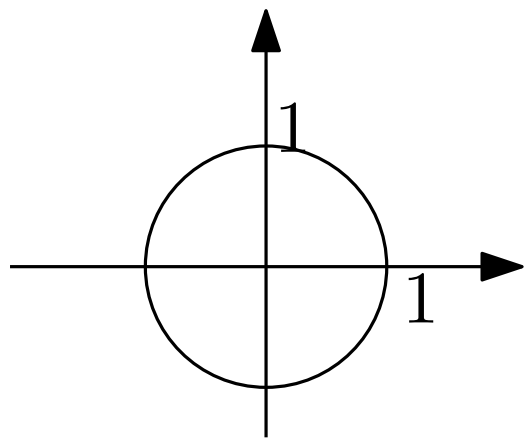


## §3.1-3.3: Determinants

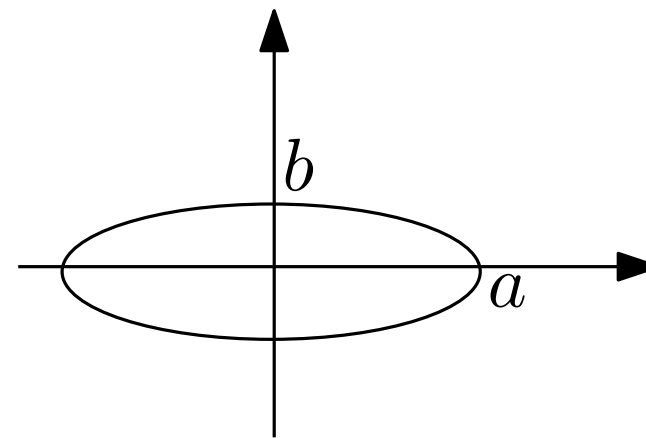
Conceptually, the determinant  $\det A$  of a square  $n \times n$  matrix  $A$  is the **signed area/volume scaling factor** of the linear transformation  $T(\mathbf{x}) = A\mathbf{x}$ , i.e.:

- For any region  $S$  in  $\mathbb{R}^n$ , the volume of its image  $T(S)$  is  $|\det A|$  multiplied by the original volume of  $S$ ,
- If  $\det A > 0$ , then  $T$  does not change “orientation”. If  $\det A < 0$ , then  $T$  changes “orientation”.

**Example:** Area of ellipse =  $\det \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \times \text{area of unit circle} = ab\pi$ .



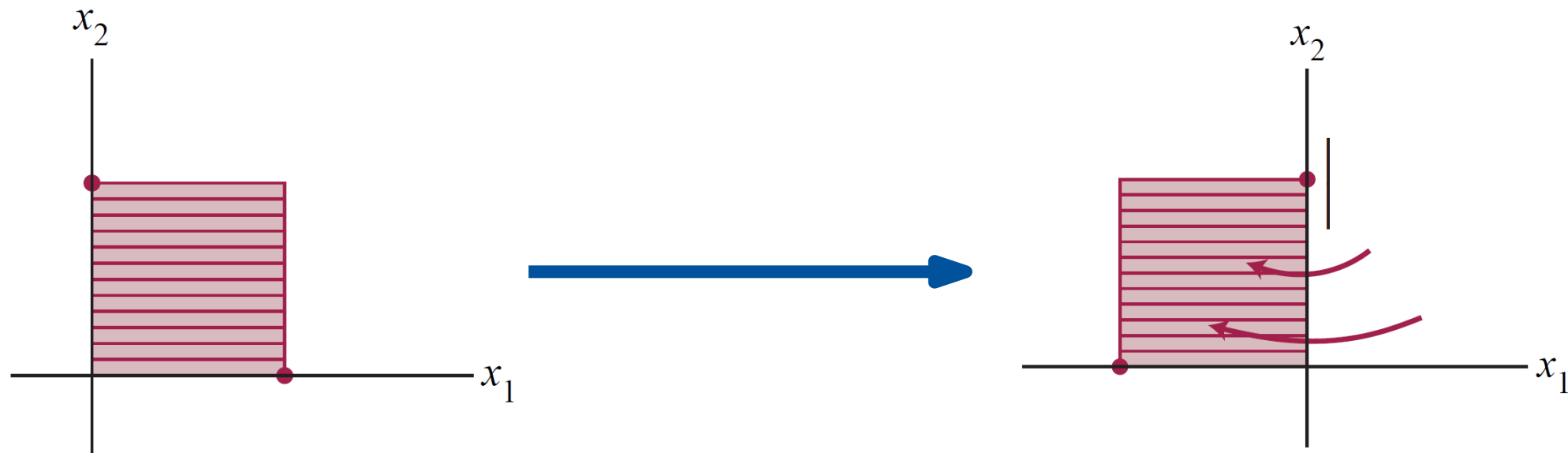
$$\mathbf{x} \mapsto \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \mathbf{x}$$



