Lecture 5: Naive Bayes Classification, Features, Linear Models, Perceptron

USC VSoE CSCI 544: Applied Natural Language Processing

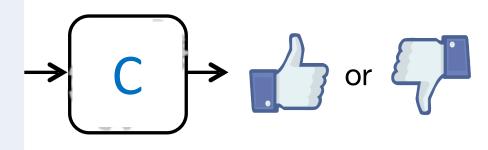
Jonathan May -- 梅約納

September 6, 2017

Sentiment Analysis

Recall the task:

Filled with horrific dialogue, laughable characters, a laughable plot, ad really no interesting stakes during this film, "Star Wars Episode I: The Phantom Menace" is not at all what I wanted from a film that is supposed to be the huge opening to the segue into the fantastic Original Trilogy. The positives include the score, the sound



- This is a classification task: our input is free text but our output is a fixed set of labels
- In this lecture, input/observed data is denoted x (or set X) and output/prediction is y (or set Y)

Our Previous Rule-Based Classifier

Note: example code from lecture 2 is slightly different but functionally equivalent

```
good = { 'yay', 'love', ...}
                                            from our pos/neg
bad = { 'terrible', 'boo', ...}
                                             word list!
score = 0
for w in x:
  if w in good:
    score \pm = 1
  elif w in bad:
    score -=1
if score \geq = 0:
  return 'pos'
return 'neg'
```



Supervised Classification

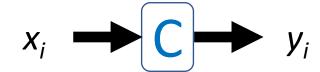
- Rather than top-down features, let's use data-driven features
 - Our intuitions about word sentiment aren't perfect
- **Supervised** (aka Inductive) = learn from **labeled** examples. Recipe:
 - training corpus of (x, y) (review, label) pairs
 - learning algorithm
- Other kinds of learning (not covered here):
 - Unsupervised: Data is provided but no labels are given
 - Semi-Supervised: Data is provided but only some of it is labeled
 - Reinforcement: No clear labels, but feedback (in the form of a reward) is accessible

Supervised Our Previous Rule Based Classifier

```
good = { ... from training ...}
bad = { ... from training ...}
score = 0
for w in x:
  if w in good:
    score +=1
  elif w in bad:
    score -=1
if score >= 0:
  return 'pos'
return 'neg'
```

Notation

- Training examples: $X = (x_1, x_2, ..., x_N)$
- Labels of training examples: $Y = (y_1, y_1, ..., y_N)$
- A classifier C maps x_i to y_i
- A learner L infers C from (X, Y)



$$X \rightarrow C$$

Counting-based Learner

```
from collections import Counter
scores = Counter()
for x, y in zip(X, Y):
  for w in x:
    if y == 'pos':
      scores[w] += 1
    elif y == 'neg':
      scores[w]=1
good, bad = set(), set()
for w, score in scores.items():
  if score>=0: good.add(w)
  else: bad.add(w)
return good, bad
```

A Probabilistic Classifier

Experiment: "people wrote reviews of n

Outcomes (Ω) : all possible reviews

Events: Y=pos: all positive reviews. Y=neg = all negative reviews

X=34925: "when review 34925 was written"

 $x \longrightarrow \begin{cases} probs = < model for p(y|X) > \\ return argmax probs[X] \end{cases} \qquad C \longrightarrow y$

MLE is not going to work (review 34925 shouldn't be in training)!

Review #34925: "Filled with horrific dialogue, laughable characters, a laughable plot, and really no interesting stakes during this film, "Star Wars Episode I: The Phantom Menace" is not at all what I wanted from a film that is supposed to be the huge opening to the segue into the fantastic Original Trilogy. The positives include the score, the sound..."

Aside: Library of Babel (Borges, 1941)

- Contains all 1.3m-word texts, organized
- A lot of it looks like junk
- But all useful texts are in here too!
- What's it like to be a librarian?
- Look up your favorite piece of text at https://libraryofbabel.info



