

ECE826 Lecture II:

The success of Deep Learning:
Is it all about SGD?

Contents

- On the (lack of) Implicit Bias of SGD
- Bad Local Minima Exist
- SGD Can Reach them

Last time: How fast we can approximate ERM

- The empirical cost function that we have access to

$$\min_{h \in \mathcal{H}} \left(R_S[h] = \frac{1}{n} \sum_{i=1}^n \ell(h(x_i); y_i) \right)$$

- Question: Can we approximate the solution to this minimization? If so how fast?
- The answer must depend on:
 - 1) n , the sample size
 - 2) \mathcal{H} , the hypothesis class and loss function
 - 3) \mathcal{D} , the data distribution
 - 4) the optimization algorithm that outputs our classifier

Loss landscapes and optimization in over-parameterized
non-linear systems and neural networks

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May 28, 2021

A Convergence Theory for Deep Learning via Over-Parameterization

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No bad local minima: Data independent training error guarantees for multilayer neural networks

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Overparameterized Nonlinear Learning: Gradient Descent Takes the Shortest Path?

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On the Convergence Rate of Training Recurrent Neural Networks

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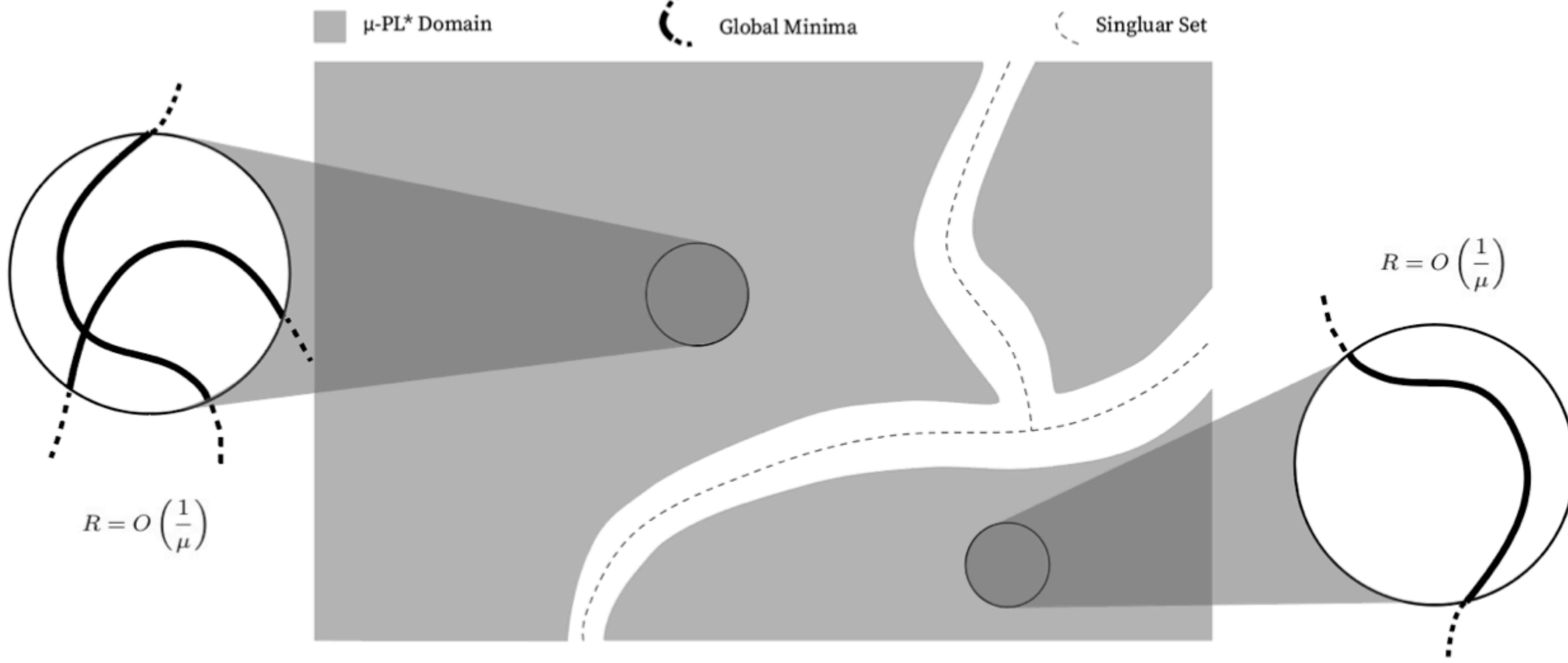
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October 28, 2018

Gradient Descent Finds Global Minima of Deep Neural Networks

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via Over-Parameterization

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PL-like conditions hold in neighborhoods around initialization/optima.

Current theoretical SOTA

Subquadratic Overparameterization for Shallow Neural Networks

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Thomas Pethick¹

Armin Eftekhari^{2†}

Volkan Cevher¹

something odd..

Table 1: Scaling with the number of training data in the overparameterization regime. QL=quadratic loss, CLL=convex and Lipschitz loss, SD=separable data.

Depth	Algorithm	Setting	Activation	Scaling	Reference
2	GD on layer 1	QL	ReLU	$\tilde{\Omega}(n^2)$	Oymak and Soltanolkotabi [38]
L	GD on layer L	CLL	ReLU	$\tilde{\Omega}(n)$	Kawaguchi and Huang [21]
2	GD	SD	ReLU	$\tilde{\Omega}(n^2)$	Song and Yang [39]
2	GD	SD and QL	ReLU	$\tilde{\Omega}(n^6)$	Du et al. [12]
L	GD	SD and QL	ReLU	$\Omega(n^8 L^{12})$	Zou and Gu [44]
2	GD	QL	Smooth	$\tilde{\Omega}(n^{\frac{3}{2}})$	This paper

A curious observation on fitting the data

Small ReLU networks are powerful memorizers: a tight analysis of memorization capacity

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Theorem:

Any data set of size n can be memorized by a 3-layer ReLU neural network with $O(n)$ weights.

These constructions can be made in linear time. Yet SGD on the same arch needs so much more larger overarm. Why??

But somehow SGD does more than just that..

Rethinking Generalization [Zhang et al. ICLR17]

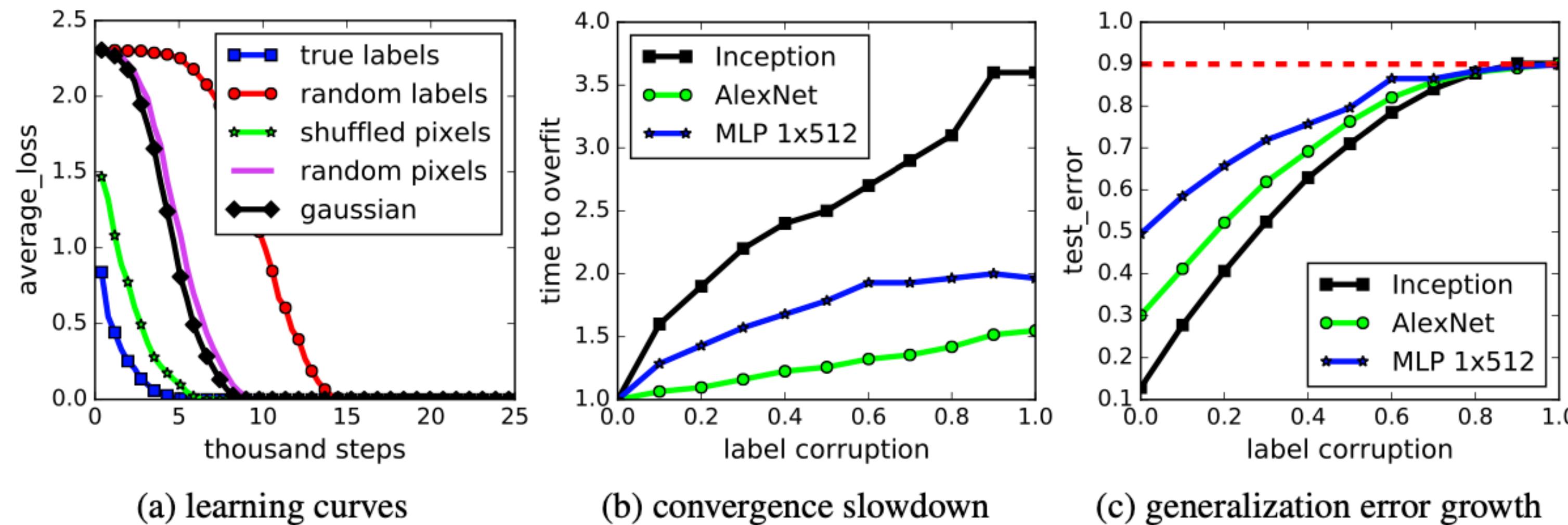


Figure 1: Fitting random labels and random pixels on CIFAR10. (a) shows the training loss of various experiment settings decaying with the training steps. (b) shows the relative convergence time with different label corruption ratio. (c) shows the test error (also the generalization error since training error is 0) under different label corruptions.

- Overparameterized, SGD-trained models :
 1. Can fit even completely random labels (i.e., huge capacity)
 2. Yet, generalize well

Rethinking Generalization [Zhang et al. ICLR17]

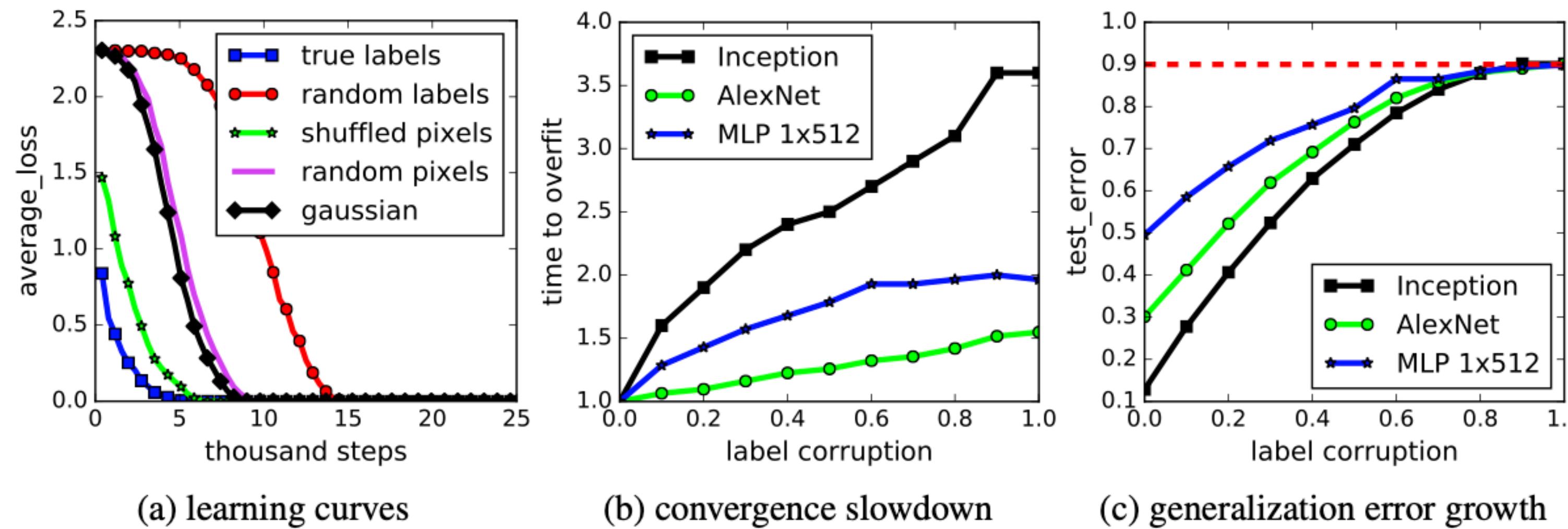


Figure 1: Fitting random labels and random pixels on CIFAR10. (a) shows the training loss of various experiment settings decaying with the training steps. (b) shows the relative convergence time with different label corruption ratio. (c) shows the test error (also the generalization error since training error is 0) under different label corruptions.

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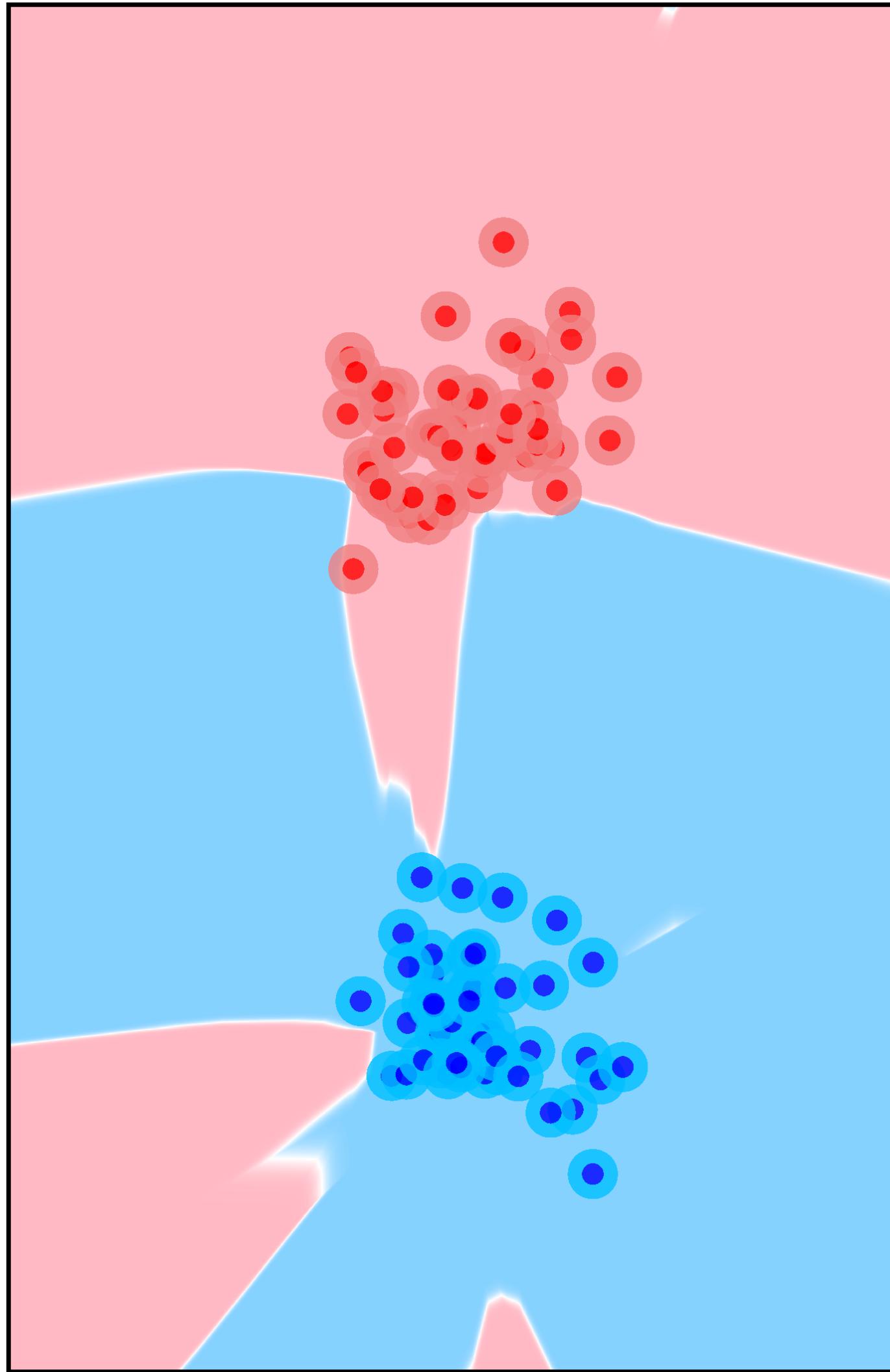
Open Question: How can this be?

