

November 12, 2019

Review Find bases for the fundamental subspaces of a matrix $A^{m \times n}$:

$$[A | I_m] \xrightarrow{G-J} E[A | I_m] = [U | E] = \left[\begin{array}{c|cc} U & E_1 \\ \hline O & E_2 \end{array} \right]_{m \times k}$$

The row vectors of U form a basis for $\text{row}(A)$.

The column vectors of U " " " " " $\text{col}(A)$.

A basis for $\text{null}(U)$ can be a basis for $\text{null}(A)$.

The row vectors of E_2 form a basis for $\text{null}(A^T)$.

Thm 7.6.4 (CR factorization)

$A = CR$, $m \times n$ matrix whose column vectors are the first columns of A
 $R : k \times n$ " " " " " row " " " " " nonzero vectors
 in the reduced row echelon form.

p.f) Let $R_0 = EA$, reduced row echelon form of A .

$$\text{Since } \text{rank}(A) = k, \quad R_0 = \left[\begin{array}{c|cc} R \\ \hline O \end{array} \right]_{m \times k}$$

Partition E^{-1} as $\left[\begin{smallmatrix} C & | & D \\ \hline k & m-k \end{smallmatrix} \right]$. Then

$$A = E^{-1}R_0 = [C | D] \left[\begin{array}{c|cc} R \\ \hline O \end{array} \right] = CR + DO = CR.$$

ETS: The columns of C are the pivot columns of A .

Note $c_j(R) = e_j$ in \mathbb{R}^k , $1 \leq j \leq k$. Then

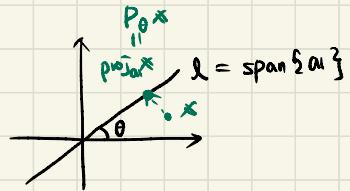
$$c_j(C) = C e_j = C c_j(R) = c_j(CR) = c_j(A) \quad \blacksquare$$

Hence $A = CR = \left[\begin{array}{c|c|c|c} c_1 & \cdots & c_k & | \\ \hline r_1 & \cdots & r_k & | \\ \hline r_1 & \cdots & r_k & | \\ \hline r_1 & \cdots & r_k & | \end{array} \right] \left[\begin{array}{c} -1r_1 \\ -1r_2 \\ \vdots \\ -1r_k \end{array} \right] = c_1 r_1 + c_2 r_2 + \cdots + c_k r_k$

$$\begin{aligned} R = \left[\begin{array}{c|c|c|c} r_{11} & \cdots & r_{1n} & | \\ \hline r_{21} & \cdots & r_{2n} & | \\ \hline \vdots & \cdots & \vdots & | \\ \hline r_{k1} & \cdots & r_{kn} & | \end{array} \right]_{k \times n} \Rightarrow CR &= \left[r_{11} c_1 + \cdots + r_{1n} c_k \quad | \quad r_{21} c_1 + \cdots + r_{2n} c_k \quad | \quad \cdots \quad | \quad r_{n1} c_1 + \cdots + r_{nn} c_k \right] \\ &= c_1 [r_{11} \cdots r_{1n}] + c_2 [r_{21} \cdots r_{2n}] + \cdots + c_k [r_{n1} \cdots r_{nn}] \end{aligned}$$

§ 7.7. Projection theorem

Recall that $P_\theta = \begin{bmatrix} \cos^2\theta & \sin\theta \cos\theta \\ \sin\theta \cos\theta & \sin^2\theta \end{bmatrix}$



Let $\alpha \in \mathbb{R}^n - \{\mathbf{0}\}$.

The orthogonal projection of x onto the line $\text{span}\{\alpha\}$ is

$$\text{proj}_{\alpha^\perp} x = \frac{x \cdot \alpha}{\|\alpha\|^2} \alpha$$

\therefore Since $\text{proj}_{\alpha^\perp} x = k\alpha$ for some $k \in \mathbb{R}$, we need to find k .

