Iterative Methods

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1 Introduction

In this assignment, we implement the Jacobi and Gauss-Seidel algorithms to solve the Ax = b. These are the iterative methods for determining the solutions of a strictly diagonally dominant system of linear equations.

2 Program

2.1 User Input

To read input from the user and store it in the variables n and niter we are using the function scanf, which is from the C library stdio.

2.2 Memory Allocation

According to the input provided by the user, we need to allocate memory dynamically to hold the matrices. For this purpose, we use the function malloc provided by the C library. We are using this function to allocate memory for three matrices named A, B, and X. stdlib.

2.3 Error handling

While allocating the required memory using the above function, it is possible that it cannot be allocated. In this case, the malloc function will return 0, that is NULL. Hence, we are checking if any of the pointers to the matrices A, B, and X are NULL. If so, we are calling the function free to deallocate the dynamically allocated memory and printing a message Failed to allocate memory., followed by gracefully exiting the program with a function exit.

2.4 Matrix Initialization

To initialize the matrices with the given conditions we are using the function initializeArrays. In this function, we are filling the memory allocated for the matrices with 0 and updating the matrices by using the following conditions, For matrix A,

$$A(i, i) = 2.0$$
, where $i = 0, ..., (n - 1)$
 $A(i, i + 1) = -1.0$; $A(i + 1, i) = -1.0$; $i = 0, ..., (n - 2)$

For matrix B, all the elements will be zero, except the first and last which will be 1.0

$$B(0) = 1.0; B(n-1) = 1.0$$

For matrix X, since we are using two methods that will solve for the same A and B. We can use only one matrix, with two columns for storing values of X from both methods. Hence X will be,

$$X = \begin{bmatrix} 0 & 0 \\ \cdot & \cdot \\ \cdot & \cdot \\ 0 & 0 \end{bmatrix}$$

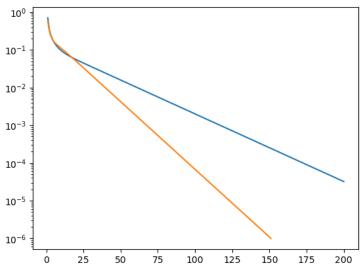
This method is also used by the Lapack library for solving linear systems. This function can also be used to reset the matrices.

2.5 Error

The solution error and the L2 norm of the error of the functions are calculated at iteration 20. And if we change the value of n, we get the following results,

| n | Jacobi | Gauss Seidel |
|------|-----------|--------------|
| 10 | 0.0962991 | 0.110722 |
| 100 | 0.096299 | 0.083265 |
| 1000 | 0.096299 | 0.083265 |





2.6 Profiling

To measure the time required for the program to execute all the calculations when niter is set to 200, we are using the clock_t which is the data type used to represent processor time.

| n | Time in sec. |
|------|--------------|
| 10 | 0.001000 |
| 100 | 0.024000 |
| 1000 | 2.008000 |

2.7 Output

The output of the program of the matrix X when n = 10 and niter = 30.

| Jacobi | Gauss-Seidel |
|----------|--------------|
| 0.962742 | 0.962742 |
| 0.931390 | 0.931390 |
| 0.907964 | 0.907964 |
| 0.893697 | 0.893697 |
| 0.888999 | 0.888999 |
| 0.893485 | 0.893485 |
| 0.906073 | 0.906073 |
| 0.925120 | 0.925120 |
| 0.948602 | 0.948602 |
| 0.974301 | 0.974301 |

References

- [1] MathWorks: Gauss-Seidel Method, Jacobi Method https://www.mathworks.com/matlabcentral/fileexchange/ 63167-gauss-seidel-method-jacobi-method.
- [2] Chat-GPT: scanf explaination https://chat.openai.com/share/14cfe5be-777f-4d0f-bef2-1fa0f1f5f345.