Possible Explanations of Generalization

- Maybe every model that fits the training data generalizes (no bad global minima)
- Maybe SGD is special “can avoid” bad global minima (implicit regularization)?
- Maybe the data distribution is what allows everything to fall into place?

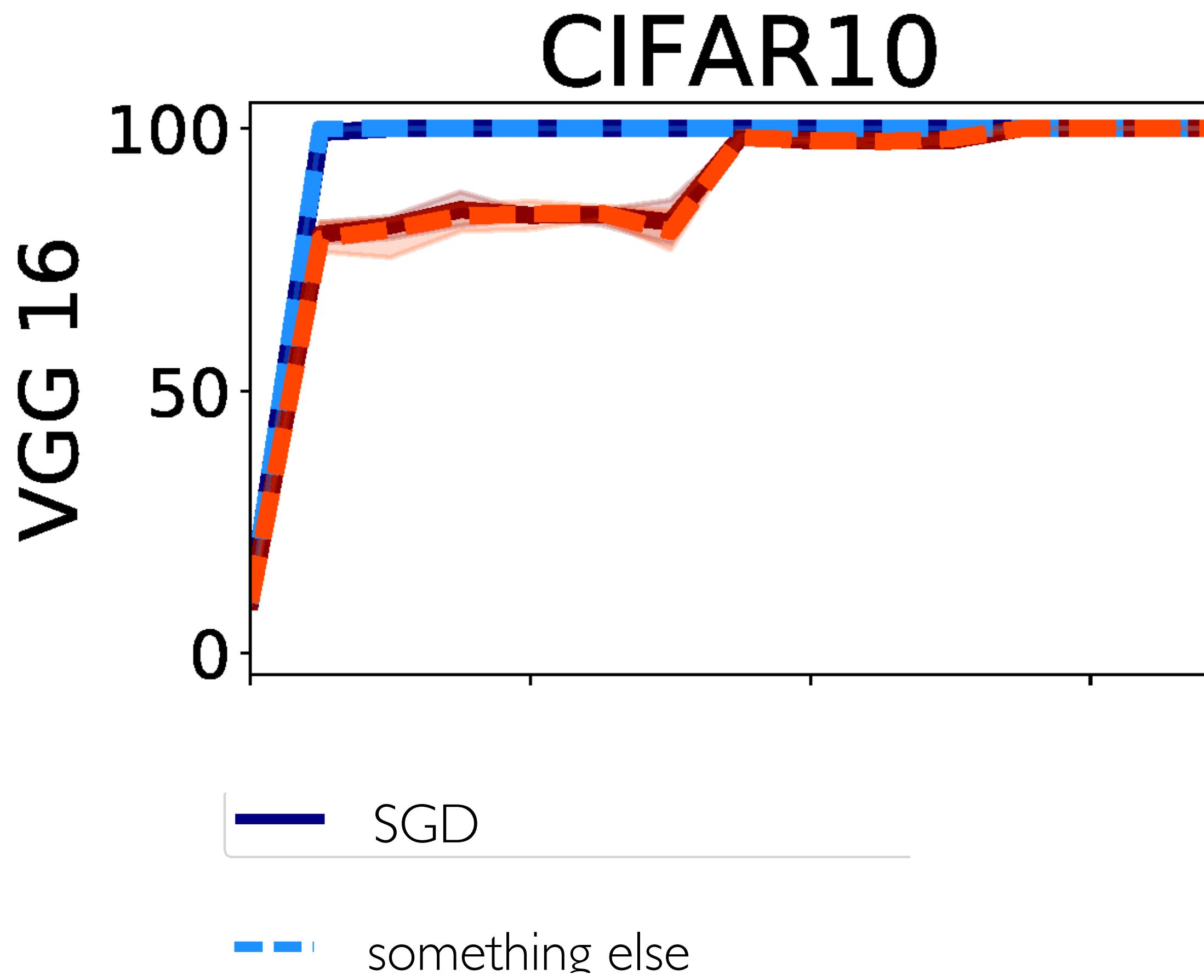
Maybe all interpolating points generalize!

What is a bad global minimum?



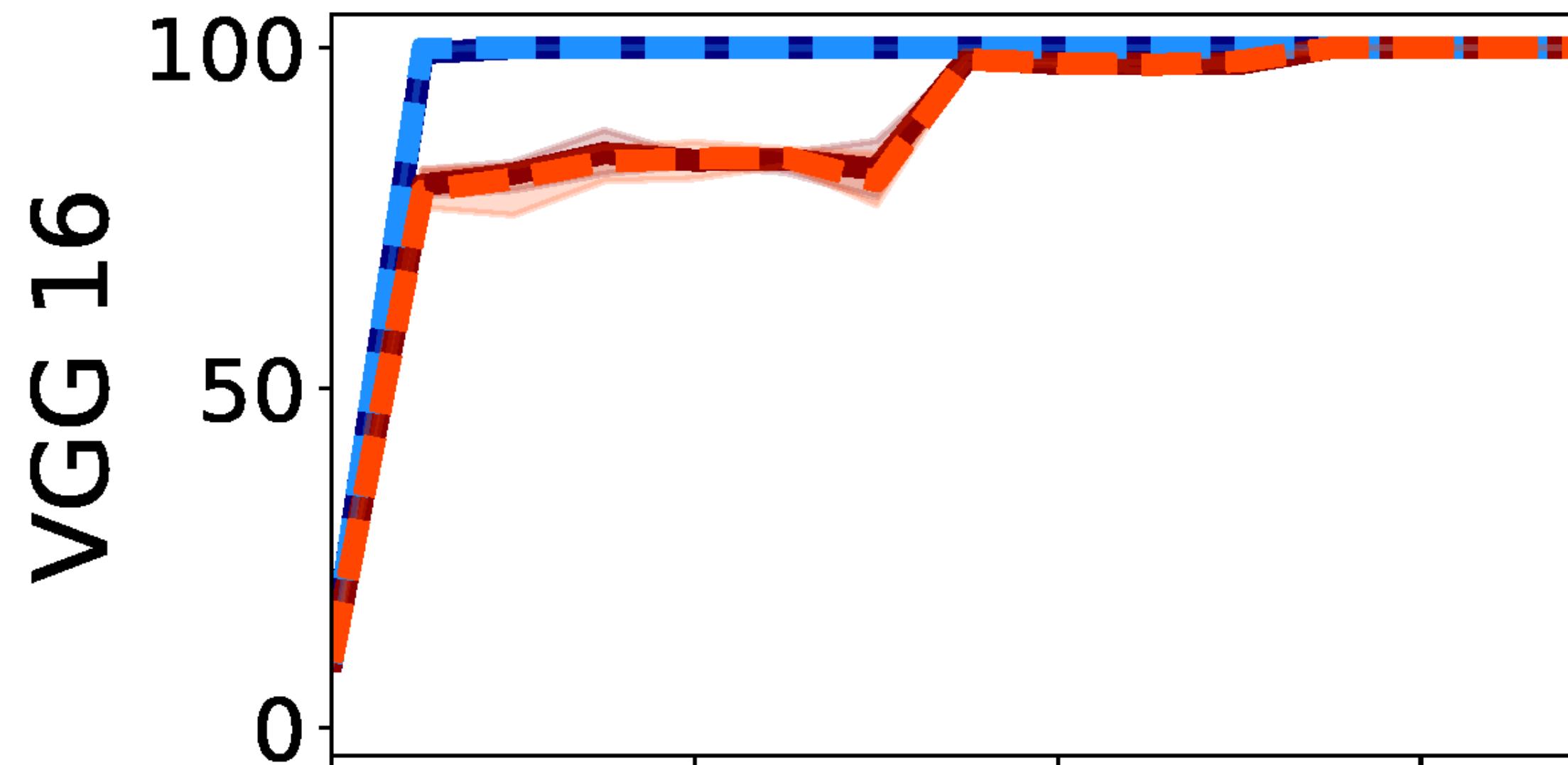
Bad Minima = zero margin/complex boundary
=> 100% train error + poor test

