

# What is Feedback Control?

Control: Process of causing a system (output) variable to conform to some desired value

reference

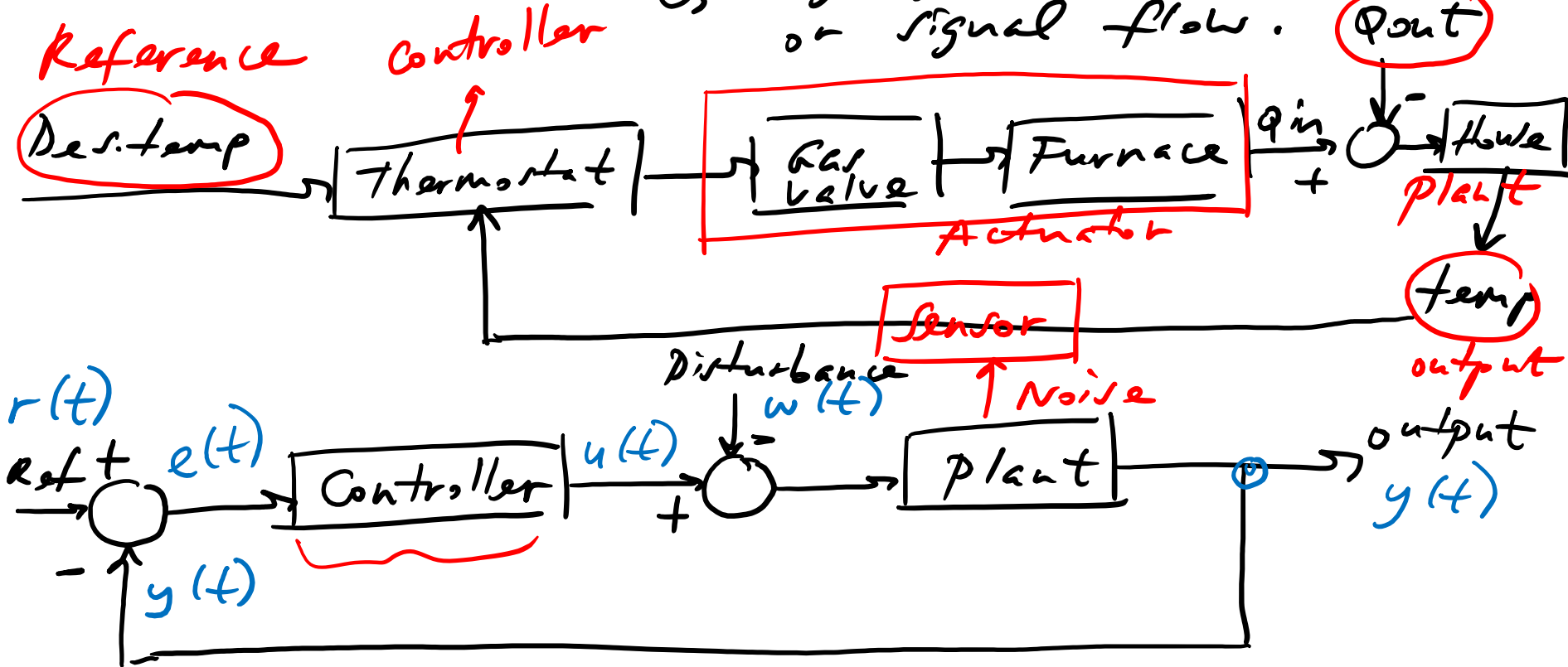
ef.  
temperature

Feedback: measuring the output and using that info. to adjust the input (control variable) to influence the value of that output.

\* Feedback is not necessary for control!  
Necessary to deal w/ uncertainty.

Represent a feedback control system using a block diagram

- ↳ identifies major components
- ↳ highlights the info/energy or signal flow.

