

```

while (true)
{
    // item not produced
    while ((in+1) % BS == out)
    ;// do nothing as the Buffer is Full
    buffer [in] = next-produced-item;
    in = ( in + 1 ) % BS ;
}

```

```

while (true)
{
    // item not consumed
    while (in == out)
    ;//do nothing as Buffer is Empty
    next-consumed-item = buffer[out];
    out = (out + 1 ) % BS ;
}

```

BS- Buffer Size

buffer - circular array with two pointers / access indices

in - next free position in the buffer array ;

out - first full position in the buffer array ;

in == out implies EMPTY; (in+1) % BS == out implies FULL buffer

- **Message passing** – processes communicate without shared variables
- IPC facility provides two operations: - **send(message)** – message size fixed or variable and **receive(message)**
- **Steps for IPC** - **Establish a communication link** between processes and - **Exchange messages** via send/receive

Communication link types –

- **Direct or indirect ; Synchronous or asynchronous - Automatic or explicit buffering**

DIRECT

- Processes must name each other explicitly:
- **send(P , message)** – send a message to process P -
receive(Q , message) – receive a message from process Q
- **Links are established automatically between the two processes**
- **A link is associated with exactly one pair of communicating processes**
- **Between each pair there exists exactly one link**
- **The link may be unidirectional, but is usually bi-directional**

INDIRECT

- ❑ Messages sent / received from mailboxes (aka ports)
- ❑ Every mailbox has a id- Processes can communicate only if they share a mailbox
 - Link established only if processes share a common mailbox
 - A link may be associated with more than two processes
 - Each pair of processes may share several communication links –
 - Link may be unidirectional or bi-directional

Operations - Create a new mailbox - Send and receive messages through mailbox - Destroy a mailbox

- ✓ **send(A , message)** – send a message to mailbox A
- ✓ **Receive(A , message)** – receive a message from mailbox A

MAILBOX SHARING

Assume - P1, P2, and P3 share mailbox A - P1, sends; P2 and P3 receive ; Issue to resolve who gets it ?

- link to be associated with at most two processes
- only one process at a time to execute a receive operation
- system arbitrarily selects receiver and sender is informed of the same. Sender is

SYNCHRONIZATION

- ✓ Message passing 2 types - blocking ; non-blocking
- ✓ Blocking = synchronous and Non blocking = asynchronous
- Blocking send - sender blocked until the message is received
- Blocking receive - receiver blocked until a message is available
- Non-blocking send - sender sends message & continues
- Non-blocking receive - receiver receives a valid message or null

Messages are always queued (Buffer)

3 types of Buffers

(1) Zero capacity – queue has maximum length of 0

- Sender must wait (or block) until the receiver gets the message

(2) Bounded capacity – queue has finite length of n messages
Sender must wait if link full

(3) Unbounded capacity – queue has 'infinite' length ; Sender never waits

- ✓ POSIX library has support for various interfaces to perform shared memory such as shmat, shmdt, shmctl, etc. to support Inter Process Communication.
- ✓ We will visit SHM mode of IPC post PIPES to be explored first for its convenience ; code simplicity ; synchronous nature
- ✓ SHM is best for async and multiple process setup



PIPES for IPC

- Act as conduit to allow process to communicate
- Simpler mechanism for IPC
- Issues to be addressed : Bi or Uni directional communication
- Simplex – data can travel only in one direction (source and destination ends are fixed)
- Half Duplex – data can travel only in 1 direction at a time
- Full Duplex – both directions at a time possible
- What sort of relationship (P-C) between communicating processes
- Can pipes communicate over a network
- Ordinary Pipes – 2 Processes communicate in standard Producer Consumer Fashion



PIPES for IPC

- Ordinary Pipes – 2 Processes communicate in standard Producer Consumer Fashion
- Producer writes at one end of the pipe (write end)
- Consumer Reads from other end of the pipe (read end)
- Ordinary pipes are unidirectional – One way communication
- Simulate Bi directional communication with two pipes – with each sending data in different direction
- Process writes message onto pipe which is read by other processes.
- System call – `pipe (int fd[2]);` // function declaration
- `fd[0]` – read end of the pipe ; `fd[1]` – write end of the pipe
- `fd` - file descriptor

PIPES for IPC

- **Simplex** – one direction transfer only at a time ;
- **Half Duplex** – Both directions data exchange possible but not both at the same time
- **Full Duplex** – Both directions data exchange at the same time possible
- Ordinarily Pipes cannot be accessed from outside the process that created it
- Ideal setup – Parent creates pipe and used to communicate with the child process
- Child process inherits pipes from parent process

