

Markov Chain Monte Carlo

Review

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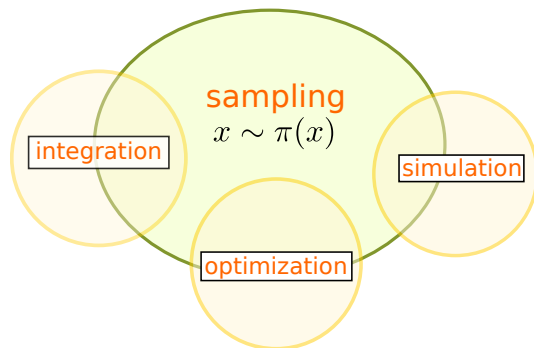
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Monte Carlo: The Big Picture

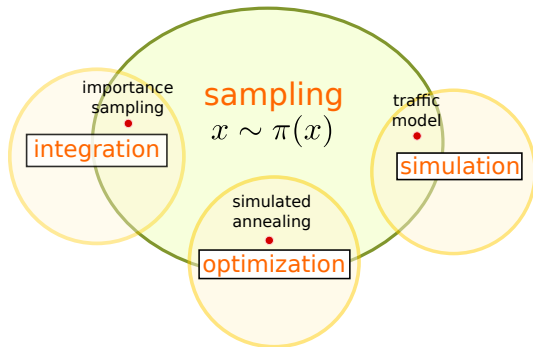


integration: high-dimensions, marginalization, normalization

optimization: global extrema, rough landscape

simulation: scenario modeling, emergent phenomena

Monte Carlo: The Big Picture



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Sampling Methods

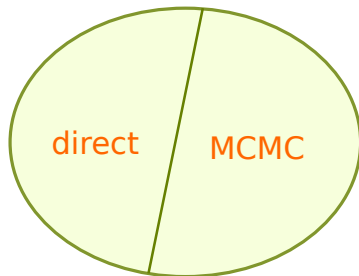
How do I sample from $x \sim \pi(x)$?

Direct Sampling

- ▶ accept-reject
- ▶ transformation

MCMC

- ▶ Metropolis
- ▶ Metropolis-Hastings
- ▶ MC³
- ▶ Gibbs
- ▶ Slice, HMC etc



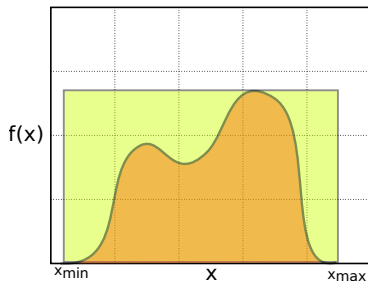
Sampling Methods

Accept-Reject

Inspiration: “integration by darts”

simple algorithm, shift burden from human to computer.

- (i) pick $x \sim U[x_{\min}, x_{\max}]$
- (ii) pick another random number $u \sim U[0, f_{\max}]$
- (iii) If $u \leq f(x)$, then accept x . If not, reject x and repeat.



Disadvantages:

- (i) infinite domains
- (ii) rejection of points: *adaptive rejection sampling*
- (iii) peaked distributions, higher dimensions

Transformation Method

Efficient direct sampling method for arbitrary 1D $\pi(x)$.

Unlike accept-reject there are no rejections

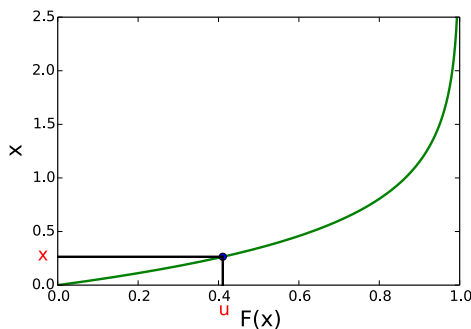
(i) Find CDF $F(x)$

$$F(x) = \int \pi(x) dx$$

(ii) Method is given by

$$u = F(x)$$

where $u \sim U[0, 1)$



Method works best when $x = F^{-1}(u)$ is explicitly available.