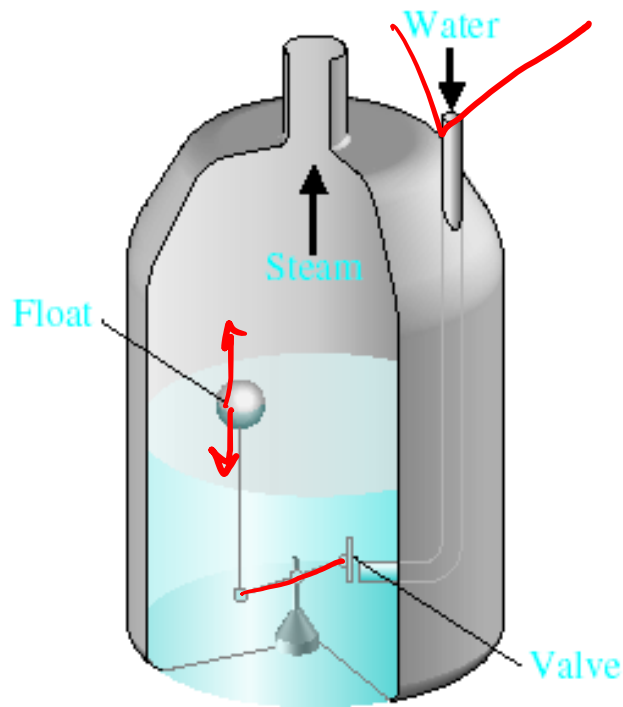


> General Feedback Control System <

## Control system objectives

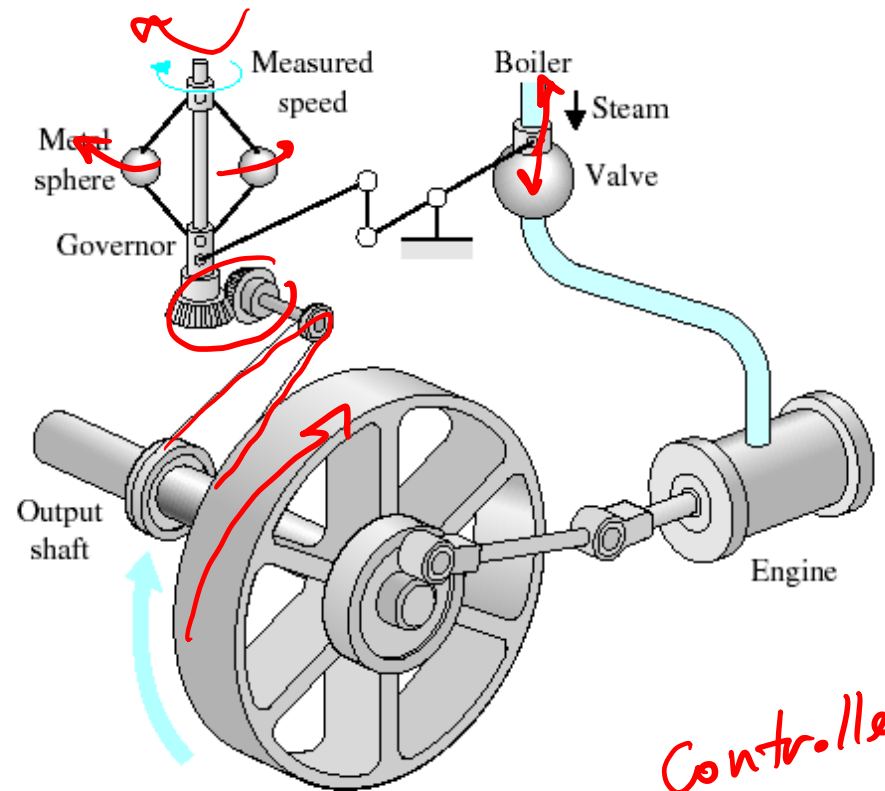
- 1) Reject disturbance (minimize the plant response to disturbance)
- 2) Acceptable long-term performance (steady-state response)
- 3) Acceptable short-term performance (transient response)
- 4) Minimize sensitivity to plant parameter variations (robustness)

# EXAMPLES



*FLAMES*

Water-level float regulator (BC)



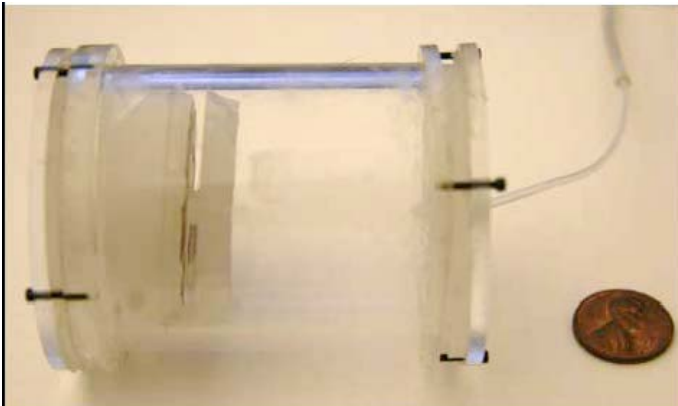
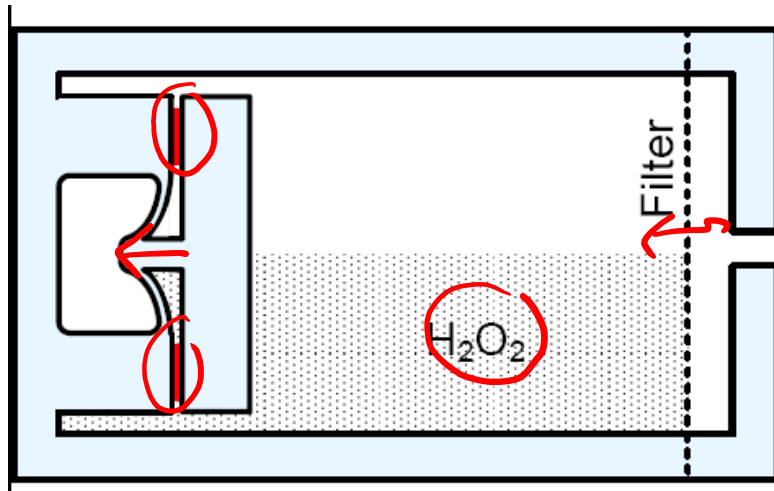
Watt's Flyball Governor  
(18<sup>th</sup> century)

