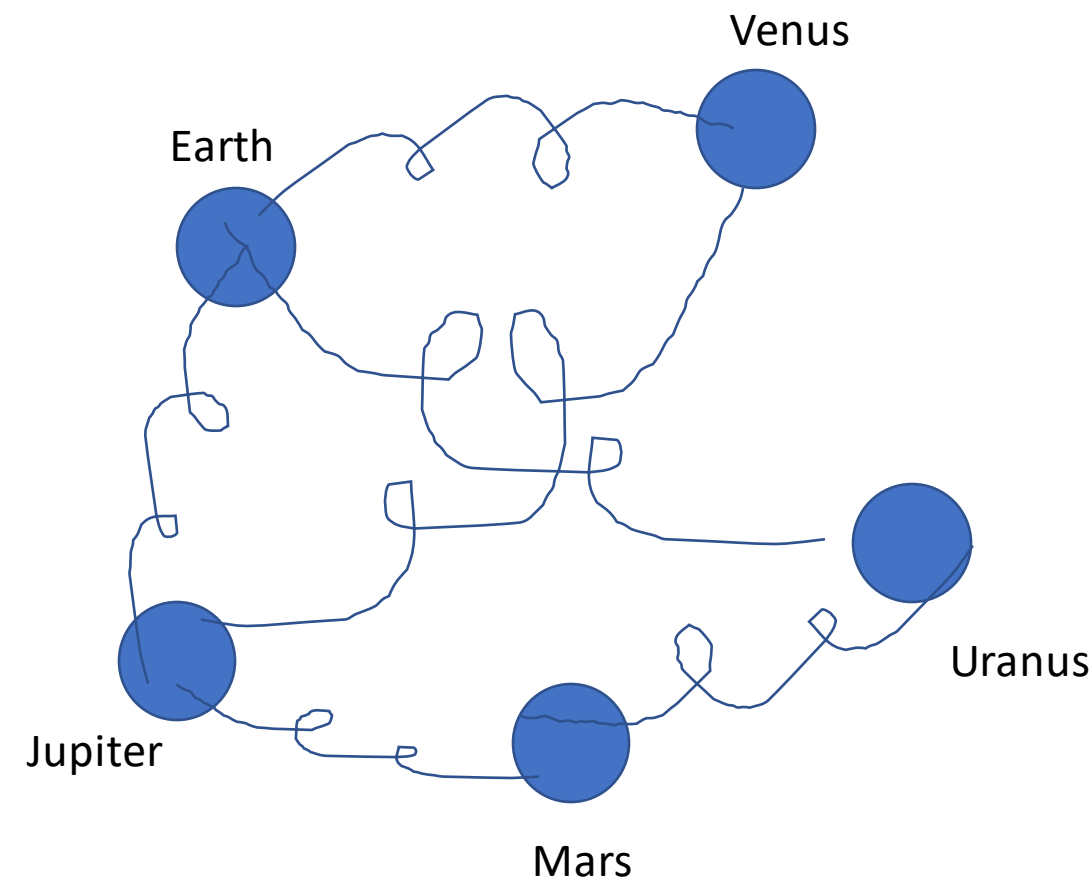
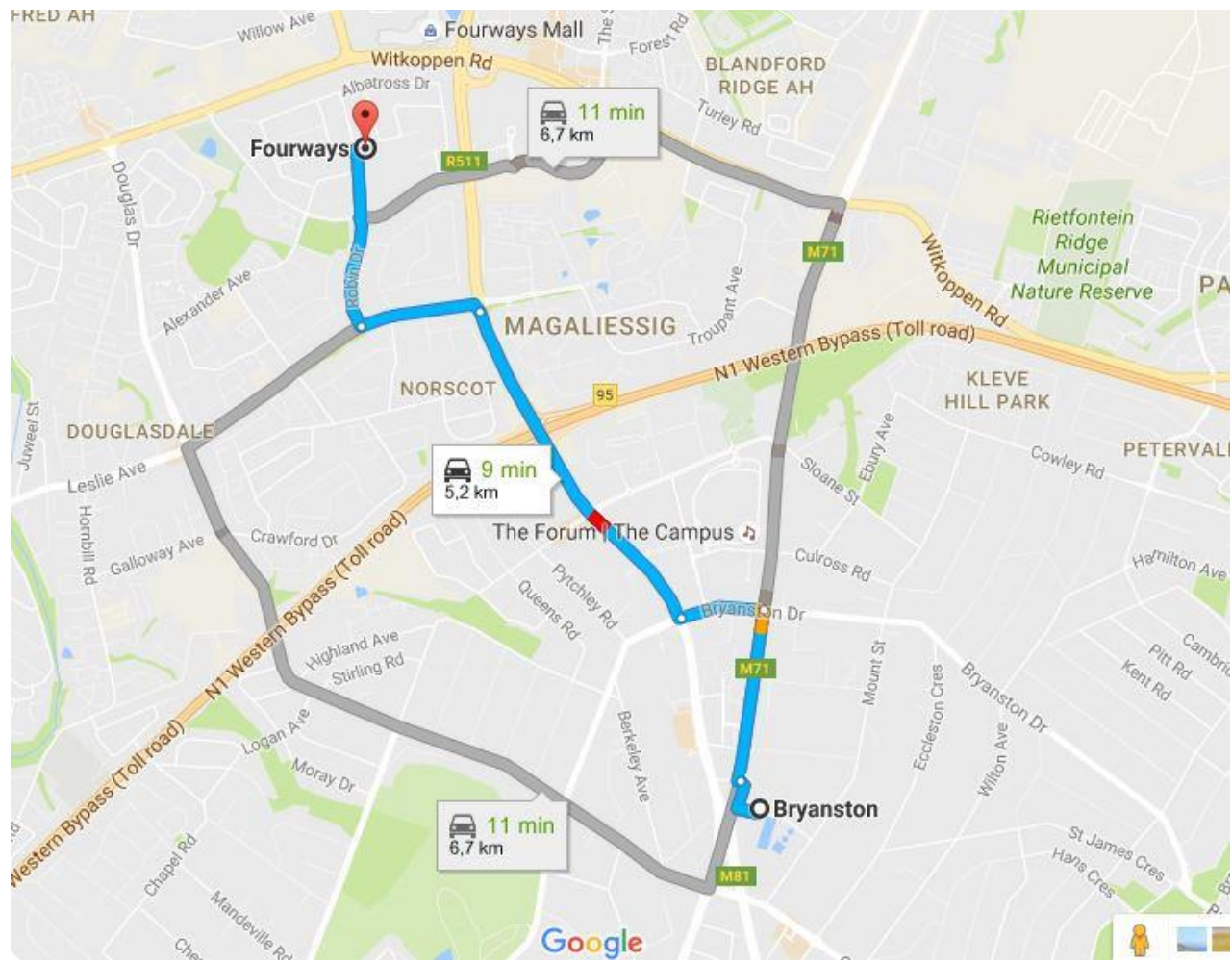


