§8.1: Diagonal and Triangular form: Review/Update: Let och(V,V), A=[o] (=[o])

Def: A is similar to B if I invertible P such that  $A = PBP^{-1}$ i.e. I basis B such that  $[\sigma]_B = B$ 

Def: A is diagonalisable if 3 invertible P, diagonal D with A=PDP". Def 8.1.2: (if dim  $V < \infty$ )  $\sigma$  is diagonalisable if  $\exists$  basis B such that  $[\sigma]_B = D$ , a diagonal matrix

i.e. Let 
$$B = \{p_1, \dots, p_n\}$$
, then  $[\sigma]_B = ([\sigma(\beta)]_B \dots [\sigma(\beta)]_B) = (\lambda_1, \dots, \lambda_n)$ 

first column:  $[\sigma(\beta_i)]_B = \begin{pmatrix} \lambda_i \\ 0 \end{pmatrix}$   $\longrightarrow \sigma(\beta_i) = \lambda_i \beta_i + O\beta_2 + \cdots + O\beta_n$ Similar in other columns:  $\sigma(\beta_i) = \lambda_i \beta_i$ 

o(Bi)=lißi for some liEF.

of is a A-eigenvector of A if Ax=>x and x +3.

 $\mathcal{E}_{\lambda} = Nul(A-\lambda I)$  is the  $\lambda$ -eigenspace of A.

Def 8.1.2 B is A-eigenvector of or if o(p)= 2 p and p + 0 Ex = ker (o-21) is the 2-eigenspace of o. Note: B is a 2-eigenvector of o = [B] is a 2-eigenvector of A=[o]A if B is an eigenvector, then  $\sigma(Spon SB3) \subseteq Spon SB3.$ 

To find eigenvectors, first find eigenvalues: solve the characteristic polynomial  $X_{A}(x) = det(A-xI)$ 

Def 8.1.1: The characteristic polynomial of o is  $\chi_{\sigma}(x) = dt([\sigma]_{A} - xI)$  for any basis x (it does not depend on A: see 2207 week 10 p31)

Def: A is triangularisable if I invotible P such that P'AP is upper-triangular or is triangularisable if I basis B such that [0] B is upper-triangular. i.e.  $[\sigma(\beta_n)]_{\mathcal{B}} \dots [\sigma(\beta_n)]_{\mathcal{B}} = \begin{pmatrix} \lambda_1 & \lambda_2 & \lambda_1 \\ \lambda_2 & \lambda_2 \end{pmatrix}$ first column:  $\sigma(\beta_i) = \lambda, \beta, + 0\beta_2 + \cdots + 0\beta_n \in Span \{\beta_i\}.$ Second column:  $\sigma(\beta_2) = *\beta_1 + \lambda_2 \beta_2 + O\beta_3 + \cdots O\beta_n \in Span \{\beta_1, \beta_2\}$ Similarly:  $O(\beta_K) = *\beta_1 + \dots + *\beta_{k-1} + \lambda_k \beta_k + O\beta_{k+1} + \dots + O\beta_n \in Span \{\beta_1, \beta_2, \dots, \beta_k\}$  $(Span \{\beta_1,...,\beta_k\}) = Span \{\sigma(\beta_1),...,\sigma(\beta_k)\} \subseteq Span \{\beta_1,...,\beta_k\} \quad (:each \sigma(\beta_i) \in Span \{\beta_1,...,\beta_k\} \text{ for } i \in k\}$   $i.e. Span \{\beta_1,...,\beta_k\} \text{ is an invariant subspace.}$  Def 8.1.4. A subspace W=V is invariant under of if  $\sigma(W) \subseteq W$ . Advantages over diagonalisation: . The eigenvalues are on the diagonal. · Schur Theorem: every linear transformation over ( is triangularisable (orthogonally, see \$10.4).

(for other fields, e.g. {0,1} = Z2 - use a bigger field where all polynomials have solutions. — find an eigenvector,

· Triangularisation is more stable on computers