*Controller*

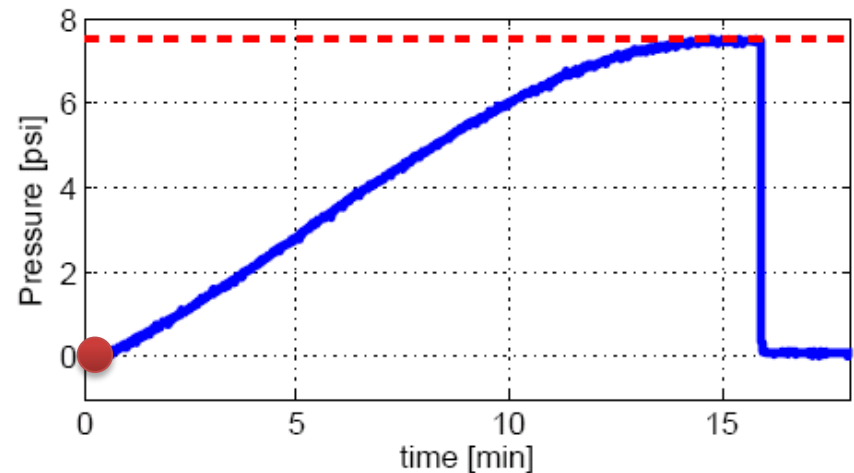
# Portable Pneumatic Battery

[ISRR 2011]

Self-regulating chemical pressure generator



Experimental data of pressure self-regulation



- $2\text{H}_2\text{O}_2 \xrightarrow{\text{Catalyst}} 2\text{H}_2\text{O} + \text{O}_2$
- 10%  $\text{H}_2\text{O}_2$  solution in water

# Portable Pneumatic Battery

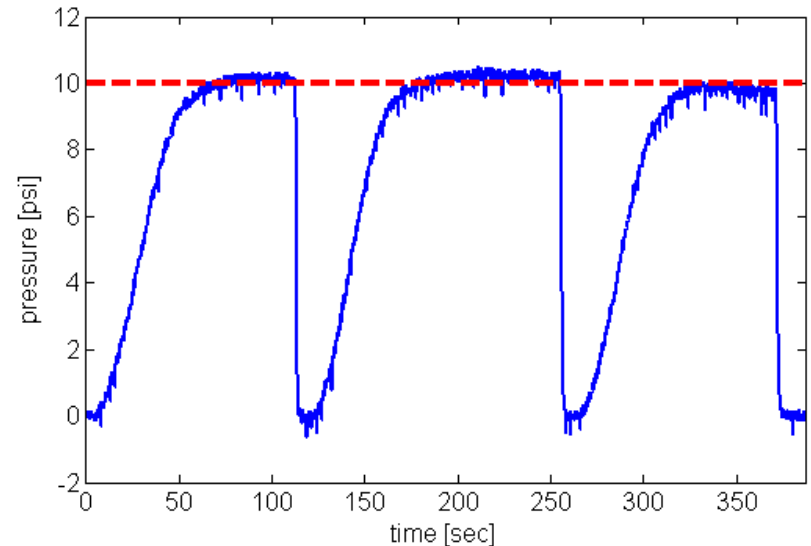
[ISRR 2011]

- Deflector membrane deforms and covers catalyst for self regulation:

$$w(r) = \frac{\Delta P r_m^4}{64K} \left( 1 - \left( \frac{r}{r_m} \right)^2 \right)^2$$

- Air chamber internal pressure must satisfy:

$$\frac{r_m^4}{192K} P_{in}^2 + \left( h - \frac{P_c r_m^4}{192K} \right) P_{in} - h P_o = 0$$



- 50% H<sub>2</sub>O<sub>2</sub> solution in water
- 10 psi cut-off pressure ( $P_c$ )

## Methodology

0. Choose sensors and actuators

1. Develop models

2. Design controller  $\rightarrow$  based on models  
design criteria

3. Evaluate design (simulations, experiments)

4. Iterate!