Wormhole problem

Muhamed_20180539@fci.Helwan.edu.eg



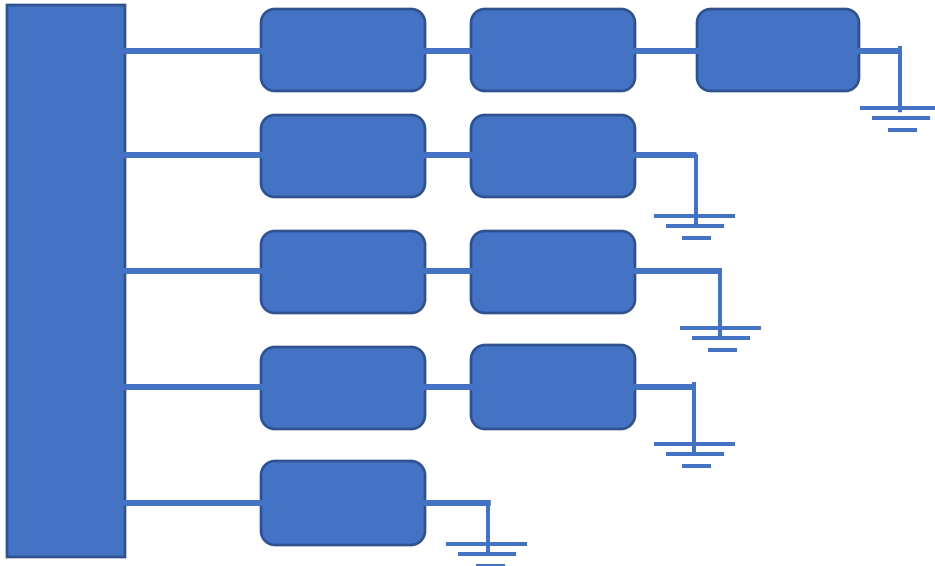
Data Structure

After reading the problem description I asked myself, what type of data structures will I use to solve this problem !!

it's Graph !!!

