Compression2

May 7, 2022

```
[]: import numpy as np # linear algebra
     import pandas as pd # data processing, CSV file I/O (e.g. pd.read_csv)
     import os
     from tensorflow import keras
     import tensorflow as tf
     from keras import Sequential
     from keras.layers import Dense, Conv2D, MaxPooling2D, Activation, U
     →BatchNormalization, Flatten
     from keras.utils.np_utils import to_categorical
     from keras.preprocessing.image import ImageDataGenerator
     import matplotlib.pyplot as plt
     import matplotlib.image as mpimg
     from numpy.lib.stride_tricks import as_strided
     from natsort import natsorted
     import cv2
     import glob
```

```
[]: from google.colab import drive
     drive.mount('/content/drive')
```

Mounted at /content/drive

On s'intéresse à présent à la degradation des image au passage par un filtre gaussien 2D

```
[]: import pathlib
     data_loc = tf.keras.utils.get_file(
         "dataset.zip",
         "https://github.com/anajmedd/Image-Compression/blob/main/dataset.zip?
      →raw=true",
         extract=False)
     import zipfile
     with zipfile.ZipFile(data_loc, 'r') as zip_ref:
         zip_ref.extractall('/content/datasets')
```

```
data_loc = pathlib.Path('/content/datasets/datasets')
print(data_loc)
print(os.path.abspath(data_loc))
```

Construction du dataset des image en noir et blanc

```
[]: path = '/content/datasets/datasets/cat/flickr_cat_000056.jpg'
w = 11
sigma = 2
img = cv2.imread(path)
img_gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

f = plt.figure(figsize=(10,13))
f.add_subplot(121).imshow(img)
plt.axis('off')
f.add_subplot(122).imshow(img_gray, cmap='gray')
plt.axis('off')
```

[]: (-0.5, 511.5, 511.5, -0.5)





```
[]: fd = '/content/datasets/datasets/cat'
fd1 = '/content/datasets/datasets/dog'
```

```
[]: dir = '/content/datasets/datasets_bw/cat'
#os.mkdir('/content/datasets/datasets_bw')
#os.mkdir('/content/datasets/datasets_bw/cat')
from PIL import Image
c=1
for filename in os.listdir(fd):
    if '.jpg' in filename:
        path = fd+'/'+filename
        img = cv2.imread(path)
        name = 'cat' + str(c)+ '_bw.jpg'
        c+=1
        img_gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        cv2.imwrite(os.path.join(dir , name), img_gray)
        cv2.waitKey(0)
```

Construction de la réponse du filtre gaussien

```
def get_all_window(M, w):
    M = np.pad(M, w//2, 'symmetric')
    sub_shape = (w, w)
    view_shape = tuple(np.subtract(M.shape, sub_shape) + 1) + sub_shape
    arr_view = as_strided(M, view_shape, M.strides * 2)
    arr_view = arr_view.reshape((-1,) + sub_shape)
    return arr_view

def convolution_2d(im, K):
    w, _ = K.shape
    m,n = im.shape
    im_all_subw = get_all_window(im, w)
    X = np.sum(np.sum(im_all_subw * K, 1), 1)
    return X.reshape(m,n)
```

```
[]: def filtre2D(w, sigma):
    w = w + (w % 2 == 0)
    F = np.zeros([w,w])
    mid = w//2
    k = np.arange(w) - mid
    for i in k:
        for j in k:
            par = (i**2 + j**2)/(2*sigma**2)
            F[i + mid,j + mid] = np.exp(-par)/(2*np.pi*sigma**2)
    return F
```

```
[]: h = filtre2D(w, sigma)
  im_gauss = convolution_2d(imgrey, h)

f = plt.figure(figsize=(10,13))
  f.add_subplot(221, title='Originale').imshow(img_gray, cmap='gray')
```

```
plt.axis('off')
f.add_subplot(222, title='Resultat').imshow(im_gauss, cmap='gray')
plt.axis('off')
```

[]: (-0.5, 511.5, 511.5, -0.5)





