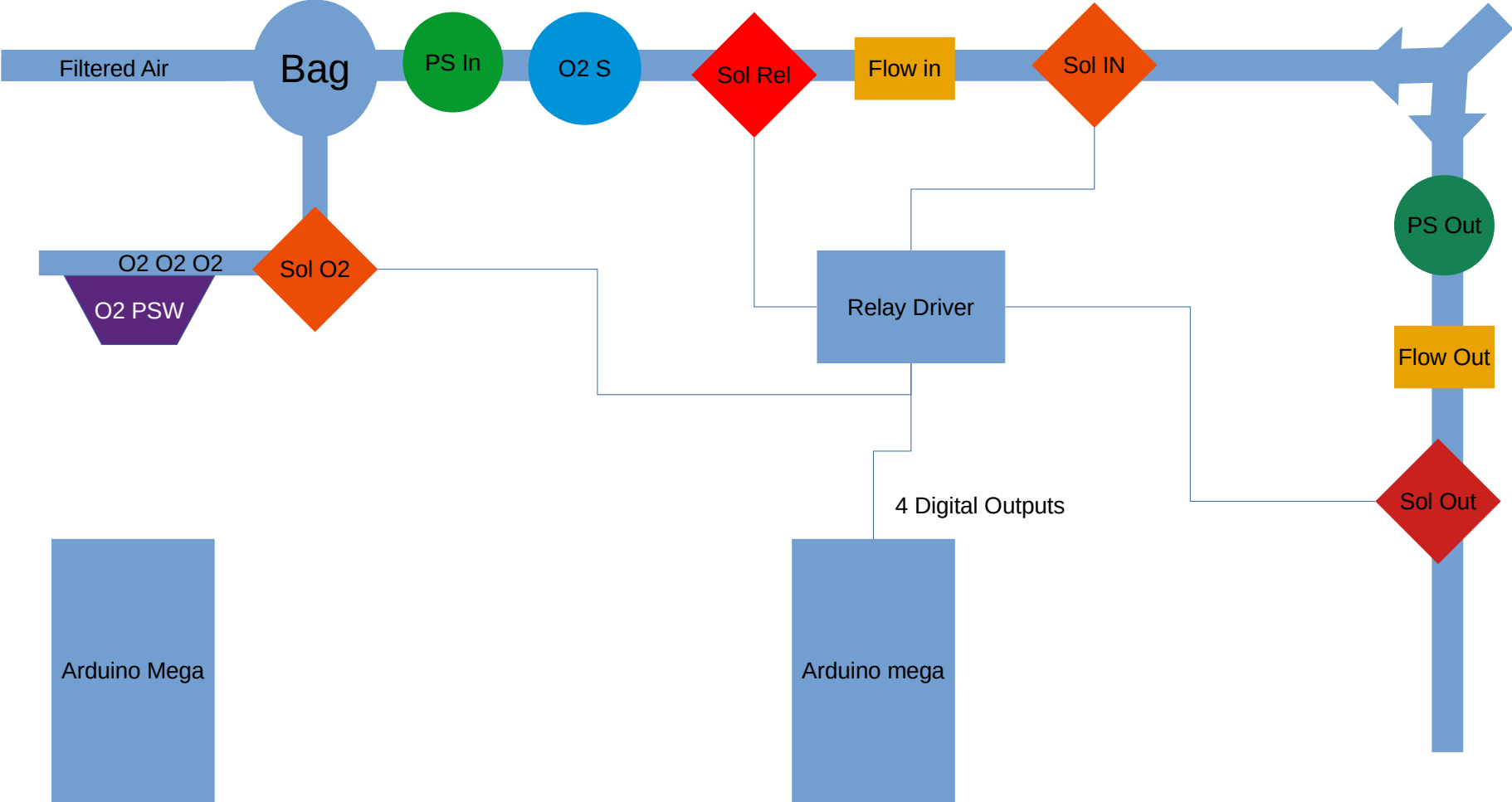