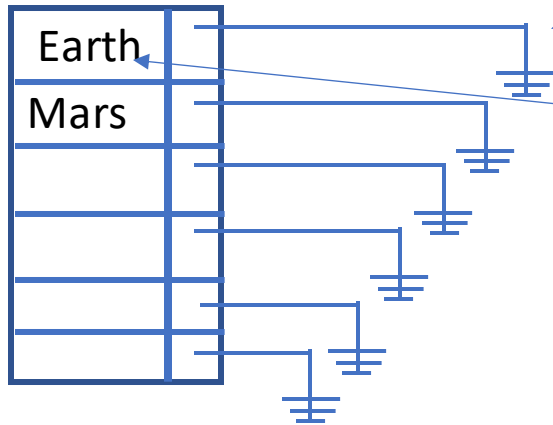
There are planets as Vertexes

And there are wormholes as Edges



```
1  #ifndef GRAPH_H_INCLUDED
2  #define GRAPH_H_INCLUDED
3  #include <stdlib.h>
4  #include<string.h>
5  #define maxvertex 1000
6  #define IN 9999
7  typedef char graphentry[25];
8
9
10 typedef struct edge{
11     int endpoint;
12     int cost;
13     struct edge *nextedge;
14 }Edge;
15
16 typedef struct vertex{
17     graphentry entry;
18     Edge * firstedge;
19 }Vertex;
20
21 typedef struct graph{
22     int n;
23     int E;
24     Vertex entry[maxvertex];
25 }Graph;
26
27
28
29 void creategraph(Graph *);
30 int dijkstra(Graph *,graphentry ,graphentry );
31 void AddEdge(Graph*,int,int,int);
32 void removeEdge(Graph * , graphentry, graphentry );
33 void AddVertex(Graph * , int ,graphentry);
34 void removeVertex(Graph * , graphentry);
35
36 #endif // GRAPH_H_INCLUDED
```

Graph methods

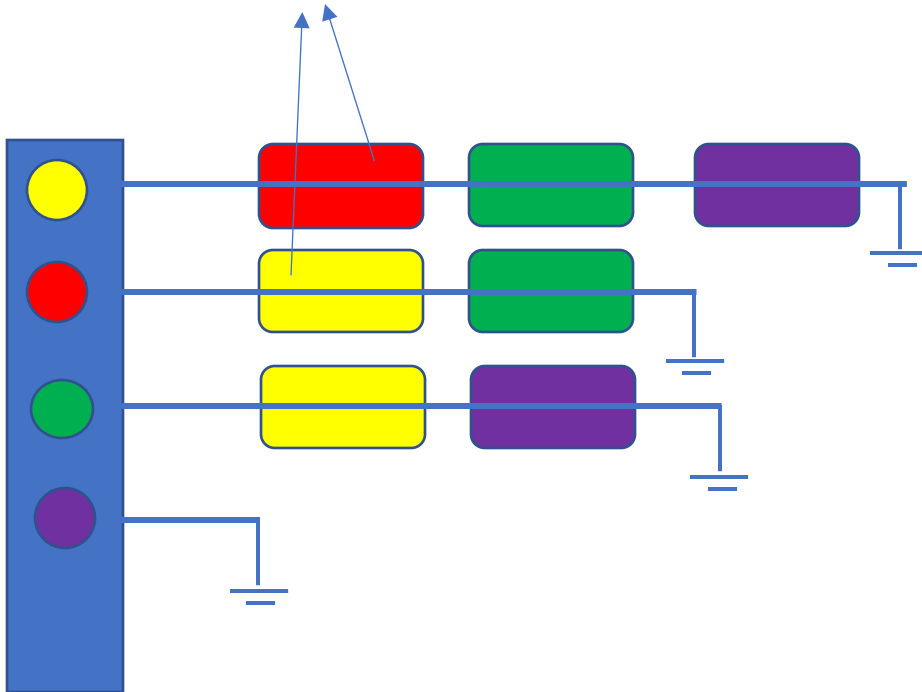


```
2
3 void creategraph(Graph *pg)
4 {
5     for (int i =0 ; i<maxvertex; i++)
6     {
7         pg->entry[i].firstedge=NULL;
8     }
9     pg->n=0;
10    pg->E=0;
11 }
12
```

```
130
131 void AddVertex(Graph *pg, int i,graphentry name)
132 {
133     strcpy(pg->entry[i].entry, name);
134     pg->n++;
135 }
136
137 void removeVertex(Graph *pg, graphentry vertex)
138 {
139     int vertec_index=findindex(&pg,vertex);
140     Edge *q=pg->entry[vertec_index].firstedge;
141     while(q)
142     {
143         removeEdge(&pg,pg->entry[vertec_index].entry,pg->entry[q->endpoint].entry);
144         q=q->nextedge;
145     }
146     pg->n --;
147 }
148
```

