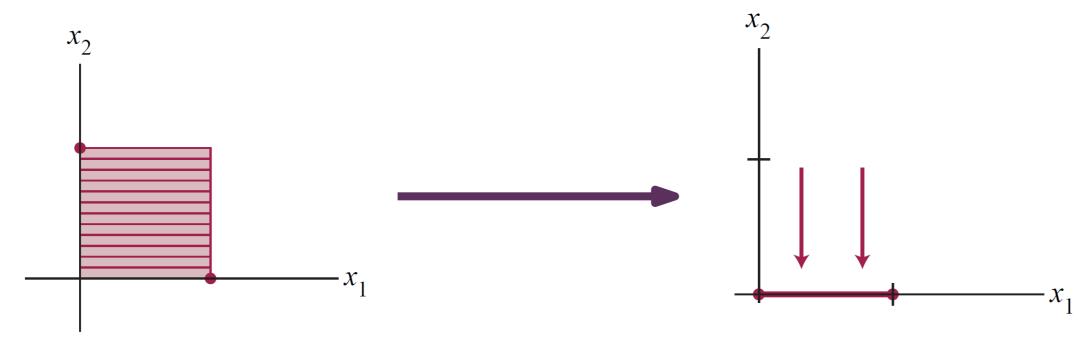
Its determinant is  $-1 \cdot 1 - 0 \cdot 0 = -1$ : reflection does not change area, but changes orientation.



Exercise: Guess what the determinant of a rotation matrix is, and check your answer.

Formula for 
$$2 \times 2$$
 matrix:  $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$ .

**Example**: The standard matrix of projection onto the  $x_1$ -axis is  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ . Its determinant is  $1 \cdot 0 - 0 \cdot 0 = 0$ . Projection sends the unit square to a line, which has zero area.



**Theorem**: A is invertible if and only if  $\det A \neq 0$ .

How the determinant changes under row operations:

- 1. Replacement: add a multiple of one row to another row. determinant does not change.
- $R_i \to R_i + cR_j$

2. Interchange: interchange two rows. determinant changes sign.

- $R_i o R_j$ ,  $R_j o R_i$
- 3. Scaling: multiply all entries in a row by a nonzero constant.  $R_i \to cR_i, c \neq 0$  determinant scales by a factor of c.

To help you remember:

	after	after	
original	replacement	interchange	after scaling
$\begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 1,$	$\begin{vmatrix} 1 & c \\ 0 & 1 \end{vmatrix} = 1,$	$\begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} = -1,$	$\begin{vmatrix} c & 0 \\ 0 & 1 \end{vmatrix} = c.$

Because we can compute the determinant by expanding down columns instead of across rows, the same changes hold for "column operations".

- 1. Replacement:  $R_i \rightarrow R_i + cR_i$  determinant does not change.
- 2. Interchange:  $R_i \to R_j$ ,  $R_i \to R_i$  determinant changes sign.
- 3. Scaling:  $R_i \to cR_i$ ,  $c \neq 0$  determinant scales by a factor of c.

Usually we compute determinants using a mixture of "expanding across a row or down a column with many zeroes" and "row reducing to a triangular matrix".

## **Example**:

Example: 
$$\begin{vmatrix} 2 & 3 & 4 & 6 \\ 0 & 5 & 0 & 0 \\ 5 & 5 & 6 & 7 \\ 7 & 9 & 6 & 10 \end{vmatrix} = 5 \begin{vmatrix} 2 & 4 & 6 \\ 5 & 6 & 7 \\ 7 & 6 & 10 \end{vmatrix} = 5 \cdot 2 \begin{vmatrix} 1 & 2 & 3 \\ 5 & 6 & 7 \\ 7 & 6 & 10 \end{vmatrix} = 5 \cdot 2 \begin{vmatrix} 1 & 2 & 3 \\ 5 & 6 & 7 \\ 7 & 6 & 10 \end{vmatrix} = 5 \cdot 2 \begin{vmatrix} 1 & 2 & 3 \\ 5 & 6 & 7 \\ 7 & 6 & 10 \end{vmatrix} = 5 \cdot 2 \begin{vmatrix} 1 & 2 & 3 \\ 5 & 6 & 7 \\ 7 & 6 & 10 \end{vmatrix} = 5 \cdot 2 \begin{vmatrix} 1 & 2 & 3 \\ 0 & -4 & -8 \\ 0 & -8 & -11 \end{vmatrix}$$

