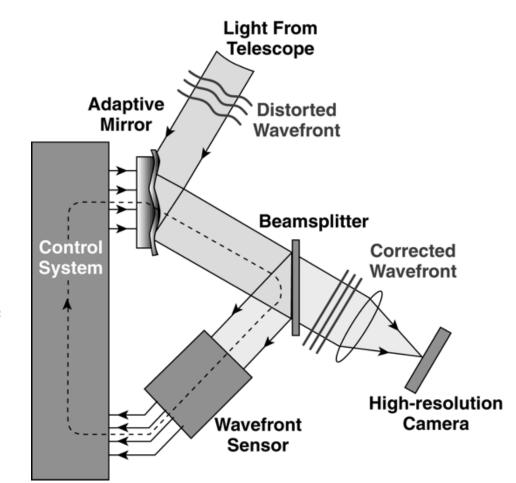
#### Schematic of adaptive optics system



Feedback loop: next cycle corrects the (small) errors of the last cycle

e.g. SHACK-HARTMANN WAVEFRONT SENSOR or PYRAMID WAVEFRONT SENSOR

## Part II - PSF theory

#### **Optical Path Difference**

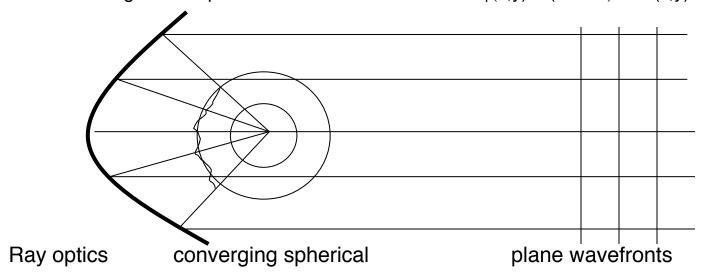
This is the deviation of the wavefront from 'perfect'... when talking of an image being formed by a converging wavefront,

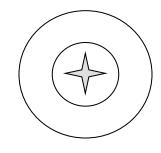
THE DEVIATION OF THE WAVEFRONT FROM THE PERFECT SPHERICAL CONVERGING WAVE

is the optical path difference.

In a collimated beam such as an interferometer, the deviation of a wavefront from the perfect, flat wavefront is the OPD.

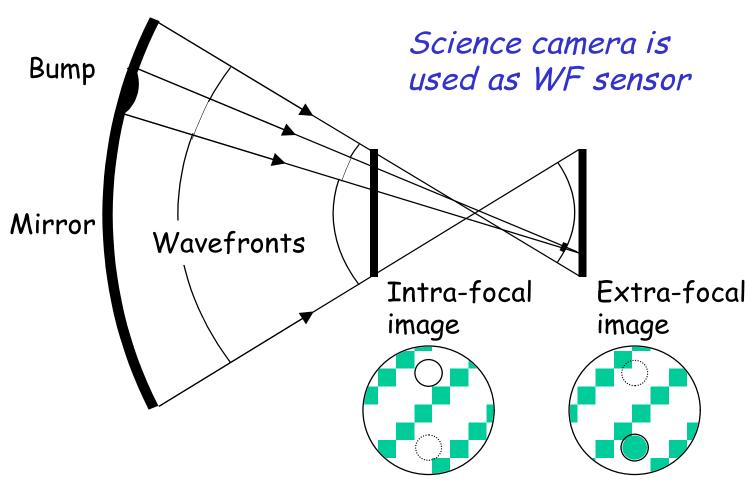
OPD(x,y) is a real function in 'pupil space', dimensions of LENGTH usually At wavelength it is expressed in RADIANS of PHASE:  $\phi(x,y) = (2 \pi / \lambda) OPD(x,y)$ 





diverging spherical

#### UNFOCUSSED IMAGES MEASURE THE MIRRORS



S. BASINGER

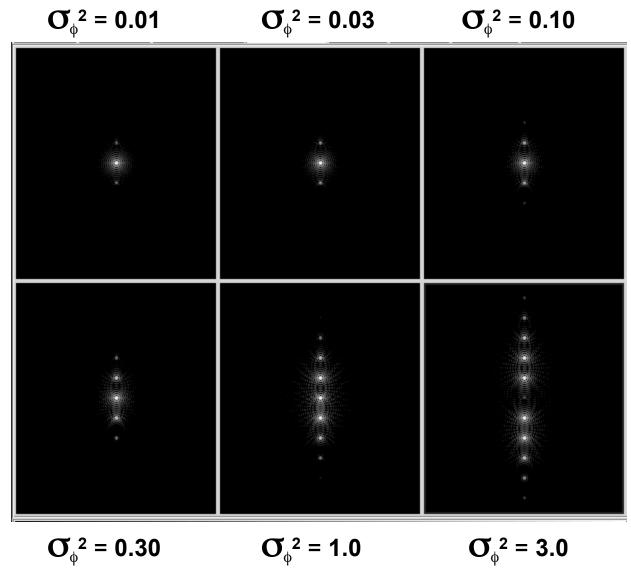
### Phase aberrations in cycles per diameter

