Stephen's Work Log

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 $March\ 12,\ 2020$

Contents

1	1.1	Kipoi Dropout Research	3
2	2.1	DeepSea Uncertainty Estimates	4 4
3	3.1 3.2	Kipoi Uncertainty Estimates Cont	6 6
4	4.1	Kipoi Uncertainty Estimates Cont	8 8
5	5.1	Misc	10 10
6	6.1 6.2	Past few days	11 11 11
7	7.1	Past few days	12 12
8	8.1 8.2	Recap	13 13 14
9	9.1 9.2	Recap	15 15 15
10	10.1	Cumont Status	18

CONTENTS	2
----------	---

11										19
	11.1	Current Status								19
	11.2	Defining a motif similarity threshold								19

Those present Stephen Malina Date January 29, 2020

List of topics

1.1 Kipoi Dropout Research

My current understanding is that, assuming DeepSea is a PyTorch model in Kipoi (will verify shortly), I should be able to run a simple function like the following to activate Dropout in the Kipoi model (source 1, source 2).

```
def apply_dropout(m):
    if type(m) == nn.Dropout:
        m.train()

model.eval()

model.apply(apply_dropout)
```

This means that the next step is to figure out the best way to generate repeated predictions for the same sequence using Kipoi while ensuring that we use the same dropout mask on predictions for wild type and mutated sequences. Unfortunately, this most likely means we won't be able to use kipoi-interpret's out-of-box in-silico mutagenesis code.

Those present Stephen Malina Date January 30, 2020

List of topics

2.1 Dee	pSea Uncertainty Estimates	4
2.1.1	Verifying that we don't need precision for classification	4
2.1.2	Verifying that torch uses 1 Dropout mask for an entire mini-batch	5
2.1.3	Working with Kipoi to get uncertainty estimates	

2.1 DeepSea Uncertainty Estimates

Huzzah! I'm able to force DeepSEA to apply Dropout at evaluation time using the strategy I mentioned yesterday. That said, one thing that's not clear to me is whether it's OK that not every layer is using Dropout... For now, I'm going to assume it is and flag it as something to follow up on.

Now, the next step is to figure out the best way to ensure that Kipoi uses the same Dropout mask for original and diff predictions.

2.1.1 Verifying that we don't need precision for classification

I found the appendix to Yarin Gal's "Dropout as a Bayesian Approximation" paper and I'm pretty confident that for classification that the predictive variance is just the empirical variance of the predicted probability.

One question that I'm putting aside for now is the question whether 0-normalizing is necessary.

MINUTES 2. 5

2.1.2 Verifying that torch uses 1 Dropout mask for an entire mini-batch

So it's looking like torch does **not** use the same Dropout mask within the same mini-batch. This means either we:

- 1. Hot swap the torch dropout layers with custom ones which use 1 mask per mini-batch.
- 2. Use the standard dropout layers and accept that we'll lose the $\mathrm{Cov}(X,Y)$ term from the

$$Var(X - Y) = Var(X) + Var(Y) - 2 \cdot Cov(X, Y)$$

formula for the variance of our predicted difference.

One caveat with option 1 is that, even if torch did use the same mask for the mini-batch, I'm not sure that we'll be able to fit all 4000 mutated sequences in the same batch. I *think* we will but will have to verify.

I think ultimately we should go with the first option, but I'm tempted to start with the second just to get all the scaffolding in place and then we can switch.

2.1.3 Working with Kipoi to get uncertainty estimates

The key question determining whether we can use the built-in mutagenesis code is whether Kipoi makes all the predictions as part of one batch. If it doesn't, that precludes us from ever going with option 2 and calls into question whether it makes sense to use the built-in mutagenesis code in the first place.