wormholes

Same Edge



```

88
89
90 void AddEdge(Graph *pg, int startpoint, int endpoint, int cost)
91 {
92
93     Edge *t = (Edge*)malloc(sizeof(Edge));
94     t->endpoint=endpoint;
95     t->cost=cost;
96
97     Edge *q = (Edge*)malloc(sizeof(Edge));
98     q->endpoint=startpoint;
99     q->cost=cost;
100
101     t->nextedge=pg->entry[startpoint].firstedge;
102     pg->entry[startpoint].firstedge=t;
103     q->nextedge=pg->entry[endpoint].firstedge;
104     pg->entry[endpoint].firstedge=q;
105     pg->E+=2;
106
107 }

```

```

108 void removeEdge(Graph *pg, graphentry start, graphentry end)
109 {
110     int temp;
111     int startpoint = findindex(&pg, start);
112     int endpoint = findindex(&pg, end);
113     for (int i=0; i<2; i++)
114     {
115         Edge *q=pg->entry[startpoint].firstedge;
116         Edge *t;
117         while(q->nextedge->endpoint != endpoint)
118             q=q->nextedge;
119
120         t=q->nextedge;
121         q->nextedge=q->nextedge->nextedge;
122         free(t);
123
124         temp = startpoint;
125         startpoint = endpoint ;
126         endpoint = temp;
127     }
128     pg->E-=2;
129 }

```

Main.c

- 1- Create graph
- 2- Build Graph
 - 1) take the number of Vertices from user
 - 2) take name of vertices
 - 3) take all wormhole costs

```
#include <stdio.h>  
#include <stdlib.h>  
#include "graph.h"  
  
int main()  
{  
    Graph g;  
    createGraph(&g);  
    graphentry startpoint,target,newstartpoint;  
    int shourtpath,n;  
    int w,i,j;  
    //welcome to my problem  
    printf("\t\t\t\t\t\t\twormhole problem\n");  
    printf("\t\t\t\t The Shortest Path between two planet( DIJKSTRA'S ALGORITHM) \n\n");  
    //input the number of planets  
    printf("\tEnter the number of planets : ");  
    scanf("%d",&n);  
    graphentry vertexes[n];  
    //input the names of planets  
    printf("\tEnter your vertexes names.\n");  
    for(int count=0 ; count<n; count++)  
    {  
        printf("\tVertex[%d]: ",count+1);  
        scanf("%s",vertexes[count]);  
        AddVertex(&g,count,vertexes[count]); // add Vertex to graph  
    }  
  
    //inputs all time costs of wormholes  
    for(i =0; i<n; i++)  
    {  
        for(j=0; j<n; j++)  
        {  
            if(j>i)  
            {  
                printf("\ttthe Time_cost between %s and %s: ",vertexes[i],vertexes[j]);  
                scanf("%d",&w);  
                if(w!=0)  
                    AddEdge(&g,i,j,w); //add edge in my graph  
            }  
        }  
    }  
}
```


Main.c

3- take source and target planet from user

4- call Dijkstra Algorithm to find and print the shortest path and this function will return the time cost which

5- check if happen mal function take the new source vertex so go to step 5

End

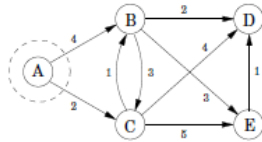
```

44 printf("graph has built\n");
45 printf("\n\tEnter your source : ");
46 scanf("%s",startpoint);
47 printf("\tEnter your target : ");
48 scanf("%s",target);
49 printf("\n\n\n");
50
51 shourtpath = dijkstra(&g,startpoint,target);//calling Dijkstra algorithm to find
52 printf("\n\n\n\t\t\t\t\tyour path will take : %d unit of time\n ",shourtpath); //ou
53 //malfunction part
54 printf("\n\n\t if happen malfunction press 1 or 0 if you arrived :");
55 scanf("%d",&i);
56 if(i)
57 {
58     printf("\tplease enter your location : ");
59     scanf("%s",newstartpoint);
60     printf("\n\n\n");
61     shourtpath = dijkstra(&g,newstartpoint,target); //calling Dijkstra algorithm
62     printf("\n\n\n\t\t\t\t\tyour path will take : %d unit of time ",shourtpath);//o
63 }
64
65 printf("\n\n\n\t\t\t\t\tthanks\n\n\n");
66
67 }

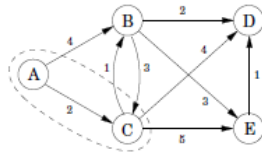
```

