

Homework 7

1. $G(s) = \frac{k}{s(s+1)(s+8)}$

for $k = 10$:

$$G(j\omega) = \frac{10}{j\omega(j\omega+1)(j\omega+8)} = \frac{10}{(j\omega-w^2)(j\omega+8)} = \frac{10}{-w^2 + 8j\omega - jw^3 - 8w^2}$$
$$= \frac{10}{-9w^2 + j(8w - w^3)}$$

@ ω_{pc} , $G(j\omega) = 0$

$$8w - w^3 = 0$$

$$w = \cancel{0}, 2\sqrt{2} \text{ rad/sec}$$

$$\omega_{pc} = 2\sqrt{2} = 2.8284 \text{ rad/sec}$$

Gain margin = $20 \log(\text{mag})$

$$\text{mag} = \frac{1}{|G(j\omega)|_{\omega=\omega_{pc}}} = \frac{1}{10} = 7.2$$

$$|G(j\omega)|_{\omega=\omega_{pc}} = \frac{1}{|-9(2\sqrt{2})^2|}$$

$$20 \log(7.2) = 17.1466 \text{ dB}$$

Cross-over frequency:

$$\frac{10}{\sqrt{(8w-w^3)^2 + (-9w^2)^2}} = 1$$

$$100 = (8w-w^3)^2 + (-9w^2)^2$$

$$100 = w^2(8-w^3)^2 + 81w^4$$

$$100 = w^2(64 - 16w^2 + w^4) + 81w^4$$

$$100 = 64w^2 - 16w^4 + w^6 + 81w^4$$

$$100 = w^6 + 65w^4 + 64w^2$$

$$w^6 + 65w^4 + 64w^2 - 100 = 0$$

$$w = 0.9158 \text{ rad/sec}$$

Phase margin:

$$\phi = |G(j\omega)|_{\omega=0.9158} = - \left[180 - \tan^{-1} \left(\frac{8w-w^3}{9w^2} \right) \right]$$

$$= - \left[180 - \tan^{-1} \left(\frac{8(0.9158) - (0.9158)^3}{9(0.9158)^2} \right) \right]$$

$$= -139.0139$$

$$180 - 139.0139 = 40.986^\circ$$

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1 Cont.

for $K = 1000$:

$$G(j\omega) = \frac{1000}{-9\omega^2 + j(8\omega - \omega^3)}$$

$$@ \omega_{pc} \quad G(j\omega) = 0$$

$$8\omega - \omega^3 = 0$$

$$\omega = 2\sqrt{2}$$

Gain margin:

$$\frac{1}{\left| \frac{1000}{-9\omega^2} \right|} = \frac{1}{\left| \frac{1000}{9(2\sqrt{2})^2} \right|} = 0.072$$

$$20 \log(0.072) = -22.8533 \text{ dB}$$

Cross-over frequency:

$$\frac{1000}{\sqrt{(8\omega - \omega^3)^2 + (-9\omega^2)^2}} = 1$$

$$10^6 = (8\omega - \omega^3)^2 + (81\omega^4)$$

$$10^6 = 64\omega^2 - 16\omega^4 + \omega^6 + 81\omega^4$$

$$10^6 = \omega^6 + 65\omega^4 + 64\omega^2$$

$$\omega = 9.06665 \text{ rad/sec}$$

Phase Margin:

$$PM = 180 + \phi$$

$$\phi = |G(j\omega)|_{\omega=9.06665} = - \left[180 + \tan^{-1} \left(\frac{8\omega - \omega^3}{-9\omega^2} \right) \right]$$

$$= - \left[180 + \tan^{-1} \left(\frac{\omega^2 - 8}{9\omega} \right) \right]$$

$$= - \left[180 + \tan^{-1} \left(\frac{9.06665^2 - 8}{9(9.06665)} \right) \right]$$

$$= - [180 + 42.28]$$

$$= -222.2822^\circ$$

$$PM = 180 - 222.2822 = -42.2822^\circ$$

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2. $G(s) = \frac{K}{s(s^2 + s + 4)}$

$$G(j\omega) = \frac{K}{j\omega(j\omega^2 + j\omega + 4)} = \frac{K/4}{j\omega\left(-\frac{\omega}{4} + \frac{j\omega}{4} + 1\right)} = \frac{K/4}{j\omega\left(\left(\frac{j\omega}{2}\right)^2 + \frac{j\omega}{4} + 1\right)}$$

$$\left[\begin{array}{l} \star s^2 + 2\zeta\omega_0 s + \omega_0^2 \\ \star \left(\frac{s}{\omega_0}\right)^2 + 2\zeta\left(\frac{s}{\omega_0}\right) + 1 \end{array} \right]$$

$$\omega_0 = 2 \quad 2 \cdot \zeta \cdot \omega_0 = \frac{1}{2} \cdot 2 \quad \zeta = \frac{1}{4}$$

$$\phi = -90^\circ - \tan^{-1} \left[\frac{2\zeta \frac{\omega}{\omega_0}}{1 - \left(\frac{\omega}{\omega_0}\right)^2} \right]$$