This idea is useful in multivariate calculus.

Formula for  $2 \times 2$  matrix:  $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$ .

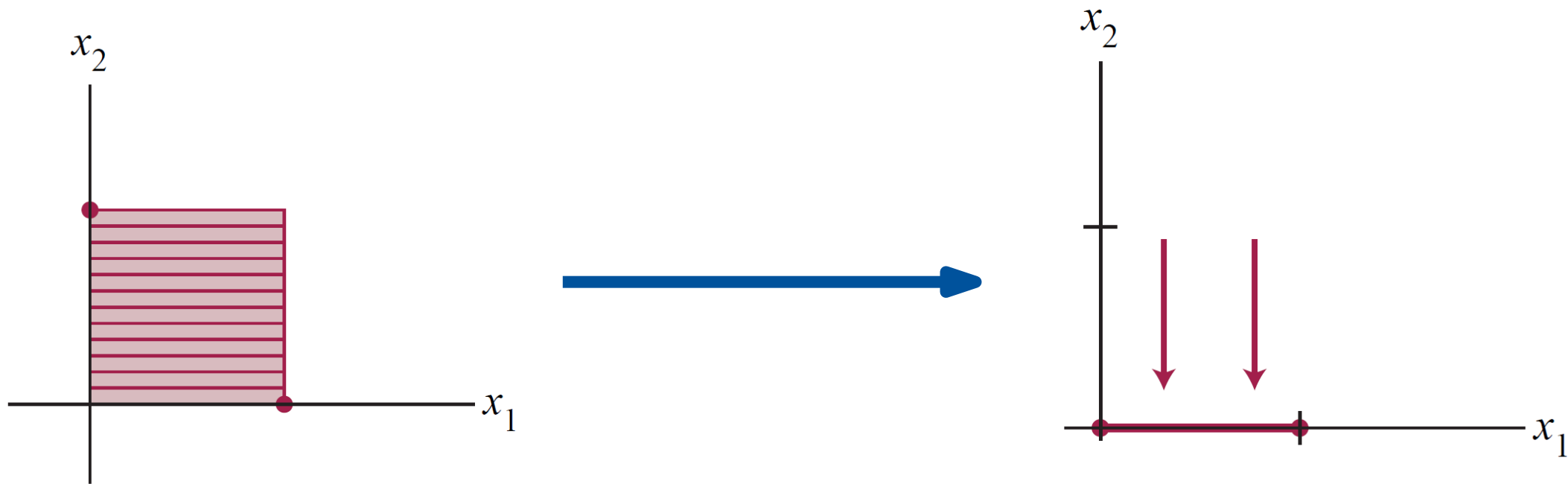
**Example:** The standard matrix for reflection through the  $x_2$ -axis is  $\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$ .  
Its determinant is  $-1 \cdot 1 - 0 \cdot 0 = -1$ : reflection does not change area, but changes orientation.



Exercise: Guess what the determinant of a rotation matrix is, and check your answer.

Formula for  $2 \times 2$  matrix:  $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$ .

**Example:** The standard matrix of projection onto the  $x_1$ -axis is  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ . Its determinant is  $1 \cdot 0 - 0 \cdot 0 = 0$ . Projection sends the unit square to a line, which has zero area.