Construction du dataset contenant les image filtrées

```
[]: !rm -rf /content/datasets/data_filtered
     os.mkdir('/content/datasets/data_filtered')
     os.mkdir('/content/datasets/data_filtered/cat')
     data_loc1 = '/content/datasets/datasets/cat'
     data_loc3 = '/content/datasets/data_filtered/cat'
[]: import os
     c=1
     for filename in os.listdir(data_loc1):
         if filename.endswith(".jpg"):
             path = data_loc1 +'/' + filename
             img = cv2.imread(path)
             name='cat'+str(c)+'_filtred.jpg'
             c+=1
             img_gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
             im_gauss = convolution_2d(img_gray, h)
             cv2.imwrite(os.path.join(data_loc3 , name), im_gauss)
             cv2.waitKey(0)
         else:
              continue
```

```
[]: def load_img(filepath):
         img = cv2.cvtColor(cv2.imread(filepath), cv2.COLOR_BGR2RGB)
         img = img.astype(np.float32)
         img = img / 255.
         return img
[]: from skimage.metrics import peak_signal_noise_ratio, structural_similarity
     def print_arr_metrics(m, n):
         x = [peak_signal_noise_ratio(a, b) for a, b in zip(m, n)]
         y = [structural_similarity(a, b, multichannel=True, data_range=1) for a, b_
      \rightarrowin zip(m, n)]
         print(f"PSNR: {np.mean(x)}")
         print(f"SSIM: {np.mean(y)}")
          return x, y
[]: !rm -rf /content/datasets/folder
[]: import shutil
     target = '/content/datasets/folder'
     pw1 = '/content/datasets/datasets_bw/cat'
     pw2 = '/content/datasets/data_filtered/cat'
     os.mkdir(target)
     for filename in os.listdir(pw1):
       shutil.copyfile(pw1+'/'+filename,target+'/'+filename)
     for filename in os.listdir(pw2):
       shutil.copyfile(pw2+'/'+filename,target+'/'+filename)
[]: bw files = natsorted(glob.glob('/content/datasets/folder/* bw.jpg'))
     filtred_files = natsorted(glob.glob('/content/datasets/folder/*_filtred.jpg'))
[]: bw images = [load img(v) for v in bw files]
                                                    ## Black and white images
     filtred_images = [load_img(v) for v in filtred_files]
[]: print(bw_files[0])
     print(filtred_files[0])
    /content/datasets/folder/cat1_bw.jpg
    /content/datasets/folder/cat1_filtred.jpg
[ ]: def print_arr_metrics(m, n):
         x = [peak_signal_noise_ratio(a, b) for a, b in zip(m, n)]
         y = [structural_similarity(a, b, multichannel=True, data_range=1) for a, b_
      \rightarrowin zip(m, n)]
         print(f"PSNR: {np.mean(x)}")
         print(f"SSIM: {np.mean(y)}")
```

```
return x, y
 []: print_arr_metrics(filtred_images, bw_images)
     PSNR: 26.99100209033164
     SSIM: 0.743821117465575
        Dégradation des images par la SVD
parent_dir = '/content/datasets/datasets_SVD'
     cat_dir = '/content/datasets/datasets_SVD/cat'
     os.mkdir(parent_dir)
     os.mkdir(cat_dir)
[83]: c=1
            ## Valeur à changer pour visualiser l'effet sur le PSNR
     r=50
     data loc1 = '/content/datasets/datasets/cat'
     for filename in os.listdir(data_loc1):
         if filename.endswith(".jpg"):
             img = Image.open(data_loc1+'/'+filename)
             imggray = img.convert('LA')