Those present Stephen Malina Date February 02, 2020

List of topics

3.1 Kipoi Uncertainty Estimates Cont	6
3.1.1 Custom Dropout	6
3.1.2 In-silico mutagenesis with uncertainty	6
3.2 GPU Memory Issues	6

3.1 Kipoi Uncertainty Estimates Cont.

3.1.1 Custom Dropout

After fiddling around a bit with the code and reading some helpful PyTorch forum posts, I got custom Dropout working. I'm using a **barely** modified version of SalesForce's LockedDropout class code to do Dropout with a constant mask (within a batch). I'm using an also **barely** modified version of this convert_layers code to replace the original Dropout layers with my own.

3.1.2 In-silico mutagenesis with uncertainty

I now have code that can generate batches of (currently un-)mutated sequences and feed them to DeepSEA. Unfortunately, this is really slow...

3.2 GPU Memory Issues

I'm encountering weird behavior where Kipoi / Torch allocate a huge amount of memory (¿10 GB) just to make predictions for a single 1000-record batch of data. Now, since each sequence is 1000 base pairs, I get that this is a non-trivial amount of data, but there's no way it requires 10 GB just to load and make

MINUTES 3. 7

predictions on. There are two other pieces of evidence that convinced me that something else must be going on:

- 1. The 10 GB stick around after I make the predictions until I free the model
- 2. Calling predict_on_example doesn't cause the same issues even though Managed to resolve these by just using small batch sizes.

Those present Stephen Malina Date February 04, 2020

List of topics

4.1 Kipoi Uncertainty Estimates Cont.....

4.1 Kipoi Uncertainty Estimates Cont.

Managed to get mean, variance, and covariance estimates using all the stuff I've been working on this past week. In the process, I made two graphs which seem worth capturing here.

The first depicts predictive variance versus predictive mean with colors representing different sequences (each dot is for a maybe mutated variant of the sequence). As expected, predictive variance increases as predictions become more uncertain (become closer to 0.5).

MINUTES 4. 9

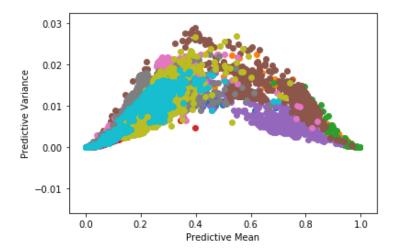


Figure 4.1: Plot of predictive mean vs. predictive variance. Colors code for different sequences.

Those present Stephen Malina Date February 06, 2020

List of t	opics
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5.1 Misc	10
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5.1 Misc.

I spent most of my work time today reading about MR-Egger while waiting for my run to finish. After that, I realized that I'd implicitly been leaving a bunch of un-mutated sequence predictions at the end of the final batch for each sequence in the data. Fixed that by making the batch size an even divisor of 3000. Altogether, not the most productive day...

Those present Stephen Malina Date February 10, 2020

List of topics

6.1	Past few days	11
6.2	Today	11

6.1 Past few days

I forgot to log some of my work over the past few days here but essentially I've just been futzing around with the post-Kipoi data processing a bit and also reading a bunch about MR-Egger regression, which I now mostly understand.

6.2 Today

Now I'm finally ready to actually run the MR-Egger code in R with NN-generated data.

Spent a lot of time getting all the annoying R stuff setup locally. I think I have stub code that's *this* close to allowing me to run MR-Egger on our predictions. However, before I do that, I need to remember to re-run the prediction code with batch size set to 301 instead of 300 so that there are no extra un-mutated sequences in the batches. I also need to remember to generate new random sequences equally sampled from binding / no binding regions for FOXA2 not CTCF.

Those present Stephen Malina Date February 13, 2020

List of topics

7.1 Past few days

Over the past few days, I got the MR-Egger code working and revamped the random sequence selection code to work with FOXA2 data from

Those present Stephen Malina Date February 25, 2020

List of topics

8.1	Recap	 										13	
8.2	Today	 										14	

8.1 Recap

I've been bad about recording progress so I'm using this to recap all that's happened since my last entry.

