

Last time:

(6.3.6) $\text{span}(S)$ is the intersection of all subspaces containing S .

(6.3.8) i.e. if any subspace $W \supseteq S$, then $W \supseteq \text{span}(S)$.

(6.3.9) Equivalently,

$$\text{span}(S) = \left\{ \sum_{i=1}^n a_i \alpha_i \mid \begin{array}{l} \alpha_i \in S \\ a_i \in F \\ \text{some } n \in \mathbb{N} \end{array} \right\}$$

Proof of 6.3.9:

show $\text{span}(S) \subseteq U$: use 6.3.8

$U \supseteq S$ (in the sum, take $n=1$ and $a_i=1$)

and U is a subspace

$\therefore \vec{0} \in U$ (when $n=0$
- empty linear combination)

$$\subset \left(\sum_{i=1}^n a_i \alpha_i \right) + \sum_{i=1}^m b_i \beta_i$$

$$= \sum_{i=1}^n (ca_i) \alpha_i + \sum_{i=1}^m b_i \beta_i$$

a linear combination of vectors in S .

show $U \subseteq \text{span}(S)$

= intersection of all
subspaces containing S

\therefore enough to show that

$U \subseteq$ any subspace containing S ,
call this subspace W .

Take $\alpha \in U$

i.e. $\alpha = a_1 \alpha_1 + \dots + a_n \alpha_n$, $\alpha_i \in S$.

$W \supseteq S \ni \alpha_i$ and W is a subspace

\therefore closed under linear combinations

$\therefore \alpha \in W$.

§6.4 Bases

Def 6.4.1 $A \subseteq V$ is a basis of V if:

• A is linearly independent

• $\text{span}(A) = V$

Ex: standard basis of \mathbb{F}^n

$$= \left\{ e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, e_n = \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix} \right\}$$

standard basis of $P_{\leq n}(\mathbb{F}) = \{1, x, x^2, \dots, x^{n-1}\}$

standard basis of $\mathbb{F}[x] = \{1, x, x^2, \dots\}$

Standard basis of $M_{2,2}(\mathbb{F})$:

$$\left\{ \begin{array}{l} E_{11}^{1,1}, E_{11}^{1,2}, E_{11}^{2,1}, E_{11}^{2,2} \\ \left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right) \end{array} \right\}$$

and similarly for $M_{m,n}(\mathbb{F})$.

A basis of $W = \left\{ \begin{pmatrix} a \\ 2a \\ 0 \\ b \end{pmatrix} \mid a, b \in \mathbb{R} \right\}$

$$\text{is } \left\{ \begin{pmatrix} 1 \\ 2 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$a \begin{pmatrix} 1 \\ 2 \\ 0 \\ 0 \end{pmatrix} + b \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

More methods to find bases of subspaces later.

The point of bases is unique representation:

Prop 6.4.5 Let \mathcal{A} be a linearly

independent set. If

$$\alpha = a_1 \alpha_1 + \dots + a_n \alpha_n \text{ and}$$

$$\alpha = b_1 \beta_1 + \dots + b_m \beta_m \text{ with}$$

$\alpha_i, \beta_j \in \mathcal{A}$, α_i distinct, β_j distinct

$a_i, b_j \neq 0$, then, after reordering
 $m=n$, $\alpha_i = \beta_i$, $a_i = b_i$.

(And, if \mathcal{A} is a basis of V , i.e. also spans V , then

every $\alpha \in V$ can be written as a linear combination of vectors in \mathcal{A} .)

(see also 2207 week 8 p11)

Proof: reorder the α_i, β_j so that

$$\alpha_1 = \beta_1, \alpha_2 = \beta_2, \dots, \alpha_k = \beta_k,$$

$\alpha_{k+1}, \dots, \alpha_n, \beta_{k+1}, \dots, \beta_m$ are
all different. (k can be 0)

$$\text{Then } a_1 \alpha_1 + \dots + a_n \alpha_n = b_1 \beta_1 + \dots + b_m \beta_m.$$

$$(a_1 - b_1) \alpha_1 + \dots + (a_k - b_k) \alpha_k + a_{k+1} \alpha_{k+1} + \dots$$

$$+ a_n \alpha_n - b_{k+1} \beta_{k+1} - \dots - b_m \beta_m = \vec{0}.$$

\mathcal{A} is linearly independent \therefore it has no linear dependence relations

$$\therefore a_1 - b_1 = 0, \dots, a_k - b_k = 0, a_{k+1} = \dots = a_n = 0$$

$$b_{k+1} = \dots = b_m = 0.$$

But we assumed $a_i, b_j \neq 0$. so $k=n=m \therefore a_i = b_i$
 $\alpha_i = \beta_i \forall i$

How to find a basis 1: by taking a subset of
a spanning set.

The theory: Th 6.3.11 :

If α is a linear combination of ^{other} vectors in S , then $\text{span}(S) = \text{span}(S \setminus \{\alpha\})$.

\therefore given a spanning set $\{\alpha_1, \dots, \alpha_n\}$, remove one-by-one any α_i that is a linear combination of other α_j 's.

(see 2207 week 8 p10
"spanning set theorem")

In practice: (for subspaces of \mathbb{F}^n
for other spaces, use
coordinates)

remove ALL unnecessary α_i at the
same time, using casting out
algorithm: row reduce $\begin{pmatrix} | & & | \\ \alpha_1 & \dots & \alpha_n \\ | & & | \end{pmatrix}$

take the α_i whose columns have pivots:

Ex 3.6.4: $W = \text{Span} \left\{ \underbrace{\begin{pmatrix} 1 \\ 0 \\ -1 \\ 1 \end{pmatrix}}_{\alpha_1}, \underbrace{\begin{pmatrix} 0 \\ 1 \\ 2 \\ -1 \end{pmatrix}}_{\alpha_2}, \underbrace{\begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix}}_{\alpha_3}, \underbrace{\begin{pmatrix} -1 \\ 1 \\ 1 \\ 2 \end{pmatrix}}_{\alpha_4}, \underbrace{\begin{pmatrix} -2 \\ 3 \\ 2 \\ 7 \end{pmatrix}}_{\alpha_5} \right\}$

$$\begin{pmatrix} 1 & 0 & 1 & -1 & -2 \\ 0 & 1 & 1 & 1 & 3 \\ -1 & 2 & 1 & 1 & 2 \\ 1 & -1 & 0 & 2 & 7 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 & -1 & -2 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

echelon form

$\therefore \{\alpha_1, \alpha_2, \alpha_4\}$ is a basis for W .

Proof of 6.3.11

$$\text{span}(S \setminus \{\alpha\}) \subseteq \text{span}(S)$$

(use 6.3.8) $\text{span}(S)$ is a subspace.

$$\text{span}(S) \supseteq S \supseteq S \setminus \{\alpha\}.$$

$$\text{span } S \subseteq \text{span}(S \setminus \{\alpha\}). \quad (\text{use 6.3.8})$$

$\text{span}(S \setminus \{\alpha\})$ is a subspace and

$$\text{span}(S \setminus \{\alpha\}) \supseteq S \setminus \{\alpha\}. \quad \text{and}$$

$$\text{span}(S \setminus \{\alpha\}) \ni \alpha \quad \therefore \alpha = a_1 \alpha_1 + \dots + a_n \alpha_n$$

with $\alpha_i \in S \setminus \{\alpha\}$.

$$\subseteq \text{span}(S \setminus \{\alpha\})$$

and $\text{span}(S \setminus \{\alpha\})$ is closed under
linear combinations.

(Different proof using Th. 6.3.9
— substitute for α in the linear combination)