Last time: (6.3.6) span (S) is the intersection of all subspaces containing S. (6.3.8) i.e. if any subspace W≥S then W= spon(S). (6.3.9) Equivalently. Span(S)=) = a; d; di∈S a; EF some net

Proof of 6.3.9: show span (S) & U: use 6.3.8 UZS (in the sum, take nel and a, el) and 0 is a subspace : BEU (when n=0 - empty linear combination) c (& a. x.) + & b. B. = Elen (cai) din Elbisi a linear combination of vartors in 5,

show U = spon (s) = intersection of all subspaces containing S i. erough to show that Us any subspace containing S, call this subspace W. lake del i.e. d=a,d,+...+andn, d,es. WZS 3 0%; and W is a subspace i. closed under linear combinations i. KEW.

36.4 Bases Def 6.4.1 ASV is a basis of V if: · A is linearly independent Ex: standard basis of Fr $= \left\{ e_{i} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, e_{z} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \dots, e_{n} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\}$ standard basis of P=(#)=[1,x,2, ,,x"] standard basis of IF [-2] = {1, x, x2, ...}

Standard basis of M2,2 (IF): $\begin{bmatrix} E'' & E'^2 & E^{2,1} & E^{2,2} \\ II & II & II \end{bmatrix}$ (00), (01), (00), (00)and similarly for Mm,n (7). $is \left\{ \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$ thools to find subspaces later.

The point of bases is unique representation: Prop 6.4.5 Let A be a linearly independent set. If $d = a, d, + \dots + and n$ and $d = b, \beta, + \dots + b_m \beta_m$ with $\alpha_i, \beta_j \in \mathcal{A}$, α_i distinct, β_j distinct a; b; \$0, then, after reordering m=n, $\alpha_i=\beta_i$, $\alpha_i=b_i$. (And, if X is a basis of V, i.e. also spans V, then

every devicen be written as a linear combination of vectors in 1.)

see also 2207 week 8 p11) Proof: reorder the di, B; so that 01=B1, d2=B2, ..., dx=Bx, dun, ..., dn, Bru, ..., Bm are all different. (k can be 0) Then a, x, + ... + and n = b, B, + ... + bm Bm. (a,-b,) x,+...+ (ax-bx) xx + axy xxxx... .. + andn-bu, Brun-bm Bm = 0.

A is linearly independent in it has no linear dependence relations : a,-b,=0, ..., ax-bx=0, ax====an=0 bx1=...=bm=0. But we assumed ai, b; \$0. so k=n=m :. a;=bi d;=B; yi How to find a basis 1: by taking a subset of a spanning set.

The theory: Th 6.3.11: If & is a linear combination of vectors in S, then spon(S) = spon(S/Sas) .. given a spanning set {d,...,dn}, remove one-by-one any X: that is a linear combination of other x;'s. See 23007 mæl 8 210 "Spanning set theorem")

In practice: (for subspaces of IF? for other spaces, use coordinates) remove ALL unnecessary di at the same time, using casting out algorithm: row reduce (x, ... x,

$$\begin{array}{c|cccc}
 & 1 & 1 & 1 & 2 \\
 & 1 & 2 & 1 & 1 & 2 \\
 & 1 & 2 & 1 & 1 & 2 \\
 & 1 & -1 & 0 & 2 & 7
\end{array}$$

$$\begin{array}{c|ccccc}
 & 1 & 1 & 1 & 3 \\
 & 1 & 2 & 1 & 1 & 2 \\
 & 1 & -1 & 0 & 2 & 7
\end{array}$$

$$\begin{array}{c}
 & 1 & 1 & 1 & 3 \\
 & 0 & 0 & 0 & 0 & 0 \\
 & 0 & 0 & 0 & 0 & 0 \\
 & 0 & 0 & 0 & 0 & 0 \\
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span S = span (S12x3). (use 6.3.8) span (S) {x3) is a subspace and span(5) 25\ 2x3. and Span (S) {23}) > 2 ... x = a, d, +... + andn with x; es/sas. Spam(S\{\alpha\}) and span (S) [xi]) is closed under linear combinations. Different proof using Th. 6.39 1 — substitute for x in the linear combination)