Bad Global Minima Exist

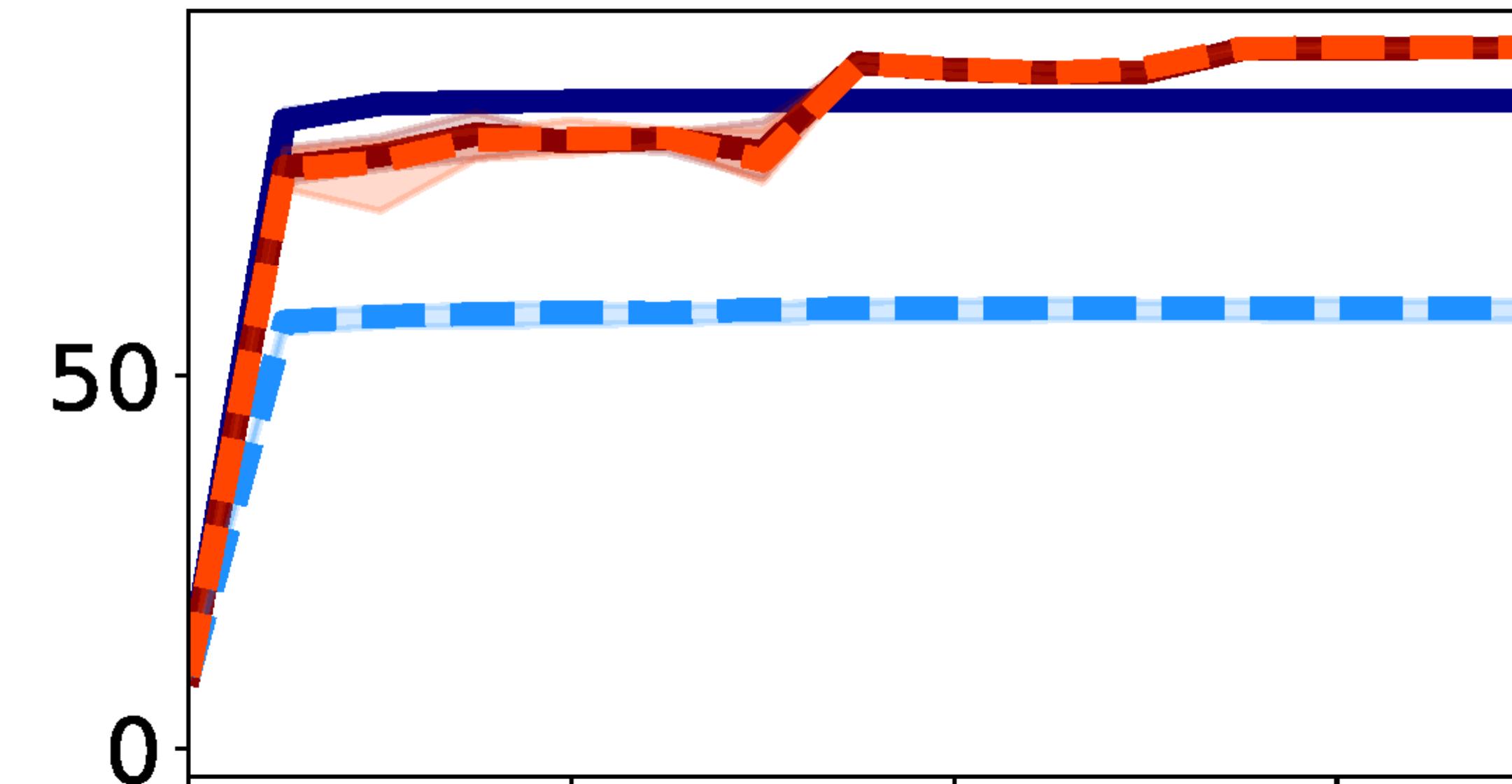


Bad Global Minima Exist

CIFAR10

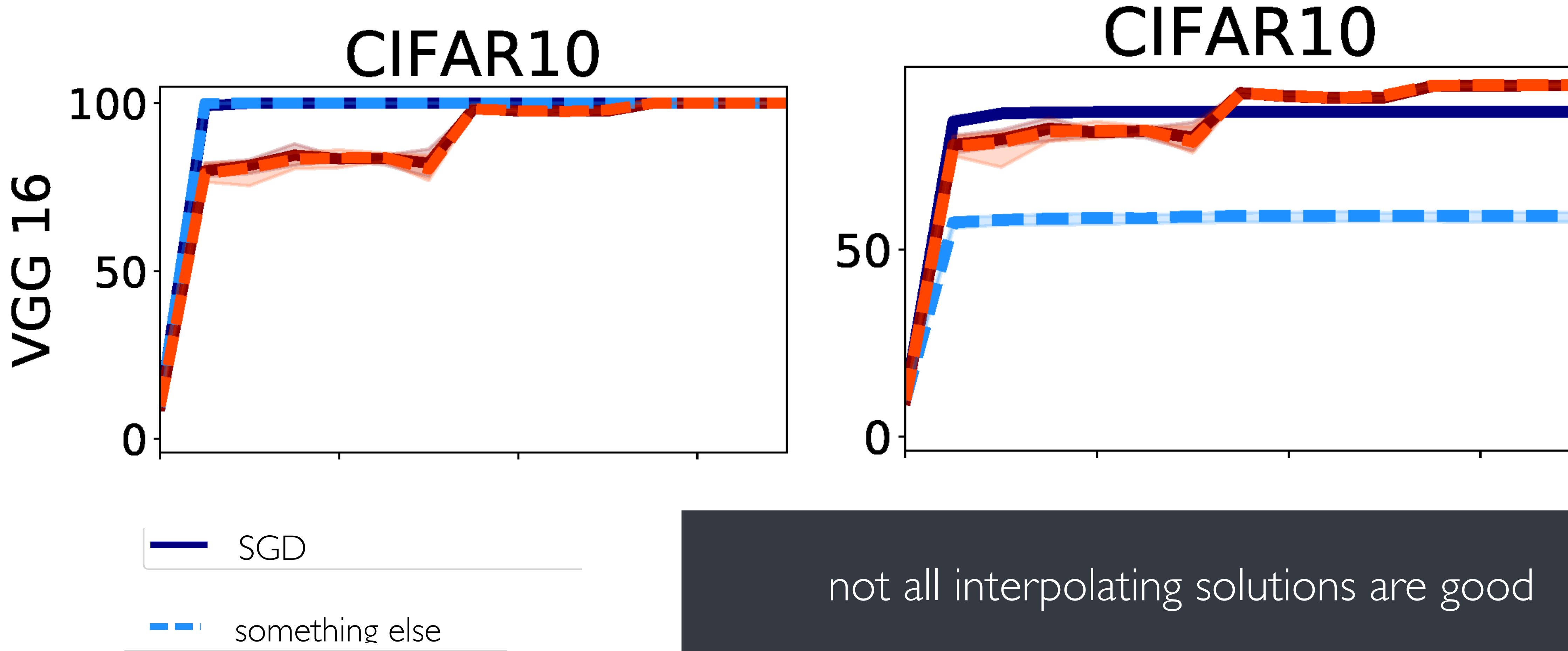


CIFAR10



- SGD
- - - something else

Bad Global Minima Exist



Possible Explanations of Generalization

nope

- Maybe every model that fits the training data generalizes (no bad global minima)
- Maybe SGD is special “can avoid” bad global minima (implicit regularization)?
- Maybe the data distribution is what allows everything to fall into place?

Maybe (S)GD is special?

GD + LS = a red herring

- Let's say we want to solve a least squares problem $\min_w \|X^T w - y\|^2$ with GD

GD + LS = a red herring

- Let's say we want to solve a least squares problem $\min_w \|X^T w - y\|^2$ with GD
- The iterates of GD look like

$$\begin{aligned}w_{k+1} &= w_k - \frac{\gamma}{2} \nabla L(w_k) \\&= w_k - \gamma X(X^T w_k - y)\end{aligned}$$

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$$w_{k+1} = \gamma \left(\sum_{i=0}^{k-1} (I_d - \gamma X X^T)^i \right) X y$$

- What does that imply? Let's take GD to infinity

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$$w_\infty = \gamma \left(\sum_{i=0}^{\infty} (I_d - \gamma X X^T)^i X y \right)$$

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$$w_\infty = \gamma \left(\sum_{i=0}^{\infty} (I_d - \gamma X X^T)^i X y \right)$$

- Do you remember what this infinite sum converges to?

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- What does that imply? Let's take GD to infinity

$$w_\infty = \gamma \left(\sum_{i=0}^{\infty} (I_d - \gamma X X^T)^i X y \right)$$

- Do you remember what $\sum_{i=0}^{\infty} (I_d - \gamma X X^T)^i$ converges to?

GD + LS = a red herring

- Let's say we want to solve a least squares problem $\min_w \|X^T w - y\|^2$ with GD
- Let's take GD to infinity

$$w_\infty = (X^T X)^{-1} X y$$

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- Let's say we want to solve a least squares problem $\min_w \|X^T w - y\|^2$ with GD
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- Do you remember what this is called?

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- Do you remember what this is called?
- The minimum Euclidean norm solution of squares solution to $X^T w = y$

$$\arg \min_w \|w\|_2, \text{ s.t. } W^T x = y$$

IMPLICIT BIAS/Regularization??!!!

- Let's say we want to solve a least squares problem $\min_w \|X^T w - y\|^2$ with GD
- Let's take GD to infinity

$$w_\infty = (X^T X)^{-1} X y$$

- Do you remember what this is called?
- The minimum Euclidean norm solution of squares solution to $X^T w = y$

$$\arg \min_w \|w\|_2, \text{ s.t. } W^T x = y$$

out of all the linear functions that interpolate the training data, (S)GD selects the minimal Euclidean norm one.

Wow.

GD + LS = a red herring

Theorem

For linear least squares GD converges to the minimum norm solution of $X^T w = y$

GD is IMPLICITLY regularizing against large norm solutions? It's Implicitly biased towards GENERALIZABLE solutions?

Well, linear LS is what's special

Theorem

ANY algorithm that converges to 0-error and whose iterates converge to $w_\infty = \sum_i a_i x_i$ returns a min norm solution to the LS problem.

- Proof:

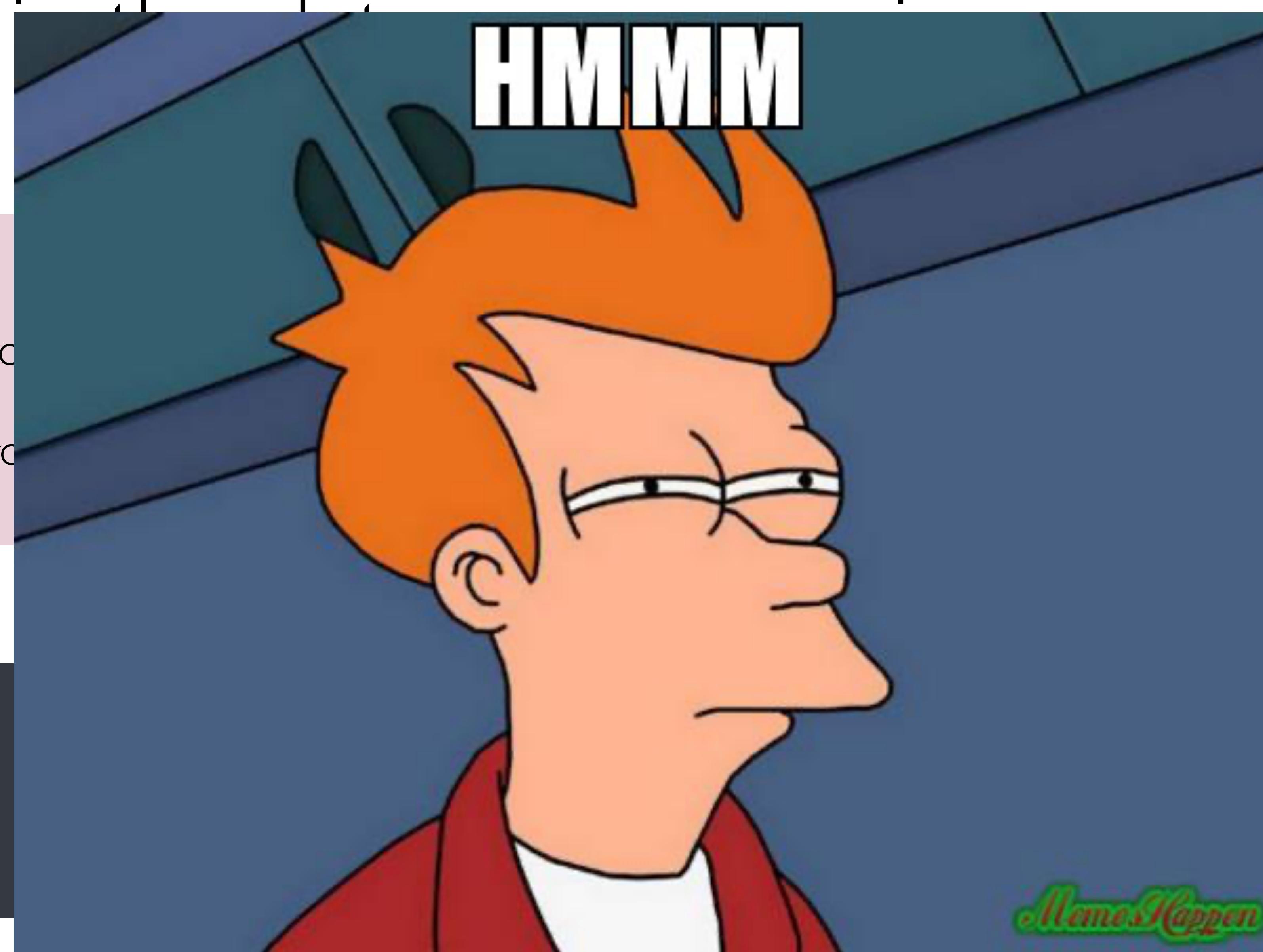
All interpolating solutions in the data span are min norm

Theorem

ANY algorithm that converges to 0-error and whose iterates converge to $w_\infty = \sum_i a_i x_i$ returns a min norm solution to the LS problem.

OK so maybe GD is ... not that special???

All interpolating solutions



Theorem

ANY algorithm that c

solution to the LS pro

turns a min norm

Implicit Bias of Gradient Descent on Linear Convolutional Networks

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On the Spectral Bias of Neural Networks

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Implicit Regularization in Deep Matrix Factorization

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for some problems, GD does look like it's converging on solutions that seem to be regularized (small norm), in some sense

Implicit Regularization in Matrix Factorization

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Characterizing Implicit Bias in Terms of Optimization Geometry

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Implicit Regularization in Nonconvex Statistical Estimation: Gradient Descent Converges Linearly for Phase Retrieval and Matrix Completion

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Implicit Bias of Gradient Descent for Wide Two-layer Neural Networks Trained with the Logistic Loss

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IN SEARCH OF THE REAL INDUCTIVE BIAS: ON THE ROLE OF IMPLICIT REGULARIZATION IN DEEP LEARNING

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The Implicit Bias of Gradient Descent on Separable Data

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Theorem 3 *For any dataset which is linearly separable (Assumption 1), any β -smooth decreasing loss function (Assumption 2) with an exponential tail (Assumption 3), any stepsize $\eta < 2\beta^{-1}\sigma_{\max}^{-2}(\mathbf{X})$ and any starting point $\mathbf{w}(0)$, the gradient descent iterates (as in eq. 2) will behave as:*

$$\mathbf{w}(t) = \hat{\mathbf{w}} \log t + \boldsymbol{\rho}(t), \quad (3)$$

where $\hat{\mathbf{w}}$ is the L_2 max margin vector (the solution to the hard margin SVM):

$$\hat{\mathbf{w}} = \underset{\mathbf{w} \in \mathbb{R}^d}{\operatorname{argmin}} \|\mathbf{w}\|^2 \text{ s.t. } \mathbf{w}^\top \mathbf{x}_n \geq 1, \quad (4)$$

and the residual grows at most as $\|\boldsymbol{\rho}(t)\| = O(\log \log(t))$, and so

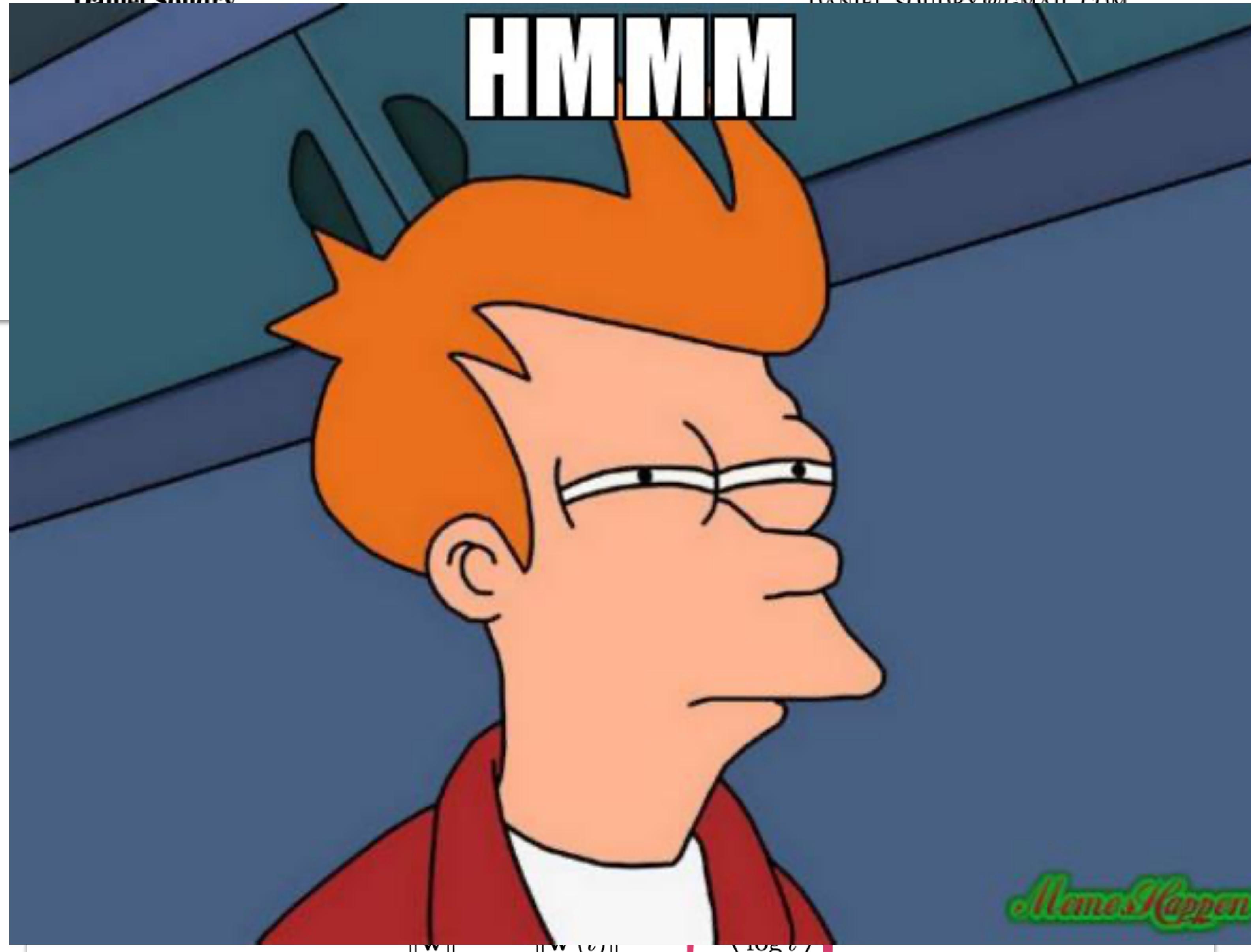
$$\lim_{t \rightarrow \infty} \frac{\mathbf{w}(t)}{\|\mathbf{w}(t)\|} = \frac{\hat{\mathbf{w}}}{\|\hat{\mathbf{w}}\|}.$$

Furthermore, for almost all data sets (all except measure zero), the residual $\rho(t)$ is bounded.