Since $x - \text{proj}_{\alpha^\perp} x$ is orthogonal to α ,

$$(x - k\alpha) \cdot \alpha = 0$$

$$\therefore k = \frac{x \cdot \alpha}{\alpha \cdot \alpha}$$

Using the above formula, we can recover the matrix P_θ as follows:

Let $u_1 := (\cos\theta, \sin\theta)$. i.e., u_1 is a unit vector spanning the straight line l . Then

$$\begin{bmatrix} \text{proj}_{u_1^\perp} e_1 & \text{proj}_{u_1^\perp} e_2 \\ | & | \end{bmatrix} = \begin{bmatrix} | & | \\ \cos\theta u_1 & \sin\theta u_1 \\ | & | \end{bmatrix} = \begin{bmatrix} \cos^2\theta & \cos\theta \sin\theta \\ \cos\theta \sin\theta & \sin^2\theta \end{bmatrix}$$

Theorem 7.7.1

Given $\alpha \in \mathbb{R}^n - \{\mathbf{0}\}$, every $x \in \mathbb{R}^n$ can be expressed in exactly one way as $x = x_1 + x_2$, where $x_1 \in \text{span}\{\alpha\}$ and $x_2 \in \alpha^\perp$. Moreover,

$$x_1 = \frac{x \cdot \alpha}{\|\alpha\|^2} \alpha \quad \& \quad x_2 = x - x_1 = x - \frac{x \cdot \alpha}{\|\alpha\|^2} \alpha.$$

pf) ① Existence : Clearly, $x_1 \in \text{span}\{\alpha\}$ and

$$x_2 \cdot \alpha = x \cdot \alpha - x_1 \cdot \alpha = x \cdot \alpha - \frac{x \cdot \alpha}{\|\alpha\|^2} \alpha \cancel{\cdot \alpha} = 0$$

$$\therefore x_2 \in \alpha^\perp.$$

② Uniqueness : Suppose that x can also be written as

$$x = x_1' + x_2',$$

where $x_1' \in \text{span}\{\alpha\}$ & $x_2' \in \alpha^\perp$.

Then $x = x_1 + x_2 = x_1' + x_2'$

$$\Rightarrow x - x_1' = x_2' - x_2 \in \text{span}\{\alpha\} \cap \alpha^\perp = \{0\}.$$

$$\therefore x_1 = x_1' \quad \& \quad x_2' = x_2.$$

□

Def. Given $\alpha \in \mathbb{R}^n - \{0\}$, for every $x \in \mathbb{R}^n$,

the orthogonal projection of x onto $\text{span}\{\alpha\}$ is denoted by

$\text{proj}_\alpha x$ and is defined by $\text{proj}_\alpha x = \frac{x \cdot \alpha}{\|\alpha\|^2} \alpha$.

We call $\text{proj}_\alpha x$ the vector component of x along α , and

$x - \text{proj}_\alpha x$ the vector component of x orthogonal to α .

Note that the length of $\text{proj}_\alpha x$ is $\frac{|x \cdot \alpha|}{\|\alpha\|}$.

Define $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ by $T(x) = \text{proj}_\alpha x$. Then T is called the orthogonal projection of \mathbb{R}^n onto $\text{span}\{\alpha\}$.

Thm 7.7.3 For a nonzero column vector α in \mathbb{R}^n , the standard matrix for the orthogonal projection T of \mathbb{R}^n onto $\text{span}\{\alpha\}$ is

$$P = \frac{1}{\alpha^\top \alpha} \alpha \alpha^\top.$$

The matrix P is symmetric and has rank 1.

pf) Let $a_1 = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \in \mathbb{R}^n - \{\mathbf{0}\}$. Then $T(e_j) = \frac{e_j \cdot a_1}{a_1 \cdot a_1} a_1 = \frac{a_j}{a_1^T a_1} a_1$.

$$\text{Hence } [T] = \begin{bmatrix} T(e_1) & \cdots & T(e_n) \end{bmatrix} = \begin{bmatrix} a_1 & \frac{a_2}{a_1^T a_1} a_1 & \cdots & \frac{a_n}{a_1^T a_1} a_1 \end{bmatrix}$$

$$= \frac{a_1}{a_1^T a_1} [a_1 \ a_2 \ \cdots \ a_n] = \frac{1}{a_1^T a_1} a_1 a_1^T$$

Since $a_1 a_1^T$ is symmetric and has rank 1,

P is also symmetric and has rank 1. \square

If we take $u_1 := \frac{a_1}{\|a_1\|}$ in the previous theorem, then $P = u_1 u_1^T$.

