

$$\frac{\delta x_i}{\delta \epsilon} = \begin{bmatrix} I & [x_i]_x \end{bmatrix}$$

(derivative of the exponential map)

Jacobian is computed for all pixels in the image and summed.

Use Cholesky decomposition to solve the linear equations of the form $A = LL^T$.

$\nabla \epsilon$ is found iteratively until it is converged.

$$T_c \leftarrow T_c T(\nabla \epsilon)$$