

Vote Prediction Models for Signed Social Networks

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May 21, 2020

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Voting and Signed Networks

Voting in Communities

- Communities need to take collective action
- Voting is a popular method
- Members of the community vote on the agenda
- E.g.
 - Politicians voting for bills in the parliament
 - Wikipedia users voting for promoting administrators
- Understanding voting behaviour is beneficial
- Can propose agendas items which will be be successful
- Identify ideological fault lines amongst members

Votes as Signed Graphs

- Votes are usually for or against an agenda
- Intuitively maps to positive and negative edges in signed graphs
- More tools to analyse voting patterns, e.g.,
 - Correlation clustering [Brito et al., 2020, Arinik et al., 2017]
 - Balance and Status [Levorato and Frota, 2016, Derr and Tang, 2018]
- Two main prediction tasks exist with regard to voting
 - 1 Predicting the Result
 - 2 Predicting an individual vote
- We focus on predicting votes

Predicting Votes

Predicting a vote can be split into two phases

① **Who** will vote next

- Same as link prediction task
- Is trivial when voting order is known, e.g., parliament roll calls
- Combinatorial if no known underlying process

② **How** they will vote

- Same as sign prediction task
- Triad features encode balance and status theory
- Train a supervised ML model using network and triad features
[Leskovec et al., 2010a, Leskovec et al., 2010b]

We propose an *unsupervised iterative model* to predict the sign of a vote using balance and status theory.

Local Signed Network

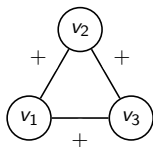
- Current voting session is a signed graph $S = (V_S, E_S, w_S)$
- It contains current voter v , candidate c and prior set of voters U
- We also have a signed *Relationship Graph*, $R = (V_R, E_R, w_R)$
- It is created from the history of voting sessions H
- The *Local Signed Network* is the intersection of these two graphs
 $LSN = S \cap R$
- Essentially the subgraph of the voter's neighbours in R who have already voted in S
- Can use balance and status theory in the LSN to predict votes

- RfAs are an election-esque process to gain admin rights
- Anyone can nominate a **candidate** or self-nominate
- 7 day long period of voting and discussion
- Any registered editor can comment and vote :
 - Support
 - Oppose
 - Neutral
- Highly intense process with Q&A with the candidate about Wiki policy etc
- Final decision is made by a bureaucrat
- Decision is based on if a **consensus** has been reached
- Successful RfAs usually have 75% support

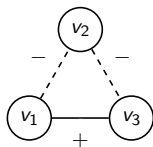
Balance Theory

Balance Theory

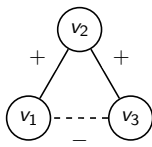
- Balance theory works for undirected signed graphs
- A cycle is balanced if it has even number of negative links
- A graph is balanced if every cycle is balanced
- Triads B_1 , B_2 are balanced
- Triads B_3 and B_4 are unbalanced



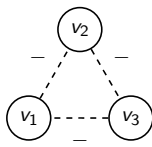
B_1



B_2



B_3



B_4

Agreement Graph

- Define a symmetric relationship based on **agreement**
- Subtract 0.5 from agreement ratio to get a signed measure
- Create an *Agreement Graph*, $A = (V_A, E_A, w_A)$

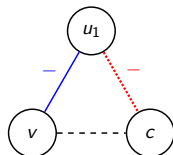
Signed Symmetric Measure

$$w_A((u, v)) = \frac{\text{Number of times } u \text{ and } v \text{ have voted similarly}}{\text{Number of common RfAs for } u \text{ and } v} - 0.5$$

How to measure balance?