             imgmat = np.array(list(imggray.getdata(band=0)),float)
             imgmat.shape= (imggray.size[1], imggray.size[0])
             imgmat = np.matrix(imgmat)
             U, sigma, V = np.linalg.svd(imgmat)
             name='cat' +str(c)+'_svd.jpg'
             c+=1
             reconsting = np.matrix(U[:, :r]) * np.diag(sigma[:r]) * np.matrix(V[:r,:
      →])
             im = Image.fromarray(reconsting)
             rgb_im = im.convert('RGB')
             rgb_im.save(cat_dir+'/'+name,'JPEG')
         else:
              continue
[84]: import shutil
     !rm -rf /content/datasets/folder2
     target2 = '/content/datasets/folder2'
```

```
[!rm -rf /content/datasets/folder2
target2 = '/content/datasets/folder2'
pwd1 = '/content/datasets/datasets_bw/cat'
pwd2 = '/content/datasets/datasets_SVD/cat'
os.mkdir(target2)
for filename in os.listdir(pwd1):
    shutil.copyfile(pwd1+'/'+filename,target2+'/'+filename)
for filename in os.listdir(pwd2):
    shutil.copyfile(pwd2+'/'+filename,target2+'/'+filename)
```

```
[85]: bw_files = natsorted(glob.glob('/content/datasets/folder2/*_bw.jpg'))
      svd_files = natsorted(glob.glob('/content/datasets/folder2/*_svd.jpg'))
[86]: bw_images = [load_img(v) for v in bw_files]
      svd_images = [load_img(v) for v in svd_files]
[89]: print(bw_files[0])
      print(svd_files[0])
     /content/datasets/folder2/cat1_bw.jpg
     /content/datasets/folder2/cat1_svd.jpg
[90]: print_arr_metrics(svd_images, bw_images)
     PSNR: 28.83465742408829
     SSIM: 0.7838102175738757
     Création du modèle des images dégradées par filrage
 []: batch_size = 3
      img_height = 200
      img_width = 200
      parent_dir1 = '/content/datasets/Compressed_data_gauss_filter'
      train_data01 = tf.keras.preprocessing.image_dataset_from_directory(
        parent_dir1,
        validation_split=0.2,
        subset="training",
        seed=42,
        image_size=(img_height, img_width),
        batch_size=batch_size)
      val_data01 = tf.keras.preprocessing.image_dataset_from_directory(
        parent_dir1,
        validation_split=0.2,
        subset="validation",
        seed=42,
        image_size=(img_height, img_width),
       batch_size=batch_size)
      class_names1 = val_data01.class_names
      print(class names1)
 []: from tensorflow.keras import layers
      num_classes = 2
      model1 = tf.keras.Sequential([
          layers.experimental.preprocessing.Rescaling(1./255),
          layers.Conv2D(128,4, activation='relu'),
```

```
layers.MaxPooling2D(),
   layers.Conv2D(64,4, activation='relu'),
   layers.MaxPooling2D(),
   layers.Conv2D(32,4, activation='relu'),
   layers.MaxPooling2D(),
   layers.Conv2D(16,4, activation='relu'),
   layers.MaxPooling2D(),
   layers.Flatten(),
   layers.Dense(64,activation='relu'),
   layers.Dense(num_classes, activation='softmax')
])
model1.compile(optimizer='adam', loss=tf.losses.
→SparseCategoricalCrossentropy(from_logits=True), metrics=['accuracy'],)
logdir="logs"
tensorboard_callback1 = keras.callbacks.
→TensorBoard(log_dir=logdir,histogram_freq=1, write_images=logdir,⊔
→embeddings_data=train_data02)
history1 = model1.fit(train_data01, validation_data=val_data01, epochs=25, u
```

