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## DSAL - ASSIGNMENT 4

\* TETLE : HASH - THOLE IMPLEMENTATION

\* Problem Statement:

Consider telephone database of N clients. Make use of a hash table implementation to quickly look up clients's telephone number. Make use of 2 collision handling techniques of compare them using using number of comparisons required to find a set of telephone numbers. (One linear probing with & without replacement)

\* OBJECTIVE:
To understand practical implementation of usage of hash table for solving the problems.

Eclipse (++ - IDE

\* THEORY:

- Hash Table is one of the most impostant data

structures that uses a special function known as a

hash function that maps a given value with a key

to access the elements faster.

A hash table is a data structure that stores some information, I the information has basically 2 main components in key I value. The hash table

can be implemented with the help of an associative array. The efficiency of mapping depends upon the efficiency of the hash function used for mapping.

Hashing is one of the seasching techniques that uses a constant time. The time complexity in hashing is O(1). In hashing technique, the house table of hash function are used. Using the hash function, we can calculate the address at which the value can be stored. The main idea behind the hashing is to create the (hey/value) pairs. If the key is given, then the algorithm computes the index at which the value would be stored. It can be written as, index = hash (hey)

· Collision!
- When 2 different values have the same howh value,

then the problem occurs between the 2 values,

known as collision. To resolve the collisions,

we have some techniques known as collision

techniques.

- The following are collision techniques:

i) Open Hashing > It is also known as closed addressing

ii) Closed Hashing = It is also known as open addressing

Linear Probing:

When the hash function causes a collision by mapping a new key to a cell of the hash table that is already occupied by another key linear probing searches the table for the closest following free location I inserts the new key there lookups are performed in the same way, by searching the ta table sequentially starting at the new position given by the hash function, until finding a cell with a matching key or an empty cell. Here, array as host table is considered circular because when the last slot reached an empty location not found then the search proceeds to the first location of the array

\* ALGORITHMS / PSEUDOCODES:
· Class Data Item !-

class Data Item & int data; int hey; 3;

· Hash Method :-

int hash (ode (int key) {

seturn key % size;

```
· Seasch Operation ;-
    Algorithm * seearch (key) }
           //get the hash
            hash Index = hash (ode (key);
           I move in array until an empty stat is found.
           while (hash Array [hash Index] != NOLL) {
                      If (hash Assey [hash Index] -> key => key)
                              retion hasharray[hash Index]
                     ++ hosh Index;
                      hagh Intex =/= size;
          return NULL;
· Insert Operation;
 Algorithm Joseph (key, Data) &
      Hem = new Data Item;
      item -> data = Data >
      item - hey = key 5
      hash Index = hash (ode (key);
     while (host Array [hast Index] = null like host Array [hast Index]
                                         -> key ! = -1) {
                 + + hash Index 3
                  hash Index 0/0=size;
     hash Assay [hush Index] = item 3
```

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	· Delete 0	peration,								
	Dala Them	* delete (item)	S							
		ey = h item -> 1								
		howh Index = howh (ode (key) 5								
			[hash Index != n	011) {						
		it (.hash	Array [hwhIndex ]	-> key = = key)	2					
		stoe.								
	Struct Data Item * temp = hash Assay [had I day]									
	hashAssay [hashIndexi] = dummy Item;									
	3									
	++ hagh Index;									
			o/o = size;							
	3									
	88-1-	van null;								
	3	3								
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