$$\phi = -90^\circ - \tan^{-1} \left[\frac{2 \cdot \frac{1}{4} \cdot \frac{\omega}{2}}{1 - \left(\frac{\omega}{2}\right)^2} \right]$$

$$PM = 180 + \phi \Rightarrow 50 = 180 + \phi \Rightarrow -130 = \phi$$

$$-130 = -90^\circ - \tan^{-1} \left[\frac{\frac{\omega}{4}}{1 - \frac{\omega^2}{4}} \right]$$

$$40^\circ = \tan^{-1} \left[\frac{\frac{\omega}{4}}{1 - \frac{\omega^2}{4}} \right]$$

$$\omega = \cancel{2.68276}, 1.49$$

Cross-over frequency:

$$|G(j\omega)|_{\omega=1.49} = \left| \frac{K}{j\omega(j\omega^2 + j\omega + 4)} \right| = \left| \frac{K}{1.49j((1.49j)^2 + 1.49j + 4)} \right|$$

$$= \left| \frac{K}{1.49j(-2.22 + 1.49j + 4)} \right|$$

$$= \left| \frac{K}{1.49j(1.77 + 1.49j)} \right|$$

$$1 = \frac{K}{1.49 \sqrt{1.77^2 + (1.49)^2}}$$

$$1.49^2(1.77^2) + 1.49^4 = K^2$$

$$K = 3.46$$

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2 Cont.

Gain margin:

gain cross-over frequency:

$$\phi = -90^\circ - \tan^{-1} \left(\frac{\omega_{pc}}{4 - \omega_{pc}^2} \right) = -180^\circ$$

$$\tan^{-1} \left(\frac{\omega_{pc}}{4 - \omega_{pc}^2} \right) = 90^\circ$$

$$4 - \omega_{pc}^2 = 0$$

$$4 = \omega_{pc}^2$$

$$\omega_{pc} = 2$$

$$K_g = \frac{1}{|G(j\omega_{pc})|}$$

$$= \frac{1}{\left| \frac{3.46}{j\omega((j\omega)^2 + j\omega + 4)} \right|_{\omega=2}}$$

$$= \frac{1}{\left| \frac{3.46}{2j((2j)^2 + j2 + 4)} \right|}$$

$$= \frac{|4|^2}{3.46}$$

$$= 1.156$$

$$20 \log(1.156) = \boxed{1.26 \text{ dB}}$$

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$$3. \quad G(s) = K \left(\frac{s+1}{s+5} \right) \left(\frac{10}{s(s+1)} \right) = \frac{10K(s+1)}{s(s+5)(s+1)} = \frac{2K(1+10s)}{s(s+1)(2s+1)}$$

$$G(j\omega) = \frac{2K(10j\omega+1)}{j\omega(j\omega+1)(2j\omega+1)}$$

magnitude:

$$|G(j\omega)| = \frac{2 \sqrt{(10\omega)^2 + 1}}{\omega \sqrt{\omega^2 + 1} (\sqrt{4\omega^2 + 1})}$$

$$\text{gain} = 20 \log(2) + 20 \log(\sqrt{100\omega^2 + 1}) - 20 \log(\omega) - 20 \log(\sqrt{\omega^2 + 1}) - 20 \log(\sqrt{4\omega^2 + 1})$$

$$\angle G(j\omega) = \angle (10j\omega+1) - 90^\circ - \angle (j\omega+1) - \angle (2j\omega+1)$$

$$\phi = \tan^{-1}(10\omega) - 90^\circ - \tan^{-1}(\omega) - \tan^{-1}(2\omega) = -130$$

$$PM = 180^\circ + \phi = 50^\circ \Rightarrow \phi = -130$$

$$\omega = 1.44 \text{ rad/sec}$$

magnitude @ $\omega = 1.44$:

$$\begin{aligned} \text{gain} &= 20 \log(2) + 20 \log(\sqrt{100(1.44)^2 + 1}) - 20 \log(1.44) - 20 \log(\sqrt{1.44^2 + 1}) - 20 \log(\sqrt{4(1.44)^2 + 1}) \\ &= 11.5 \text{ dB} \end{aligned}$$

