

# LAB ASSIGNMENT

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Department : 2<sup>nd</sup> year Bsc. physics (Aided)

Aim : To simulate projectile motion using Euler's method and plot  $y$  vs  $x$ ,  $y$  vs  $t$  and  $x$  vs  $t$  graphs. compare, Horizontal range, Time of flight and Maximum height reached with theoretical results, include the effect of air resistance and freefall. and plot  $y$  vs  $x$  and  $y$  vs  $t$  graphs.

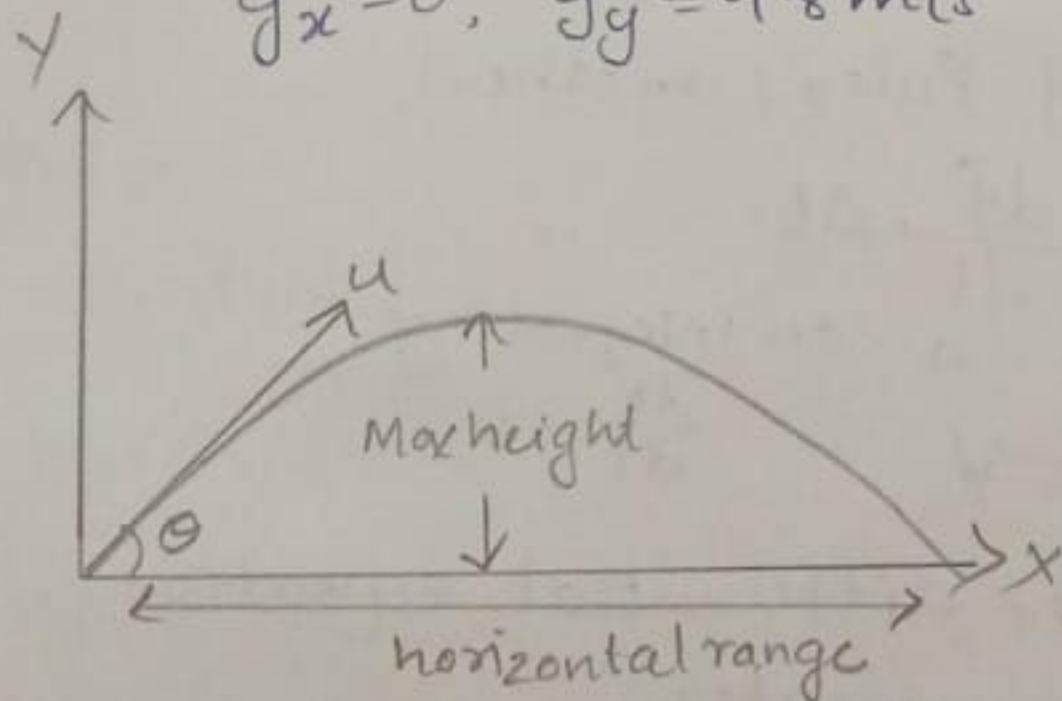
principle : consider a body projected at some angle ' $\theta$ ' with an initial velocity ' $u$ '. Neglecting the air resistance, components of acceleration exerted on the body along the two directions are

$$g_x = 0, \quad g_y = 9.8 \text{ m/s}^2$$

$$a = -g$$

$g_x$  = gravity along x-axis

$g_y$  = gravity along y-axis



components of velocity vector at time ' $t$ '

$$V_x(t) = V \cos \theta$$

$$V_y(t) = V \sin \theta - g_y t$$

position vectors are given by

$$X = V \cos \theta$$

$$Y = V \sin \theta - \frac{1}{2} g t^2$$



Total horizontal distance 'R' covered by projectile is given by

$$\text{Horizontal Range, } R = \frac{v^2 \sin 2\theta}{g}$$

Maximum height reached by the projectile

$$H = \frac{v^2 \sin^2 \theta}{2g}$$

Time of flight of the projectile

$$T = \frac{2v \sin \theta}{g}$$

If Air resistance is included,

$$a_x = -k V_x$$

$$a_y = -g - \frac{k V_y}{m}$$

Theory: Euler method is a numerical technique to solve ordinary differential equations by approximating the solution at small time steps.