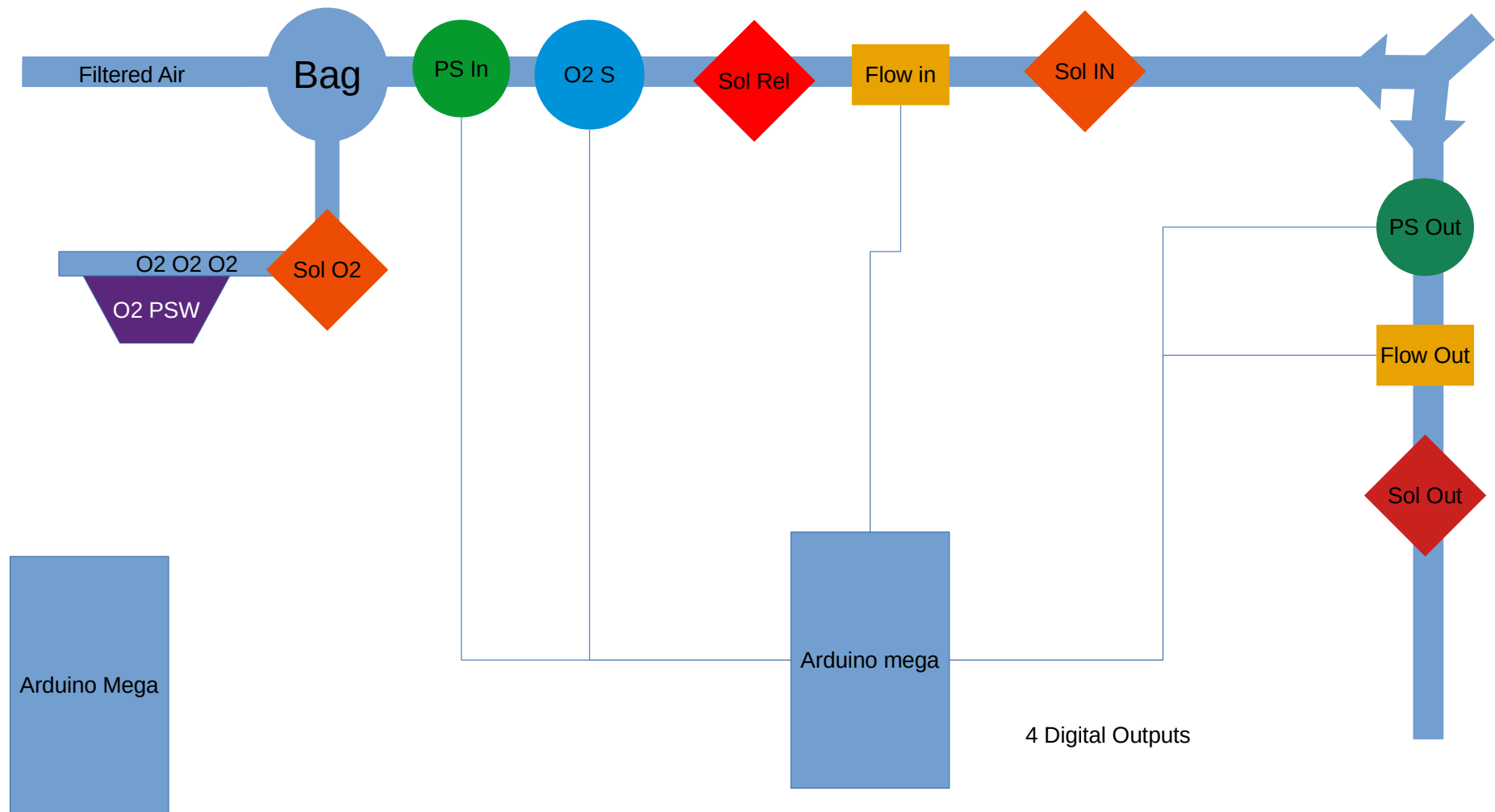