The Implicit Bias of Gradient Descent on Separable Data

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MemeHappen

Does SGD really regularize??

Implicit Regularization in ReLU Networks with the Square Loss

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Weizmann Institute of Science

Editors: Mikhail Belkin and Samory Kpotufe

Abstract

Understanding the implicit regularization (or implicit bias) of gradient descent has recently been a very active research area. However, the implicit regularization in nonlinear neural networks is still poorly understood, especially for regression losses such as the square loss. Perhaps surprisingly, we prove that even for a single ReLU neuron, it is impossible to characterize the implicit regularization with the square loss by any explicit function of the model parameters (although on the positive side, we show it can be characterized approximately). For one hidden-layer networks, we prove a similar result, where in general it is impossible to characterize implicit regularization properties in this manner, except for the “balancedness” property identified in [Du et al. \(2018\)](#). Our results suggest that a more general framework than the one considered so far may be needed to understand implicit regularization for nonlinear predictors, and provides some clues on what this framework should be.

Implicit Regularization in ReLU Networks with the Square Loss

Gal Vardi

Weizmann Inst.

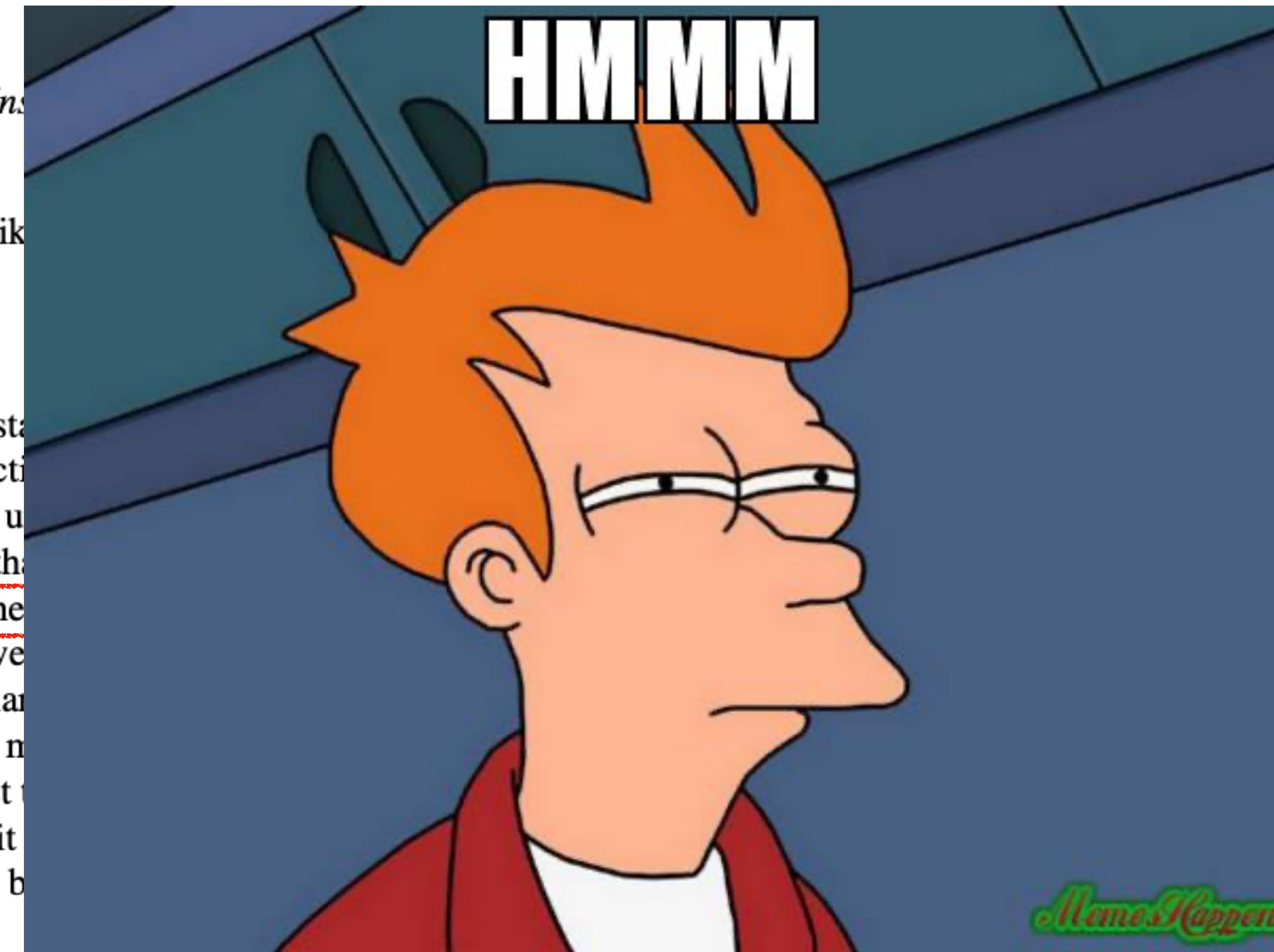
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Understand very active poorly understand prove that with the side, we a similar in this new suggest implicit should b

HM MM

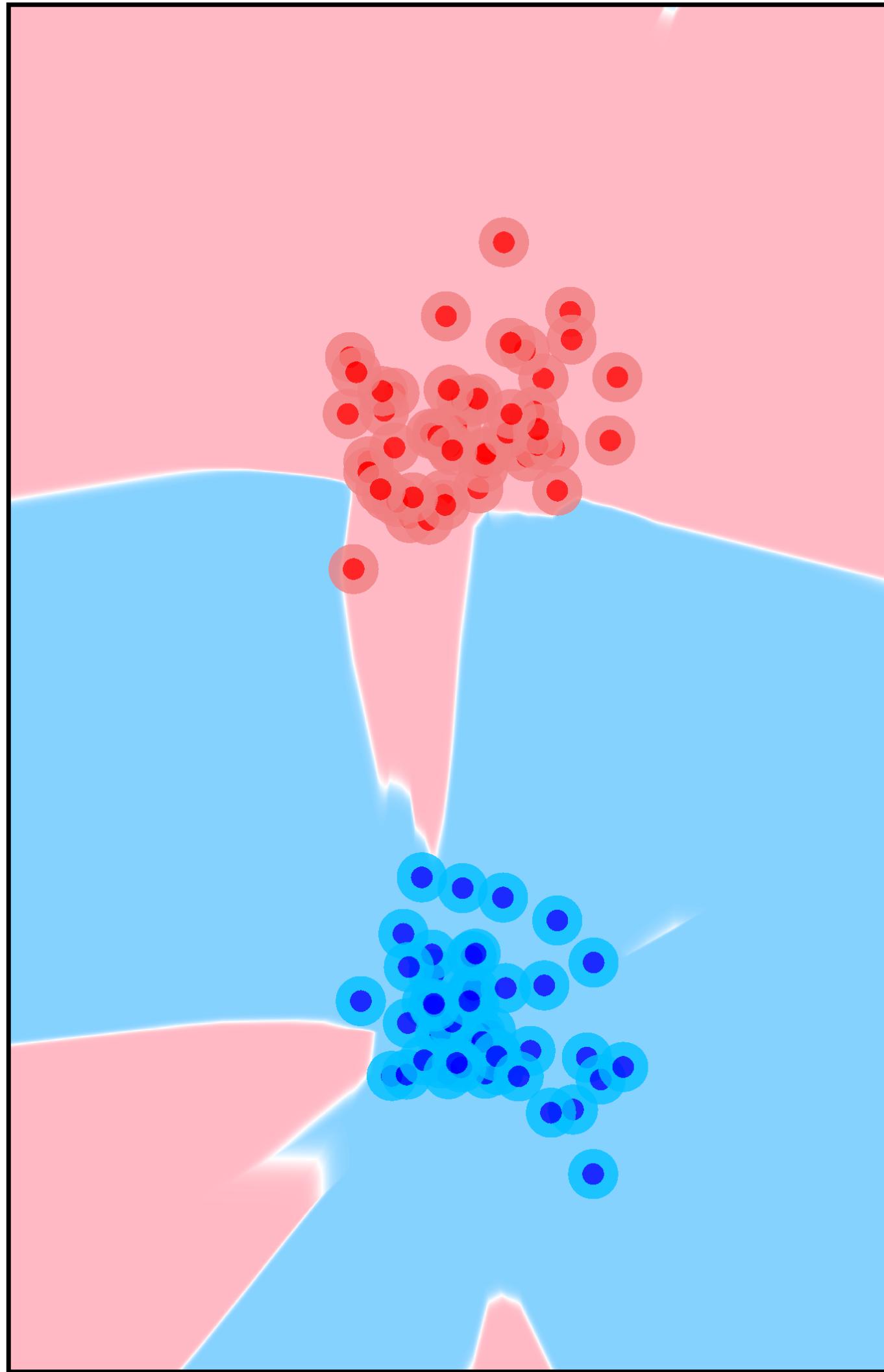
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MemesHappen

But maybe some form of hard to describe regularization is happening???

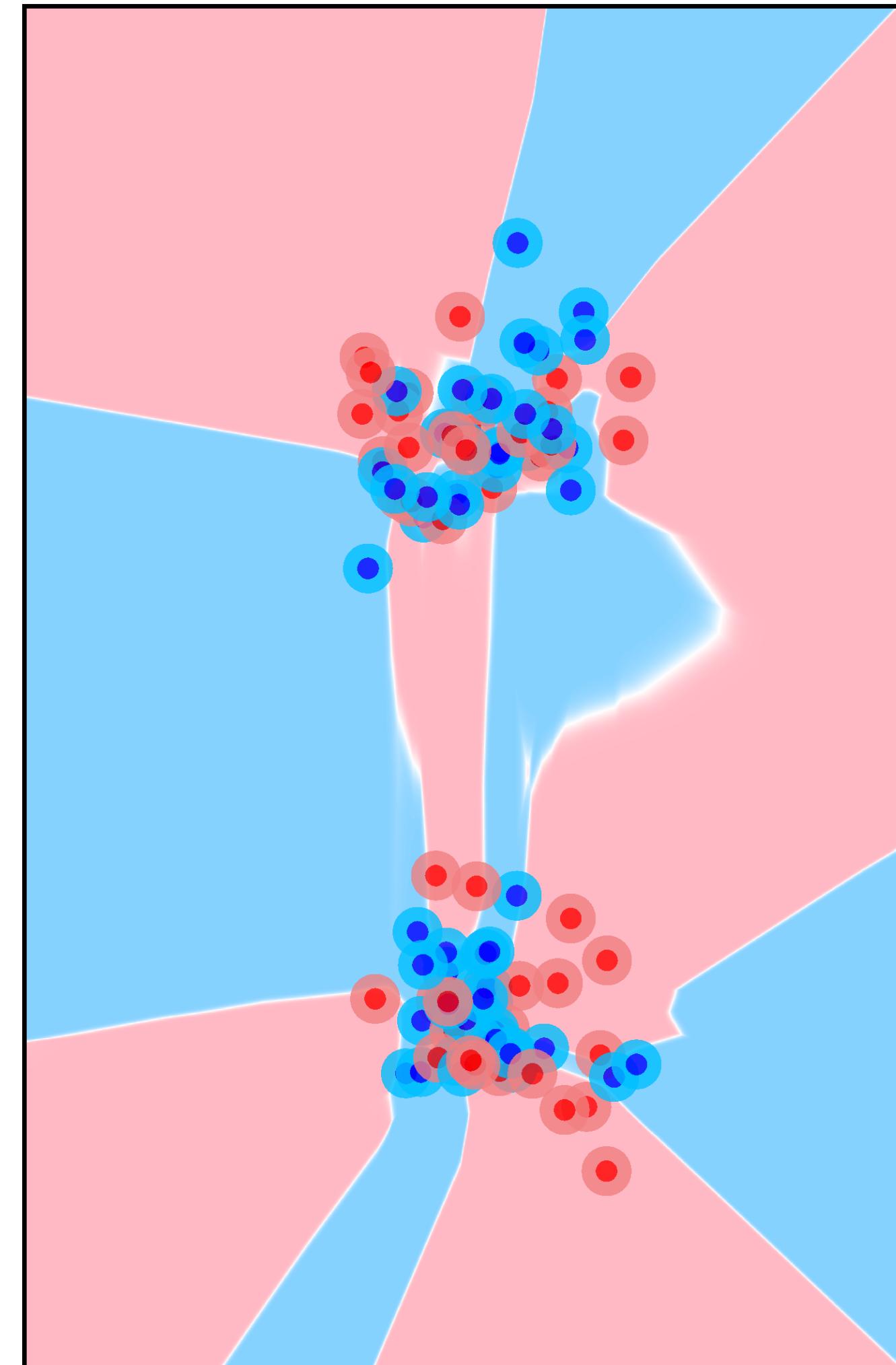
Can SGD reach bad global minima?