Thm 7.7.4 (Projection theorem for subspaces)

Let W be a subspace of \mathbb{R}^n . Then every $x \in \mathbb{R}^n$ can be expressed in exactly one way as $x = x_1 + x_2$, where $x_1 \in W$ and $x_2 \in W^\perp$.

* In the above theorem, x_1 is denoted by $\text{proj}_W x$ and it is called the orthogonal projection of x on W , and x_2 is denoted by $\text{proj}_{W^\perp} x$ and it is called the orthogonal projection of x on W^\perp .

proof) ① If $W = \{\mathbf{0}\}$, then $W^\perp = \mathbb{R}^n$. : $\forall x \in \mathbb{R}^n$, $x = \mathbf{0} + x$. ok.

② Now assume $W \neq \{\mathbf{0}\}$. Then there is a basis for W .

Let $\{w_1, \dots, w_k\}$ be a basis for W and form a matrix $M = [w_1 \ \cdots \ w_k]$. Then $W = \text{col}(M)$ & $W^\perp = \text{null}(M^T)$.

Note that $\left\{ \begin{array}{l} \bullet \ x_1 \in W \iff x_1 = Mw \text{ for some } w \in \mathbb{R}^k \\ \bullet \ x_2 \in W^\perp \iff M^T x_2 = \mathbf{0} \end{array} \right.$

$\left\{ \begin{array}{l} \bullet \ \text{Uniqueness} \iff M^T(x - Mw) = \mathbf{0} \text{ has a unique sol. for each } x \in \mathbb{R}^k. \end{array} \right.$

Since M has full column rank, $M^T M$ is invertible.

$$\therefore M^T(x - Mw) = \mathbb{0} \iff w = (M^T M)^{-1} M^T x.$$

Hence $x = \underbrace{Mw}_{\in W} + \underbrace{(x - Mw)}_{\in W^\perp}$, where $w = (M^T M)^{-1} M^T x$.

Thm 7.7.5

Let W be a subspace of \mathbb{R}^n .

Let M be any matrix whose column vectors form a basis for W .

Then $\text{proj}_W x = M(M^T M)^{-1} M x$.

Hence the standard matrix for a linear operator $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ given by $T(x) = \text{proj}_W x$ is $P = M(M^T M)^{-1} M$. Moreover, $I-P$ is the standard matrix for the linear operator $U: \mathbb{R}^n \rightarrow \mathbb{R}^n$ given by $U(x) = \text{proj}_{W^\perp} x$.

* M is not unique, but we get the same matrix P .

If the column vectors of M form an orthonormal basis for W , then $P = M M^T$.

November 14, 2019

Projection theorem for subspaces

W : a subspace for \mathbb{R}^n

$$\Rightarrow \forall \mathbf{x} \in \mathbb{R}^n, \quad \mathbf{x} = \mathbf{x}_1 + \mathbf{x}_2$$

\uparrow \uparrow
 W W^\perp

From the above theorem, we can find two projections

$$\text{proj}_W: \mathbb{R}^n \rightarrow W \subseteq \mathbb{R}^n \quad \text{and} \quad \text{proj}_{W^\perp}: \mathbb{R}^n \rightarrow W^\perp \subseteq \mathbb{R}^n$$

so that $\mathbf{x} = \text{proj}_W \mathbf{x} + \text{proj}_{W^\perp} \mathbf{x}$.

For a nonzero subspace W of \mathbb{R}^n ,

if M is a matrix whose columns form a basis for W ,

then $\text{proj}_W \mathbf{x} = M(M^T M)^{-1} M^T \mathbf{x}$.

If M is a matrix whose columns form an orthonormal basis for W ,

then $M^T M = I_n$, and hence $\text{proj}_W \mathbf{x} = M M^T \mathbf{x}$.

Theorem 2.7.6 Let P be an $n \times n$ matrix.