**Theorem:**  $A$  is invertible if and only if  $\det A \neq 0$ .

How the determinant changes under row operations:

1. Replacement: add a multiple of one row to another row.  $R_i \rightarrow R_i + cR_j$   
determinant does not change.
2. Interchange: interchange two rows.  $R_i \rightarrow R_j, R_j \rightarrow R_i$   
determinant changes sign.
3. Scaling: multiply all entries in a row by a nonzero constant.  $R_i \rightarrow cR_i, c \neq 0$   
determinant scales by a factor of  $c$ .

To help you remember:

$$\begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 1, \quad \begin{vmatrix} 1 & c \\ 0 & 1 \end{vmatrix} = 1, \quad \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} = -1, \quad \begin{vmatrix} c & 0 \\ 0 & 1 \end{vmatrix} = c.$$

Because we can compute the determinant by expanding down columns instead of along rows, the same changes hold for “column operations”.

1. Replacement:  $R_i \rightarrow R_i + cR_j$  determinant does not change.
2. Interchange:  $R_i \rightarrow R_j, R_j \rightarrow R_i$  determinant changes sign.
3. Scaling:  $R_i \rightarrow cR_i, c \neq 0$  determinant scales by a factor of  $c$ .

Usually we compute determinants using a mixture of “expanding across a row or down a column with many zeroes” and “row reducing to a triangular matrix”.

### Example:

$$\begin{aligned}
 & \begin{vmatrix} 2 & 3 & 4 & 6 \\ 0 & 5 & 0 & 0 \\ 5 & 5 & 6 & 7 \\ 7 & 9 & 6 & 10 \end{vmatrix} \xrightarrow{\text{factor out 2 from } R_1} 5 \begin{vmatrix} 2 & 4 & 6 \\ 5 & 6 & 7 \\ 7 & 6 & 10 \end{vmatrix} \xrightarrow{\begin{matrix} R_2 \rightarrow R_2 - 5R_1 \\ R_3 \rightarrow R_3 - 7R_1 \end{matrix}} 5 \cdot 2 \begin{vmatrix} 1 & 2 & 3 \\ 5 & 6 & 7 \\ 7 & 6 & 10 \end{vmatrix} \\
 & \xrightarrow{\begin{matrix} R_2 \rightarrow R_2 - 5R_1 \\ R_3 \rightarrow R_3 - 7R_1 \end{matrix}} 5 \cdot 2 \begin{vmatrix} 1 & 2 & 3 \\ 0 & -4 & -8 \\ 0 & -8 & -11 \end{vmatrix} \xrightarrow{\text{factor out -4 from } R_2} 5 \cdot 2 \cdot (-4) \begin{vmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & -8 & -11 \end{vmatrix} \\
 & \xrightarrow{R_3 \rightarrow R_3 + 8R_2} 5 \cdot 2 \cdot (-4) \begin{vmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 5 \end{vmatrix} = 5 \cdot 2 \cdot (-4) \cdot 1 \cdot 1 \cdot 5 = -200.
 \end{aligned}$$

1. Replacement:  $R_i \rightarrow R_i + cR_j$  determinant does not change.
2. Interchange:  $R_i \rightarrow R_j, R_j \rightarrow R_i$  determinant changes sign.
3. Scaling:  $R_i \rightarrow cR_i, c \neq 0$  determinant scales by a factor of  $c$ .