- Of course ... if you initialize at a bad global min.
- But, SGD still converges to them, if adversarially initialized
even without loss-landscape knowledge

We can construct initializers
using only unlabeled data
From which SGD is attracted to bad global minima

Adversarial Initialization



Input: Training dataset S ; Replication factor R ; Noise factor N

for every image $x \in S$ repeat R times

zero-out a random subset of $N\%$ pixels in x

give it a random label

Add it to set C

Train to 100% accuracy on C , from a random init using vanilla SGD

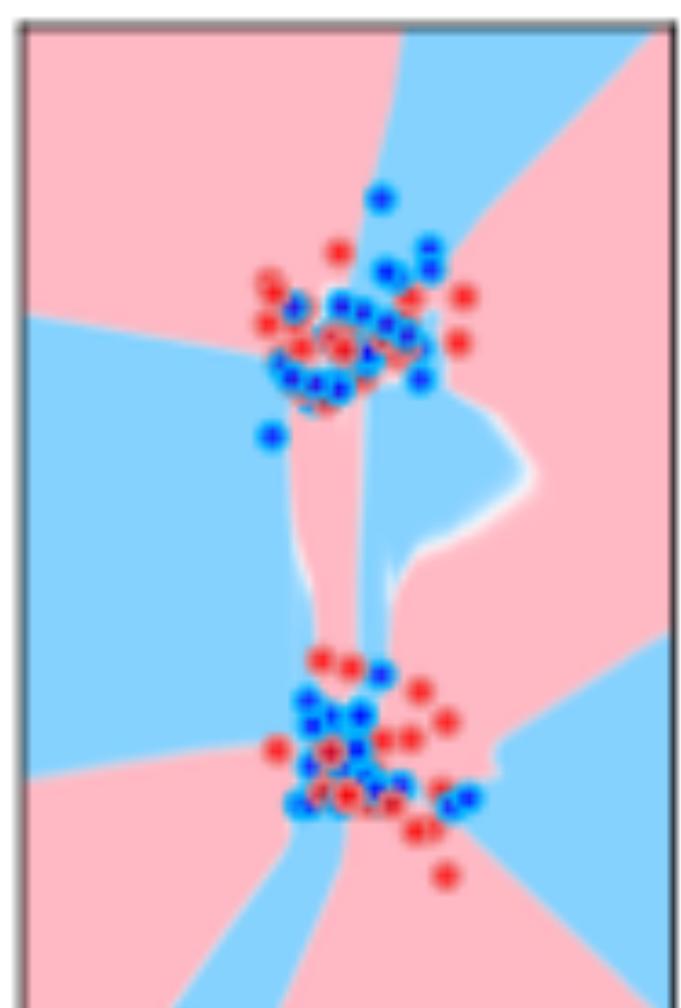
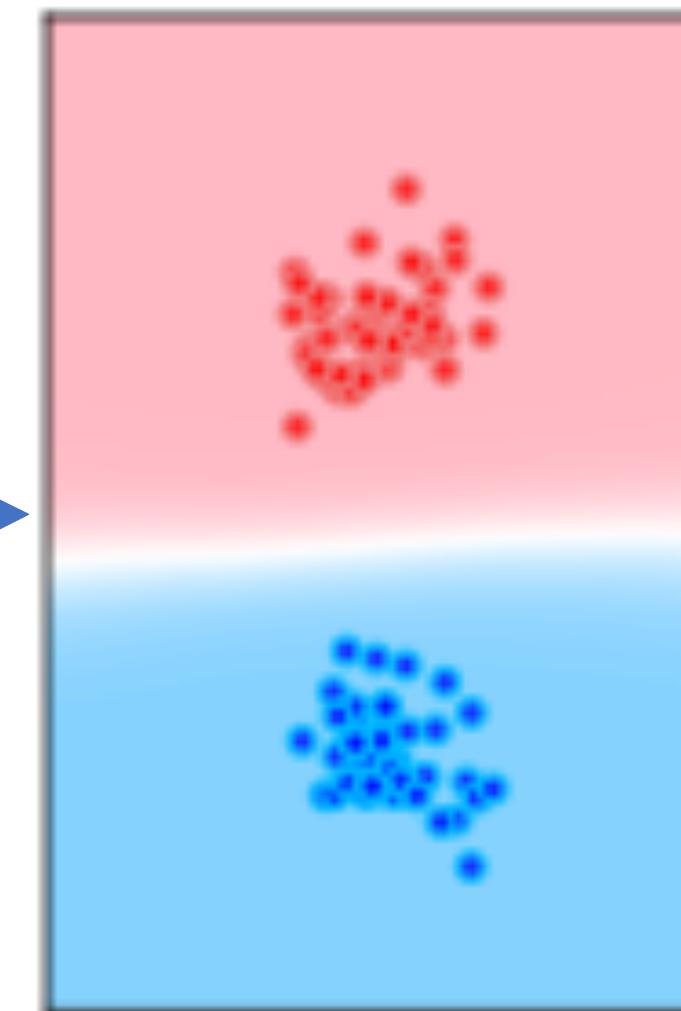
How Vanilla SGD gets in bad global minima

Random
Initialization

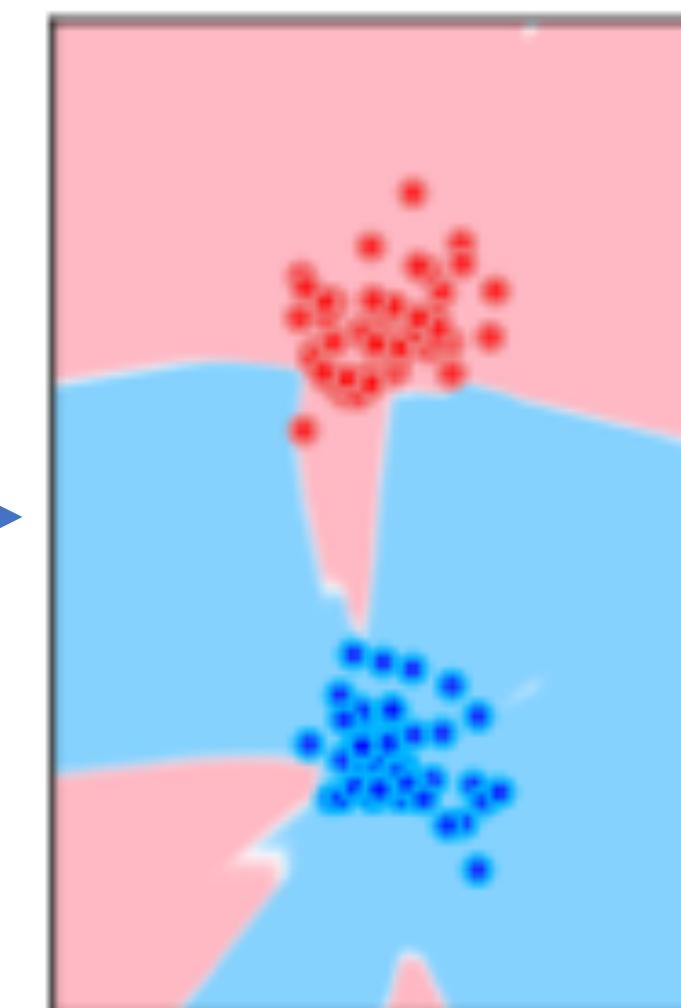
True labels



Random labels



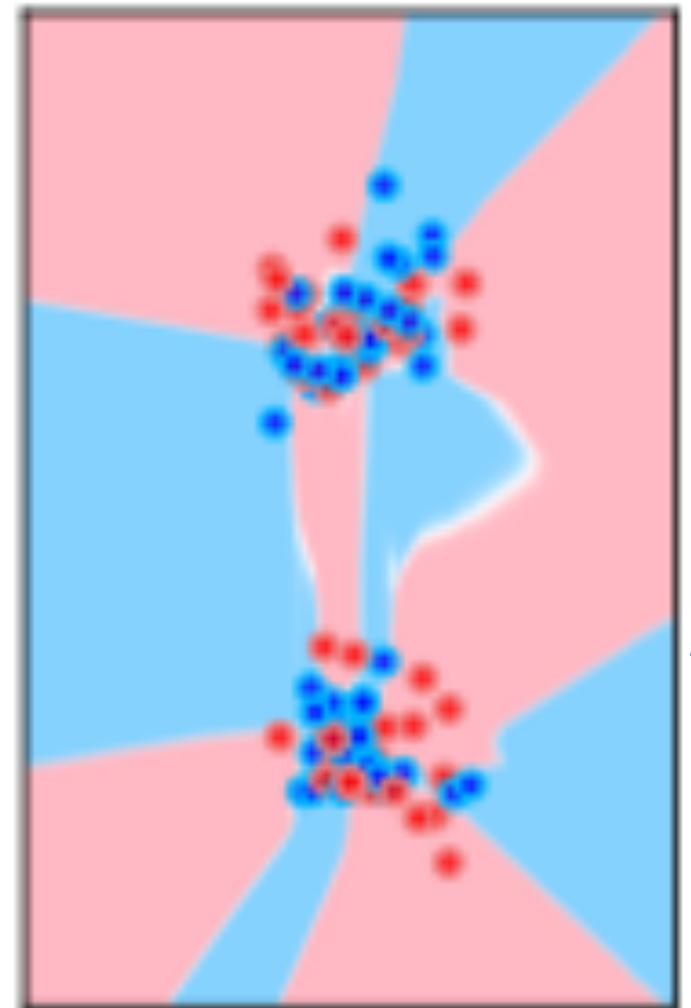
True labels



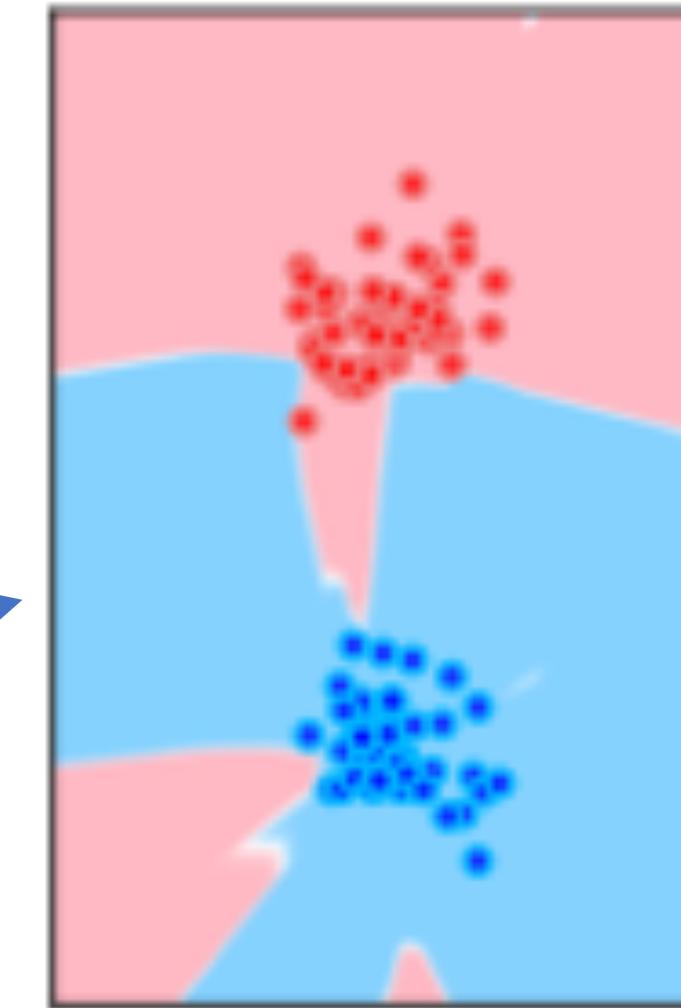
SGD “repairs” the
boundary just
enough to fit the data