P is the standard matrix for an orthogonal projection of \mathbb{R}^n onto a k -dim'l subspace W of \mathbb{R}^n .

$\Leftrightarrow P$ is symmetric, idempotent, and has rank k .

The subspace W is $\text{col}(P)$

Proof) (\Rightarrow) $P = M(M^T M)^{-1} M^T, \quad P^T = (M^T)^T ((M^T M)^{-1})^T M^T = M ((M^T M)^{-1})^T M^T$

Since $(M^T M)(M^T M)^{-1} = I_n, \quad ((M^T M)^{-1})^T \underbrace{(M^T M)^T}_{M^T M} = I_n$.

$\therefore ((M^T M)^{-1})^T = (M^T M)^{-1}$

$M(M^T M)^{-1} M^T$
" P

$$P^2 = M(M^T M)^{-1} M^T M (M^T M)^{-1} M^T = M(M^T M)^{-1} M^T = P$$

Since $\dim W = k$ and $\text{ran}(T) = \text{col}(P)$ has rank k . $\therefore \text{rank}(P) = k$.

(\Rightarrow) Let $W = \text{col}(P)$.

$$\forall \mathbf{x} \in \mathbb{R}^n, \mathbf{x} = P\mathbf{x} + (I-P)\mathbf{x}$$

Note $P\mathbf{x} \in \text{col}(P)$ & $(I-P)\mathbf{x} \in \text{null}(P)$

$$(\because P(I-P)\mathbf{x} = P\mathbf{x} - P^2\mathbf{x} = P\mathbf{x} - P\mathbf{x} = \mathbf{0})$$

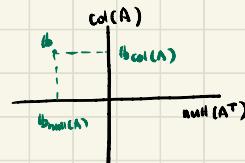
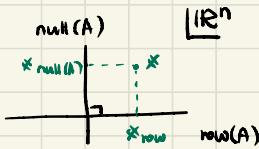
$$\text{Since } P = P^T, \text{ null}(P) = \text{null}(P^T) = W^\perp.$$

◻

* Strong diagram

$A: m \times n$ matrix

$$\Rightarrow \begin{cases} \forall \mathbf{x} \in \mathbb{R}^n, \mathbf{x} = \mathbf{x}_{\text{row}(A)} + \mathbf{x}_{\text{null}(A)} \\ \forall \mathbf{b} \in \mathbb{R}^m, \mathbf{b} = \mathbf{b}_{\text{col}(A)} + \mathbf{b}_{\text{null}(A^T)} \end{cases}$$



$$\therefore A\mathbf{x} = \mathbf{b} \text{ is consistent} \Leftrightarrow \mathbf{b}_{\text{null}(A^T)} = \mathbf{0}.$$

Thm 7.7.2

$A: m \times n$ matrix & $\mathbf{b} \in \text{col}(A)$ ($\rightsquigarrow A\mathbf{x} = \mathbf{b}$ is consistent)

(a) If A has full column rank, then $A\mathbf{x} = \mathbf{b}$ has a unique solution and that sol. is in $\text{row}(A)$.

(b) If A does not have full column rank, then $A\mathbf{x} = \mathbf{b}$ has infinitely many sol. but there is a unique sol. in $\text{row}(A)$. Moreover, among all the solutions of the system, the sol. in $\text{row}(A)$ has the smallest norm.

(f) Let $\mathbf{x} = \mathbf{x}_{\text{row}(A)} + \mathbf{x}_{\text{null}(A)}$. Then $A\mathbf{x} = A\mathbf{x}_{\text{row}(A)} + A\mathbf{x}_{\text{null}(A)}$.

(a) If A has full column rank, then $A\mathbf{x} = \mathbf{b}$ has a unique sol. $\& \text{null}(A) = \{\mathbf{0}\}$. ($\because \text{rank}(A) = n \& \text{nullity}(A) = 0$)

$\therefore \mathbf{x} = \mathbf{x}_{\text{row}(A)}$ is unique.

(b) If A does not have full col. rank, then $A\mathbf{x} = \mathbf{b}$ has infinitely many sol.

(i) $A\mathbf{x} = \mathbf{b}$ has a unique sol. in $\text{row}(A)$.

