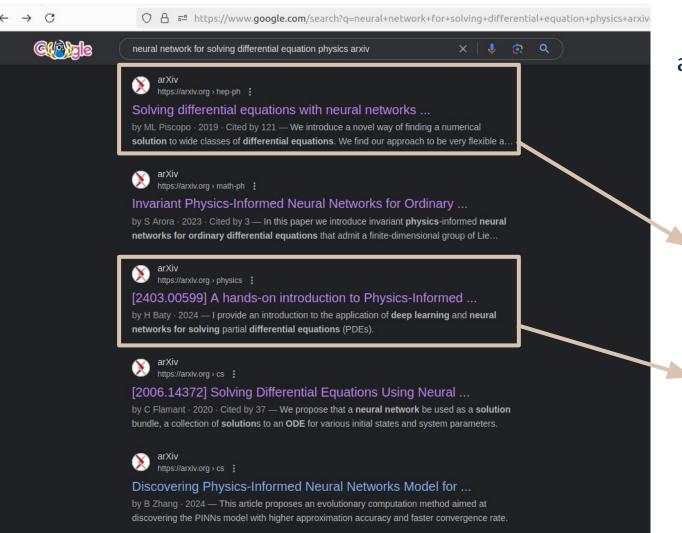
PHY654

Machine learning (ML) in particle physics



Swagata Mukherjee • IIT Kanpur 5th and 7th September 2024



Solving DE using NN: an active research area

PINN: Physics-Informed Neural Networks

Applications to the calculation of cosmological phase transitions. *Phys. Rev. D 100, 016002 (2019)*

Laplace equation,
Poisson equations,
Helmholtz equations,
Grad-Shafranov equations,
etc

Mini-batch gradient descent

What if m is VERY large? Eg: 5 or 10 Million. m=number of training example.

In that case, it's difficult to process all m examples together, instead do mini-batch gradient descent.

Split your large training set into several mini training sets (mini-batches).

Mini-batch size: what to choose?

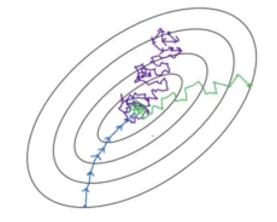
Two extremes

Mini-batch size: $m \rightarrow Batch Gradient Descent$

Mini-batch size: 1 → Stochastic Gradient Descent (very noisy)

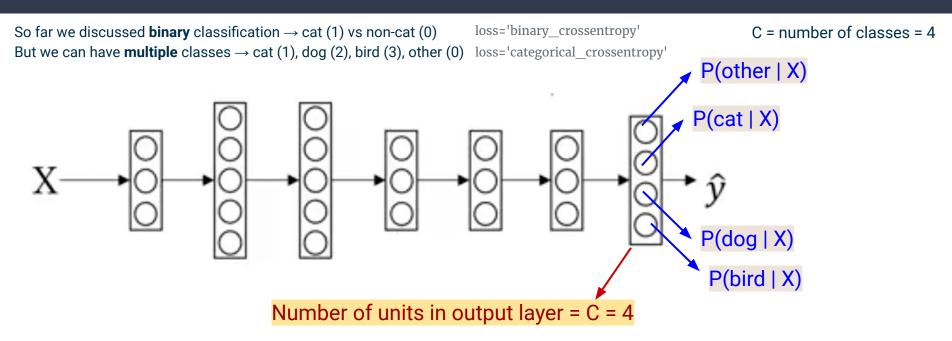
In practise we use something in between.

Generally one can try mini-batch sizes of 64 or 128 or 1024



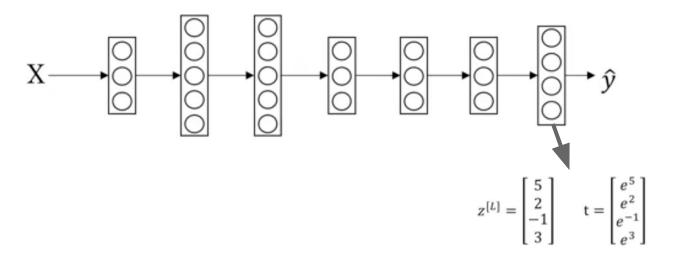
The way computer memory is laid out and accessed, code may run faster if mini-batch size is 2^x

Multi-class classification



 \hat{y} is (4,1) dimensional vector

Softmax activation function



$$\mathbf{a^{[l]}} = g^{[L]}(z^{[L]}) = \begin{bmatrix} e^5/(e^5 + e^2 + e^{-1} + e^3) \\ e^2/(e^5 + e^2 + e^{-1} + e^3) \\ e^{-1}/(e^5 + e^2 + e^{-1} + e^3) \\ e^3/(e^5 + e^2 + e^{-1} + e^3) \end{bmatrix} = \begin{bmatrix} 0.842 \\ 0.042 \\ 0.002 \\ 0.114 \end{bmatrix}$$

Non-numerical data

```
[1] from sklearn.preprocessing import LabelEncoder

colors = ['red', 'blue', 'green', 'red', 'green']
encoder = LabelEncoder()

encoded_colors = encoder.fit_transform(colors)
print(encoded_colors)

[2 0 1 2 1]
```

Use label encoding to convert non-numerical data into numerical form.