Can’t “forget” the
bad initialization

Regularization saves the day



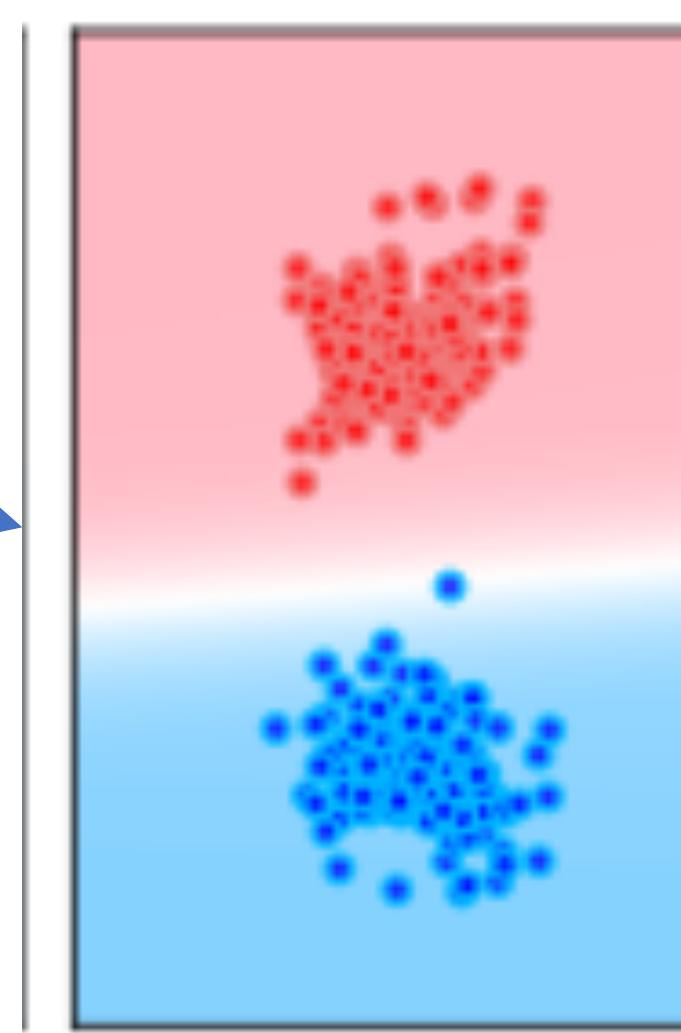
Vanilla SGD



Data augmentation

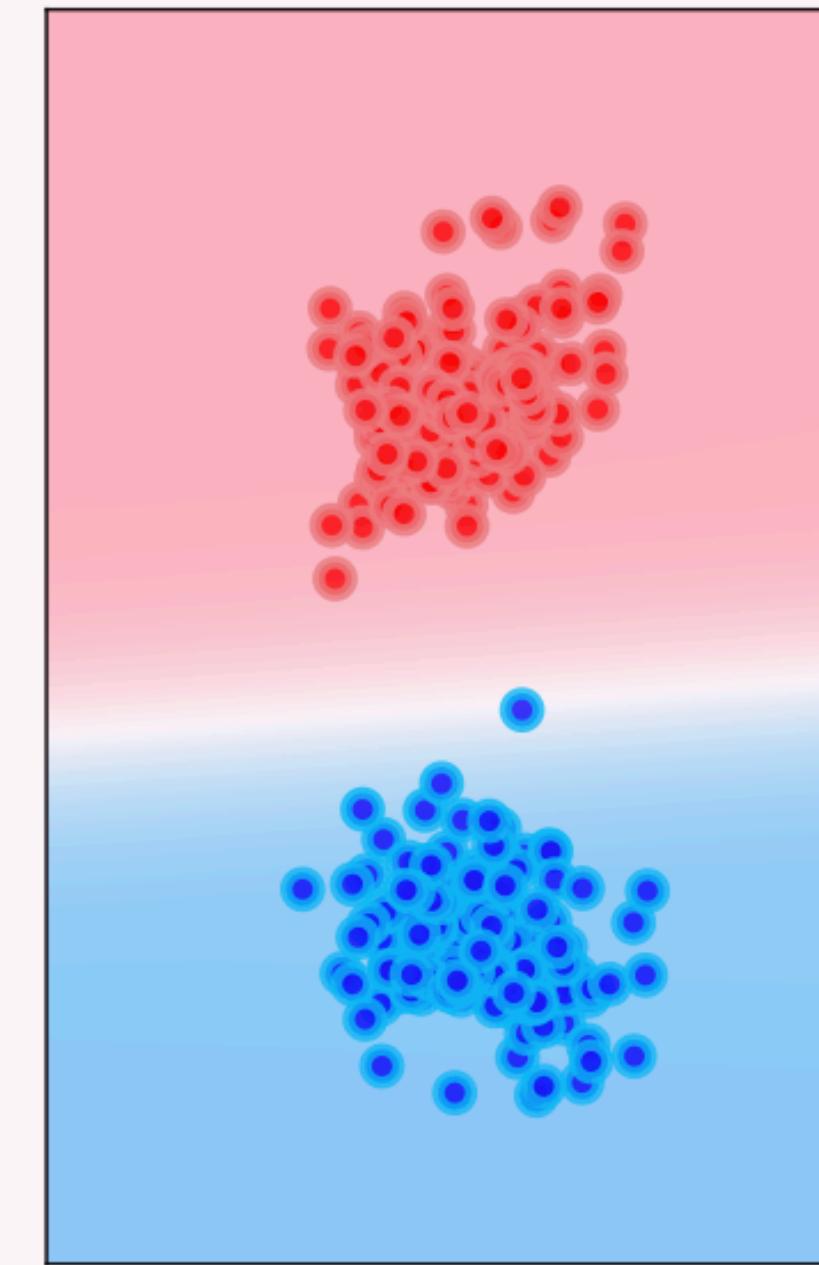
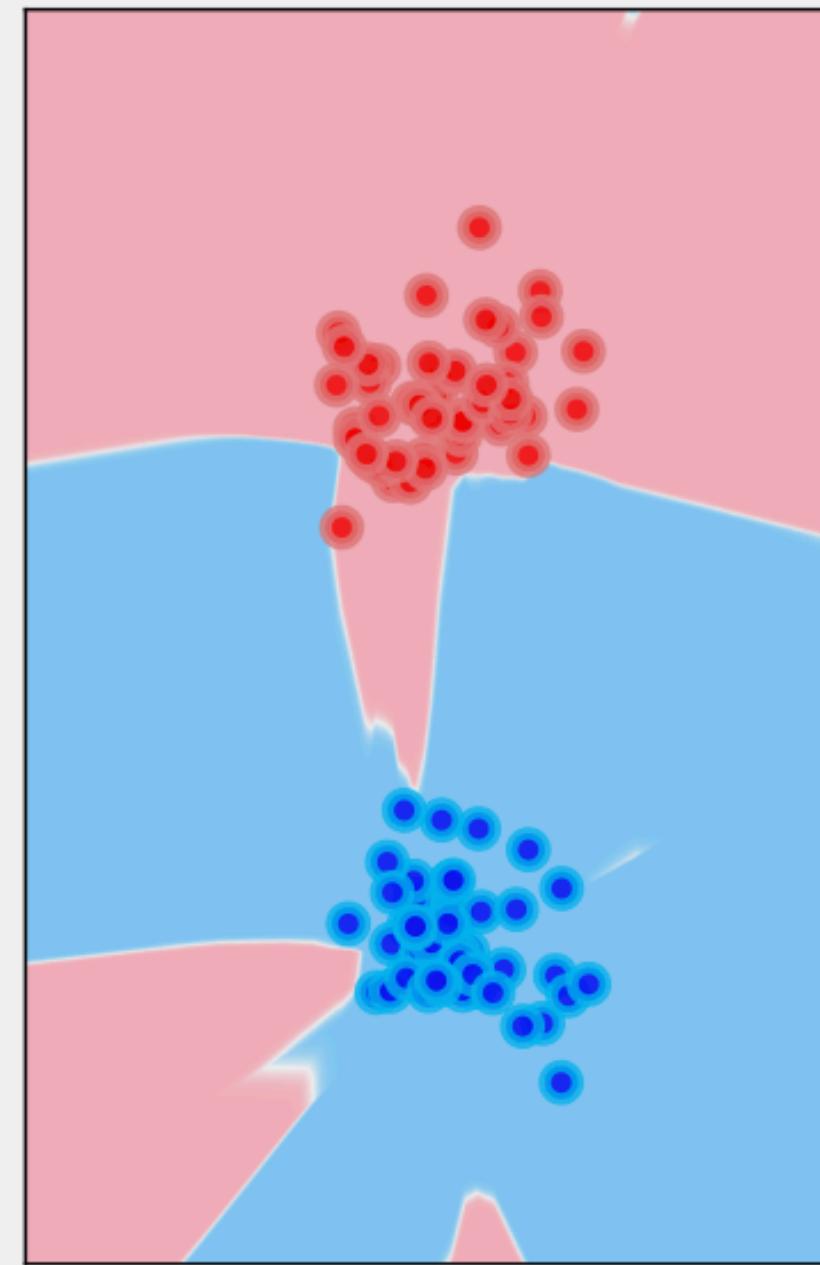
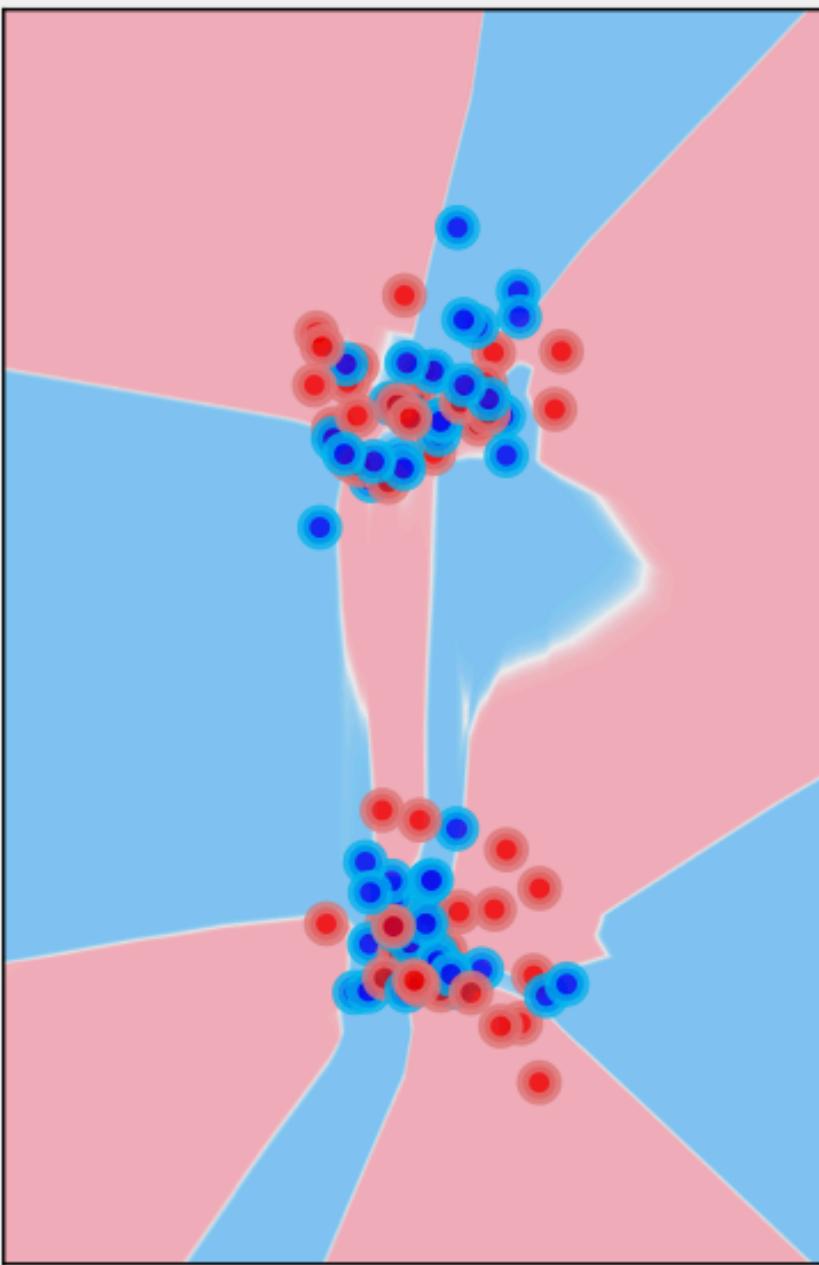
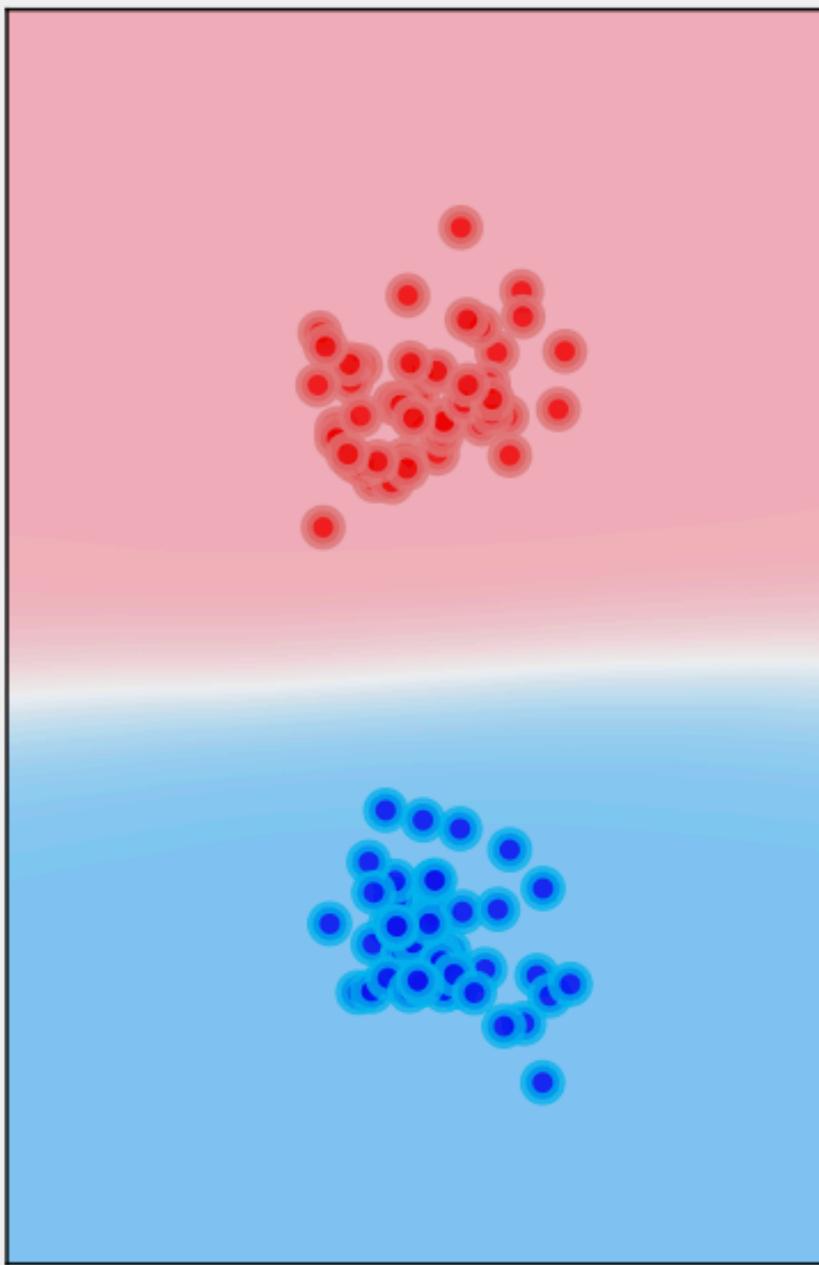
+