Dijkstra Algorithm

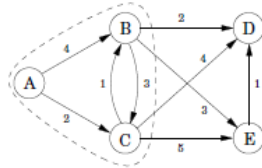
Find shortest path from one source



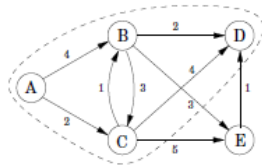
A: 0	D: ∞
B: 4	E: ∞
C: 2	



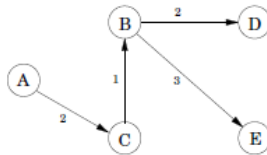
A: 0	D: 6
B: 3	E: 7
C: 2	



A: 0	D: 5
B: 3	E: 6
C: 2	



A: 0	D: 5
B: 3	E: 6
C: 2	



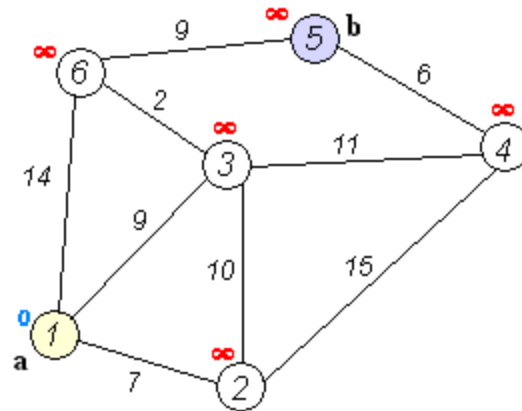
```

15 {
24 int dijkstra(Graph *pg, graphentry sourcename, graphentry targetname )
25 {
26     int start= findindex(pg, sourcename);
27     int target= findindex(pg, targetname);
28     Edge *t = pg->entry[start].firstedge;
29     int dist[pg->n], prev[pg->n], i, m, min, d, j=0;
30     int selected[pg->n];
31     graphentry path[pg->n];
32     for(i=0; i< pg->n ; i++) //complexity O(v)
33     {
34         dist[i] = IN;
35         prev[i] = -1;
36         selected[i]=0;
37     }
38     selected[start]=1;
39     dist[start] = 0;
40 }
    
```

```

int findindex(Graph *pg, graphentry point)
{
    for(int i=0; i< pg->n; i++)
    {
        if (strcmp(pg->entry[i].entry, point)==0)
        {
            return i ;
        }
    }
}
    
```


Core part



```

41 while(!selected[target]&& j++ !=pg->n)//complexity sO(v) path on all Vertex
42 {
43     min = IN;
44     m = 1;
45     while(t) //complexity O(v-1) in case of complete graph
46     {
47         i=t->endpoint;
48         d = dist[start] +t->cost;
49         if(d< dist[i]&&(selected[i]==0))
50         {
51             dist[i] = d;
52             prev[i] = start;
53         }
54         if(min>dist[i] && (selected[i]==0))
55         {
56             min = dist[i];
57             m = i;
58         }
59
60         t=t->nextedge;
61     }
62     start = m;
63     t=pg->entry[start].firstedge;
64     selected[start] =1;
65 }
66 if (selected[target]){
67     pathshow(pg,prev,path,target);
68 }else{
69     printf("\t\t\t\tthe target is isolated planet for your location");
70 }
71
72 return dist[target];
73 }
74

```

Show the shortest
path

```
72
73 void pathshow(Graph *pg,int *prev,graphentry *path,int start ){
74
75     int j=0;
76     while(start != -1) //complexity O(v)
77     {
78         strcpy(path[j++],pg->entry[start].entry);
79         start = prev[start];
80     }
81
82     printf("\t\t\t\tthe best path from %s",path[--j]);
83     for(int i = j-1 ; i>=0; i--)
84     {
85         printf(" --to--> %s",path[i]);
86     }
87
88 }
89
```

Record

- 1- what is wormhole problem ? (00:00:00 to 00:37:00)
- 2- why I used Graph as data Structuer? (00:37:00 to 00:53:00)
- 3- why undirected graph ? (00:53:00 to 01:11:00)
- 4-why adjacent list not matrix ? (01:11:00 to 02:39:00)
- 5-why I used Dijkstra algorithm & what is Dijkstra ? (02:39:00 to 03:32:00)
- 6- My solution to solve this Ploblem (03:32:00 to 05:16:74)

Link : [20180539_voice](#)