- Instead of estimating p(Y|Filled with horrific...) directly, let's make two modeling assumptions:
 - 1. The **Bag of Words (BoW) assumption**: Assume the order of the words in the document doesn't matter:

```
p(Y|Filled with horrific ...) = P(Y|with, horrific, Filled, ...)
```

a sequence

independent word events

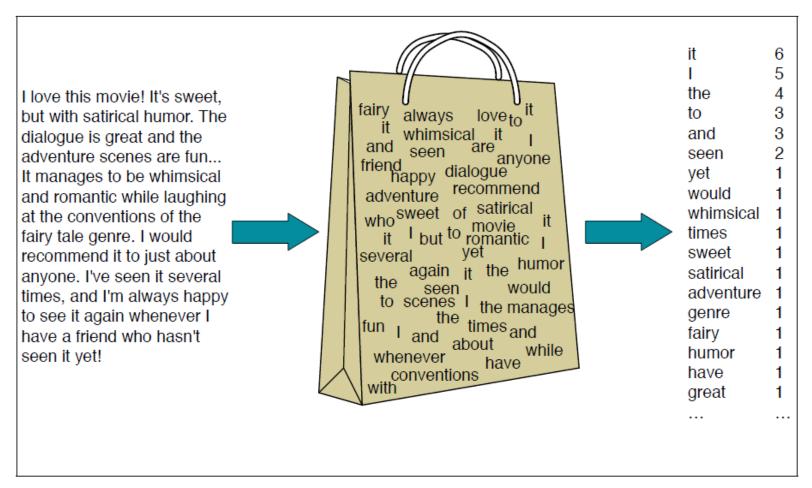


Figure 7.1 Intuition of the multinomial naive Bayes classifier applied to a movie review. The position of the words is ignored (the *bag of words* assumption) and we make use of the frequency of each word.

Figure from J&M 3rd ed. draft, sec 6.1

- Instead of estimating p(Y|Filled with horrific...) directly, let's make two modeling assumptions:
 - 1. The **Bag of Words (BoW) assumption**: Assume the order of the words in the document doesn't matter:

```
p(Y|Filled with horrific ...) = P(Y|with, horrific, Filled, ...)
```

a sequence

independent word events

So called because a **bag** or **multiset** is a data structure that stores counts of elements, but not their order

- The BoW assumption isn't enough unless you happen to have seen one of 34925's anagrams in your training data (e.g. 4088293). Hence:
 - 2. The **naive Bayes assumption**: Words are independent conditioned on their class:
 - P(Filled, with, horrific... | Y) = P(Filled | Y) x P(with | Y) x P(horrific | Y) ...
- Wait, but we were estimating P(Y|with, horrific, Filled, ...). What should we do?
- Bayes Rule!

- 1) If P is a probability function, which of the following is equal to P(x | y, z)?
 - A) P(x) / P(y, z)
 - B) P(y)P(z) / P(x, y, z)
 - C) P(x, y, z) / P(y, z)
 - D) P(x)P(x|y)P(x|z)

- 2) Which is/are guaranteed to be true (assume no null event cases)?
 - A) \forall y \forall z, Σ_x P(x | y, z) = 1
 - B) \forall x, $\Sigma_{v} \Sigma_{z} P(x | y, z) = 1$
 - C) $\Sigma_{x} P(x) = 1$
 - D) \forall y \forall z, $\Sigma_x P(x) P(y|x) P(z|x, y) = 1$

- Which of the following is/are equal to P(A|B, C, D)?
 - 1) P(B, C, D | A) P(A)
 - 2) P(B|C, D) P(B|A, C) P(B|A, D)
 - 3) P(D, C, B | A) P(A) / P(D, C, B)
 - 4) P(A | D, C, B)
- Note that while P(A|B, C, D) ≠ P(B, C, D | A) P(A), argmax_A P(A|B, C, D) = argmax_A P(B, C, D | A) P(A), and that's what we care about.

Put the assumptions/rule together:

```
    p(Y|Filled with horrific ...) = P(Y|with, horrific, Filled, ...) (BoW assmptn)
```

= P(Y) x P(with|Y) x P(horrific|Y) x P(Filled|Y)...
(Naive Bayes assmptn)

Is this a good model?

- "all models are wrong, but some are useful" George Box, statistician
- What's wrong with the BoW assumption?
- What's wrong with the Naive Bayes assumption?
- But does it work?
 - Yes, for many tasks
 - And that's kind of all that matters

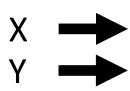
Naive Bayes Classifier

```
from numpy import argmax
wprobs = { from training }
cprobs = { from training }
totals = []
for c in classes:
  total = class_probs[c]
  for w in x:
    total *= wprobs[w][c]
  totals.append(total)
return argmax(totals)
```