L2 regularization



Regularization allows
SGD to escape
adversarial
initializations

A recap of the setups

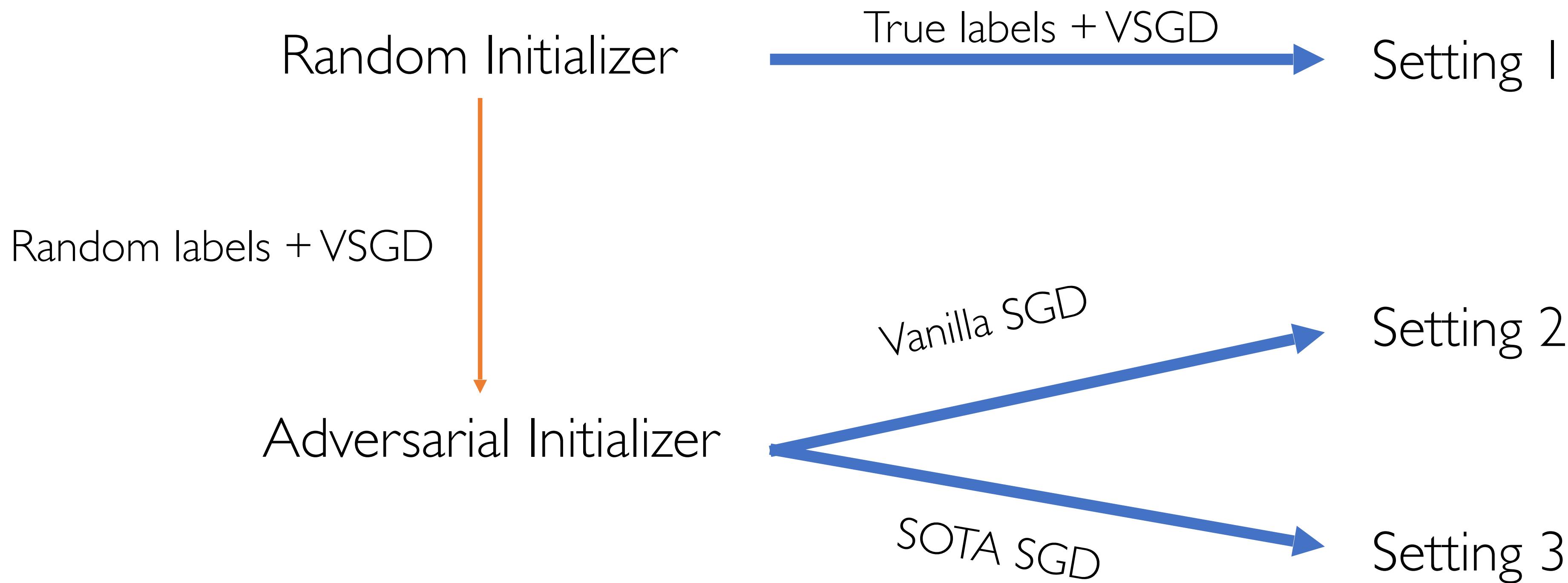


Vanilla SGD

SOTA SGD

Experiments

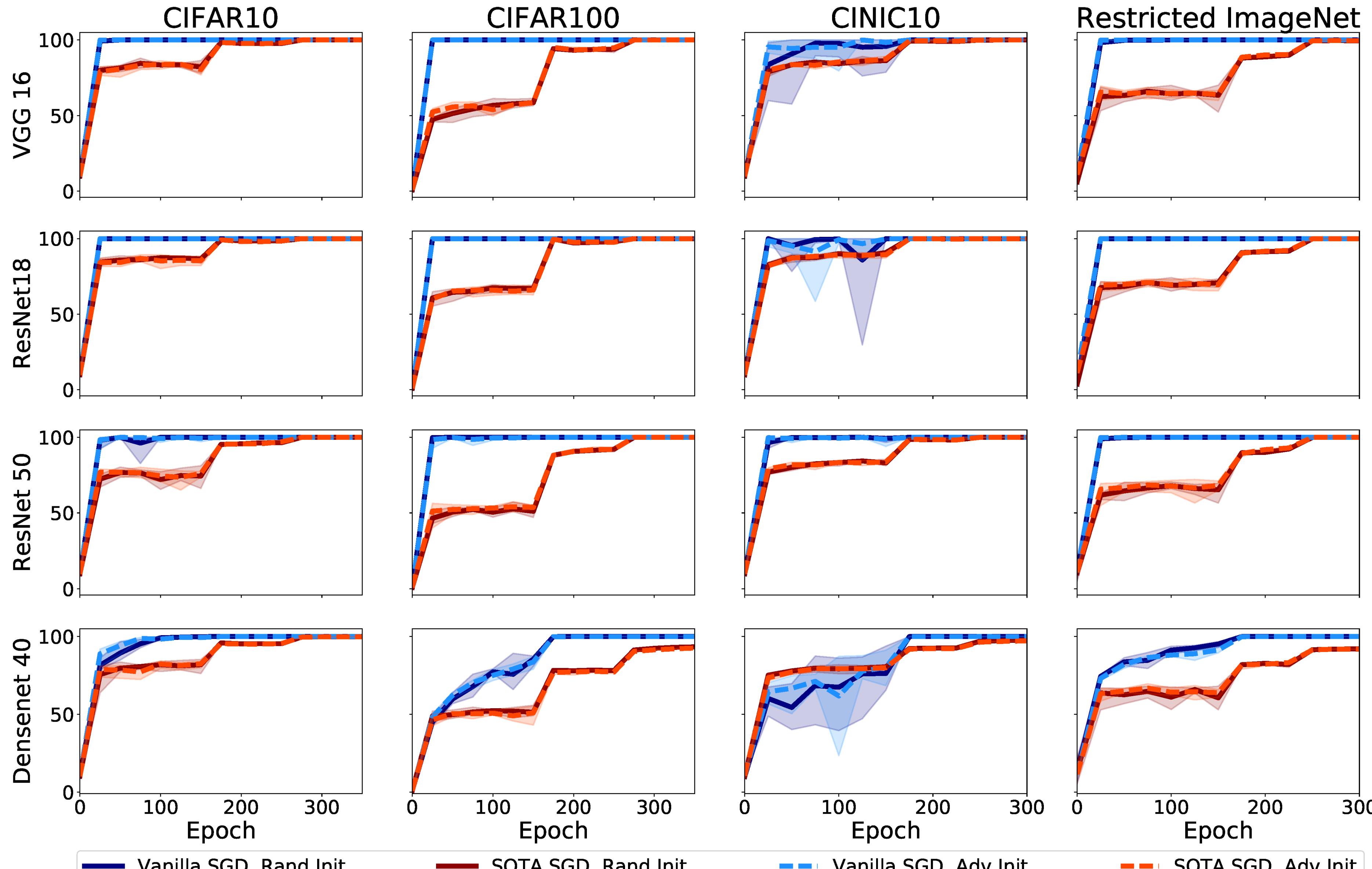
- **Data Sets:** Cifar10/100, CINIC10, Restricted Imagenet
- **Architectures:** VGG16, Resnet18/50, DenseNet40
- Hyperparameters tuned for faster convergence on train



Main Findings

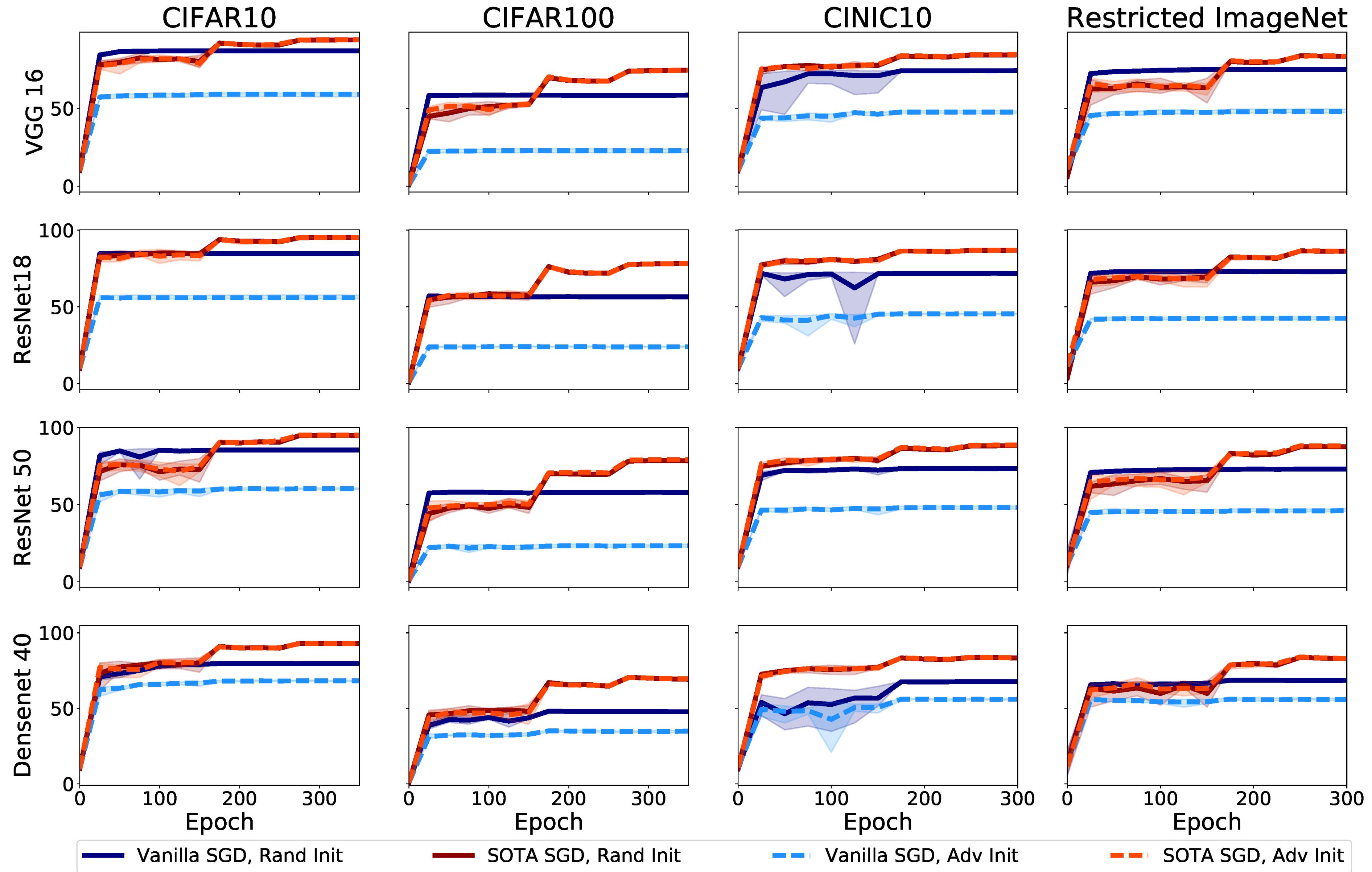
- Adversarial initialization causes VSGD up to 40% drop in test accuracy
- The model found is close to the adversarial initialization.
- Data augmentation, momentum, and L2 regularization all contribute to SGD escaping adversarial initialization.
- Any two of {DA, M, L2} are enough.

Train Accuracy



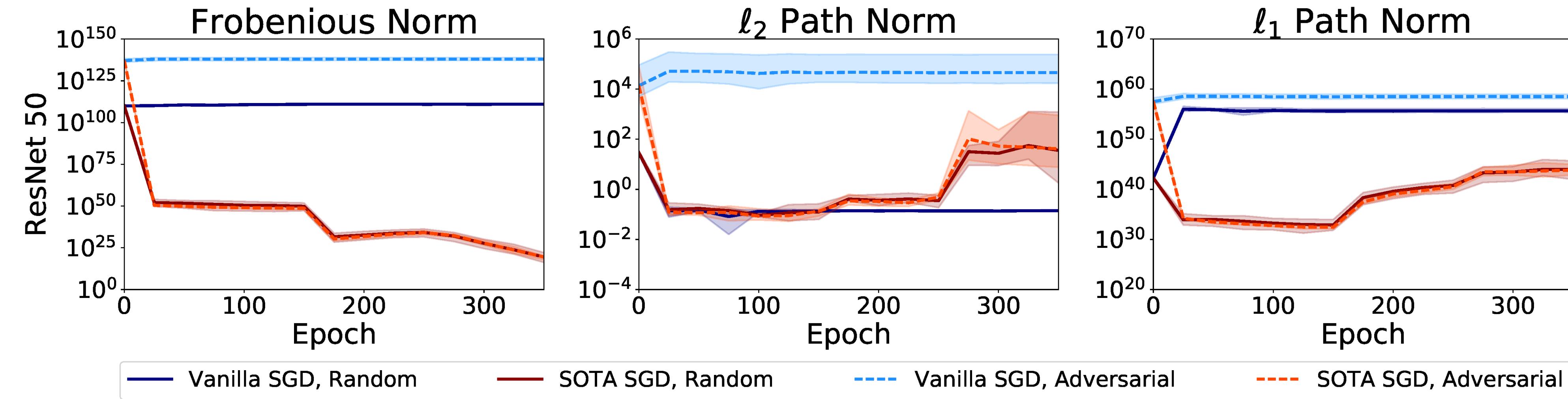
TL;DR:
Everything
converges to 100%
train accuracy