**Useful fact:** If two rows of  $A$  are multiples of each other, then  $\det A = 0$ .

**Proof:** Use a replacement row operation to make one of the rows into a row of zeroes, then expand along that row.

**Example:**

$$R_3 \rightarrow R_3 - 2R_1$$

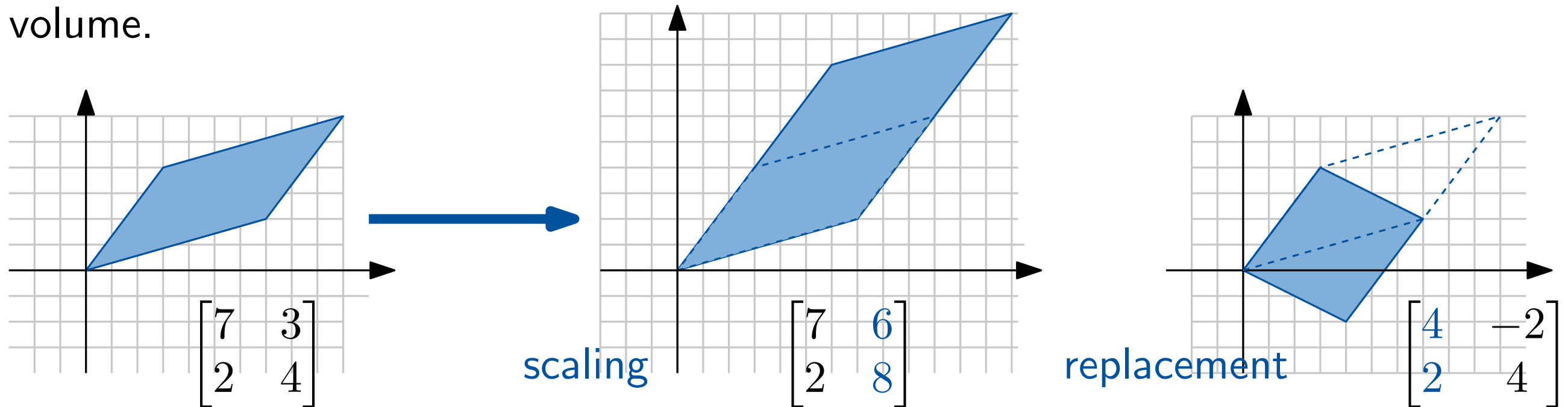
$$\begin{vmatrix} 1 & 3 & 4 \\ 5 & 9 & 3 \\ 2 & 6 & 8 \end{vmatrix} = \begin{vmatrix} 1 & 3 & 4 \\ 5 & 9 & 3 \\ 0 & 0 & 0 \end{vmatrix} = 0 \begin{vmatrix} 3 & 4 \\ 9 & 3 \end{vmatrix} - 0 \begin{vmatrix} 1 & 4 \\ 5 & 3 \end{vmatrix} + 0 \begin{vmatrix} 1 & 3 \\ 5 & 9 \end{vmatrix} = 0.$$

Why does the determinant change like this under row and column operations? Two views:

Either: It is a consequence of the expansion formula in Theorem 1;

Or: By thinking about the signed volume of the image of the unit cube under the associated linear transformation:

2. Interchanging columns changes the orientation of the image of the unit cube.
3. Scaling a column applies an expansion to one side of the image of the unit cube.
1. Column replacement rearranges the image of the unit cube without changing its volume.



Properties of the determinant:

$$\det(A^T) = \det A.$$

**Theorem 6: Determinants are multiplicative:**

$$\det(AB) = \det A \det B.$$

In particular:

$$\det(A^{-1}) = \frac{1}{\det A}.$$

$$\det(cA) = c^n \det A,$$



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In particular:

$$\det(A^{-1}) = \frac{I_n}{\det A} = \frac{1}{\det A}, \quad \det(cA) = \det \begin{bmatrix} c & & 0 \\ & \ddots & \\ 0 & & c \end{bmatrix} \det A = c^n \det A.$$

Properties of the determinant:

**Theorem 4: Invertibility and determinants:** A square matrix  $A$  is invertible if and only if  $\det A \neq 0$ .

Proof 1: By the Invertible Matrix Theorem,  $A$  is invertible if and only if  $\text{rref}(A)$  has  $n$  pivots. Row operations multiply the determinant by nonzero numbers. So  $\det A = 0$  if and only if  $\det(\text{rref}(A)) = 0$ , which happens precisely when  $\text{rref}(A)$  has fewer than  $n$  pivots.