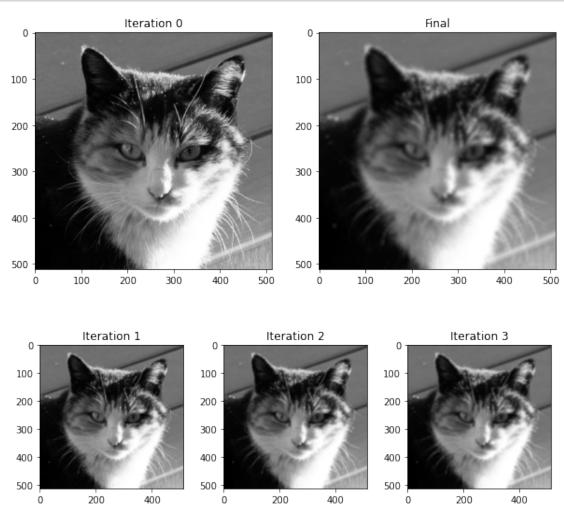
Adaptative filter

```
[]: grad_operators = {
         'prewitt':(
             np.array([[-1,0,1],
                        [-1,0,2],
                       [-1,0,1]]),
             np.array([[1,1,1],
                        [0,0,0],
                        [-1,-1,-1]])
         ),
         'robertcross':(
             np.array([[1,0],
                        [0,1]]),
             np.array([[0,-1],
                       [-1,0]
         ),
         'sobel':(
             np.array([[-1,0,1],
                        [-2,0,2],
                        [-1,0,1]]),
             np.array([[1,2,1],
                        [0,0,0],
```

```
[-1, -2, -1]
         )
     }
     # Distance euclidienne
     def euclidean(Gx, Gy):
         return np.sqrt((Gx**2)+(Gy**2))
[]: def adaptive_weight(Gx, Gy, h):
         return np.exp(np.sqrt(euclidean(Gx, Gy) / (2 * (h ** 2))))
     def adaptive_convolution_2d(im, weight):
         w = 3
         m,n = im.shape
         im_all_subw = get_all_window(im, w)
         weight_all_subw = get_all_window(weight, w)
         X = np.sum(np.sum(im_all_subw * weight_all_subw, 1), 1) / np.sum(np.
      ⇒sum(weight_all_subw, 1), 1)
         return X.reshape(m,n)
     def adaptive_filter(im, n=5, h=1.5, operator='sobel'):
         # 1. K = 1, fixer l'itération n et le coefficient de l'amplitude du edge h.
         \#K = 1
         #h = 1.5
         weights = []
         iteration_result = [im]
         # loop
         for i in range(n):
             # 2. Calcul du gradient Gx et Gy
             op = grad_operators[operator]
             Gx = convolution_2d(im,op[0])
             Gy = convolution_2d(im,op[1])
             # 3. Calcul du poids
             weight = adaptive_weight(Gx, Gy, h)
             weights.append(weight)
             # 4. Convolution
             im = adaptive_convolution_2d(im, weight)
             iteration_result.append(im)
         return im, weights, iteration_result
```

```
[]: N =5
im_adaptive, adaptive_weights, adaptive_iteration_result =

→adaptive_filter(imgrey, N)
```



```
[]: !!rm -rf /content/datasets/Compressed_data
#os.mkdir('/content/datasets/Compressed_data_adapted_filter')
#os.mkdir('/content/datasets/Compressed_data_adapted_filter/cat')
#os.mkdir('/content/datasets/Compressed_data_adapted_filter/dog')
parent_dir2 = '/content/datasets/Compressed_data_adapted_filter'
cat_dir = '/content/datasets/Compressed_data_adapted_filter/cat'
dog_dir = '/content/datasets/Compressed_data_adapted_filter/dog'
```

```
[]: import os
     data_loc1 = '/content/datasets/datasets/cat'
     c=0
     for filename in os.listdir(data_loc1):
         if filename.endswith(".jpg"):
             im = mpimg.imread(data_loc1+'/'+filename)
             imgrey = np.round(0.3 * im[:,:,0] + 0.59 * im[:,:,1] + 0.11 * im[:,:]
      \rightarrow,2]).astype(int)
             name='imgcat' +str(c)+'.jpg'
             im_adaptive, adaptive_weights, adaptive_iteration_result =_
      →adaptive_filter(imgrey, N)
             img_arra = Image.fromarray(im_adaptive)
             rgb im = img arra.convert('RGB')
             rgb_im.save(cat_dir+'/'+name, 'JPEG')
             c=c+1
         else:
              continue
```

```
[]: import os
     data_loc2 = '/content/datasets/datasets/dog'
     c=0
     for filename in os.listdir(data_loc2):
         if filename.endswith(".jpg"):
             im = mpimg.imread(data_loc2+'/'+filename)
             imgrey = np.round(0.3 * im[:,:,0] + 0.59 * im[:,:,1] + 0.11 * im[:,:]
      \rightarrow,2]).astype(int)
             name='imgdog' +str(c)+'.jpg'
             im_adaptive, adaptive_weights, adaptive_iteration_result =_
      →adaptive_filter(imgrey, N)
             img_arra = Image.fromarray(im_adaptive)
             rgb_im = img_arra.convert('RGB')
             rgb_im.save(dog_dir+'/'+name, 'JPEG')
             c=c+1
         else:
              continue
```

```
batch_size = 3
img_height = 200
img_width = 200

train_data02 = tf.keras.preprocessing.image_dataset_from_directory(
   parent_dir2,
   validation_split=0.2,
   subset="training",
   seed=42,
   image_size=(img_height, img_width),
   batch_size=batch_size)
```

