



Innovation Learning Platform







### **PROJECT: SAFE GUARD MONITOR (SGM)**

- > SGM 0.1 Introduction
- > SGM 0.2 Hardware/Circuit making
- **> SGM 0.3 Coding**
- > SGM 0.4 Project Review



#### **SGM 0.1 - Introduction**

#### What We'll Make?

Safe Guard Monitor

#### What We'll Learn?

- Variables
- Data Type
- #define function
- Commands
  - 'delayMicroseconds()'
- Control Structure
  - -'if..else'





## How to make Safe guard monitor?

#### **Components Required:**

- □ Arduino Uno-1
- USB Cable -1
- □ HC-SR04 Module-1
- □ Buzzer -1
- □ LED-1
- $\square$  Resistor(330 ohm)-1
- $\square$  Resistor(100 ohm)-1
- □ Breadboard -1
- □ Jumper cables (MM)-12





# Working



- Distance alarm system made with buzzer, LED & Ultrasonic sensor
- When someone enters the sensor range, the buzzer beeps.
- The LED indicator lights up.







#### SGM 0.2 - Hardware/Circuit Making



### Steps Involved

STEP 1: Take components from kit

STEP 2: Connect the components as per circuit diagram

STEP 3: Connect the Ultrasonic Sensor Trigger pin to 13 & Echo pin to pin 12 of Arduino

STEP 4: Connect Buzzer (output) with pin 7 of Arduino via resistor

STEP 5: Connect LED (output) with pin 8 of Arduino via resistor

STEP 6: Upload Code

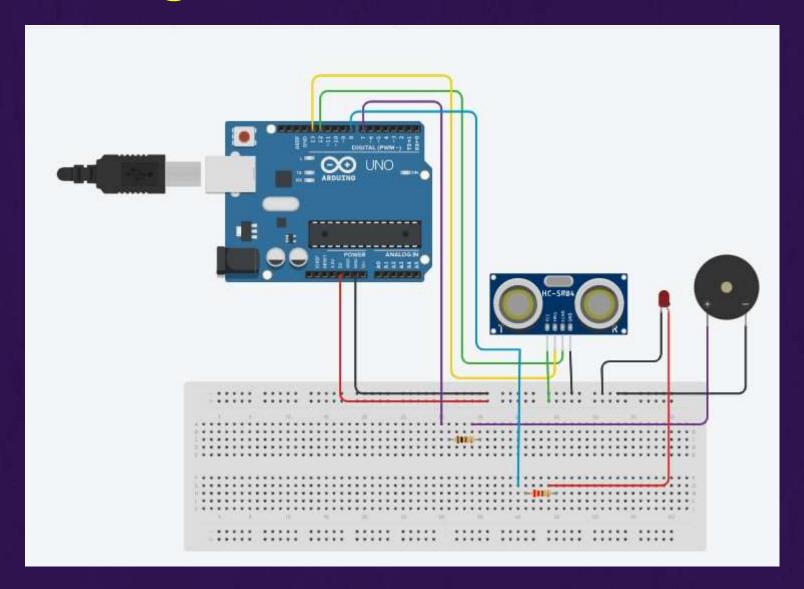
STEP 7: Check for errors

STEP 8: Check Output





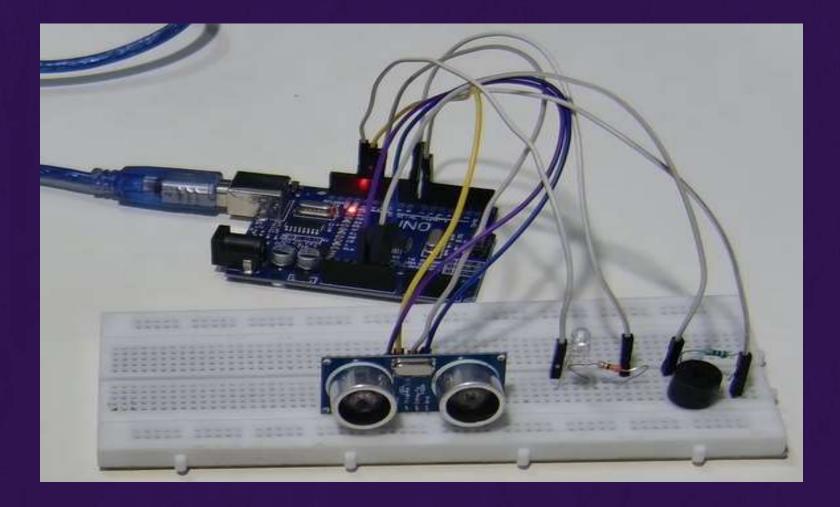
## Circuit Diagram







# **Connection Diagram**











SGM 0.3 - Coding



#### Code

```
/* This simple project describes how to make an ultrasonic alarm system using LED,
Ultasonic Sensor(HC-SR04) and a buzzer.*/
//Firstly the connections of ultrasonic Sensor.Connect +5v and GND normally &
trigger pin to 12 & echo pin to 13.
#define trigPin 13
#define echoPin 12
int Buzzer = 7; // Connect buzzer pin to 7
int ledPin= 8; //Connect LED pin to 8
int duration, distance; //to measure the distance and time taken void
setup() {
    //Define the output and input objects(devices)
    pinMode(trigPin, OUTPUT);
    pinMode(echoPin, INPUT);
    pinMode(Buzzer, OUTPUT);
    pinMode(ledPin,OUTPUT);
```





```
void loop() { digitalWrite(trigPin,
  HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  duration = pulseIn(echoPin, HIGH);
  distance = (duration/2) / 29.1;
  //when distance is greater than or equal to 10 OR less than or equal to 0,the buzzer and LED
are off
 if (distance \geq 10 \parallel distance \leq 0)
    digitalWrite(Buzzer,LOW);
    digitalWrite(ledPin,LOW);
 else {
    digitalWrite(ledPin,HIGH);
   digitalWrite(Buzzer,HIGH);
```





# **Applications**

- Smart Dustbin
- Touchless Door Opener
- Social distance Alarm









SGM 0.4- Project Review



### What We Learnt?

- ✓ Variables
- ✓ Data Type
- ✓ #define function
- ✓ Commands
  - 'delayMicroseconds()'
- ✓ Control Structure -if..else
- ✓ Applications





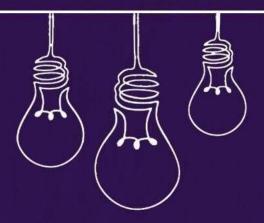
### Task#

Make Safe Guard Monitor using 2 LED and Buzzer...









# THANK YOU!