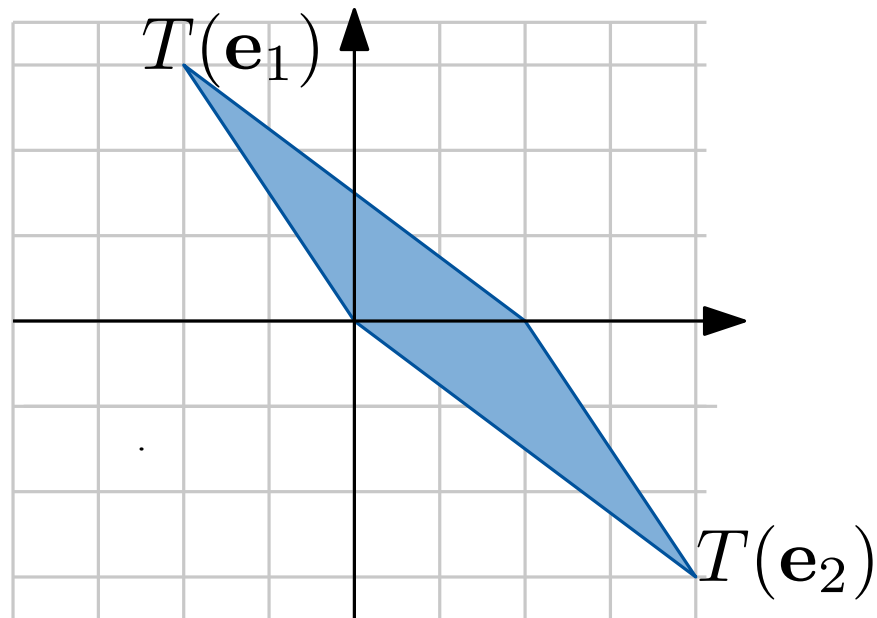
Proof 2: By the Invertible Matrix Theorem,  $A$  is invertible if and only if its columns span  $\mathbb{R}^n$ . Since the image of the unit cube is a subset of the span of the columns, this image has zero volume if the columns do not span  $\mathbb{R}^n$ .

So we can use determinants to test whether  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  in  $\mathbb{R}^n$  is linearly

independent, or if it spans  $\mathbb{R}^n$ : it does when  $\det \begin{pmatrix} \left[ \begin{array}{ccc} | & | & | \\ \mathbf{v}_1 & \dots & \mathbf{v}_n \\ | & | & | \end{array} \right] \end{pmatrix} \neq 0$ .

Other applications: finding volumes of regions with determinants

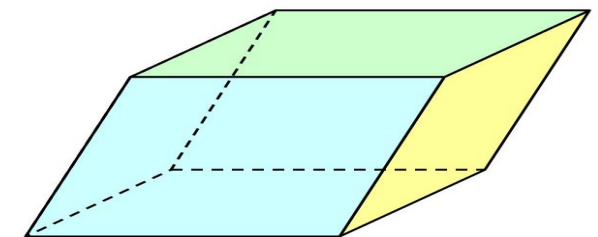
**Example:** Find the area of the parallelogram with vertices  $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} -2 \\ 3 \end{bmatrix}$ ,  $\begin{bmatrix} 4 \\ -3 \end{bmatrix}$ ,  $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$ .



**Answer:** This parallelogram is the image of the unit square under a linear transformation  $T$  with  $T(\mathbf{e}_1) = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$  and  $T(\mathbf{e}_2) = \begin{bmatrix} 4 \\ -3 \end{bmatrix}$ .

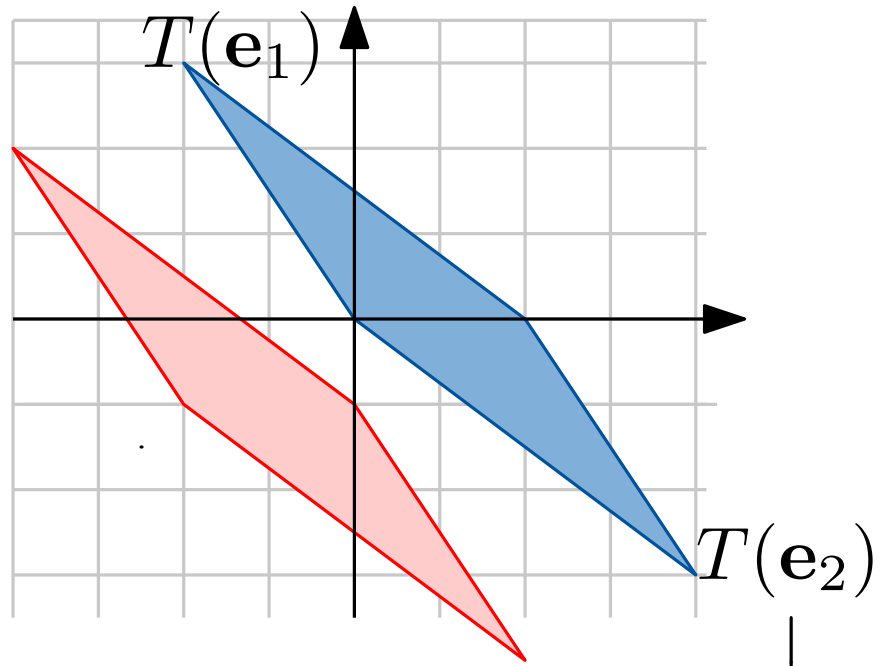
So area of parallelogram =  $\left| \det \begin{bmatrix} -2 & 4 \\ 3 & -3 \end{bmatrix} \right| \times \text{area of unit square} = |-12| \cdot 1 = 12$ .

