Hardware Realization of Lock Instruction

```
boolean TestAndSet(boolean *target) {
  boolean rv = *target;
  *target = TRUE;
  return rv;
}

do {
  while (TestAndSetLock(&lock))
    ; // do nothing

    // critical section

lock = FALSE;

  // remainder section
}while (TRUE);
```

Alternate Realization of Lock Instruction

```
int compare_and_swap(int *value, int expected, int new_value) {
  int temp = *value;

  if (*value == expected)
     *value = new_value;

  return temp;
}

do {
  while (compare_and_swap(&lock, 0, 1) != 0)
     ; /* do nothing */
     /* critical section */
  lock = 0;
     /* remainder section */
} while (true);
```

Bounded-waiting mutual exclusion with TestAndSet().

```
do {
  waiting[i] = TRUE;
  key = TRUE;
  while (waiting[i] && key)
    key = TestAndSet(&lock);
  waiting[i] = FALSE;
     // critical section
  j = (i + 1) % n;
  while ((j != i) && !waiting[j])
    j = (j + 1) % n;
  if (j == i)
    lock = FALSE;
  else
    waiting[j] = FALSE;
    // remainder section
}while (TRUE);
```

- The key feature of the above algorithm is that a process blocks on the AND of the critical section being locked and that this process is in the waiting state.
- On Critical Section Exit, process does not just unlock the critical section and let the other processes have a free-for-all trying to get in.
- But searches in an orderly progression (starting with the next process on the list) for a process that has been waiting, and if it finds one, then it releases that particular process from its waiting state, without unlocking the critical section,
- thereby allowing a specific process into the critical section while continuing to block all the others.
- Only if there are no other processes currently waiting; is the general lock removed, allowing the next process to access to the critical section