After getting the MR Egger code up & running, we realized that the uncertainty estimates for individual predictions were 'too' high, leading to I^2 scores of 0. This roughly means that Egger's estimates will suffer from 'weak instrument bias'.

Given that, I spent some time looking at Gaussian processes to try and figure out whether there was a principled way to set the dropout rate p that also might reduce or at least explain our large standard errors. I found that the dropout probability emerges in the GP VI approximation derivation as a mixing weight for a two-component mixture of Gaussians in which one component represents the NN weights and one represents 'zero'.

The GP formalism turned out to be not that helpful for figuring out a principled way to set the dropout probabilities. That said, in the process, we did discover a different paper which talks about the Expected Calibration Error (ECE) metric for testing calibration. The computable version of the ECE formula requires first breaking the range [0,1] into k equal-sized bins. For each bin, we compute the absolute difference between mean predicted probability of samples and true fraction of samples with label 1. And then the ECE is a weighted average (by number of samples per bin) of the bin-level differences.

They use this method to compare different forms of MC dropout and NN ensembling and find that something called *dropChannel* works best.

MINUTES 8.

8.2 Today

I'm working on implementing dropChannel and will test it as a substitute for the current dropout layers to see whether the s.e. estimates seem smaller.

Before switching to dropChannel, I'm going to try changing all the dropout probabilities in the network to be equal $(.5 \rightarrow .2$ after the last conv layer) and see whether that meaningfully changes the networks' predictions. I didn't check super rigorously but it seemed like the s.e.s look similar for the two sequences I sampled with all dropout rates set to .2.

Using dropChannel seemingly has not decreased the standard errors and has in fact increased them.

Those present Stephen Malina Date February 25, 2020

List of topics

±	
9.1 Recap	15
9.2 Moving Forward	15
9.2.1 Standard Error Calibration	16
Yarin Gal knows MC dropout isn't calibrated	16

9.1 Recap

I have again been bad about recording progress... I spent a bunch of time learning about neural network calibration and then tried something Brielin suggested - regressing CA effects on TF effects just to see whether there's a clear relationship. There is!

9.2 Moving Forward

So now I'm left with two threads to pursue:

- 1. Verify by hand that mutations that reduce binding probability often disrupt known motifs for FOXA1.
- 2. Understand what the hell is going in with our uncertainty estimates from MC dropout. Why are they so large?

Now the question remains of which to do first? Seems like I should do the one which has higher expected information value per unit of work first. My hunch is by that metric 2 wins out because we know that DeepSEA seemed to do the 'right thing' with respect to motifs from the paper.

MINUTES 9. 16

Assuming I'm going with 2, there's a sub-question of whether it makes more sense to calibrate DeepSEA's predictions first or to see how well its uncertainty estaimtes are calibrated. My **guess** is that the uncertainty estimates will get a bit better if the predictions become more calibrated because I have an intuition that the effect of dropout's noise won't grow linearly with the probability differences. But I don't have great justification for that so it's unclear how much stock to put in it.

Looking at this from a different perspective, I'm going to want to check the calibration of the standard errors before and after calibration to see whether they improve so I might as well write the code to check their calibration now since I'll need it later anyway.

In terms of how I'm going to test standard error calibration, I'm unclear on whether it makes sense to assume that the predictions should be normally distributed with mean equal to the predictive mean and variance equal to the predictive variance. I vaguely remember that the motivation for the t-distribution is to come up with an analogue to the normal distribution for sample means and sample variances. I should look into that before moving ahead...

9.2.1 Standard Error Calibration

I didn't make any concrete progress but I do feel like I have a better understanding of what make work. One thing that make work for testing calibration would be to assume that each point's predictions should be normally distributed around the population mean. Then I think we can use normal quantiles to test whether $\alpha\%$ of actual predictions fall within the $1-\alpha\%$ interval. However, this is weird for 2 reasons:

- 1. I'm confused about whether the distribution of predictions around the mean should follow a normal distribution or something else like a t-distribution.
- 2. This all makes a lot of sense in the regression case but is weirder given that we're doing classification. It's weirder because our predictions are estimates of the probability that a Bernoulli random variable has value 1 and then we're imposing a distribution on the estimates of the probability.