Test Accuracy



TL;DR:
Test error
deteriorates for
Vanilla SGD and
Adv initialization

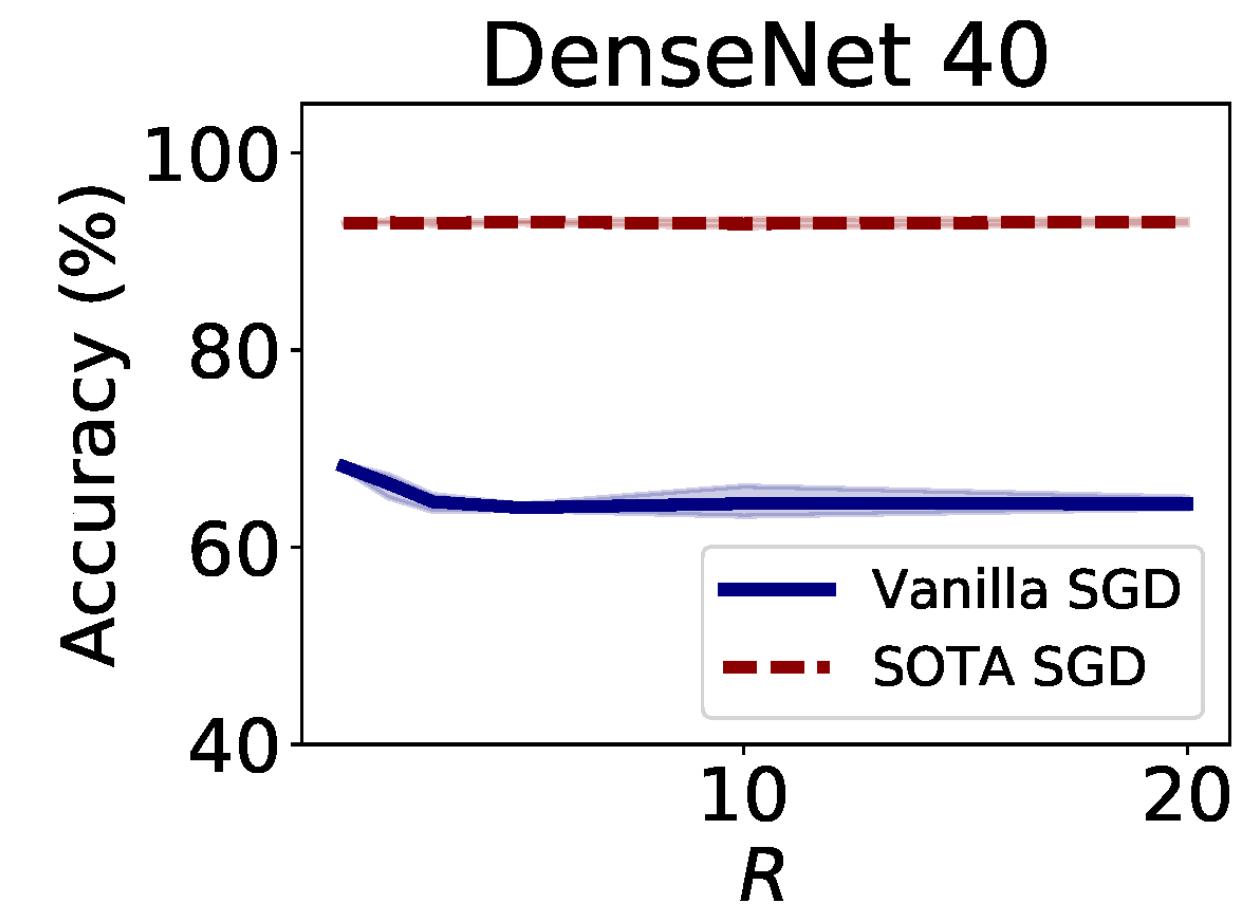
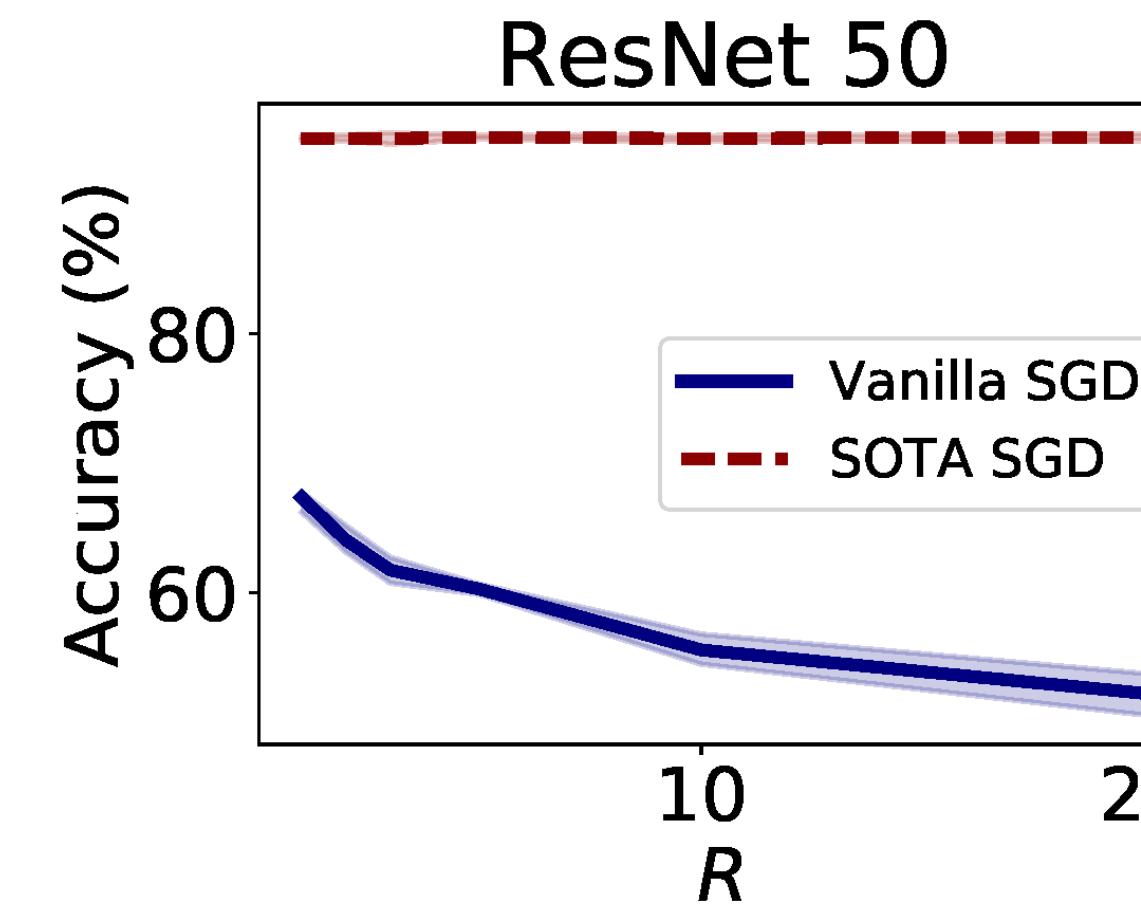
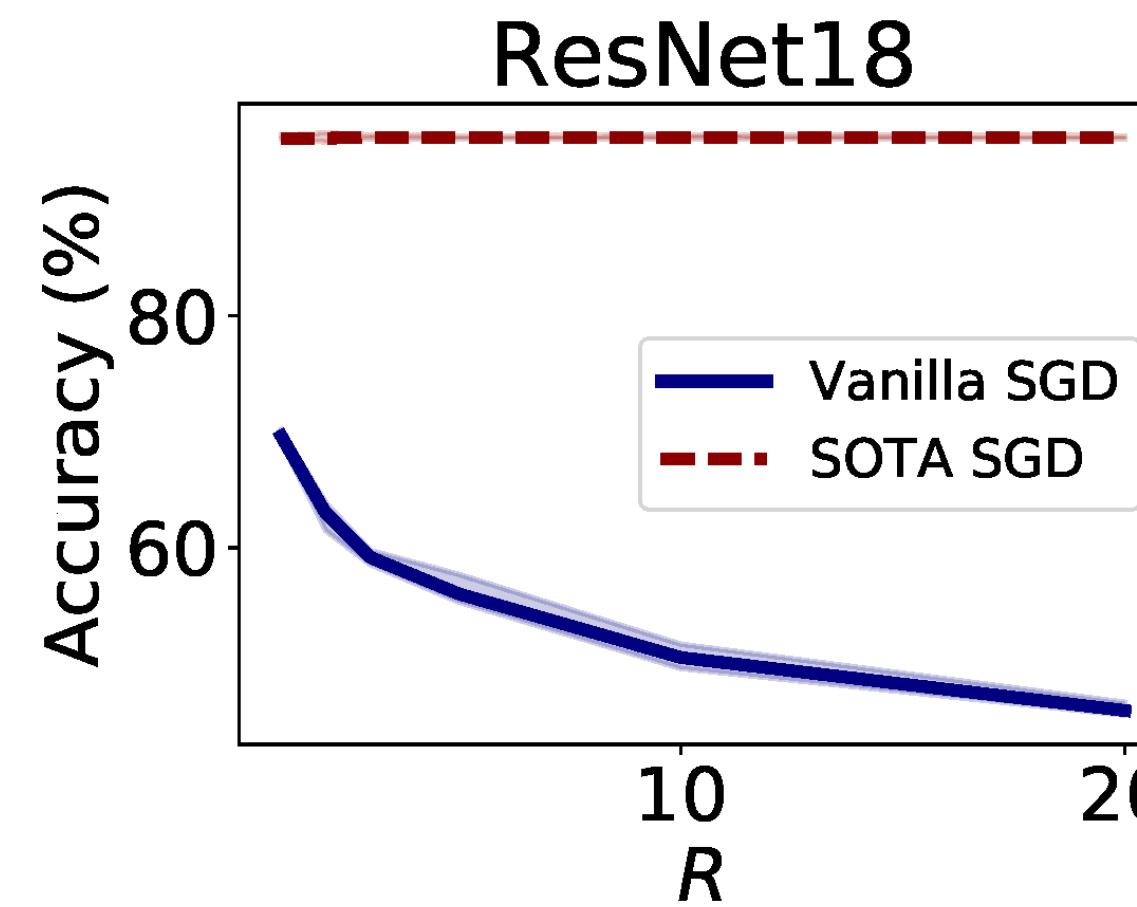
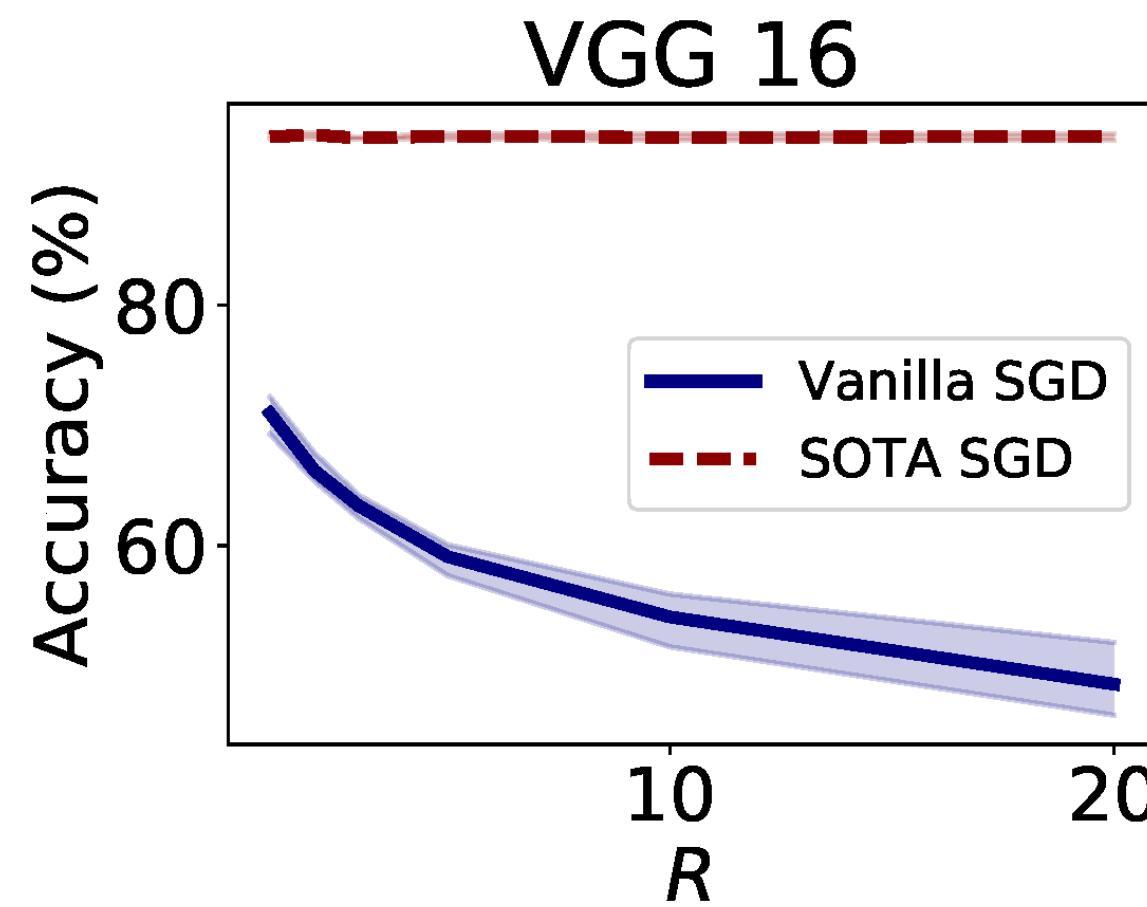
Model Complexity



ResNet 50 trained on CIFAR 10.

TL;DR:
SGD on adv init has higher complexity measures
compared to all other models

Effect of Replication Factor



TL;DR:

The more you augment the randomly labeled set,
the worse test error becomes

What is the point of all this

Implicit bias is likely weak in comparison to explicit regularization

Regularization affects the entire search dynamics, not just around global minima

The importance of regularization even very far away from the minima of the loss landscape.

Possible Explanations of Generalization

nope

- Maybe every model that fits the training data generalizes (no bad global minima)

Current implicit bias studies can't capture such a strong effect

- Maybe SGD is special “can avoid” bad global minima (implicit regularization)?

- Maybe the data distribution is what allows everything to fall into place?

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Nobody knows

reading list

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