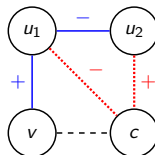
- Triads can be capture local balance of a network
- Need capture information from longer cycles [Chiang et al., 2011]
- Smallest eigenvalue λ_1 of the signed Laplacian \bar{L} is a measure of the imbalance of the network [Hou, 2005]
- We state that a voter chooses to maintain the balance of the LSN
- Therefore, can use λ_1 as basis for predictions in model

Iterative Balance Model



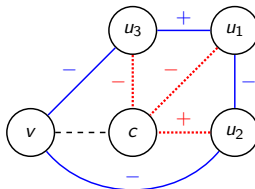
$$\lambda_1^+ = 0, \lambda_1^- = 1$$

(a) $i = 1$



$$\lambda_1^+ = 0.58, \lambda_1^- = 0$$

(b) $i = 2$



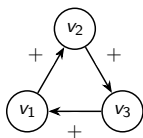
$$\lambda_1^+ = 0.55, \lambda_1^- = 0.55$$

(c) $i = 3$

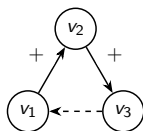
Status Theory

Status Theory

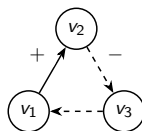
- Status theory is based on relative merit of nodes
- Edge $u \xrightarrow{+} v$: v has higher status than u
- Edge $u \xrightarrow{-} v$: v has lower status than u
- Status and Balance theories can contradict each other when used to predict edges
- Triads S_2 , S_3 and S_4 adhere to status theory
- Only triads S_1 and S_3 are balanced



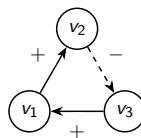
S_1



S_2



S_3



S_4

Follows Graph

- Define an asymmetric relationship based on **following**
- Create an *Follow Graph*, $F = (V_F, E_F, w_F)$
- An edge $u \rightarrow v$ indicates u votes after v
- Weight is 0.5 subtracted from the *followe ratio*

Signed Asymmetric Measure

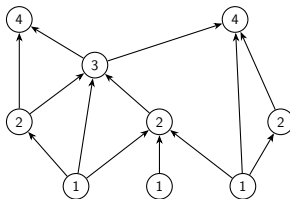
$$w_F((u, v)) = \frac{\text{Number of times } u \text{ voted after and agreed with } v}{\text{Number of times } u \text{ voted after } v} - 0.5$$

How to measure status?

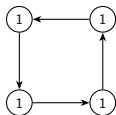
- Directed triads and other graph motifs can be a proxy for measuring status [Liu et al., 2019]
- Heuristic for status like $\sigma(v) = d_{\text{in}}^+(v) + d_{\text{out}}^-(v) - d_{\text{out}}^+(v) - d_{\text{in}}^-(v)$ [Leskovec et al., 2010a]
- These still only capture local effect of status
- Cannot measure violations of status in larger cycles
- The concept of a nodes possessing an implicit status is very similar to a hierarchy

- Assume a ranking for nodes, $r : V \rightarrow \mathbb{N}$
- An edge $u \rightarrow v$ causes **agony** if $r(u) < r(v)$
- Quantified as $\max(r(u) - r(v) + 1, 0)$ for an edge
- Agony of a graph G wrt r is
$$A(G, r) = \sum_{(u,v) \in E} \max(r(u) - r(v) + 1, 0)$$
- Agony of a graph is lowest possible agony over all rankings
$$A(G) = \min_{r \in \text{Rankings}} A(G, r)$$
- Lower agony means better hierarchy $h(G) = 1 - \frac{1}{|E|} A(G)$

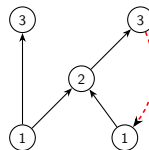
Examples



(a) DAG has perfect hierarchy, $h(G) = 1$
and agony of each edge is 0



(b) A cycle has no hierarchy,
 $h(G) = 0$ and each edge has agony
of 1

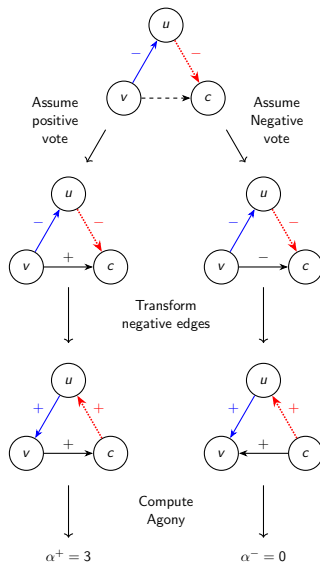


(c) Graph with some hierarchy
 $h(G) = 2/5$. Red dashed edge has
agony of 3 and solid black edges
have 0 agony.