Naive Bayes Learner

```
from collections import Counter
cscores = Counter()
wscores = []
for c in classes:
  wscores.append(Counter())
for x, y in zip(X, Y):
  cscores[y] += 1
  for w in x.split():
    wscores[y][w]+=1
cprobs, wprobs = [], []
for c in classes:
  cprobs = cscores[c]/len(Y)
  wprob = \{\}
  for w, score in wscores[c].items():
    wprob[w] = score/cscores[c]
  wprobs.append(wprob)
return cprobs, wprobs
```



Parameters

- Every probability or other value that is **learned** and used by the classifier is called a **parameter** (e.g. everything the learner sent the classifier)
- Naive Bayes has two kinds of parameters:
 - Class prior distribution P(Y) = belief in the class
 - Likelihood distribution P(W|Y) = likelihood of observing a word in a class
- If there are K classes and V words, how many parameters are in a Naive Bayes classifier?

Practicalities: Smoothing

• Recall:

```
for w in x:
  total *= wprobs[w][c]
```

- What if you see a new word, or word unassociated with that class, at test time?
- Whole probability will be 0!

Laplace (add-1) smoothing

- Assume we've seen a special symbol called OOV (out of vocabulary) once per class. And assume we've seen all possibilities once more.
- Before: p(wonderful | pos) = count(wonderful, pos)/count(*, pos)
 p(terrible | pos) = count(terrible, pos) = 0/count(*, pos) = 0!

vocabulary	pos	neg
wonderful	398	17
terrible	0	228
•••	•••	•••
TOTAL (5000 types)	147808	167585

Laplace (add-1) smoothing

- Assume we've seen a special symbol called OOV (out of vocabulary)
 once per class. And assume we've seen all possibilities once more.
- After: p(wonderful | pos) =
 [count(wonderful, pos)+1]/[count(*, pos) + |V|+1]
 p(terrible | pos) = p(OOV | pos) = 1/[count(*, pos) + |V|+1]

vocabulary	pos	neg
wonderful	398	17
terrible	0	228
		* * *
TOTAL (5000 types)	147808	167585

vocabulary	pos	neg
wonderful	399	18
terrible	1	229
•••	+1	+1
OOV	1	1
TOTAL (5001 types)	147808+5001	167585+5001

Generalization: Additive (Lidstone) Smoothing

- We can use values other than 1. In general we use α
- p(wonderful | pos) = [count(wonderful, pos)+ α]/[count(*, pos) + α |V|+ α] p(terrible | pos) = p(OOV | pos) = α /[count(*, pos) + α |V|+ α]

vocabulary	pos	neg
wonderful	398	17
terrible	0	228

TOTAL (5000 types)	147808	167585

$$\alpha$$
=0.5

vocabulary	pos	neg
wonderful	398.5	17.5
terrible	0.5	228.5
	+0.5	+0.5
OOV	0.5	0.5
TOTAL (5000 types)	147808+2500.5	167585+2500.5

Practicalities: Underflow

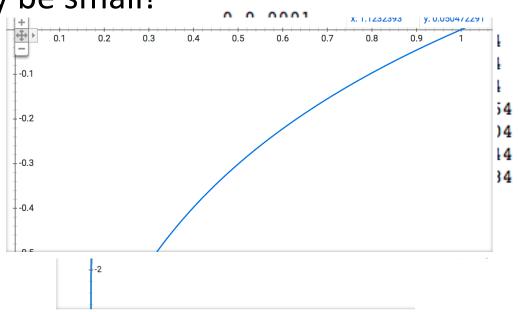
• Recall:

```
for w in x:
  total *= wprobs[w][c]
```

x may be long! wprobs[w][c] may be small!

- But remember log math!
 - exp(log(x)) = x
 - log(xy) = log(x) + log(y)
 - $\forall x, y > 0, x > y \iff \log(x) > \log(y)$

```
a=1
for i in range(100):
    a*=.0001
    if i % 10 == 0:
        print(i, a)
```



