

**1** Indicate whether the following statements are true(**T**) or false(**F**). You do **not** need to justify your answer.

3+3+4  
points

- (a) Let  $V$  be the line in  $\mathbb{R}^3$  through the origin spanned by  $\mathbf{u} = (6, 2, -3)$ , and  $W$  be the plane in  $\mathbb{R}^3$  whose equation is  $2x + 3y + 6z = 0$ . Then  $V$  is a subspace of  $W$ .
- (b) Let  $T, S : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be linear transformations. If  $T \circ S \circ T$  is not one-to-one, then there exists  $\mathbf{v} \in \mathbb{R}^n$  such that  $\mathbf{v} \notin \text{ran}(T \circ S)$ .
- (c) Let  $S$  be a set of nonzero vectors in  $\mathbb{R}^3$  such that  $|S| = 4$ . ( $|A|$  denotes the number of elements of a finite set  $A$ .) If  $\text{span}(S) = \mathbb{R}^3$ , then the number of possible  $S_0 \subset S$  such that  $S_0$  is a basis for  $\mathbb{R}^3$  is at least 2.

*Solution.*

- (a) True. Since  $\mathbf{u} \in W$ ,  $V = \text{span}(\{\mathbf{u}\}) \subset W$ .
- (b) True. Let  $A, B$  be the standard matrices for  $T, S$ . Since  $ABA$  is the standard matrix for  $T \circ S \circ T$ ,  $0 = \det ABA = (\det A)^2(\det B)$ . Thus  $\det A = 0$  or  $\det B = 0$ . Since  $AB$  is the matrix representation for  $T \circ S$  and  $\det AB = \det A \det B = 0$ ,  $T \circ S$  is not onto.
- (c) True. Note that there exists  $S_0 \subset S$  such that  $S_0$  is a basis for  $\mathbb{R}^3$ . Thus it suffices to show that the number of possible  $S_0 \subset S$  such that  $S_0$  is a basis for  $\mathbb{R}^3$  cannot be 1. Suppose it is 1. Let  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} \subset S$  be a basis for  $\mathbb{R}^3$  and  $\mathbf{v}_4$  be the last vector of  $S$ . Then  $\mathbf{v}_4$  is contained in  $\text{span}(\{\mathbf{v}_1, \mathbf{v}_2\})$ ,  $\text{span}(\{\mathbf{v}_1, \mathbf{v}_3\})$ ,  $\text{span}(\{\mathbf{v}_2, \mathbf{v}_3\})$ . Set

$$\mathbf{v}_4 = a\mathbf{v}_1 + b\mathbf{v}_2 = c\mathbf{v}_2 + d\mathbf{v}_3 = e\mathbf{v}_1 + f\mathbf{v}_3.$$

Since  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is linearly independent,  $\mathbf{v}_4 = \mathbf{0}$ , a contradiction. Thus the number of possible  $S_0 \subset S$  such that  $S_0$  is a basis for  $\mathbb{R}^3$  is at least 2.

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- 2** Let  $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  where  $\mathbf{v}_1 = (2, 1, -1)$ ,  $\mathbf{v}_2 = (3, 3, 2)$ ,  $\mathbf{v}_3 = (-3, -1, 3)$ . Determine whether  $\dim(\text{span}(S)) = 3$  or not. Explain your answer.
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- 10 points

*Solution.* If  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is linearly independent, then  $\dim(\text{span}(S)) = 3$ . Let  $A = [\mathbf{v}_1 | \mathbf{v}_2 | \mathbf{v}_3]^T$ . Then  $A$  is non-singular if and only if  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is linearly independent. Since  $\det A = 1 \neq 0$ ,  $A$  is non-singular. Thus  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is linearly independent, which means  $\dim(\text{span}(S)) = 3$ .