$\left(\begin{array}{l} \text{Suppose } \mathbf{x}_1, \mathbf{x}_2 \in \text{row}(A) \text{ are sol. of } A\mathbf{x} = \mathbf{b}. \\ \text{Then } \mathbf{x}_1 - \mathbf{x}_2 \in \text{row}(A) \cap \text{null}(A) = \{\mathbf{0}\} \\ \therefore \mathbf{x}_1 = \mathbf{x}_2 \end{array} \right)$

(ii) Among all the sol's of the system, \mathbf{x}_1 has the smallest norm.

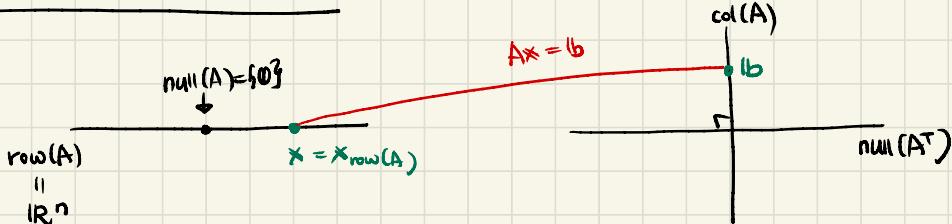
$\because \mathbf{x}$ is a sol. of $A\mathbf{x} = \mathbf{b}$, then $\mathbf{x} = \mathbf{x}_1 + (\mathbf{x} - \mathbf{x}_1)$

By Pythagoras

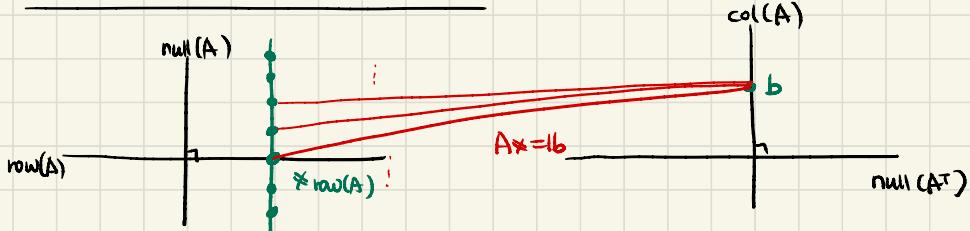
$$\|\mathbf{x}\| \geq \sqrt{\|\mathbf{x}_1\|^2 + \|\mathbf{x} - \mathbf{x}_1\|^2} \geq \|\mathbf{x}_1\|.$$

$\therefore \mathbf{x}_1$ has the smallest norm among solutions. \square

A has full col. rank



A does not have full col. rank



The solution set of $A\mathbf{x} = \mathbf{b}$ is parallel to $\text{null}(A)$.

Thm 7.7.8 (Double perp thm)

For every subspace W of \mathbb{R}^n , $(W^\perp)^\perp = W$.

Pf) $\text{① } W \subseteq (W^\perp)^\perp$ (clear!) $\text{② } W = (W^\perp)^\perp$. $\forall \mathbf{w} \in (W^\perp)^\perp \subseteq \mathbb{R}^n$, $\mathbf{w} = \mathbf{w}_1 + \mathbf{w}_2$

Claim $\mathbf{w}_2 = \mathbf{0}$. Since $\mathbf{w} \in (W^\perp)^\perp$ & $\mathbf{w}_2 \in W^\perp$, $\mathbf{w} \cdot \mathbf{w}_2 = 0$.

$$\begin{aligned} \mathbf{w}_1 \cdot \mathbf{w}_2 + \mathbf{w}_2 \cdot \mathbf{w}_2 &= 0 \\ \mathbf{w}_2 \cdot \mathbf{w}_2 &= 0 \\ \|\mathbf{w}_2\|^2 &= 0 \\ \therefore \|\mathbf{w}_2\| &= 0 \end{aligned}$$

$$\therefore \|\mathbf{w}_2\|^2 = 0 \Rightarrow \mathbf{w}_2 = \mathbf{0}.$$

\square

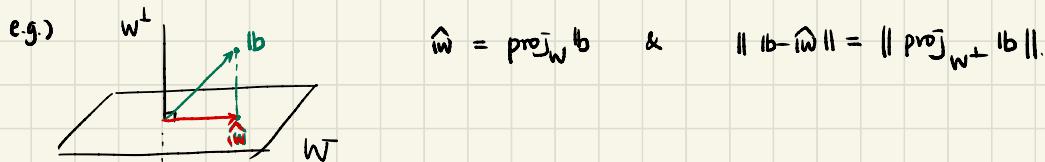
§ 7.8. Best approximation & Least squares.

