

- **a)** Find the differential equation(s) that model this system.
- **b)** Identify state variables, and represent your model in the state-space form.

$$M_{1}\dot{y}_{1} = u_{1} - k_{2}(y_{1} - 0) 
 - k_{3}(y_{1} - y_{2}) 
 - c_{3}(y_{1} - y_{2}) - c_{2}(y_{1} - y_{2})$$

Mass 2:  

$$m_2 \dot{y}_2^2 = -u_2 - k_1 (y_2 - 0) - k_3 (y_2 - y_1) - c_3 (\dot{y}_2 - \dot{y}_1) - c_1 (\dot{y}_2)$$

$$M_{1}\dot{y}_{1} = u_{1} - k_{2}\dot{y}_{1} - k_{3}\dot{y}_{1} + k_{3}\dot{y}_{2} - c_{3}\dot{y}_{1} + c_{3}\dot{y}_{2} - c_{2}\dot{y}_{1}$$

$$M_{1}\dot{y}_{1} = u_{1} - (k_{2} + k_{3})\dot{y}_{1} + k_{3}\dot{y}_{2} - (c_{2} + c_{3})\dot{y}_{1} + c_{3}\dot{y}_{2}$$

$$M_{2}\dot{y}_{1} = u_{1} - (k_{2} + k_{3})\dot{y}_{1} + k_{3}\dot{y}_{2} - (c_{2} + c_{3})\dot{y}_{1} + c_{3}\dot{y}_{2}$$

control inputs: 4,192 =  $\frac{1}{x_{1}} = y_{1} \leftarrow \begin{vmatrix} \dot{x}_{1} \\ \dot{x}_{2} \\ \dot{x}_{1} = y_{1} \leftarrow \begin{vmatrix} \dot{x}_{1} \\ \dot{x}_{2} \\ \dot{x}_{1} \end{vmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -k_{1}-k_{1} & -k_{1}-k_{1} & k_{2} \\ m_{1} & m_{1} & m_{1} & m_{1} \\ 0 & 0 & 0 & 1 \\ k_{1} & m_{2} & m_{2} & m_{2} \end{bmatrix} \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} = y_{2} & x_{1} \\ x_{1} & x_{2} & x_{3} \\ x_{2} & x_{3} & x_{4} \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1/m_{1} & 0 \\ 0 & 0 \\ 0 & -1 \\ m_{2} & m_{2} & m_{2} \end{bmatrix}$ State varables Derivatives at state Vantaslas  $\begin{cases}
\dot{x}_{1} = \dot{y}_{1} = \chi_{2} \\
\dot{x}_{2} = \dot{y}_{1} = \frac{1}{m_{1}} \left[ 1.u_{1} - (k_{2} + k_{3})\dot{y}_{1} + k_{3}\dot{y}_{2} - (c_{2} + c_{3})\dot{y}_{1} + c_{3}\dot{y}_{2} \right] \\
- \dot{x}_{3} = \dot{y}_{2} = \chi_{4} - \chi_{3} \\
\dot{x}_{4} = \dot{y}_{2} = \frac{1}{m_{2}} \left[ (-1) u_{2} - (k_{1} + k_{3}) u_{2} + k_{3} u_{1} - (c_{1} + c_{3}) u_{2} + c_{3}\dot{y}_{1} \right]$ 

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \\ \chi_4 \end{pmatrix} \quad \text{output} \quad \text{eqn.}$$

Please find the differential equation(s) that model the electrical system shown.

KCL QA:

$$\frac{Vin^{-0}}{R_1} = \frac{0 - Vout}{R_2} + c \frac{d(o - Vout)}{dt}$$