This works for any parallelogram where the origin is one of the vertices (and also in  $\mathbb{R}^3$ , for parallelopipeds).



Other applications: finding volumes of regions with determinants

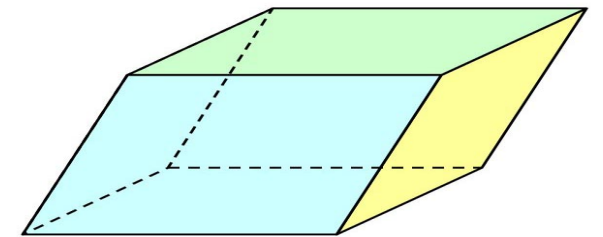
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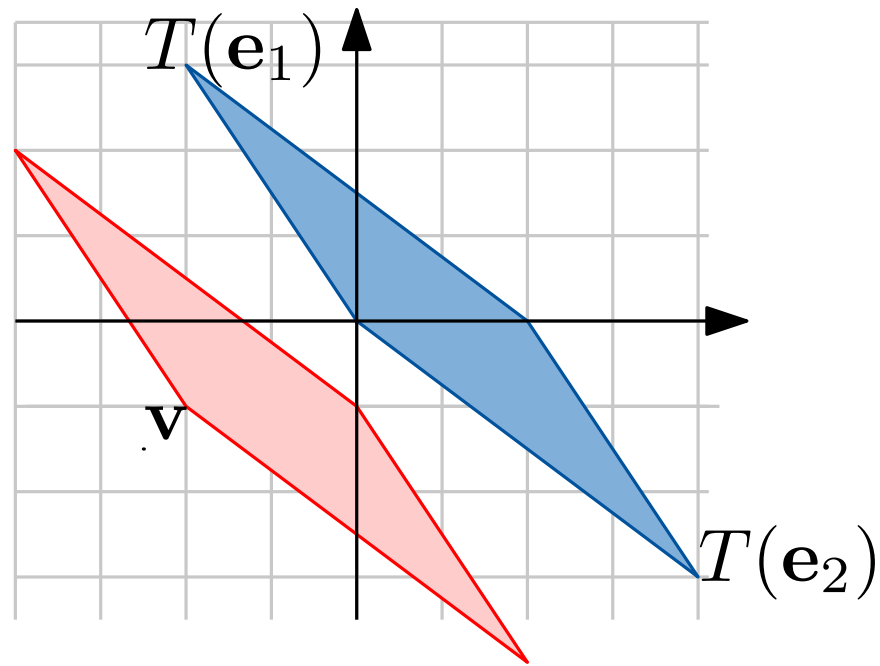
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Other applications: finding volumes of regions with determinants

**Example:** Find the area of the parallelogram with vertices  $\begin{bmatrix} -2 \\ -1 \end{bmatrix}$ ,  $\begin{bmatrix} -4 \\ 2 \end{bmatrix}$ ,  $\begin{bmatrix} 2 \\ -4 \end{bmatrix}$ ,  $\begin{bmatrix} 0 \\ -1 \end{bmatrix}$ .



**Answer:** Use a translation to move one of the vertices of the parallelogram to the origin - this does not change the area.


The formula for this translation function is  $\mathbf{x} \mapsto \mathbf{x} - \mathbf{v}$ , where  $\mathbf{v}$  is one of the vertices of the parallelogram.