factor out -4 from 
$$R_2$$
  $R_3 \rightarrow R_3 + 8R_2$   $= 5 \cdot 2 \cdot -4 \begin{vmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & -8 & -11 \end{vmatrix} = 5 \cdot 2 \cdot -4 \begin{vmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 5 \end{vmatrix} = 5 \cdot 2 \cdot -4 \cdot 1 \cdot 1 \cdot 5 = -200.$ 

- 1. Replacement:  $R_i \to R_i + cR_j$  determinant does not change.
- 2. Interchange:  $R_i \to R_j$ ,  $R_j \to R_i$  determinant changes sign.
- 3. Scaling:  $R_i \to cR_i$ ,  $c \neq 0$  determinant scales by a factor of c.

**Useful fact**: If two rows of A are multiples of each other, then  $\det A = 0$ .

**Proof**: Use a replacement row operation to make one of the rows into a row of zeroes, then expand along that row.

**Example**:

$$\begin{vmatrix} R_3 \to R_3 - 2R_1 \\ \begin{vmatrix} 1 & 3 & 4 \\ 5 & 9 & 3 \\ 2 & 6 & 8 \end{vmatrix} = \begin{vmatrix} 1 & 3 & 4 \\ 5 & 9 & 3 \\ 0 & 0 & 0 \end{vmatrix} = 0 \begin{vmatrix} 3 & 4 \\ 9 & 3 \end{vmatrix} - 0 \begin{vmatrix} 1 & 4 \\ 5 & 3 \end{vmatrix} + 0 \begin{vmatrix} 1 & 3 \\ 5 & 9 \end{vmatrix} = 0.$$

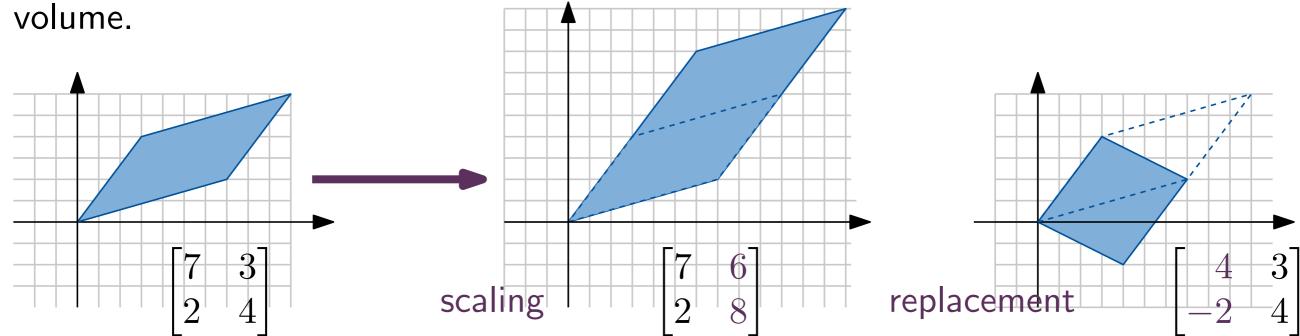
Why does the determinant change like this under row and column operations? Two views:

Either: It is a consequence of the expansion formula in Theorem 1;

Or: By thinking about the signed volume of the image of the unit cube under the associated linear transformation:

- 2. Interchanging columns changes the orientation of the image of the unit cube.
- 3. Scaling a column applies an expansion to one side of the image of the unit cube.

1. Column replacement rearranges the image of the unit cube without changing its



$$\det(A^T) = \det A.$$

**Theorem 6: Determinants are multiplicative:** For square matrices A and B:

$$\det(AB) = \det A \det B$$
.