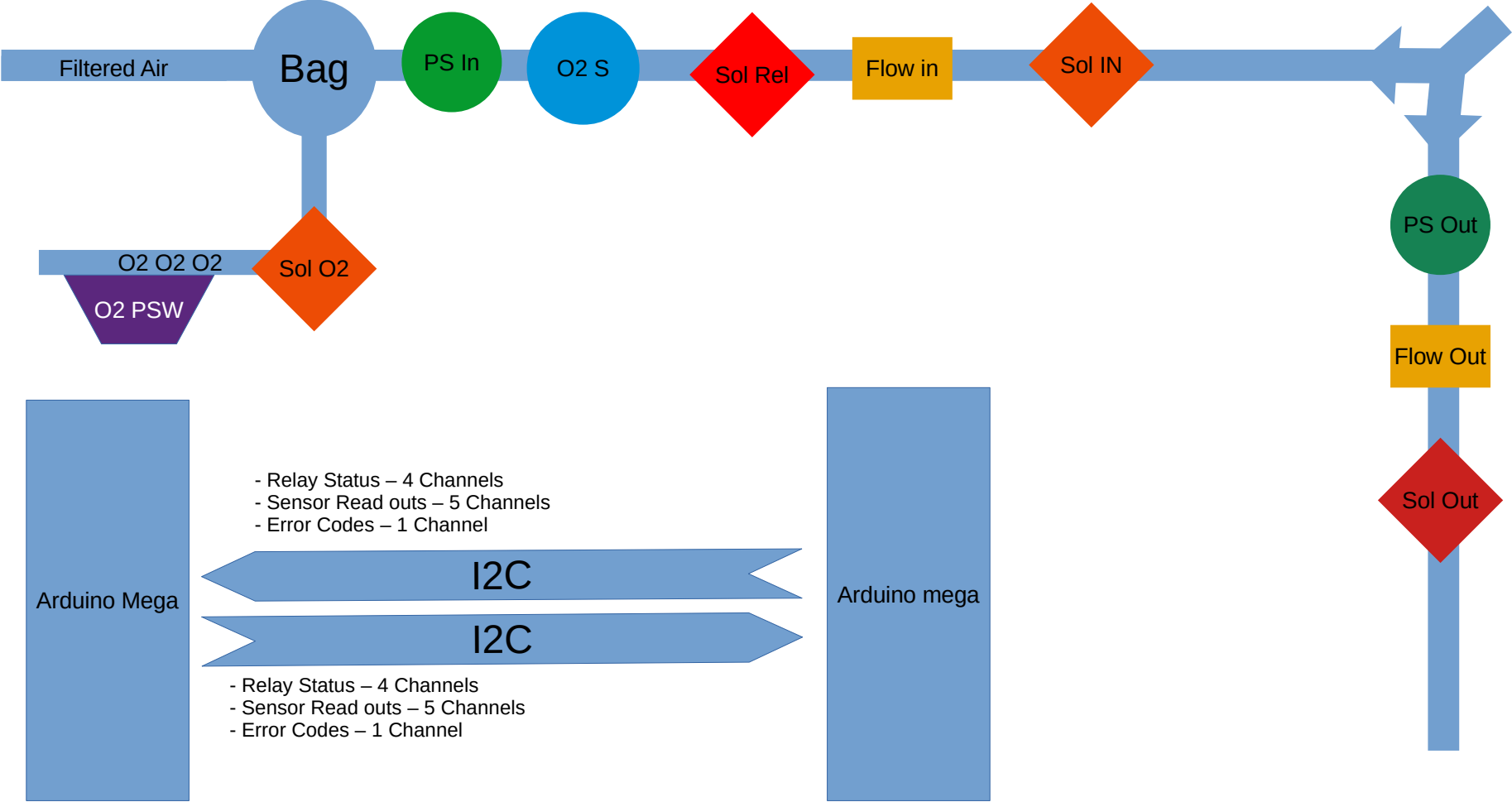
# Outputs



Inputs

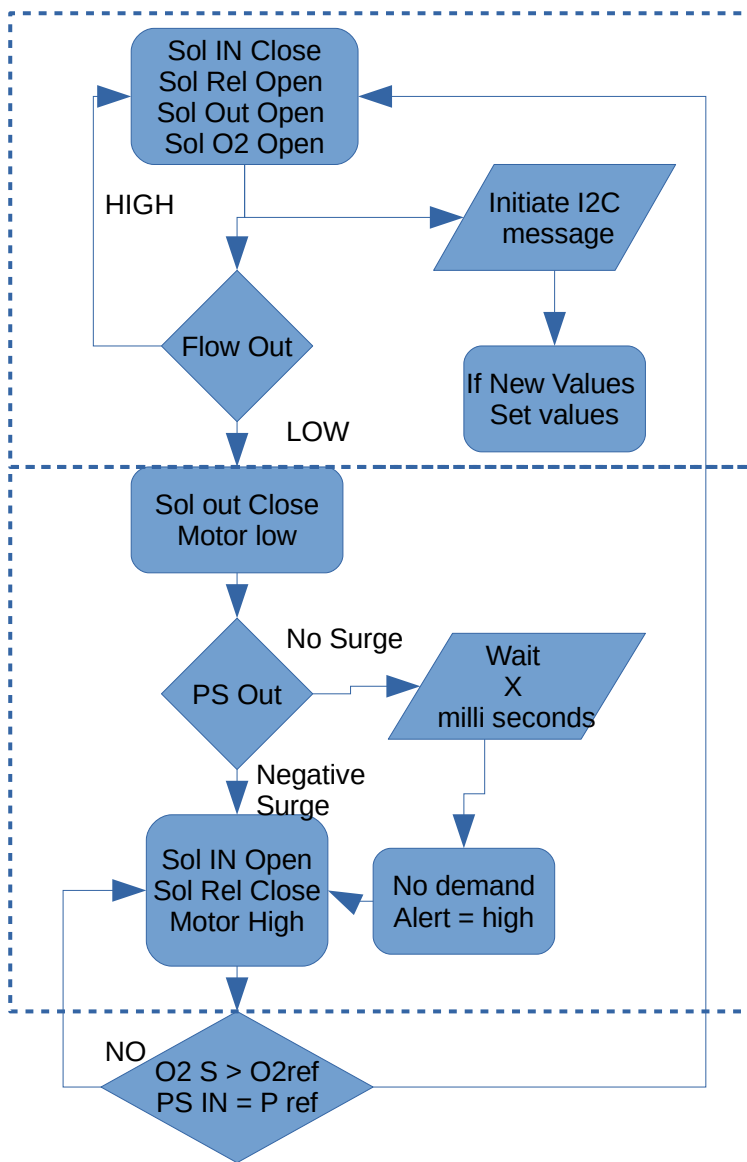


# Inputs



## - Process

- Close Sol IN
- Open Sol Out
- If Flow Out becomes low
- Close Sol Out
- If PS Out surges → Open Sol IN → Motor High
- If PS IN reaches Pref → Close Sol IN → Open Sol Out → Motor Low
- Send Values (PS IN, PS Out, Flow In , Flow Out) Via I2C. If any values received edit P ref, Wait time
-



- Exhale

- Inhale