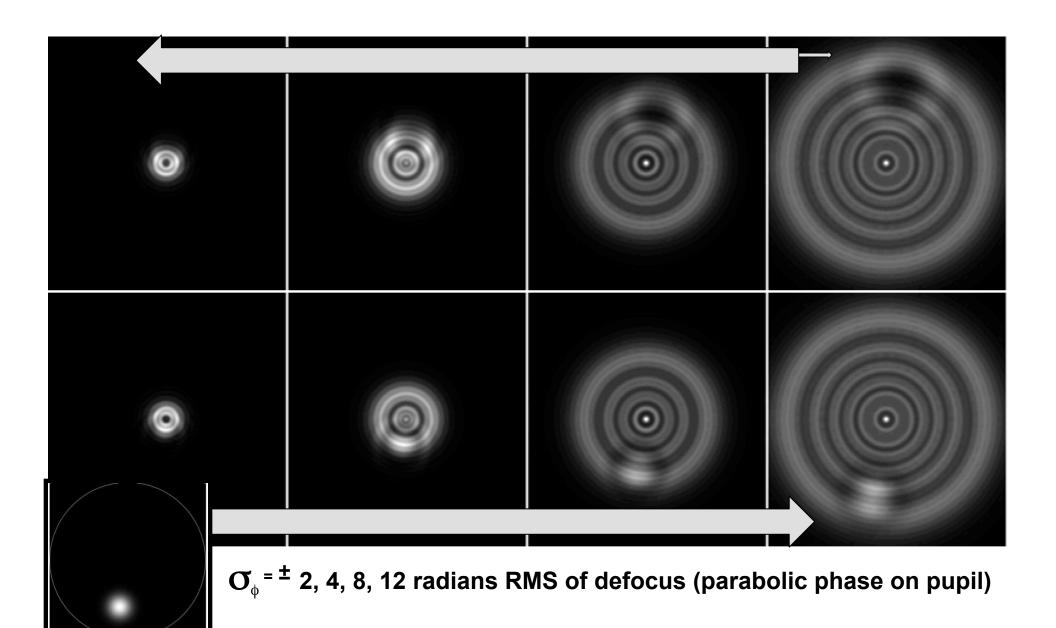
**Think Fourier** 

Sine wave aberration is a pair of delta functions in its 'Fourier transform domain'

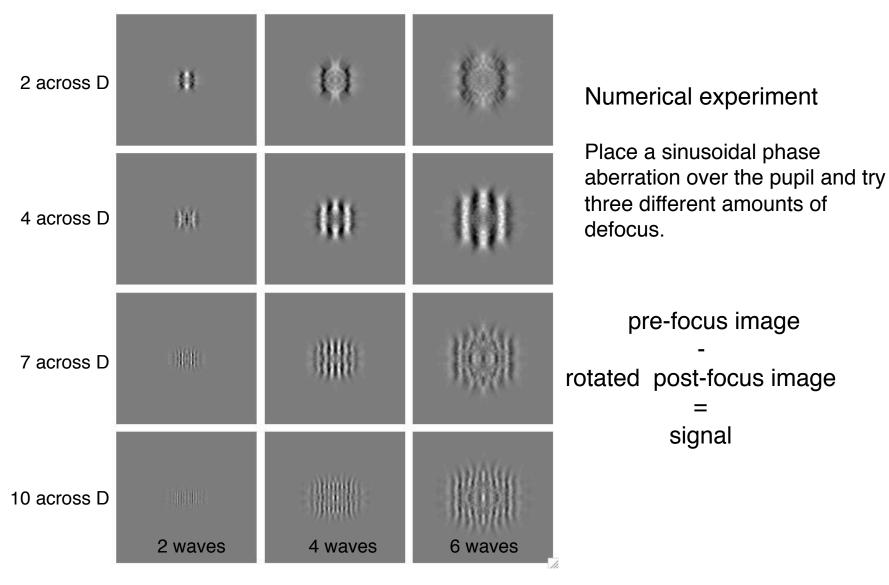
At small amplitudes this corresponds to pair of bright spots in the PSF: pupil:  $exp(i\phi) \sim 1 + i\phi$  image:  $\delta(0) + FT(sine)$ 

As size of aberration increases, exp(iφ) expansion gets higher order terms. Quadratic terms produce spots at twice the separation...