In particular:

$$(let B = A^{-1})$$

$$\det(A^{-1}) = \frac{\det I_n}{\det A}$$

$$\det(cA) =$$

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 (where  $A$  is  $n \times n$ )

**Theorem 4: Invertibility and determinants**: A square matrix A is invertible if and only if  $\det A \neq 0$ .

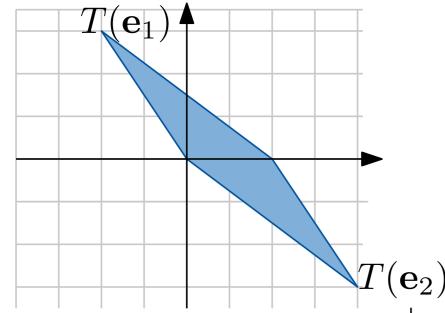
Proof 1: By the Invertible Matrix Theorem, A is invertible if and only if  $\operatorname{rref}(A)$  has n pivots. Row operations multiply the determinant by nonzero numbers. So  $\det A=0$  if and only if  $\det(\operatorname{rref}(A))=0$ , which happens precisely when  $\operatorname{rref}(A)$  has fewer than n pivots.

Proof 2: By the Invertible Matrix Theorem, A is invertible if and only if its columns span  $\mathbb{R}^n$ . Since the image of the unit cube is a subset of the span of the columns, this image has zero volume if the columns do not span  $\mathbb{R}^n$ .

So we can use determinants to test whether  $\{\mathbf v_1,\dots,\mathbf v_n\}$  in  $\mathbb R^n$  is linearly independent, or if it spans  $\mathbb R^n$ : it does when  $\det\begin{pmatrix} \begin{bmatrix} 1 & 1 & 1 \\ \mathbf v_1 & \dots & \mathbf v_n \\ 1 & 1 & 1 \end{pmatrix} \neq 0$ .

Application in MultiCal (MATH2205): determinants and volumes

**Example**: Find the area of the parallelogram with vertices  $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} -2 \\ 3 \end{bmatrix}$ ,  $\begin{bmatrix} 4 \\ -3 \end{bmatrix}$ ,  $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$ .

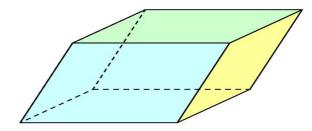


**Answer**: This parallelogram is the image of the unit square under a linear transformation T with

$$T(\mathbf{e}_1) = \begin{bmatrix} -2\\3 \end{bmatrix}$$
 and  $T(\mathbf{e}_2) = \begin{bmatrix} 4\\-3 \end{bmatrix}$ .

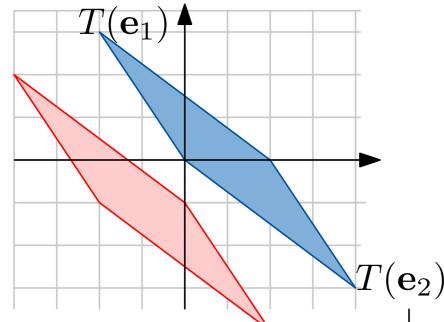
So area of parallelogram 
$$= \left| \det \begin{bmatrix} -2 & 4 \\ 3 & -3 \end{bmatrix} \right| \times \text{ area of unit square } = |-6| \cdot 1 = 6.$$

This works for any parallelogram where the origin is one of the vertices (and also in  $\mathbb{R}^3$ , for parallelopipeds).



Application in MultiCal (MATH2205): determinants and volumes

**Example**: Find the area of the parallelogram with vertices  $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} -2 \\ 3 \end{bmatrix}$ ,  $\begin{bmatrix} 4 \\ -3 \end{bmatrix}$ ,  $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$ .

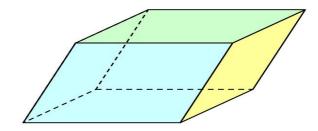


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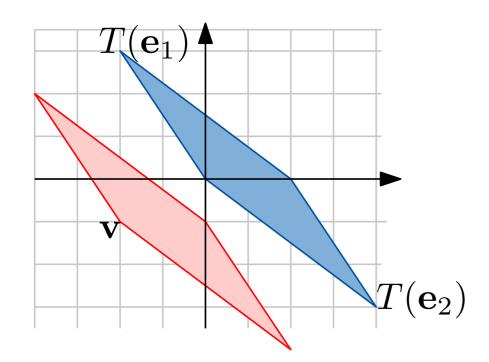
$$T(\mathbf{e}_2)$$
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This works for any parallelogram where the origin is one of the vertices (and also in  $\mathbb{R}^3$ , for parallelopipeds).