$$20 \log(K) = -11.5 \text{ dB}$$

$$K = 0.2666$$

or

$$\left| \frac{2K(10j(1.44)+1)}{j(1.44)(1.44j+1)(2(1.44)j+1)} \right| = 1$$

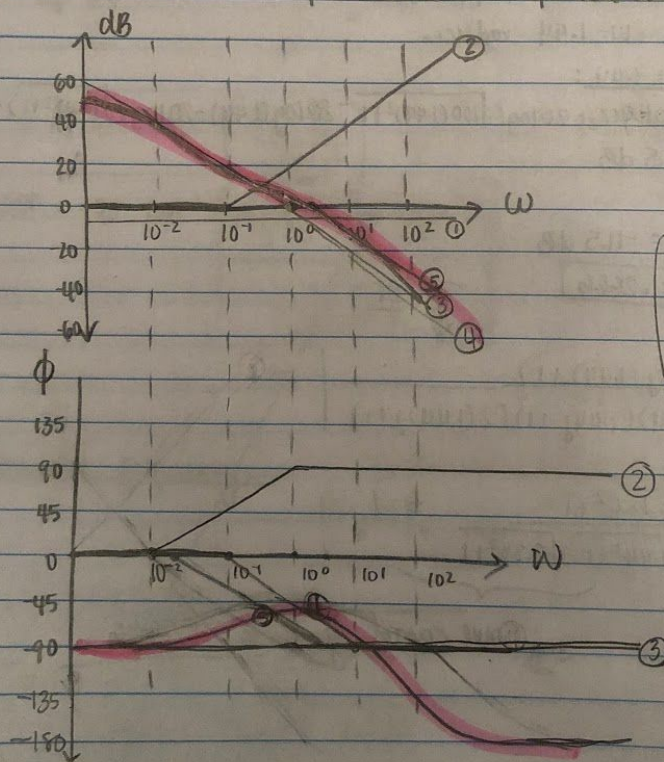
$$\frac{2K \sqrt{14.4^2 + 1}}{1.44 \sqrt{1.44^2 + 1} \sqrt{2.88^2 + 1}} = 1$$

Solve and get $K = 0.2666$

3 cont.

$$G(s) = \frac{2(.2666)(1+10s)}{s(1+s)(1+2s)} = \frac{.532(1+10s)}{s(1+s)(1+2s)} = \frac{.532(\frac{s}{.1} + 1)}{s(s+1)(\frac{s}{.5} + 1)}$$

factor	gain	phase
① .532	$20 \log(.532)$ $= -5.482$	0
② $w_0 = .1$	0 until .1 (10^{-1}) then 20	$-1(.1) = .01 \rightarrow +90^\circ = 1 \times 10^{-2}$ $10(.1) = 1 \quad 1 \times 10^0$
③ $\frac{1}{s}$	-20, go thru 0 @ $w=1 \quad 10^0$	-90°
④ $w_0 = 1$	0 until 1 then -20	$-1(1) = -.1 \rightarrow -90^\circ = 10^{-1}$ $10(1) = 10 \quad 10^1$
⑤ $w_0 = .5$	0 until .5 then -20	$-1(.5) = .05 \rightarrow -90^\circ$ $10(.5) = 5$



Since the values for all the frequencies are greater than 180°, the gain margin is $\boxed{+\infty}$

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4. (Bonus)

$$\text{OLTF: } G(s) = \frac{1}{s(s+1)}$$

$$\text{PM} = 180^\circ + \angle G(j\omega)H(j\omega)|_{\omega = \omega_{gc}}$$

$$60^\circ = 180^\circ + \underbrace{\angle G(j\omega)}_{\phi_c} \cdot G_c(j\omega)H(j\omega)|_{\omega = \omega_{gc}}$$

$$\phi_c = -120^\circ$$

TF of lead compensator:

$$G_c(s) = \frac{1+Ts}{1+\alpha Ts}$$

$$\text{Phase of } G(s) = \frac{1}{s(1+s)}$$

$$\begin{aligned} \angle G(j\omega) &= \angle \frac{1}{j\omega(1+j\omega)}|_{\omega = \omega_{gc}} \\ &= -90^\circ - \tan^{-1}(\omega_{gc}) \end{aligned}$$

$$\text{where } \omega_{gc} = 10 \text{ rad/sec}$$

$$= -90^\circ - \tan^{-1}(10) = -174.28^\circ$$

Desired phase of compensator:

$$\angle G(j\omega) + \angle G_c(j\omega) = -120^\circ$$

$$\angle G_c(j\omega) = -120^\circ + 174.28^\circ$$

$$\angle G_c(j\omega) = 54.28^\circ$$

$$\angle G_c(j\omega) = \angle \frac{1+j\omega_{gc}T}{1+j\omega_{gc}\alpha T} = 54.28^\circ$$

$$\begin{aligned} \tan \left[\tan^{-1}(\omega_{gc}T) - \tan^{-1}(\omega_{gc}\alpha T) \right] &= [54.28^\circ] \tan \\ &= \frac{\omega_{gc}T - \omega_{gc}\alpha T}{1 + \omega_{gc}T \cdot \omega_{gc}\alpha T} \end{aligned}$$

$$= \frac{\omega_{gc}T - \omega_{gc}\alpha T}{1 + \omega_{gc}^2 T^2 \alpha} = 1.39$$

$$\frac{10T - 10\alpha T}{1 + 100T^2 \alpha} = 1.39 \quad \text{Let } \alpha = 0.1$$

$$9T = 1.4$$

$$1 + 10T^2$$

$$9T = 1.39 + 13.9T^2$$

$$13.9T^2 - 9T + 1.39 = 0 \Rightarrow T = 0.254 \text{ or } 0.393$$

$$G_c(s) = \frac{1+0.254s}{1+0.0254s}$$

$$\text{where } T = 0.254$$

$$\alpha = 0.1$$