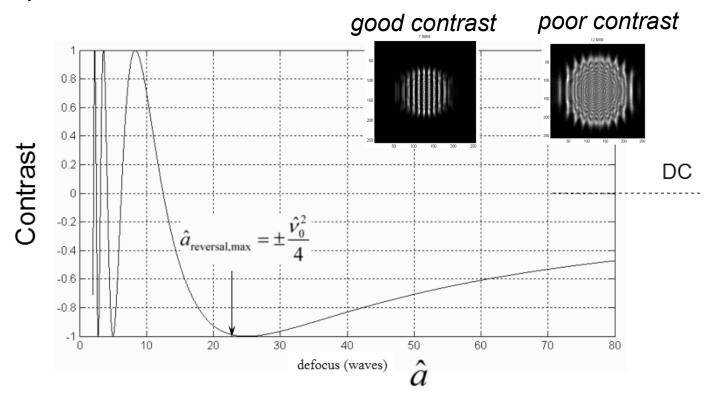


# Choosing the amount of defocus



#### What is the best defocus to use?

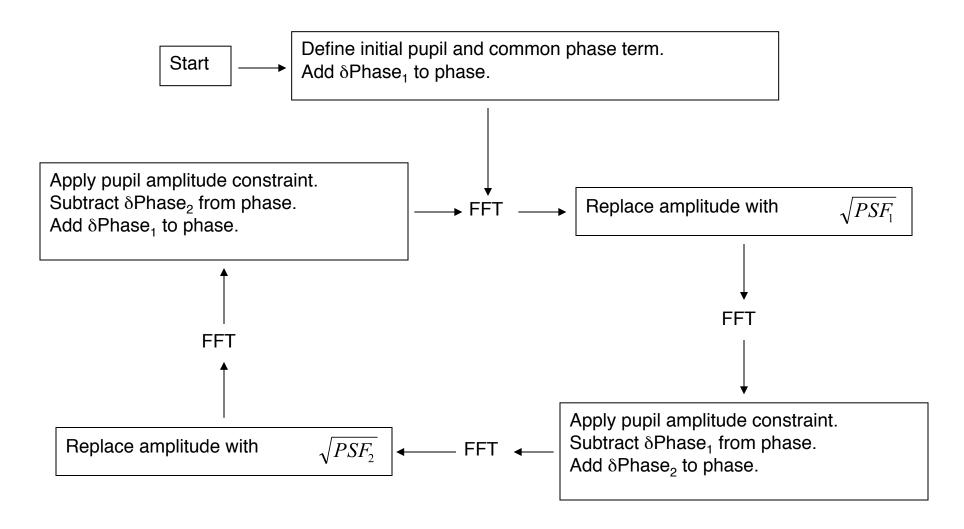
Signal strength for given spatial frequency of aberration (number of ripples across mirror) is periodic in 1/defocus



B. Dean, C. Bowers, "Diversity Selection for Phase-Diverse-Phase-Retrieval," JOSA, 20(8), 2003, pp. 1490-1504

### Missel Algorithm

Goal: Derive high-resolution exit pupil amplitude and phase maps



Pupil amp constraint: Enforce amplitude, zero outside pupil, or free everywhere

# Misell-Gerchberg-Saxton (MGS) algorithm

MGS in this case - a mapping from one guess at the phase,  $f_1(x)$ , to a better estimate,  $f_2(x)$ , using a known pupil function and image data I(k)

- Assume a pupil function A(x) and a first-guess phase f<sub>1</sub>(x)
- Calculate  $a(k) = F[(A(x) \exp \{i f_1(x)\}] = b(k) \exp \{i g(k)\}$  (b is real)
- Use measured data for intensity I(k) replace b(k) with sqrt(I(k))
- Now we have sqrt(I(k)) exp {i g(k)}
- Back-transform it we write this as  $C(x) \exp\{i f_2(x)\}$
- This gives us our revised estimate of the phase, f<sub>2</sub>(x)
- Now write the pupil field using known pupil A instead of C:  $A(x) \exp \{i f_2(x)\}$
- And do the same operations to get the next estimate,  $f_3(x)$ , for the phase

Keep going till you are happy. It WILL converge but not necessarily to the right phase -

- Incorrect A(x)
- Improperly reduced data I(k) (CR, flats, photon noise, real pixel response,...)
- Difference between FFT samples and physical pixels, etc.