The minimum distance problem in \mathbb{R}^n

Given a subspace W of \mathbb{R}^n and $lb \in \mathbb{R}^n$,

find a vector \hat{w} in W that is closest to lb in the sense that $\|lb - \hat{w}\| \geq \|lb - w\| \quad \forall w \in W - \{\hat{w}\}$.

Such a vector \hat{w} , if it exists, is called a best approximation to lb from W .



Thm 7.8.1 (Best approximation theorem)

If W is a subspace of \mathbb{R}^n and lb is a point in \mathbb{R}^n , then there is a unique best approximation to lb from W , namely $\hat{w} = \text{proj}_W lb$.

pf) $\forall w \in W, \quad lb - lw = \underbrace{(lb - \text{proj}_W lb)}_{\text{proj}_W^\perp lb \in W^\perp} + \underbrace{(\text{proj}_W lb - lw)}_w$

$$\Rightarrow \|lb - lw\| = \sqrt{\|\text{proj}_W lb\|^2 + \|\text{proj}_W^\perp lb - lw\|^2}.$$

If $lb \neq \text{proj}_W lb$, then $\|lb - lw\| > \|lb - \text{proj}_W lb\|$. ⊗

$\therefore \text{proj}_W lb$ is a best approximation to lb from W .

(Uniqueness) \hat{w}

By ⊗, any $w (\neq \text{proj}_W lb)$ in W , $\|lb - lw\| > \|lb - \hat{w}\|$

\therefore Such a vector w is not a best approximation to lb from W .

Def. The distance from a point \mathbf{b} to a subspace W is

$$d = \|\mathbf{b} - \text{proj}_W \mathbf{b}\| = \|\text{proj}_{W^\perp} \mathbf{b}\|.$$

Let A be an $m \times n$ matrix, $\mathbf{b} \in \mathbb{R}^m$.

$\hat{\mathbf{x}} \in \mathbb{R}^n$ is called a best approximate sol. or a least squares sol. of $A\mathbf{x} = \mathbf{b}$ if $\|\mathbf{b} - A\hat{\mathbf{x}}\| \leq \|\mathbf{b} - A\mathbf{x}\| \quad \forall \mathbf{x} \in \mathbb{R}^n$.

$\Rightarrow \begin{cases} \mathbf{b} - A\hat{\mathbf{x}} \text{ is called the least squares error vector} \\ \|\mathbf{b} - A\hat{\mathbf{x}}\| \text{ is called the least squares error.} \end{cases}$

Since $A\mathbf{x} \in \text{col}(A)$ and $\text{proj}_{\text{col}(A)} \mathbf{b}$ is the best approximation to \mathbf{b} from $\text{col}(A)$, $\|\mathbf{b} - A\mathbf{x}\|$ is minimized when $A\mathbf{x} = \text{proj}_{\text{col}(A)} \mathbf{b}$.

Since $A\mathbf{x} = \text{proj}_{\text{col}(A)} \mathbf{b}$ is consistent, every $A\mathbf{x} = \mathbf{b}$ has at least one least squares solution. i.e., $\exists \hat{\mathbf{x}} \in \mathbb{R}^n$ s.t. $\|\mathbf{b} - A\hat{\mathbf{x}}\| = \|\mathbf{b} - \text{proj}_{\text{col}(A)} \mathbf{b}\| \leq \|\mathbf{b} - A\mathbf{x}\|$.