Avoiding Underflow with Logs

• Now:

```
for w in x:
  total += log(wprobs[w][c])
```

```
from math import log
a = log(1)
for i in range(100):
    a += log(.0001)
    if i % 10 == 0:
        print(i, a)
```

```
0 -9.210340371976182

10 -101.31374409173802

20 -193.41714781149977

30 -285.5205515312616

40 -377.62395525102363

50 -469.72735897078564

60 -561.8307626905473

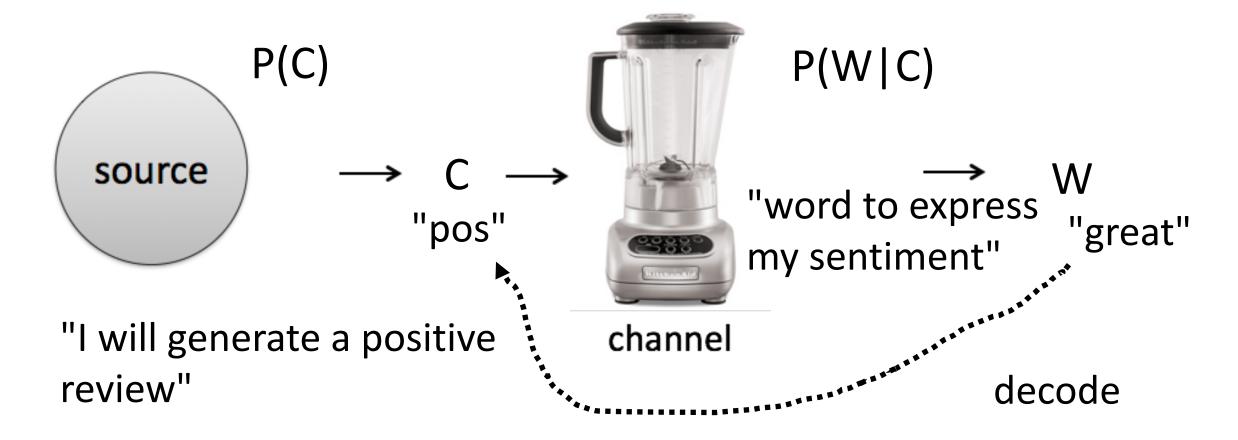
70 -653.9341664103088

80 -746.0375701300702

90 -838.1409738498317
```

Noisy Channel Model

Reminder: Using Bayes' Rule interpretation of the world



Suppose we have events A, B, C, D and are given:

$$P(A) = 0.5$$

$$P(A,B) = 0.25$$

$$P(B) = 0.3$$

$$P(B) = 0.3$$
 $P(B|C) = 0.2$

$$P(C) = 0.6$$

$$P(C) = 0.6$$
 $P(A|B,C) = 0.1$

$$P(D) = 0.4$$

$$P(D) = 0.4$$
 $P(B|A,C) = 0.7$

Compute P(A,B,C)

- 1. 0.3
- 2. 0.012
- 3. 0.5
- 4. 0.15

	pos	neg
great	4	7
think	3	4
horrible	2	12
extra	6	8

- Consider the frequency table above. What is P(great|pos), adjusted with Laplace smoothing?
 - A. 5/47
 - B. 3/15
 - C. 4/7
 - D. 4/15
 - E. 5.5/23
 - F. 5/16
 - G. 5/20

Feature Engineering: getting better results

- In general we call the elements of the representation we feed to a classifier/learner/predictor/etc. features (note: different sources may use different language here)
- So far, we have been using single words as our features (subject to a particular definition of what a word is)
- What else about a review might give us clues as to its sentiment?

I love this movie! It's sweet, but with satirical humor. The dialogue is great and the adventure scenes are fun... It manages to be whimsical and romantic while laughing at the conventions of the fairy tale genre. I would recommend it to just about anyone. I've seen it several times, and I'm always happy to see it again whenever I have a friend who hasn't seen it yet!

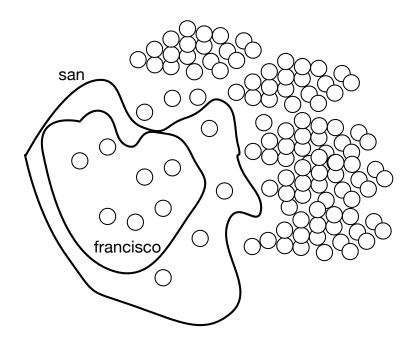
it	6
I	5
the	4
to	3
and	3
seen	2
yet	1
would	1
whimsical	1
times	1
sweet	1
satirical	1
adventure	1
genre	1
fairy	1
humor	1
have	1
great	1

Other Features

- Bigrams ("not good", "Wall Street")
 - Aside: NLPish for lengths of word sequence: unigram, bigram, trigram, 4-gram, ...
- normalized unigrams
 - root form: "like" (instead of "liked", "liking", etc.) (cf. morphology lecture)
 - uncapitalized ("great!!!" instead of "Great!!!", "GREAT!!!")
 - punc-normalized ("Great!" instead of "Great!!!", "Great!!!!")
 - spelling correction ("great" instead of "greate"...or "grate"??)
- length of the document (maybe positive reviews are shorter?)
 - average (max? min?) length of words
- other properties
 - contains sequence of all-caps words
 - author id
 - time of writing
- Much of this is application-dependent; try it out and see what works!