Application in MultiCal (MATH2205): determinants and volumes

**Example**: Find the area of the parallelogram with vertices  $\begin{vmatrix} -2 \\ -1 \end{vmatrix}, \begin{vmatrix} -4 \\ 2 \end{vmatrix}, \begin{vmatrix} 2 \\ -4 \end{vmatrix}, \begin{vmatrix} 0 \\ -1 \end{vmatrix}$ .



**Answer**: Use a translation to move one of the vertices of the parallelogram to the origin - this does not change the area.

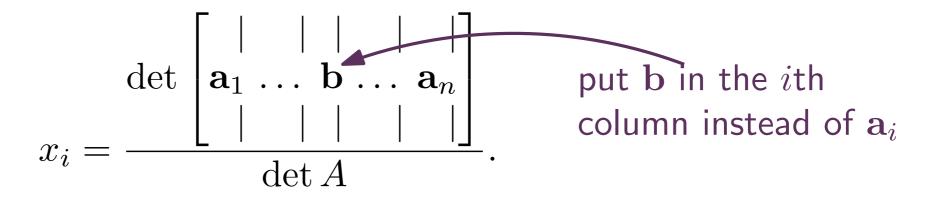
The formula for this translation function is  $x \mapsto x - v$ , where v is one of the vertices of the parallelogram.

Here, the vertices of the translated parallelogram are 
$$\begin{bmatrix} -2 \\ -1 \end{bmatrix} - \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
  $\begin{bmatrix} -4 \\ 2 \end{bmatrix} - \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$ ,  $\begin{bmatrix} 2 \\ -4 \end{bmatrix} - \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 4 \\ -3 \end{bmatrix}$ ,  $\begin{bmatrix} 0 \\ -1 \end{bmatrix} - \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$ .

So, by the previous example, the area of the parallelogram is 6.

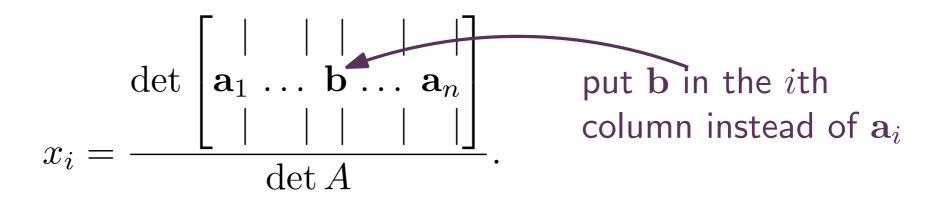
Application in ODE (MATH3405): determinants and linear systems

Cramer's rule: Let A be an invertible  $n \times n$  matrix with columns  $\mathbf{a}_1, \dots, \mathbf{a}_n$ . For any  $\mathbf{b}$  in  $\mathbb{R}^n$ , the unique solution  $\mathbf{x}$  of  $A\mathbf{x} = \mathbf{b}$  is given by



Application in ODE (MATH3405): determinants and linear systems

Cramer's rule: Let A be an invertible  $n \times n$  matrix with columns  $\mathbf{a}_1, \dots, \mathbf{a}_n$ . For any b in  $\mathbb{R}^n$ , the unique solution x of  $A\mathbf{x} = \mathbf{b}$  is given by



## **Proof**:

So

Applying Cramer's rule to  $\mathbf{b} = \mathbf{e}_i$  gives a formula for each entry of  $A^{-1}$  (see Theorem 8 in textbook; this formula is called the adjugate or classical adjoint).

The 
$$2 \times 2$$
 case of this formula is  $\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$ .

Cramer's rule is much slower than row-reduction for linear systems with actual numbers, but is useful for obtaining theoretical results.

**Example**: If every entry of A is an integer and  $\det A = 1$  or -1, then every entry of  $A^{-1}$  is an integer.

Proof: Cramer's rule tells us that every entry of  $A^{-1}$  is the determinant of an integer matrix divided by  $\det A$ . And the determinant of an integer matrix is an integer.

Exercise: using the fact  $\det AB = \det A \det B$ , prove the converse (if every entry of A and of  $A^{-1}$  is an integer, then  $\det A = 1$  or -1).