One-hot encoding

```
[10] import numpy as np
     y real = np.array([0, 0, 1, 2, 2, 1, 1, 0, 1, 2])
     type(y real)
    numpy.ndarray
[17] print (y real)
    [0 0 1 2 2 1 1 0 1 2]
    encoder y = OneHotEncoder(sparse output=False)
    y real oh = encoder y.fit transform(y real.reshape(-1,1))
    print (y_real_oh)
\rightarrow [[1. 0. 0.]
     [1. 0. 0.]
     [0. 1. 0.]
     [0. 0. 1.]
     [0. 0. 1.]
     [0. 1. 0.]
     [0. 1. 0.]
     [1. 0. 0.]
     [0. 1. 0.]
      [0. 0. 1.]]
```

Use one hot encoding to convert categorical or numerical variables into binary vectors.

Feature normalization

Use standard scaler to normalize features (X).

```
print (X_normalized)

[[-0.95126609 -0.54433105]
    [-0.75049636 -1.36082763]
    [ 0.11472556   0.81649658]
    [ 1.58703689   1.08866211]]
```

Tensorflow and Keras

- TensorFlow is an open-source library for ML.
 - Offers high level of flexibility
 - You can define every aspect of your NN architecture and training process.
 - But flexibility comes at a cost. Sometimes, it can be challenging for beginners to grasp
- Keras is an open-source library for ML that runs on top of Tensorflow.
 - Keras is designed to be user-friendly
 - Excellent choice for newcomers to deep learning.

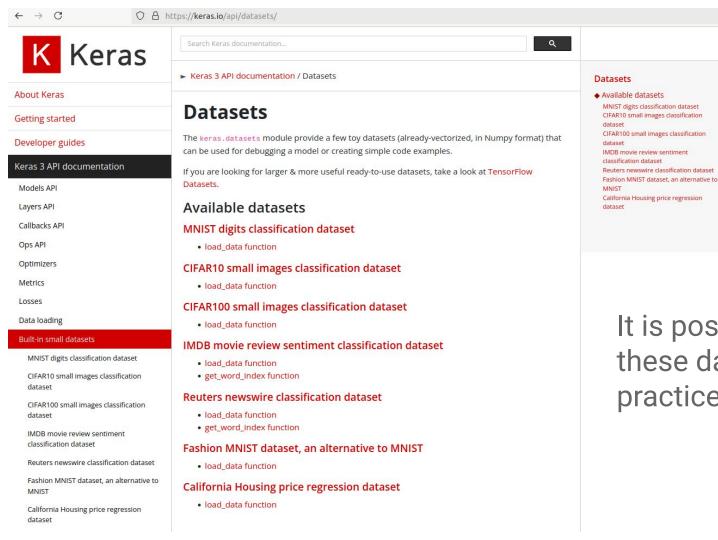
Keras: example code

XOR Gate

https://github.com/swagata87/IITKanpurPhy654/blob/main/XOR_NN_keras.ipynb

Ising model

https://github.com/swagata87/IITKanpurPhy654/blob/main/Ising_model.ipynb



It is possible to use these dataset to practice your ML skills

Multi-layer perceptron (MLP)

- Another name of Neural Net.
- Fully connected neurons with a nonlinear activation function.

CNN

Convolutional Neural Network (ConvNet)

CNN takes (mainly) images as input

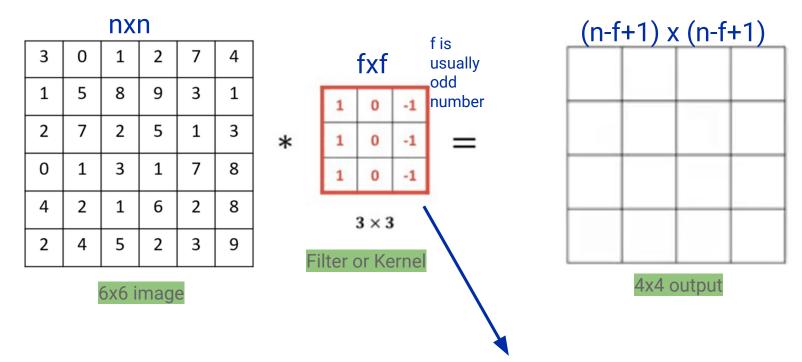
We can train a usual DNN on images as well.

But, number of features become huge. As a result, number of weights is also huge.

Difficult to train even for a small image size.

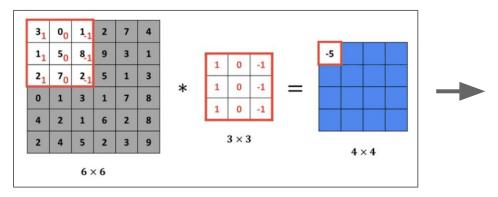
Need to exploit spatial proximity of features.

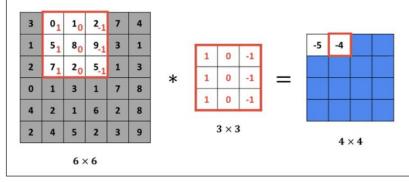
Convolution (example of 2D image, aka grayscale image)



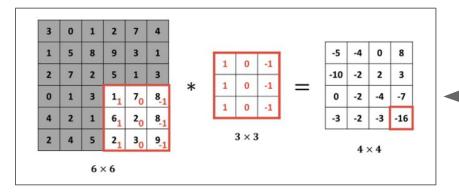
This filter can detect vertical edges in an image

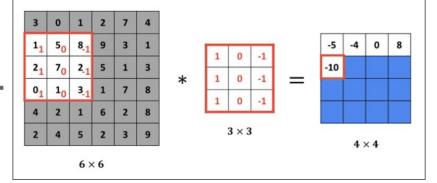
Convolution











A convolution operation converts all the pixels in its receptive field into a single value.

If you apply a convolution to an image, generally you will be decreasing the image size and bringing all the information in the receptive field together into a single pixel.

Vertical edge detector

2D image / grayscale

