

Last time:  
Th 6.5.5

$$a) W_1 + \dots + W_k = \text{Span}(W_1 \cup \dots \cup W_k)$$

$$b) \text{ if } W_i = \text{Span}(A_i), \text{ then } W_1 + \dots + W_k = \text{Span}(A_1 \cup \dots \cup A_k)$$

Proof: a):  $W_1 + W_2 \supseteq \text{Span}(W_1 \cup W_2)$   
( $k=2$ )

$\because W_1 + W_2$  is a subspace and contains  $W_1$  and  $W_2$ , contains  $W_1 \cup W_2$ .

$$\text{Span}(W_1 \cup W_2) \supseteq W_1 + W_2$$

Take  $\alpha \in W_1 + W_2 \quad \therefore \alpha = \alpha_1 + \alpha_2$  with  $\alpha_i \in W_i$

$$\alpha_1 \in W_1 \subseteq W_1 \cup W_2 \subseteq \text{Span}(W_1 \cup W_2)$$

$$\alpha_2 \in W_2 \subseteq W_1 \cup W_2 \subseteq \text{Span}(W_1 \cup W_2)$$

$\text{Span}(W_1 \cup W_2)$  is closed under addition,  
so  $\alpha = \alpha_1 + \alpha_2 \in \text{Span}(W_1 \cup W_2)$ .



b. We show  $\text{Span}(W_1 \cup W_2) = \text{Span}(A_1 \cup A_2)$

$$\begin{aligned} \cdot \text{Span}(W_1 \cup W_2) &\supseteq \text{Span}(A_1 \cup A_2): \\ \because W_1 \cup W_2 &\supseteq A_1 \cup A_2 \end{aligned}$$

(use HW1 Q4c)

$$\cdot \text{Span}(A_1 \cup A_2) \supseteq \text{Span}(W_1 \cup W_2):$$

$\because \text{Span}(A_1 \cup A_2)$  is a subspace,  
so it's enough to show (by 6.3.8)

$$\text{Span}(A_1 \cup A_2) \supseteq W_1 \cup W_2.$$

$$\text{i.e. } \text{Span}(A_1 \cup A_2) \supseteq W_1 \text{ and } \supseteq W_2.$$

$$W_1 = \text{Span}(A_1) \subseteq \text{Span}(A_1 \cup A_2)$$

$\uparrow$

( $\because$  HW1 Q4c)

$$\because A_1 \subseteq A_1 \cup A_2$$

$$W_2 = \text{Span}(A_2) \subseteq \text{Span}(A_1 \cup A_2)$$

$$\because A_2 \subseteq A_1 \cup A_2$$

$$\therefore W_1 \cup W_2 \subseteq \text{Span}(A_1 \cup A_2). \quad \square$$

To see b) in a previous example:

$$V_1 + V_2 = \mathbb{R}^3$$

$$\text{Span}\{e_1, e_2\} + \text{Span}\{e_2, e_3\} = \text{Span}\{e_1, e_2, e_3\}$$

$$\text{Span}\{e_1, e_2\} + \text{Span}\{2e_2, e_3\} = \text{Span}\{e_1, e_2, 2e_2, e_3\}$$

Notice: if  $A_i$  is a basis of  $W_i$ ,  
then  $A_1 \cup A_2$  is NOT always  
a basis of  $W_1 + W_2$ .

" $\because$  of overlap in  $W_i$ "

( $\because$  to get a basis of  
 $W_1 + W_2$ , use casting-out  
algorithm)

More precisely:

$$\text{Th 6.5.6: } \dim(W_1 + W_2) = \dim W_1 + \dim W_2 - \dim(W_1 \cap W_2)$$

in example above:

$$\begin{aligned} \dim \mathbb{R}^3 &= \dim V_1 + \dim V_2 - \dim \text{Span}\{e_2\} \\ 3 &= 2 + 2 - 1 \end{aligned}$$

$$(\text{Compare: } |A_1 \cup A_2| = |A_1| + |A_2| - |A_1 \cap A_2|)$$



Note: how to write proofs about dimensions — see also RNT

- given  $\dim U = d$  — "let  $\{\alpha_1, \dots, \alpha_d\}$  be a basis of  $U$ "
- to prove  $\dim U = d$  — make a basis of  $U$  with  $d$  vectors.  
(or use theorems)

Proof: Let  $\dim(W_1 \cap W_2) = r$

$$\dim W_1 = r + s$$

$$\dim W_2 = r + t$$

(i.e. let  $s = \dim W_1 - \dim(W_1 \cap W_2) \geq 0$   
 $\because W_1 \cap W_2$  is a subspace of  $W_1$ .)

We will build a basis of  $W_1 + W_2$  with  $(r+s) + (r+t) - r = r+s+t$  vectors,  
based on  $\star$ .



Let  $\{\alpha_1, \dots, \alpha_r\}$  be a basis of  $W_1 \cap W_2$ .

Extend to  $\{\alpha_1, \dots, \alpha_r, \beta_1, \dots, \beta_s\}$  a basis of  $W_1$

$\{\alpha_1, \dots, \alpha_r, \gamma_1, \dots, \gamma_t\}$  a basis of  $W_2$ .

(this is possible  $\because \{\alpha_1, \dots, \alpha_r\}$  is linearly independent.)

We show that  $\mathcal{A} = \{\alpha_1, \dots, \alpha_r, \beta_1, \dots, \beta_s, \gamma_1, \dots, \gamma_t\}$  is a basis of  $W_1 + W_2$ .

- $\text{Span } \mathcal{A} = W_1 + W_2$  by 6.5.5b.
- check linear independence

Suppose  $a_1\alpha_1 + \dots + a_r\alpha_r + b_1\beta_1 + \dots + b_s\beta_s + c_1\gamma_1 + \dots + c_t\gamma_t = \vec{0}$

$$\textcircled{1} \quad \underbrace{c_1\gamma_1 + \dots + c_t\gamma_t}_{\in W_2} = \underbrace{-a_1\alpha_1 - \dots - a_r\alpha_r - b_1\beta_1 - \dots - b_s\beta_s}_{\in W_1}$$

$\therefore$  both sides are in  $W_1 \cap W_2$ .

$$\therefore c_1\gamma_1 + \dots + c_t\gamma_t = d_1\alpha_1 + \dots + d_r\alpha_r$$

$\therefore \{\alpha_1, \dots, \alpha_r\}$  spans  $W_1 \cap W_2$ .

$$c_1\gamma_1 + \dots + c_t\gamma_t - d_1\alpha_1 - \dots - d_r\alpha_r = \vec{0}$$

$\{\alpha_1, \dots, \alpha_r, \gamma_1, \dots, \gamma_t\}$  is a basis for  $W_2$ ,

$\therefore$  linearly independent  $\therefore c_1 = \dots = c_t = d_1 = \dots = d_r = 0$ .

Back to  $\textcircled{1}$ :  $\vec{0} = -a_1\alpha_1 - \dots - a_r\alpha_r - b_1\beta_1 - \dots - b_s\beta_s$

$\{\alpha_1, \dots, \alpha_r, \beta_1, \dots, \beta_s\}$  is a basis for  $W_1 \therefore$  linearly independent

$$\therefore a_1 = \dots = a_r = b_1 = \dots = b_s = 0 \quad \square$$