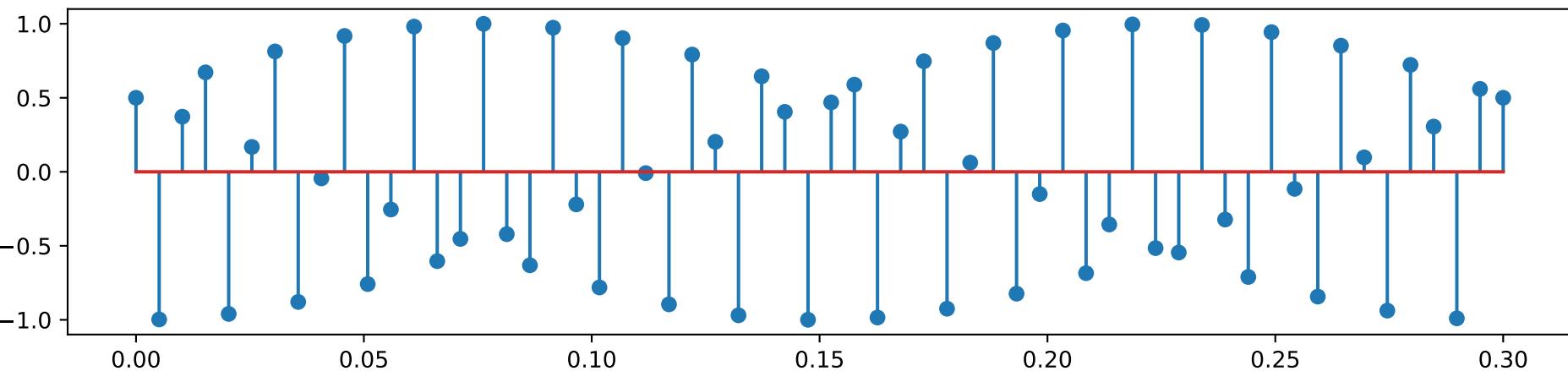
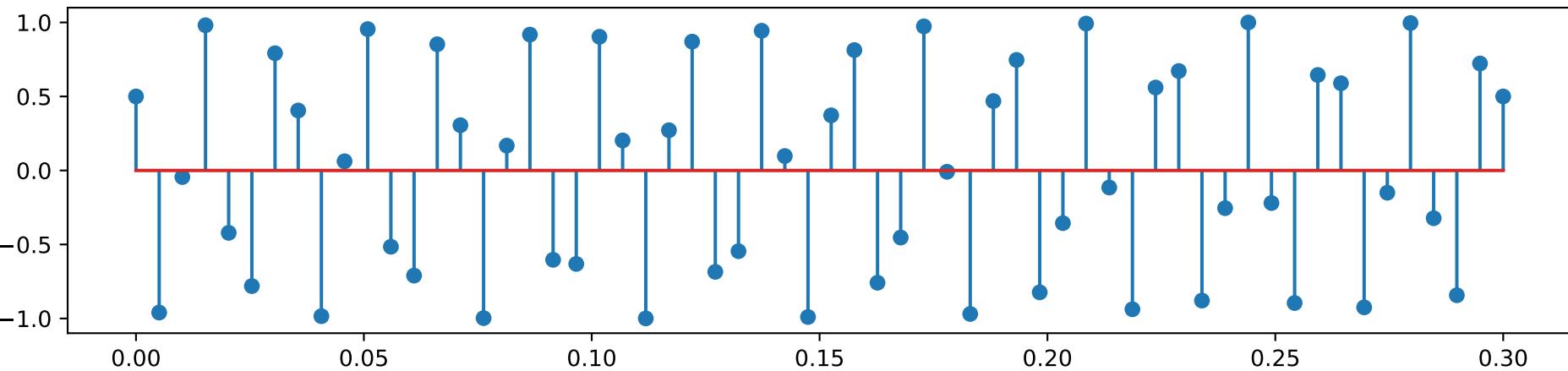


$x(t)$  $y(t)$  $z(t)$ 