On second thought, it doesn't really make sense to think of these as sampled from a Bernoulli distribution because they're never 0/1...

Yarin Gal knows MC dropout isn't calibrated

From the paper:

We can show that the dropout model is not calibrated. This is because Gaussian processes' un-certainty is not calibrated and the model draws its properties from these. The Gaussian process's uncertainty depends on the covariance function chosen, which we showed above MINUTES 9. 17

to be equivalent to the non-linearities and prior over the weights. The choice of a GP's covariance function followsfrom our assumptions about the data. If we believe, for example, that the model's uncertainty shouldincrease far from the data we might choose the squared exponential covariance function. For many practical applications this means that model uncertainty can increase with data magnitudeor be of different scale for different datasets. To calibrate model uncertainty in regression taskswe can scale the uncertainty linearly to remove data magnitude effects, and manipulate uncertaintypercentiles to compare among different datasets. This can be done by fitting a simple distribution over the training set output uncertainty, and using the cumulative distribution function to find therelative ratio of a new data point's uncertainty to that of existing ones. This quantity can be used to compare a data point's uncertainty obtained from a model trained on one data distribution to another.

Those present Stephen Malina

Date March 10, 2020

List of topics

10.1 Current Status

Yesterday I had a minor breakthrough in which I figured out part of the cause of our large standard errors. It had to do with discrepancies between np.var and np.cov – the former returns the input type, the latter always float64s; the former doesn't use Bessel's correction by default, the latter does – and a misplaced parenthesis. Now that that's resolved, I want to spot check the calibration of the standard errors, but I'm less suspicious of them on priors.

Once I check the standard errors, then I'm actually going to break open the black box and see whether the most impactful mutations result from the disruption of known motifs.

Those present Stephen Malina Date March 12, 2020

List of topics

11.1 Current Status	19
11.2 Defining a motif similarity threshold	19

11.1 Current Status

Currently working on comparing sequence snippets in which mutations disrupt FOXA1 binding in silico to FOXA1's true motifs. I currently have code to print out the sequence context for the most impactful mutations. Before I go and look for motifs, it probably makes sense to try and do some basic aggregation to see whether any motifs pop up more often than others. I have an idea for how to do this that involves looking at all k-mers for $k \in [3, 5]$ and counting appearances.

11.2 Defining a motif similarity threshold

Now that I've written the code to count appearance of k-mers around impactful mutations, I'm realizing that I need a better criteria for success than "looks like some of the motifs we find are significant." In the spirit of coming up with my own ideas before looking into existing literature, I'm going to try and frame the problem in my own words and see if I can come up with a tentative solution before looking up others'.

A starting point is just asking whether we could validate the hypothesis that the disruptions reflect **some** underlying pattern. We can frame this as a hypothesis testing problem where we want to show that the k-mer counts meaningfully differ from what we'd expect under a uniform model. I'm not going to actually go through the math but I'm confident this is doable.

MINUTES 11. 20

Writing the above out does give me an idea. I was previously thinking of this from the perspective of trying to figure out how to validate comparisons between in silico and observed motifs, but maybe that's the wrong place to start. Instead, maybe we can use the above hypothesis testing approach to find k-mers whose counts have a low probability under a uniform (or normal) counts model. If we set α for choosing a probability threshold (will be at both tails) low enough, that should leave us with few enough k-mers that we can then hopefully just use edit distance and some (different threshold) to compare to observed motifs. This doesn't deal with the question of how to decide how similar is similar enough but it does deal with the issue of having too many k-mers to deal with such that it's likely that at least a few will match the known FOXA1 motifs.