General equation of Euler's method,

$$f_{n+1} = f_n + \frac{df}{dt} \cdot \Delta t$$

We know that,  $\frac{d^2 x}{dt^2} = a$  on integrating  
 $\frac{dx}{dt} = v$   $\frac{dx}{dt} = v$

This is a first-order differential equation, Euler's method approximates,

$$\frac{dx}{dt} \approx \frac{x_{n+1} - x_n}{\Delta t}$$

rearranging,

$$x_{n+1} \approx x_n + \frac{dx}{dt} \cdot \Delta t$$

$$x_{n+1} = x_n + v \cdot \Delta t$$



Thus we get the position update equation,

$$x_{n+1} = x_n + v_x \cdot \Delta t$$

$$y_{n+1} = y_n + v_y \cdot \Delta t$$

Similarly,

$$a = \frac{dv}{dt}$$

This is also a first order differential equation  
Euler Method approximates derivative,

$$\frac{dv}{dt} \approx \frac{v_{n+1} - v_n}{\Delta t}$$

Rearranging equation, we get

$$v_{n+1} = v_n + \frac{dv}{dt} \cdot \Delta t$$

Substitute  $\frac{dv}{dt} = a$ ,

$$v_{n+1} = v_n + a \cdot \Delta t$$

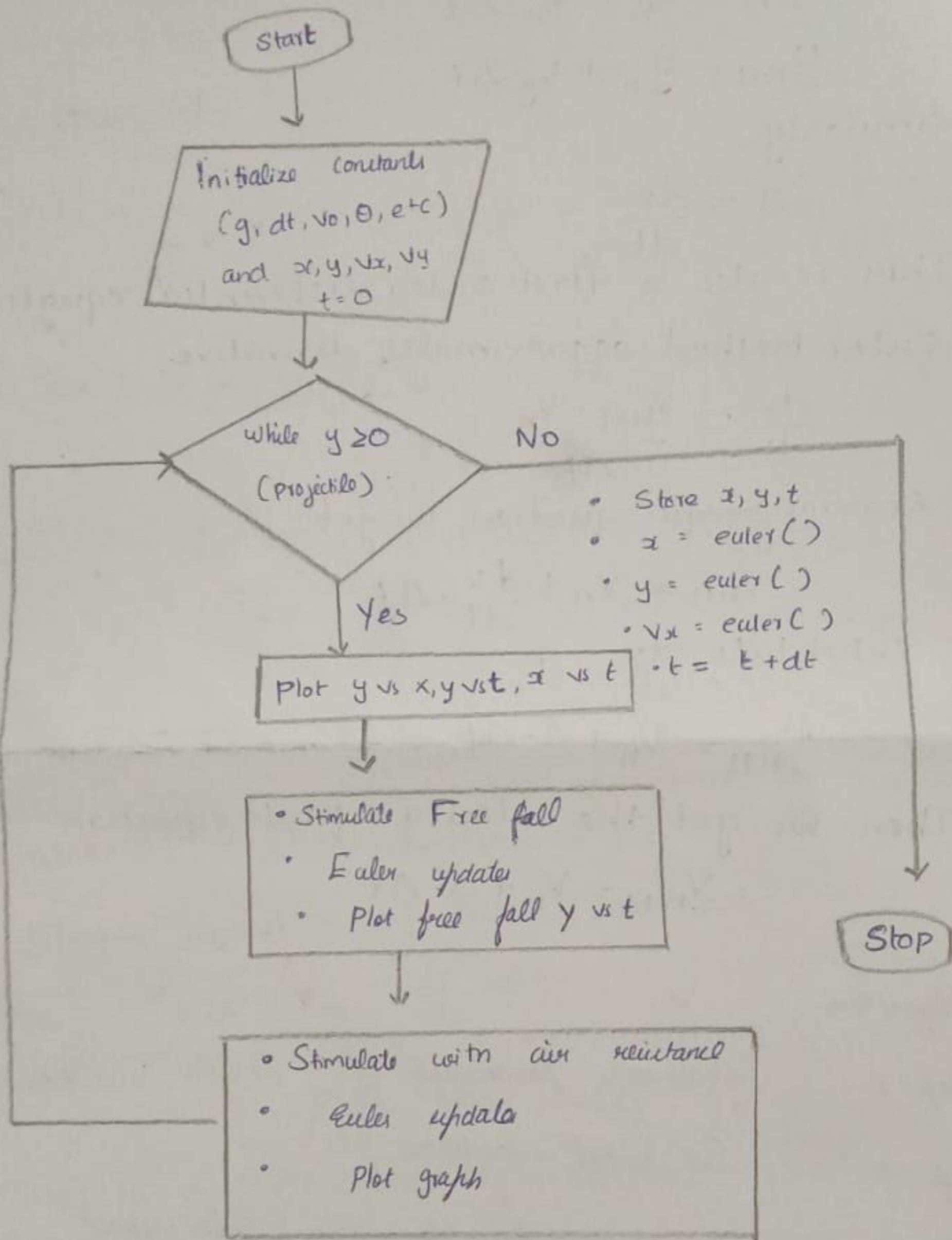
Then we get the velocity update equation.

