

Methods of Calculus of Variations

- ◆ **Objective:** To find the curve for which some line integral has a stationary (extremal) value.

Let's consider the general problem. For simplicity we start with a one dimensional problem. We have a function $f(y, y', x)$ defined on a path $y = y(x)$ between two fixed x -values x_1 and x_2 , $x_1 < x_2$. Here $y' = dy/dx$. Our main objective is to find a particular path $y(x)$ such that the line integral

$$J = \int_{x_1}^{x_2} f(y, y', x) dx$$

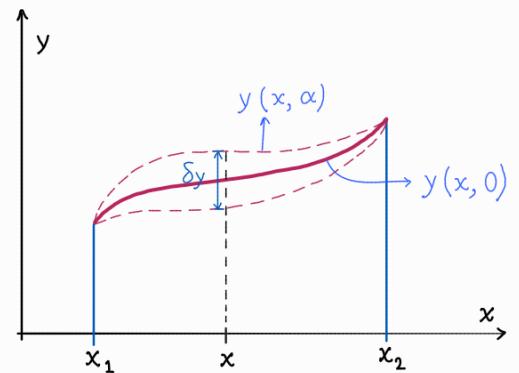
has a stationary value relative to paths differing infinitesimally from the correct one. This difference δJ is called the variation of J . δJ must be vanishing with respect to the neighbouring paths $\tilde{y}(x) = y(x, \alpha)$ (where α is a smallness parameter), infinitesimally apart from the correct one $y(x) =$

$y(x, 0)$. Here, $\tilde{y}(x) = y(x, \alpha) = y(x, 0) + \alpha \eta(x)$. The function $\eta(x)$ is such that

- it vanishes at x_1 and x_2
- it is well-behaved between x_1 and x_2 , i.e. no singularity, and continuous with continuous 1st and 2nd derivatives in the same interval.

So, $y(x, \alpha)$ gives a set of parametric curves in the y - x plot where α is the parameter. Thus,

$$J(\alpha) = \int_{x_1}^{x_2} f[y(x, \alpha), y'(x, \alpha), x] dx$$



For $J(\alpha)$ to be stationary (either minimal or maximal) we should have

$$\left. \frac{dJ(\alpha)}{d\alpha} \right|_{\alpha=0} = 0$$

(We evaluate the derivative at $\alpha=0$ because our assumption is that for $\alpha=0$, $y(x, \alpha)$ is the stationary/optimal path).

We use Leibniz rule to differentiate under the integral sign:

$$\frac{dJ(\alpha)}{d\alpha} \Big|_{\alpha=0} = \int_{x_1}^{x_2} \left(\frac{\partial f}{\partial y} \frac{\partial y}{\partial \alpha} + \frac{\partial f}{\partial y'} \frac{\partial y'}{\partial \alpha} \right) dx \Big|_{\alpha=0}$$

⚠️ Can you tell why there are no terms like $\frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial \alpha}$?

$$\begin{aligned} \Rightarrow 0 &= \int_{x_1}^{x_2} \left(\frac{\partial f}{\partial y} \frac{\partial y}{\partial \alpha} + \frac{\partial f}{\partial y'} \frac{\partial^2 y}{\partial x \partial \alpha} \right) dx \Big|_{\alpha=0} \\ &= \int_{x_1}^{x_2} \left(\frac{\partial f}{\partial y} \frac{\partial y}{\partial \alpha} \right) dx \Big|_{\alpha=0} + \left(\frac{\partial f}{\partial y'} \frac{\partial y}{\partial \alpha} \Big|_{\alpha=0} \right) \Big|_{x_1}^{x_2} - \int_{x_1}^{x_2} \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) \frac{\partial y}{\partial \alpha} dx \end{aligned}$$

Recognizing that $\frac{\partial y}{\partial \alpha} \Big|_{\alpha=0} = \eta(x)$ and using the fact that $\eta(x_1) = 0 = \eta(x_2)$, we get

$$\int_{x_1}^{x_2} \left[\frac{\partial f}{\partial y} - \frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) \right] \eta(x) dx = 0$$

The above integral vanishes for any arbitrary $\eta(x)$ with the given properties, we must have

$$\boxed{\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} = 0}$$

Now, let's have a look at the quantity

$$\delta y \equiv \frac{\partial y}{\partial \alpha} \Big|_{\alpha=0} dx$$

It is a variation of y keeping x frozen (if x is time, this δy is known as the virtual displacement). δy is the distance between the optimal path and (any of) its neighboring paths for a given x (see figure on the previous page). In the same way, the infinitesimal variation δJ of $J(\alpha)$ about the correct one is given by

$$\frac{\partial J}{\partial \alpha} \Big|_{\alpha=0} d\alpha = \frac{dJ}{d\alpha} \Big|_{\alpha=0} d\alpha = \delta J$$