Agony and Status

- [Gupte et al., 2011] and [Tatti, 2017] provide algorithms to compute agony of directed graphs
- Consider rank function r as status function σ
- For edge $u \rightarrow v$, $\sigma(u) < \sigma(v)$ is a status violation
- Therefore, agony is a measure of status violation of an edge
- The agony of a network is the **overall status compliance** of G
- What to do with signed edges?
- Flip edges $u \xrightarrow{-} v$ to $u \xrightarrow{+} v$
- Now, we say a voter chooses to reduce the agony of the LSN

Iterative Status Model



Iterative Prediction

Iterative Predictions and its Advantages

- Predictions with balance and status predictions are unsupervised
- Can be bootstrapped by starting with an empty graph R
- After predicting votes in a session, it updates R
- Iteratively gathers more information in R increasing performance
- Therefore, model can be trained on the entire dataset

Algorithm

Input: Candidate c , Relationship graph $R = (V_R, E_R, w_R)$, Order of voters in current session O and true votes w^*

Result: Predictions for current session

```
1  $k \leftarrow |O|$ 
2  $u \leftarrow O[1]$                                      // First voter
3  $V_S \leftarrow \{c, u\}$                                // candidate and first voter
4  $E_S \leftarrow \{(u, c)\}$                            // first vote
5  $w_S((u, c)) \leftarrow w^*((u, c))$                  // Assign true vote
6 Initialize session graph  $S = \{V_S, E_S, w_S\}$ 
7  $predictions \leftarrow \emptyset$ 
8 for  $i \leftarrow 2$  to  $k$  do
9    $v \leftarrow O[i]$ 
10   $V_S \leftarrow V_S \cup \{v\}$ 
11   $LSN \leftarrow S \cap R$ 
12   $p \leftarrow \text{Predict}(v, c, LSN)$ 
13   $predictions \leftarrow predictions \cup p$ 
14   $E_S \leftarrow E_S \cup \{(v, c)\}$ 
15   $w_S((v, c)) \leftarrow w^*((v, c))$                  // Assign true vote
16 end
17  $\text{Update}(R, S)$                                      // Update Relationship graph
18 return  $predictions$ 
```

Results

Tabular Results

Table: Information of relationship graphs of iterative models using entire WIKI-RFA dataset

Relationship Graph	$ V $	$ E $	density	largest component size
Agreement Graph	11924	2451028	0.0345	11908
Follow Graph	11924	3136303	0.0220	11563

Table: Results of iterative models on the complete WIKI-RFA dataset

Model	AUC-ROC	AUC-PR _{pos}	AUC-PR _{neg}
Baseline	0.5	0.784	0.216
Iterative Balance	0.835	0.935	0.635
Iterative Status	0.784	0.917	0.502

Plots

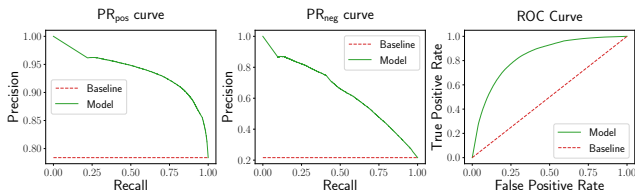


Figure: Plots for the Iterative Balance Model on the complete WIKI-RFA dataset

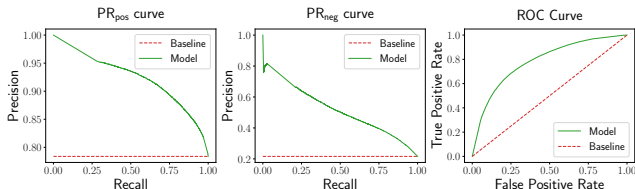


Figure: Plots for the Iterative Status Model on the complete WIKI-RFA dataset

Questions or Comments



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