$$v_{n+1} = v_n + a \cdot \Delta t$$

### Algorithm

- Step 1 : Initialize parameters
- Step 2 : Set initial conditions
- Step 3 : Stimulate projectile using Euler method
- Step 4 : Plot Trajectories
- Step 5 : Stimulate free fall
- Step 6 : Stimulate with air resistance

# Flow chart





python code:

```
import numpy as np
import matplotlib.pyplot as plt
```

```
def euler(x, y, fxy, h):
    return y + h * fxy(x, y)
```

```
g = 9.81
```

```
dt = 0.01
```

```
Vo = 50
```

```
theta = 45
```

```
theta_rad = np.radians(theta)
```

```
Vx0 = Vo * np.cos(theta_rad)
```

```
Vy0 = Vo * np.sin(theta_rad)
```

```
x, y = 0, 0
```

```
Vx, Vy = Vx0, Vy0
```

```
t = 0
```

```
x, y, T = [], [], []
```

```
while y >= 0:
```

```
    x.append(x)
```

```
    y.append(y)
```

```
    T.append(t)
```

```
    x = euler(t, x, lambda t, x: Vx, dt)
```

```
    y = euler(t, y, lambda t, y: Vy, dt)
```

```
    Vx = euler(t, Vx, lambda t, Vx: 0, dt)
```

```
    Vy = euler(t, Vy, lambda t, Vy: -g, dt)
```

```
    t += dt
```

```
plt.figure(figsize=(14, 4))
```

```
# y vs x
```

```
plt.subplot(1, 3, 1)
```

```
plt.plot(x, y)
```

```
plt.title("Trajectory (y vs x)")
```

```
plt.xlabel("x (m)")
```



```
plt.ylabel("Y (cm)")
```

```
plt.grid()
```

```
# Y vs t
```

```
plt.subplot(1, 3, 2)
```

```
plt.plot(T, Y)
```

```
plt.title("Height vs Time")
```

```
plt.xlabel("Time (s)")
```

```
plt.ylabel("Height (cm)")
```

```
plt.grid()
```

```
# X vs t
```

```
plt.subplot(1, 3, 3)
```

```
plt.plot(T, X)
```

```
plt.title("Distance vs Time")
```

```
plt.xlabel("Time (s)")
```

```
plt.ylabel("Distance (m)")
```

```
plt.grid()
```

```
plt.tight_layout()
```

```
plt.show()
```

```
print("simulation values")
```

```
print(f"Range: {X[-1]:.2f} m")
```

```
print(f"Max height: {max(Y):.2f} m")
```

```
print(f"Time of flight: {T[-1]:.2f} s")
```

```
# Free Fall
```

```
Y = 100
```

```
Vy = 0
```

```
t = 0
```

```
Yf, Tf = [], []
```

```
while y >= 0:
```

```
    Vf.append(y)
```

```
    Tf.append(t)
```

```
    Y = euler(t, Y, lambda t, Y: Vy, dt)
```



```
vy = euler(t, vy, lambda t, vy: -g, dt)
t += dt
```

```
plt.plot(Tf, Yf)
plt.title("Free fall (Y vs t)")
plt.xlabel("Time (s)")
plt.ylabel("Height (m)")
plt.grid()
plt.show()
```

# with Air resistance

```
K = 0.1
```

```
m = 1.0
```

```
x, y = 0, 0
```

```
vx, vy = 0, 0
```

```
t = 0
```

```
xa, ya = [], []
```

```
while y >= 0:
```

```
    xa.append(x)
```

```
    ya.append(y)
```

```
    ax = lambda t, vx: -K * vx / m
```

```
    ay = lambda t, vy: -g - K * vy / m
```

```
    vx = euler(t, vx, ax, dt)
```

```
    vy = euler(t, vy, ay, dt)
```

```
    x = euler(t, x, lambda t, x: vx, dt)
```

```
    y = euler(t, y, lambda t, y: vy, dt)
```

```
    t += dt
```

```
plt.plot(x, y, label = 'No Air Resistance')
```

```
plt.plot(xa, ya, label = 'With Air Resistance')
```

```
plt.title("projectile with and without Air resistance")
```

```
plt.xlabel("x (m)")
```

```
plt.ylabel("y (m)")
```

```
plt.legend()
```

plt.grid()

plt.show()