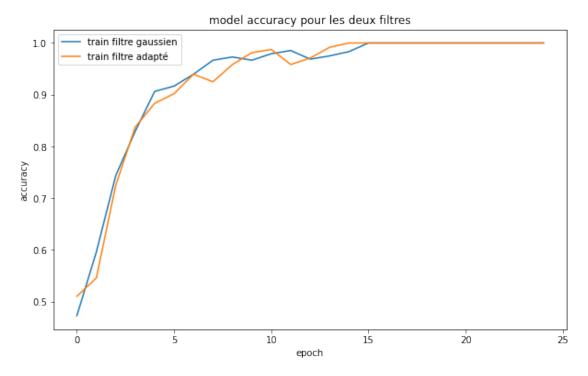
```
val_data02 = tf.keras.preprocessing.image_dataset_from_directory(
   parent_dir2,
   validation_split=0.2,
   subset="validation",
   seed=42,
   image_size=(img_height, img_width),
   batch_size=batch_size)

class_names2 = val_data02.class_names
print(class_names2)
```

```
[]: from tensorflow.keras import layers
     num_classes = 2
     model2 = tf.keras.Sequential([
         layers.experimental.preprocessing.Rescaling(1./255),
         layers.Conv2D(128,4, activation='relu'),
         layers.MaxPooling2D(),
         layers.Conv2D(64,4, activation='relu'),
         layers.MaxPooling2D(),
         layers.Conv2D(32,4, activation='relu'),
         layers.MaxPooling2D(),
         layers.Conv2D(16,4, activation='relu'),
         layers.MaxPooling2D(),
         layers.Flatten(),
         layers.Dense(64,activation='relu'),
         layers.Dense(num_classes, activation='softmax')
     ])
     model2.compile(optimizer='adam', loss=tf.losses.
     →SparseCategoricalCrossentropy(from logits=True), metrics=['accuracy'],)
     logdir="logs"
     tensorboard_callback2 = keras.callbacks.
     →TensorBoard(log_dir=logdir,histogram_freq=1, write_images=logdir,⊔
     →embeddings_data=train_data01)
     history2 = model2.fit(train_data02, validation_data=val_data02, epochs=25,__
      →callbacks=[tensorboard_callback2])
```

```
[]: figure(figsize=(10,6))
  plt.plot(history1.history['accuracy'])
  plt.plot(history2.history['accuracy'])
  plt.title('model accuracy pour les deux filtres')
```

```
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train filtre gaussien', 'train filtre adapté'], loc='upper left')
plt.show()
```



```
[]: figure(figsize=(10,6))
   plt.plot(history1.history['val_accuracy'])
   plt.plot(history2.history['val_accuracy'])
   plt.title('model accuracy pour les deux filtres')
   plt.ylabel('accuracy')
   plt.xlabel('epoch')
   plt.legend(['test filtre gaussien', 'test filtre adapté'], loc='upper left')
   plt.show()
```