Naive Bayes Assumption Revisited

- Naive Bayes Assumption: $P(A_{1_i}, A_{2_i}, ... | B) = P(A_1 | B)P(A_2 | B)...$
- Feature choice can make this assumption more naive!
 - P(san) = 11/160
 - P(francisco) = 7/160
 - P(san, francisco) = 7/160 ≈ .04
 - $P(san)*P(francisco) = 77/25600 \approx .003$
- Consequence: parts of the input that are overrepresented by features have more influence
- Analogy: ask 5 people what they thought of the movie, but they all ask the same person and repeat what she said.



Feature Engineering in Labeling Tasks

- We've been making a single classification decision about a whole document but this can apply to other tasks
 - Named Entity Recognition (NER): Where are mentions of People, Organizations, Countries, etc?
 - Words Sense Disambiguation (WSD): make semantic decisions for ambiguous words (e.g. 'interest', 'bank')
 - Part of Speech (POS) Tagging: are these words nouns, adjectives, etc? (but see next lecture)
- Let's look at a WSD example:
 - x = "Wall Street vets raise concerns about interest rates, politics"
 - interest sense 1: "financial". interest sense 2: "nonfinancial"
 - We'll call the features of $x \Phi(x)$

How To Choose Features?

- Since we're using supervision (i.e. the data) to guide us we don't have to worry too much – unimportant features won't be discriminating
- But it's helpful to know something about your domain when designing features
 - are subword units important?
 - is metadata important?
 - is there something very particular about the task at hand that should be checked (e.g. detecting the writings of a psychopath who only writes in sentences with a prime number of words)
- Should I just use every possible feature I can think of?
 - More features => more flexibility
 - More features => more expensive to train
 - More features => more overfitting

What Features? What Parameters? How to Choose?

- Most of these questions are <u>empirical</u>: do what works best on the task you have at hand
- But beware <u>overfitting</u>: doing well on your training data and then doing poorly on blind test data
- Typically we divide labeled data up as follows:
 - Training data: used to build model parameters (e.g. P(good | "pos"))
 - Development/tuning data: used to test different hyperparameters/models (e.g. which α in Lidstone smoothing)
 - Test data: estimate how well you'll do on new/blind data. Don't evaluate on this until you're done/nearly done with experiments!

ф((x)
----	-----

bias	1
capitalized?	0
#wordsBefore	6
#wordsAfter	3
relativeOffset	0.66
leftWord=about	1
leftWord=best	0
rightWord=rates	1
rightWord=in	0
Wall	1
Street	1
vets	1
best	0
in	0
Wall Street	1
Street vets	1
vets raise	1

bias feature (≈ class prior): value of 1 for every x so learned weight reflects prevalence of the class

x = Wall Street vets
raise concerns about
interest rates , politics

 $\Phi(x)$

bias	1
capitalized?	0
#wordsBefore	6
#wordsAfter	3
relativeOffset	0.66
leftWord=about	1
leftWord=best	0
rightWord=rates	1
rightWord=in	0
Wall	1
Street	1
vets	1
best	0
in	0
Wall Street	1
Street vets	1
vets raise	1

spelling feature

x = Wall Street vets
raise concerns about
interest rates , politics

T (**)
1
0
6
3
0.66
1
0
1
0
1
1
1
0
0
1
1
1

token positional features

x = Wall Street vets
raise concerns about
interest rates , politics

	• • •
bias	1
capitalized?	0
#wordsBefore	6
#wordsAfter	3
relativeOffset	0.66
leftWord=about	1
left Word = best	0
rightWord=rates	1
rightWord=in	0
Wall	1
Street	1
vets	1
best	0
in	0
Wall Street	1
Street vets	1
vets raise	1

x = Wall Street vets
raise concerns about
interest rates , politics

immediately neighboring words

ф(X)
----	----

bias	1
capitalized?	0
#wordsBefore	6
#wordsAfter	3
relativeOffset	0.66
leftWord=about	1
leftWord=best	0
rightWord=rates	1
rightWord=in	0
Wall	1
Street	1
vets	1
best	0
in	0
Wall Street	1
Street vets	1
vets raise	1

x = Wall Street vets
raise concerns about
interest rates , politics

unigrams

- Input represented as a table of features with real values (often binary)
- In practice: define feature templates, e.g. "leftWord=*" which yield many specific features