Transformation Method: 2D

Consider:

$$(X, Y) \sim f(x, y), \text{ and } (U, V) \sim g(u, v).$$

If $x(u, v)$ and $y(u, v)$ are known 1-1 maps, then,

$$g(u, v) = f(x, y) |\det(J)|,$$

where the Jacobian J is given by,

$$J = \frac{\partial(x, y)}{\partial(u, v)} = \begin{bmatrix} \partial x / \partial u & \partial x / \partial v \\ \partial y / \partial u & \partial y / \partial v \end{bmatrix}.$$

For multidimensional distributions,

- ▶ **easy**: given transformation \rightarrow determine distribution
- ▶ **hard**: given distribution \rightarrow develop transformation

Error Analysis

Integration Error in Direct Methods

Given an integral,

$$I = \int_a^b f(x) dx$$

The key results for MC integration,

$$I = (b - a) \langle f \rangle$$
$$\sigma_I = \frac{(b - a) \sigma_f}{\sqrt{n}},$$

where

$$\sigma_f^2 = \langle f^2 \rangle - \langle f \rangle^2$$

is the variance of f on the domain.

Given $f(x)$ and domain $[a, b]$, the only way to reduce error is to increase n .

Importance Sampling

Variance reduction technique: lower apparent σ_f^2 .

Select suitable $\pi(x)$ so that integral:

$$I = \int_a^b \frac{f(x)}{\pi(x)} \pi(x) dx,$$

Use “Method 2”:

1. Draw x_1, x_2, \dots, x_n from $\pi(x)$
2. Estimate $I = E(f/\pi)$ via

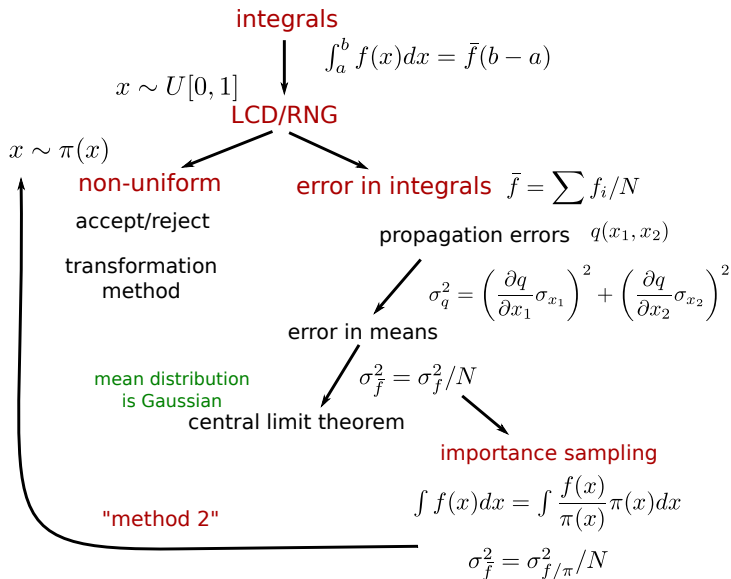
$$I \approx \frac{1}{n} \sum_{i=1}^n \frac{f(x_i)}{\pi(x_i)}.$$

For importance sampling,

$$\sigma_{I,is}^2 = \frac{\sigma_{f/\pi}^2}{n}.$$

Course Trajectory

Overview Material so Far



Quizzes

Exam Skills

- ▶ some symbolic software: sympy, Matlab, Mathematica
 - ▶ algebra, integration/differentiation
- ▶ Proficiency in plotting, histograms etc.
- ▶ Go through HWs and past exam
- ▶ Focus on multidimensional distributions and importance sampling

Exam Details

- ▶ in class: Oct 24 between 9:45am-11am
- ▶ single question: multiple parts