GMM FOR DUMMIES

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1. Introduction

1.1. **Background.** Suppose that we have a parameter vector $\theta = (\theta_1, ..., \theta_p)$ with p components. For $1 \leq j \leq p$, define the jth moment

$$\mathbb{E}_{\theta}[X^j] = \int x^j dF_{\theta}(x) \equiv \alpha_j(\theta)$$

Similarly, define the j^{th} sample moment

$$\hat{\alpha}_j = \frac{1}{n} \sum_{i=1}^{n} X_i^j$$

1.2. The Idea behind the Generalized Method of Moments. GMM is based off of the idea that there exists a *true* parameter $\theta_0 \in \Theta$ that uniquely sets a K-dimensional vector of population moments to zero, i.e.

$$\mathbb{E}[g(X_i; \theta_0)] = 0$$

where our data are $\{X_i\}_{i=1}^N$, and we have p parameters and $K \geq p$ moment conditions.

We say that $\hat{\theta}_{mm}$ is a *Method of Moments estimator* if it is the value of θ such that

$$\alpha_1(\hat{\theta}_{mm}) = \hat{\alpha}_1, \dots, \alpha_p(\hat{\theta}_{mm}) = \hat{\alpha}_p$$

Simply put, we find $\hat{\theta}_{mm}$ by setting population moments equal to the corresponding sample moments.

We say that $\hat{\theta}$ is a *GMM estimator* if it solves the following problem:

$$\hat{\theta} = \underset{\theta}{\arg \min} Q_n(\theta)$$

$$= \underset{\theta}{\arg \min} g_n(\theta)' \hat{W} g_n(\theta)$$

where $g_n(\theta) = \frac{1}{n} \sum_{i=1}^{n} g(X_i; \theta)$ is our sample objective function and \hat{W} is a $K \times K$ positive-semidefinite matrix that assigns a weight to each moment condition, telling the problem how much to penalize the violation of one moment condition relative to another.

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The corresponding population objective function is

$$Q(\theta) = g(\theta)'Wg(\theta)$$

where $g(\theta) = \mathbb{E}[g(X_t; \theta)]$ and W is the plim of \hat{W} .

2. Familiar Examples

In some cases, we can think of $\mathbb{E}[g(X_i;\theta_0)] = 0$ as being a FOC for the minimization of some objective function $m(X_t;\theta)$. Informally, the GMM estimator makes sample moment conditions as "true" as possible.

2.1. **Normal Distribution.** Suppose we have data $\{X_1, ..., X_n\} \sim \mathcal{N}(\mu, \sigma^2)$. Then, $\mathbb{E}[X] = \mu$ and $\mathbb{V}(X) = \sigma^2$. We can rewrite the variance so that we have it as a function of the second moment and the first moment, i.e. $\mathbb{V}(X) = \mathbb{E}[X^2] - \mathbb{E}[X]^2 \implies \mathbb{E}[X^2] = \mathbb{V}(X) + \mathbb{E}[X]^2$. Therefore, we have two *population* moment conditions:

$$\mathbb{E}[X] = \mu$$
$$\mathbb{E}[X^2] = \sigma^2 + \mu^2$$

Now let's write their *sample* analogues:

$$\frac{1}{n} \sum_{i}^{n} X_{i} = \hat{\mu}$$

$$\frac{1}{n} \sum_{i}^{n} X_{i}^{2} = \hat{\sigma}^{2} + \hat{\mu}^{2}$$

We have two equations in two unknowns $(\hat{\mu}, \hat{\sigma}^2)$, and as we probably already know, the solution to this system is

$$\hat{\mu} = \frac{1}{n} \sum_{i}^{n} X_{i} \equiv \bar{X}_{n}$$

$$\hat{\sigma}^{2} = \frac{1}{n} \sum_{i}^{n} (X_{i} - \bar{X}_{n})^{2}$$

We can also put this in our $g(\cdot)$ notation:

$$g_n^1(X_1, ..., X_n; \mu, \sigma) = \left(\frac{1}{n} \sum_{i=1}^n X_i\right) - \mu$$

$$g_n^2(X_1, ..., X_n; \mu, \sigma) = \left(\frac{1}{n} \sum_{i=1}^n X_i^2\right) - \left(\frac{1}{n} \sum_{i=1}^n X_i\right)^2 - \sigma^2$$

2.2. OLS estimator: Bivariate case. With our OLS estimator, the model is

$$y_i = x_i \beta + \varepsilon_i$$

For our conditional independence assumption to hold and our OLS estimator to be consistent, we need orthogonality between β and ε_i , i.e. the familiar exogeneity condition $\mathbb{E}[x_i'\varepsilon_i]$. To use GMM, we want to write this condition in terms of things we can observe:

$$\mathbb{E}[x_i'(y_i - x_i\beta)] = 0$$

$$\implies g(y_i, x_i, \beta) = x_i'(y_i - x_i\beta)$$

3. Unfamiliar Examples

- **3.1.** Suppose we have two samples, A and B. Observations in sample A are assumed to have been drawn from a distribution with a mean equal to μ . Observations in sample B are assumed to have been drawn from a distribution with a mean equal to $\mu+5$. All observations are uncorrelated. The sample means are $\bar{y}_A = 7$ and $\bar{y}_B = 9$ and their variances are estimated to be $Var(\bar{y}_A) = 1$ and $Var(\bar{y}_B) = 0.2$.
- **3.1.1.** What is the quadratic form that is a function of μ that is minimized at the asymptotically efficient GMM estimate of μ ?

$$\begin{bmatrix} \bar{y}_{A} - \mathbb{E}[y_{A}] \\ \bar{y}_{B} - \mathbb{E}[y_{B}] \end{bmatrix}' \begin{bmatrix} 1 & 0 \\ 0 & 0.2 \end{bmatrix}^{-1} \begin{bmatrix} \bar{y}_{A} - \mathbb{E}[y_{A}] \\ \bar{y}_{B} - \mathbb{E}[y_{B}] \end{bmatrix} = \begin{bmatrix} \bar{y}_{A} - \mu \\ \bar{y}_{B} - (\mu + 5) \end{bmatrix}' \begin{bmatrix} 1 & 0 \\ 0 & 0.2 \end{bmatrix}^{-1} \begin{bmatrix} \bar{y}_{A} - \mu \\ \bar{y}_{B} - (\mu + 5) \end{bmatrix} = \begin{bmatrix} 7 - \mu \\ 4 - \mu \end{bmatrix}' \begin{bmatrix} 1 & 0 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} 7 - \mu \\ 9 - (\mu + 5) \end{bmatrix}$$

Note that this matrix product yields a scalar!

3.1.2. What is the numerical value of this GMM estimate? Take the FOC and solve for $\hat{\mu}$:

$$\min_{\mu} \{ (7 - \mu)^2 + 5(9 - (\mu + 5))^2 \} = \min_{\mu} \{ (7 - \mu)^2 + 5(4 - \mu)^2 \}$$

$$\implies -2(7 - \hat{\mu}) - 10(4 - \hat{\mu}) = 0$$

$$\implies \hat{\mu} = 54/12$$