φ(x)

bias	1
capitalized?	0
#wordsBefore	6
#wordsAfter	3
relativeOffset	0.66
leftWord=about	1
leftWord=best	0
rightWord=rates	1
rightWord=in	0
Wall	1
Street	1
vets	1
best	0
in	0
Wall Street	1
Street vets	1
vets raise	1

bigrams

x = Wall Street vets
raise concerns about
interest rates , politics

- Input represented as a table of features with real values (often binary)
- In practice: define feature templates, e.g. "leftWord=*" which yield many specific features

	ф (х)	w_1	W_2
bias	1	$log(P(c_1))$	$log(P(c_2))$
capitalized?	0		
#wordsBefore	6		
#wordsAfter	3		
relative Offset	0.66		
leftWord=about	1	log(P(c ₁))	
leftWord=best	0		
rightWord=rates	1		
rightWord=in	0		
Wall	1		
Street	1		
vets	1	$log(P(vets c_1))$	$log(P(vets c_2))$
best	0		
in	0		
Wall Street	1		
Street vets	1		
vets raise	1		

X = Wall Street vets raise concerns about interest rates, politics

Shouldn't these be more important?

by NB

 $\operatorname{argmax}_{c} \operatorname{w}_{c}^{\mathsf{T}} \mathbf{\Phi}(x)$

weights learned

Iterate over all <u>possible</u> features

```
for c in classes:
   total = log(class_probs[c])
   for w in x:
     total += log(wprobs[w][c])
   totals.append(total)
return argmax(totals)
```

Can we be more general?

	φ (x)	w_{1}	W_2
bias	1	3	2.4
capitalized?	0	-3.0	-6/2
#wordsBefore	6	.22	.15
#wordsAfter	3	01	.03
relativeOffset	0.66	1.00	.85
leftWord=about	1	0	0
leftWord=best	0	-2.0	3.0
rightWord=rates	1	5.0	-1.2
rightWord=in	0	-1	-0.5
Wall	1	.8	4
Street	1	2.0	.3
vets	1		
best	0		
in	0		
Wall Street	1		
Street vets	1		
vets raise	1		

less important

X = Wall Street vets
raise concerns about
interest rates , politics

 $argmax_c w_c^T \mathbf{\Phi}(x)$

Important!

Sure, let's just come up with weights from some other source!

How about just choosing whatever weights make the classifier better?

Slight Notation Correction

	φ (x)	w_1	W_2
Wall	1	.8	4

 $\operatorname{argmax}_{c} \mathbf{w}_{c}^{\mathsf{T}} \mathbf{\Phi}(\mathbf{x})$

φ (x,y) w		
Wall ^ y=1	1	.8
Wall ^ y=2	0	4

 $\operatorname{argmax}_{c} w^{T} \mathbf{\Phi}(x,c)$

- We've been treating features as a function of just X, with a weight vector for each possible class
- Going forward we'll treat features as a function of X and Y, with a single weight vector
- The forms are equivalent but this form makes generalizing to many classes easier

Perceptron: An Error-Driven Learner/Classifier

```
import numpy as np
from classifier import feats, classify
w = np.zeros(|feats|)
for i in range (iterations):
  for t in range (datasize):
                                C is a subroutine of L
    x, y = select(X, Y)
    # run current classifier
    y' = classify(x, w)
    if y' != y:
      w += feats(x, y) - feats(x, y')
return w
```

```
X \rightarrow Y
```

```
def classify(x, w):
    scores = []
    for y in labelspace:
        scores.append(np.dot(w, feats(x,y)))
    return argmax(scores)
```

What's Going On Here (I)?

if y' != y:

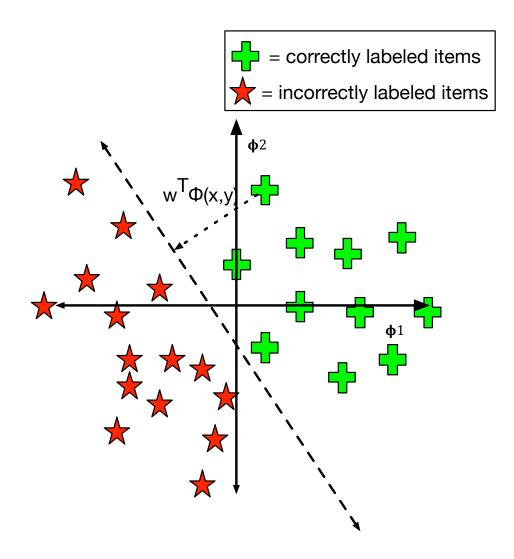
$$w += feats(x, y) - feats(x, y')$$

$\Phi(x,1) \Phi(x,2) W$				
bias ^ y=1	1	0	0.3	→ 1.3
bias ^ y=2	0	1	0.7	→ 3
Wall ^ y=1	1	0	.8 —	▶ 1.8
Wall ^ y=2	0	1	2	-1.2
this ^ y=1	0	0	2.2	▶2.2

X = Wall Street vets
raise concerns about
interest rates ,
politics

- If the wrong decision was made...
- Extra weight is given to features that should have fired (but didn't)
- extra penalty is given to features that did fire (but shouldn't have).
- Features that wouldn't have fired anyway are left alone

What's Going On Here (II)?



- Each (x, y) is a point in |feature|-dimensional space.
- Weights define a hyperplane (line) along which score is zero
- Perceptron moves the line to encourage correct items to be positive distance away

What's Going On Here (III)?

- Let's say we have pair (x, y). Perceptron chooses $argmax_{y'} w^T \mathbf{\Phi}(x, y')$; let the chosen y' be y^* .
- Ideally $y^*=y$; since we choose the argmax, we know that $w^T \mathbf{\Phi}(x,y^*) w^T \mathbf{\Phi}(x,y) >= 0$. That value is called the <u>loss</u>; the bigger it is the worse our classifier is.
- We get to choose w. Specifically we'd like to find $\operatorname{argmin}_{w'} w'^{\mathsf{T}} \boldsymbol{\Phi}(x,y^*) w'^{\mathsf{T}} \boldsymbol{\Phi}(x,y)$. This is a differentiable and continuous function, so take the derivative and move away from it.

Loss Gradient for Perceptron

- $\ell_{\text{perceptron}} = wT \mathbf{\Phi}(x,y^*) w^T \mathbf{\Phi}(x,y)$ unless the two are equal, then it's 0.
 - remember, w is a vector, so the gradient is taken for each member
 - however each variable appears exactly twice in the expanded equation
- $\partial/\partial w \ell_{perceptron} = \Phi(x,y^*) \Phi(x,y)$ (unless the two are equal...)
- And we want a negative step, so $\phi(x,y)-\phi(x,y^*)$ (unless the two are equal)

Other Perceptron Notes

- Since it's not closed-form like NB, weights need to be iteratively updated for some length of time. How long? Black art.
- What order to process the data? Probably randomly shuffle, but experimentally determined
- Avoiding overfitting
 - Averaging: Keep track of all weight vectors learned, then average them
 - Early stopping: Check performance on a dev set, then stop when it stops improving
- Support Vector Machine (SVM): Variant of perceptron trying to get the separating hyperplane farthest away from all points.

Perceptron Vs. Naive Bayes

Perceptron

- Discriminative model; can only classify given x
- Not probabilistic
- Iterative solution
- No independence assumption; arbitrary feats
- Best for more accuracy (esp. SVM), medium data, more feats

Naive Bayes

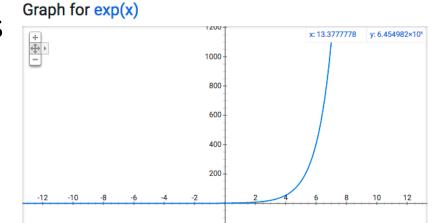
- Generative model; can be used to estimate P(x) or generate x from y
- Probabilistic
- Closed-form solution
- Overlapping features violate independence assumption
- Best for speed, lowish data, simple features

Can We Use All These Weights and Still Be Probabilistic?

- Being probabilistic allows us to quantify our uncertainty, work in pipelines, but the arbitrary weights of perceptron are freeing. Any way to have the best of both worlds?
- Recall, that the Naive Bayes objective, P(X|Y)P(Y) = P(X, Y), which is also P(Y|X)P(X)
- In classification we're given X; we don't really need to worry about it. So if we don't want to be generative (since we're not making the Naive Bayes Assumption) we just need a good model for P(Y|X)
- We have a score function for the event Y, X... $\mathbf{w}^T \mathbf{\Phi}(\mathbf{x}, \mathbf{y})$...what can we do?