So, an equivalent way of saying that $J(\alpha)$ is stationary, is to say that

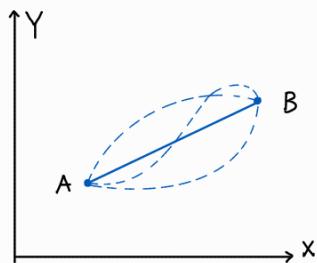
$$\boxed{\delta J = 0}$$

as $d\alpha$ can be arbitrary. We will use this throughout the course.

⚠️ What will happen if $f = f(y_1, y_2, \dots, y_n; y'_1, y'_2, \dots, y'_n; x)$?

● Applications:

(1) To find the shortest distance between two points in a plane:



The element of an arc of the curve C on a Cartesian plane is given by

$$ds = \sqrt{dx^2 + dy^2}$$

So, the distance S_c along the curve C between the points A and B is given by

$$S_c = \int_C ds = \int_A^B \sqrt{dx^2 + dy^2} \Big|_C = \int_A^B dx \sqrt{1 + \left(\frac{dy}{dx}\right)^2} \Big|_C$$

For S_c to be the minimum, we must have

$$\frac{d}{dx} \frac{\partial f}{\partial y'} - \frac{\partial f}{\partial y} = 0 ; \quad f(y, y', x) = \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$

Thus, $\frac{\partial f}{\partial y} = 0$ and $\frac{\partial f}{\partial y'} = \frac{y'}{\sqrt{1 + (y')^2}}$, so that

$$\frac{d}{dx} \left(\frac{y'}{\sqrt{1 + (y')^2}} \right) = 0$$

$$\Rightarrow \frac{y''}{\sqrt{1 + (y')^2}} - \frac{(y')^2 y''}{(1 + (y')^2)^{3/2}} = 0 \quad \Rightarrow \frac{y''}{\sqrt{1 + (y')^2}} \left(1 - \frac{(y')^2}{1 + (y')^2} \right) = 0$$

$$\Rightarrow y'' = 0, \quad \text{or} \quad \frac{(y')^2}{1 + (y')^2} = 1$$

But the latter equality is never possible and it leads to the absurd result $1 = 0$.

Thus we have

$$y'' = 0$$

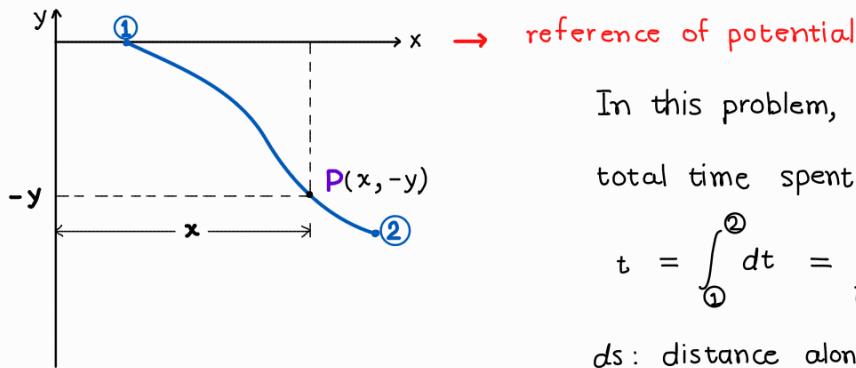
$$\Rightarrow y = ax + b, \quad \text{for some constants } a \text{ and } b.$$

This is the equation of a straight line, the optimal curve along which the distance between A and B could be the shortest.

Greek for the fastest path.

(2) Brachistochrone problem: Statement - If a point particle is falling from rest under the influence of gravity from a higher point to a lower one, which curve joining the

two points would correspond to the least time?



In this problem, we have to minimize the total time spent:

$$t = \int_{①}^{②} dt = \int_{①}^{②} \frac{ds}{v};$$

ds : distance along the curve, v : speed at any point.

