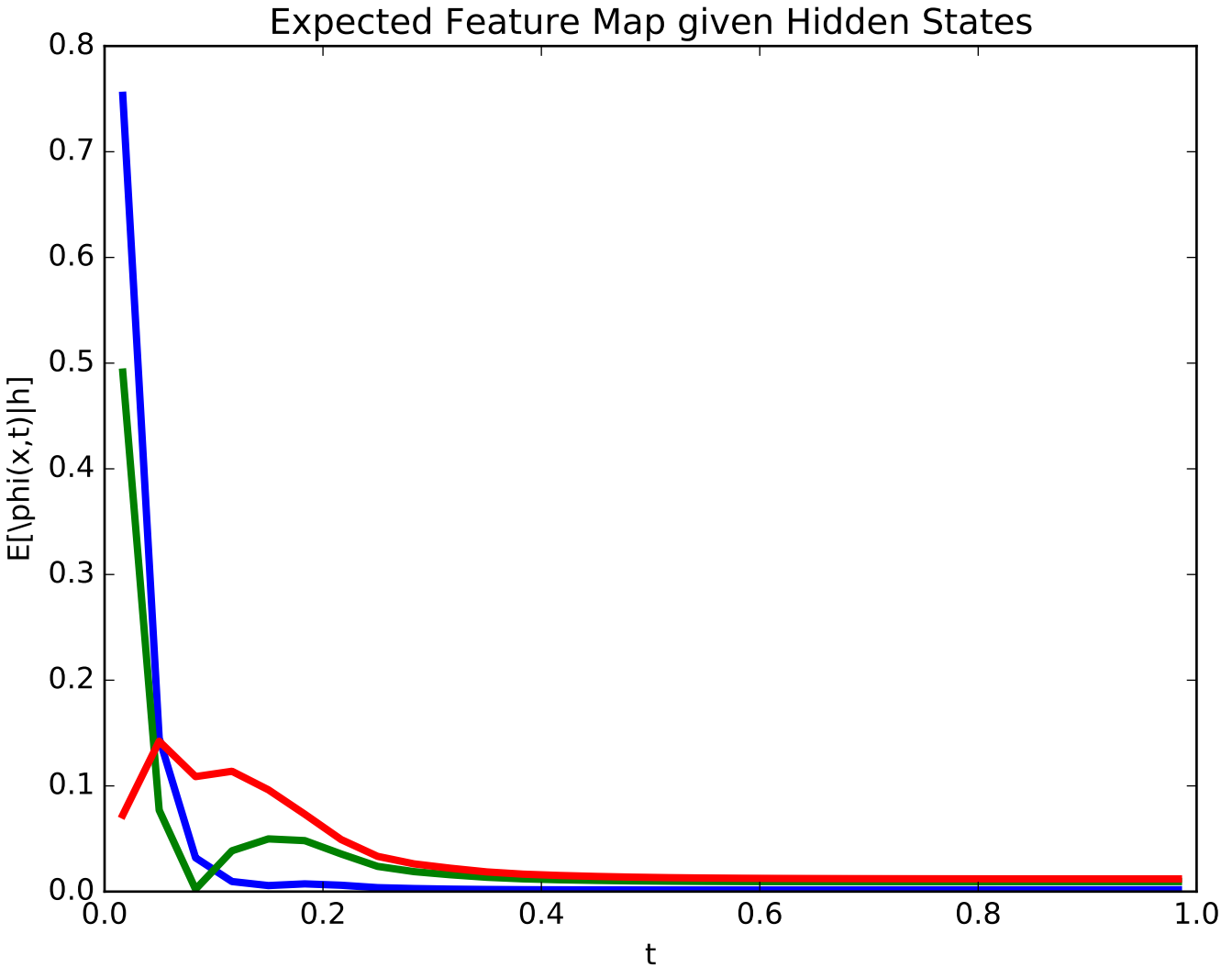
Expected Feature Map given Hidden States
E[\phi(x,t)|h]
t
0.0
0.1
0.2
0.3
0.4
0.5
0.6
0.7
0.8
0.0
0.2
0.4
0.6
0.8
1.0