Making the score function probabilistic

- $w^T \phi(x,y)$ is a score, not a probability. Further, it ranges from $-\infty$ to $+\infty$.
- Let's consider $\exp(\mathbf{w}^T \mathbf{\Phi}(\mathbf{x}, \mathbf{y}))$, which is always positive, and monotone.
- We can define P(y|x) as $\frac{\exp(w^T \phi(x,y))}{\sum_{y' \in Y} \exp(w^T \phi(x,y'))}$
- Where does the denominator come from?
 - Law of total probability
- We'd like to pick φ to maximize this likelihood over a data set



Maximizing Likelihood = Maximizing log likelihood

- We'd like to pick w to maximize $\frac{\exp(w^T\phi(x,y))}{\sum_{y'\in Y}\exp(w^T\phi(x,y'))}$ over a data set
- i.e. $\arg\max_{w} \prod_{i=1}^{n} \frac{\exp(w^{T}\phi(x^{i},y^{i}))}{\sum_{y'\in Y} \exp(w^{T}\phi(x^{i},y'))}$. Let's use our old friend log.
- = argmax_w $\sum_{i=1}^{n} \log \frac{\exp(w^T \phi(x^i, y^i))}{\sum_{y' \in Y} \exp(w^T \phi(x^i, y'))}$
- = $\operatorname{argmax}_{w} \sum_{i=1}^{n} w^{T} \phi(x^{i}, y^{i}) \sum_{y' \in Y} \exp(w^{T} \phi(x^{i}, y'))$
- A perfect classifier makes this as high as possible; the truth is very positive and everything else is very negative.

Maximizing Log Likelihood = Minimizing Log Loss

• The key general term for an item (x, y) is

$$w^T \phi(x, y) - \log \sum_{y' \in Y} \exp(w^T \phi(x, y'))$$

 A perfect classifier makes this as high as possible; the truth is very positive and everything else is very negative. The <u>loss</u> is the opposite;

$$-w^T \phi(x, y) + \log \sum_{y' \in Y} \exp(w^T \phi(x, y'))$$

 Let's minimize this by following the derivative, just like we did for perceptron

Loss Gradient for Logistic Regression (aka Maximum Entropy)

- $\ell_{\text{logreg}} = -w^T \phi(x, y) + \log \sum_{y' \in Y} \exp(w^T \phi(x, y'))$
- calculus facts:
 - $\partial/\partial x mx = mdx$;
 - $\partial/\partial x \log(x) = 1/x dx$
 - $\partial/\partial x \exp(x) = \exp(x)dx$
- $\partial/\partial w \,\ell_{\text{logreg}} = -\phi(x,y) + \sum_{y' \in Y} \frac{\exp(w^T \phi(x,y'))}{\sum_{y'' \in Y} \exp(w^T \phi(x,y''))} \phi(x,y')$
- = $-\phi(x,y) + \sum_{y' \in Y} P(y'|x) \phi(x,y')$. And we want to go away from the gradient, thus $\phi(x,y) \sum_{y' \in Y} P(y'|x) \phi(x,y')$

Gradient Update of Logistic Regression vs Perceptron

- Perceptron: $w+=\phi(x,y)-\phi(x,y^*)$; considers the single wrong decision, move away by constant amount
- Logreg: $w += \phi(x,y) \sum_{y' \in Y} P(y'|x) \phi(x,y')$; consider every alternative decision, move away by the model's confidence in that amount

Perceptron Vs. Logistic Regression

Perceptron

Logistic Regression

- Discriminative model
- Not probabilistic
- Iterative solution
- No independence assumption
- Easy to write
- Medium-fast to learn

- Discriminative model
- Probabilistic
- Iterative solution
- No independence assumption
- Slow to write
- Slow to learn
- Foundation of deep learning optimization

Conclusions

- We have seen how training data and supervised learning can produce a better classifier
 - Classifier takes an *input* (such as a text document) and predicts an *output* (such as a class label)
 - Learner takes training data and produces (statistics necessary for) the classifier

Conclusions

- Because most pieces of text are unique, it's not very practical to assume the one being classified is in the training data
 - though it is in the library of Babel!
 - We need to make **modeling assumptions** that help the learner to **generalize** to unseen inputs
- The Naive Bayes model and Bag of Words assumption are a simple, fast probabilistic approach to text classification
- The Perceptron allows more arbitrary features at the cost of slower learning and a requirement of more data
- Logistic Regression adds probabilities back into the arbitrary feature and weight capability of perceptron