Motion under gravity implies conserved energy in the absence of any dissipative forces such as friction. At ①, $T = 0$, $V = 0$. At ②, $T = \frac{1}{2}mv^2$, $V = -mgy$. Thus, $T + V = 0 = \frac{1}{2}mv^2 - mgy \Rightarrow \frac{1}{2}mv^2 = mgy \Rightarrow v = \sqrt{2gy}$; $y > 0$

Now

$$\begin{aligned} t &= \int_{①}^{②} \frac{\sqrt{dx^2 + dy^2}}{v} = \int_{①}^{②} \frac{dx \sqrt{1 + (dy/dx)^2}}{\sqrt{2gy}} = \int_{①}^{②} dx \left(\frac{1 + (y')^2}{2gy} \right)^{1/2} \\ \Rightarrow f(y, y', x) &= \left(\frac{1 + (y')^2}{2gy} \right)^{1/2} \end{aligned}$$

The correct curve would satisfy

$$\frac{d}{dx} \left(\frac{\partial f}{\partial y'} \right) - \frac{\partial f}{\partial y} = 0$$

$$\text{Now } \frac{\partial f}{\partial y} = \frac{1}{2} \left(\frac{2gy}{1 + (y')^2} \right)^{1/2} \left(-\frac{1 + (y')^2}{(2gy)^2} \right) \cdot 2g = -\frac{1}{2} \left(\frac{1 + (y')^2}{2g} \right)^{1/2} \frac{1}{y^{3/2}}$$

$$\text{and } \frac{\partial f}{\partial y'} = \frac{1}{2} \left(\frac{2gy}{1 + (y')^2} \right)^{1/2} \frac{2y'}{2gy} = \frac{y'}{\sqrt{2gy} \sqrt{1 + (y')^2}}$$

Thus, for the correct curve,

$$\begin{aligned} -\frac{1}{2} \left(\frac{1 + (y')^2}{y^3} \right)^{1/2} &= \frac{d}{dx} \left(\frac{y'}{\sqrt{y(1 + (y')^2)}} \right) \\ &= \frac{y''}{\sqrt{y(1 + (y')^2)}} - \frac{1}{2} \frac{y'}{[y(1 + (y')^2)]^{3/2}} [y'[1 + (y')^2] + y \cdot 2y'y''] \\ &= \frac{y''}{\sqrt{y(1 + (y')^2)}} - \frac{1}{2} \frac{(y')^2 [1 + (y')^2 + 2y'y'']}{[y(1 + (y')^2)]^{3/2}} \\ &= \frac{y''}{\sqrt{y(1 + (y')^2)}} - \frac{1}{2} \frac{(y')^2}{[y^3(1 + (y')^2)]^{1/2}} - \frac{(y')^2 y''}{(y[1 + (y')^2]^3)^{1/2}} \end{aligned}$$

$$\Rightarrow -\frac{1}{2} \frac{1+(y')^2}{y} = y'' - \frac{1}{2} \frac{(y')^2}{y} - \frac{(y')^2 y''}{1+(y')^2}$$

$$\Rightarrow -\frac{1+(y')^2}{2y} + \frac{(y')^2}{2y} = \frac{y''}{1+(y')^2}$$

$$\Rightarrow \frac{y''}{1+(y')^2} = -\frac{1}{2y}$$

$$\Rightarrow 2yy'' = -1 - (y')^2 \Rightarrow 2yy'' + (y')^2 + 1 = 0$$

$$\Rightarrow 2yy'y'' + (y')^3 + y' = 0$$

$$\Rightarrow y \frac{d}{dx} (y')^2 + (y')^2 \frac{dy}{dx} + \frac{dy}{dx} = 0$$

$$\Rightarrow \frac{d}{dx} [y(y')^2] + \frac{dy}{dx} = 0$$

$$\Rightarrow \frac{d}{dx} [y + y(y')^2] = 0 \Rightarrow y [1 + (y')^2] = C > 0; C \text{ is a constant.}$$

$$\Rightarrow y' = \sqrt{\frac{C-y}{y}} \Rightarrow dx = \sqrt{\frac{y}{C-y}} dy$$

Substituting $y = C \sin^2 t$, we get

$$\int dx = 2C \int \sin^2 t dt = C \int (1 - \cos 2t) dt$$

$$\Rightarrow x(t) = Ct - \frac{1}{2}C \sin(2t) + D$$

$$\text{with } y(t) = \frac{C}{2} [1 - \cos(2t)]$$

If we suppose that this path passes through the origin, then $D = 0$, and we get a family of curves parametrized by t :

$$x(t) = Ct - \frac{1}{2}C \sin(2t)$$

$$y(t) = \frac{C}{2} [1 - \cos(2t)]$$

Then we take the curve which also passes through the point ② (x_2, y_2) . This curve is part of a cycloid.

Historically, this problem led John Bernoulli to the formal foundation of the calculus of variations.