From $\mathbf{b} - A\hat{\mathbf{x}} = \mathbf{b} - \text{proj}_{\text{col}(A)} \mathbf{b}$, we have

$$A^T(\mathbf{b} - A\hat{\mathbf{x}}) = A^T(\underbrace{\mathbf{b} - \text{proj}_{\text{col}(A)} \mathbf{b}}_{\text{col}(A)^\perp = \text{null}(A^T)})$$

$$\therefore A^T A \hat{\mathbf{x}} = A^T \mathbf{b}.$$



This is called the normal equation or normal system associated with $A\hat{\mathbf{x}} = \mathbf{b}$.

Thm 7.8.3

- { the least squares solutions of $A\hat{\mathbf{x}} = \mathbf{b}$ } = { the solutions of $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$ }
- If A has full col. rank, then $\exists! \hat{\mathbf{x}} = (A^T A)^{-1} A^T \mathbf{b}$.
- If A does not have full col. rank, $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$ has ∞ -many solutions but $\exists! \hat{\mathbf{x}} \in \text{row}(A)$ s.t. $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$. Among all the solutions of $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$, $\hat{\mathbf{x}} \in \text{row}(A)$ has the smallest norm.

pf) ETS : " \exists " part of (a)

If x_0 is a solution of $A^T A x = A^T b$, then

$$b - Ax_0 \in \text{null}(A^T) = \text{col}(A)^\perp$$

Since $b = Ax_0 + (b - Ax_0)$, $Ax_0 \in \text{col}(A)$, and $b - Ax_0 \in \text{col}(A)^\perp$,

We have $Ax_0 = \text{proj}_{\text{col}(A)} b$

$$\therefore \|b - Ax_0\| \leq \|b - Ax\| \quad \forall x \in \mathbb{R}^n.$$

$\therefore x_0$ is a least squares sol. of $Ax = b$. \square

Thm 7d.4

\hat{x} : a least squares sol. of $Ax = b$

$$\Leftrightarrow b - A\hat{x} \in \text{col}(A)^\perp.$$

pf) Since $b = \text{proj}_{\text{col}(A)} b + \text{proj}_{\text{null}(A^T)} b$,

$$b - Ax = (\text{proj}_{\text{col}(A)} b - Ax) + \text{proj}_{\text{null}(A^T)} b$$

Note that \hat{x} is a least squares sol. of $Ax = b$ iff \hat{x} is a sol. of $Ax = \text{proj}_{\text{col}(A)} b$.

$\therefore \hat{x}$ is a least squares sol. of $Ax = b$ iff

$$b - A\hat{x} = \text{proj}_{\text{null}(A^T)} b \in \text{null}(A^T) = \text{col}(A)^\perp.$$

\square

Consequently, for $Ax = b$,

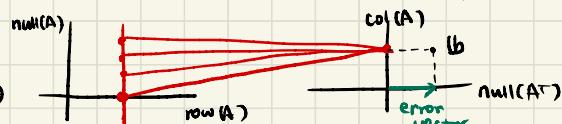
$$\begin{cases} \text{least squares error vector} = \text{proj}_{\text{null}(A^T)} b \\ \text{least squares error} = \|\text{proj}_{\text{null}(A^T)} b\| \end{cases}$$

Starg diagram

< A has full col. rank >



< A does not have full col. rank >



* Read the textbook from p.399 to p.403.

Fitting a curve to experimental data: $(x_1, y_1), \dots, (x_n, y_n)$

Mathematical model: $y = f(x) = a_0 + a_1 x + \dots + a_m x^m$

Idea: Determine the coeff. a_0, a_1, \dots, a_m that make the graph $y=f(x)$ fit the data as closely as possible.

$$\begin{bmatrix} 1 & x_1 & \dots & x_1^m \\ \vdots & \vdots & & \vdots \\ 1 & x_n & \dots & x_n^m \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$M \qquad w \qquad y$

If $m = n-1$ and x_1, \dots, x_n are pairwise distinct, then we can always find the polynomial $y=f(x)$ passing through all the points $(x_1, y_1), \dots, (x_n, y_n)$. (See p.203)

In general, we find the sol. of the normal system $MTw = MTy$ ass. with $Mw = y$.

If $m < n$ and at least $m+1$ of x_1, \dots, x_n are distinct, then M has full column rank and

$$w = (MTM)^{-1} M^T y.$$