Here, the vertices of the translated parallelogram are  $\begin{bmatrix} -2 \\ -1 \end{bmatrix} - \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} -4 \\ 2 \end{bmatrix} - \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$ ,  $\begin{bmatrix} 2 \\ -4 \end{bmatrix} - \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 4 \\ -3 \end{bmatrix}$ ,  $\begin{bmatrix} 0 \\ -1 \end{bmatrix} - \begin{bmatrix} -2 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$ .

So, by the previous example, the area of the parallelogram is 12.

Other applications: solving linear systems using determinants

**Cramer's rule:** Let  $A$  be an invertible  $n \times n$  matrix with columns  $\mathbf{a}_1, \dots, \mathbf{a}_n$ . For any  $\mathbf{b}$  in  $\mathbb{R}^n$ , the unique solution  $\mathbf{x}$  of  $A\mathbf{x} = \mathbf{b}$  is given by

$$x_i = \frac{\det \begin{bmatrix} | & | & | & | & | \\ \mathbf{a}_1 & \dots & \mathbf{b} & \dots & \mathbf{a}_n \\ | & | & | & | & | \end{bmatrix}}{\det A}.$$


put  $\mathbf{b}$  in the  $i$ th column instead of  $\mathbf{a}_i$

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put  $\mathbf{b}$  in the  $i$ th column instead of  $\mathbf{a}_i$

**Proof:**

$$A \begin{bmatrix} | & | & | & | & | \\ \mathbf{e}_1 & \dots & \mathbf{x} & \dots & \mathbf{e}_n \\ | & | & | & | & | \end{bmatrix} = \begin{bmatrix} | & | & | & | & | \\ A\mathbf{e}_1 & \dots & A\mathbf{x} & \dots & A\mathbf{e}_n \\ | & | & | & | & | \end{bmatrix} = \begin{bmatrix} | & | & | & | & | \\ \mathbf{a}_1 & \dots & \mathbf{b} & \dots & \mathbf{a}_n \\ | & | & | & | & | \end{bmatrix}.$$

So

$$\det A \det \begin{bmatrix} | & | & | & | & | \\ \mathbf{e}_1 & \dots & \mathbf{x} & \dots & \mathbf{e}_n \\ | & | & | & | & | \end{bmatrix} = \det \begin{bmatrix} | & | & | & | & | \\ \mathbf{a}_1 & \dots & \mathbf{b} & \dots & \mathbf{a}_n \\ | & | & | & | & | \end{bmatrix}.$$

this is  $x_i$  - expand along  $i$ th row

Applying Cramer's rule to  $\mathbf{b} = \mathbf{e}_i$  gives a formula for each entry of  $A^{-1}$  (see Theorem 8 in textbook; this formula is called the adjugate or classical adjoint).

The  $2 \times 2$  case of this formula is 
$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}.$$

Cramer's rule is much slower than row-reduction for linear systems with actual numbers, but is useful for obtaining theoretical results.

**Example:** If every entry of  $A$  is an integer and  $\det A = 1$  or  $-1$ , then every entry of  $A^{-1}$  is an integer.

Proof: Cramer's rule tells us that every entry of  $A^{-1}$  is the determinant of an integer matrix divided by  $\det A$ . And the determinant of an integer matrix is an integer.

Exercise: using the fact  $\det AB = \det A \det B$ , prove the converse (if every entry of  $A$  and of  $A^{-1}$  is an integer, then  $\det A = 1$  or  $-1$ ).



## Advanced application of Cramer's rule - Lagrange interpolation:

3. Find a polynomial of degree 3 (a polynomial of the form  $f(t) = a + bt + ct^2 + dt^3$ ) whose graph passes through the points  $(0, 1)$ ,  $(1, 0)$ ,  $(-1, 0)$  and  $(2, -15)$ .

The general problem: we want to find  $f(t) = a + bt + ct^2 + dt^3$  such that  $f(x_i) = y_i$  for  $i = 1, 2, 3, 4$  - i.e. we want to solve

$$\begin{bmatrix} 1 & x_1 & x_1^2 & x_1^3 \\ 1 & x_2 & x_2^2 & x_2^3 \\ 1 & x_3 & x_3^2 & x_3^3 \\ 1 & x_4 & x_4^2 & x_4^3 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}.$$

There is a general formula for the solution using Cramer's rule.