## MATLAB assignment 9

## Introduction to Linear Algebra (Week 9)

Fall, 2019

1. Let  $\mathcal{B}_1$  and  $\mathcal{B}_2$  be bases for  $\mathbb{R}^n$ . Write a function code TransMatrix which produces two transition matrices  $P_{\mathcal{B}_1 \to \mathcal{B}_2}$  and  $P_{\mathcal{B}_2 \to \mathcal{B}_1}$  as outputs when it takes two matrices U and V whose column vectors are members of  $\mathcal{B}_1$  and  $\mathcal{B}_2$ , respectively. In other words, if

$$\mathcal{B}_1 := \{\mathbf{u}_1, \cdots, \mathbf{u}_n\}$$
 and  $\mathcal{B}_2 := \{\mathbf{v}_1, \cdots, \mathbf{v}_n\}$ 

then

$$U = [\mathbf{u}_1 \mid \cdots \mid \mathbf{u}_n]$$
 and  $V = [\mathbf{v}_1 \mid \cdots \mid \mathbf{v}_n]$ 

and the line defining the function TransMatrix is:

where the P\_B12 and P\_B21 are variables for transition matrices  $P_{\mathcal{B}_1 \to \mathcal{B}_2}$  and  $P_{\mathcal{B}_2 \to \mathcal{B}_1}$ , respectively.

## Problem.

(a) Write script file which finds the transition matrices  $P_{\mathcal{B}_1 \to \mathcal{B}_2}$  and  $P_{\mathcal{B}_2 \to \mathcal{B}_1}$ , where the  $\mathcal{B}_1$  and  $\mathcal{B}_2$  are bases for  $\mathbb{R}^5$  and

$$\mathbf{u}_1 = (3, 1, 3, 2, 6) \qquad \mathbf{v}_1 = (2, 6, 3, 4, 2)$$

$$\mathbf{u}_2 = (4, 5, 7, 2, 4) \qquad \mathbf{v}_2 = (3, 1, 5, 8, 3)$$

$$\mathbf{u}_3 = (3, 2, 1, 5, 4) \qquad \mathbf{v}_3 = (5, 1, 2, 6, 7)$$

$$\mathbf{u}_4 = (2, 9, 1, 4, 4) \qquad \mathbf{v}_4 = (8, 4, 3, 2, 6)$$

$$\mathbf{u}_5 = (3, 3, 6, 6, 7) \qquad \mathbf{v}_5 = (5, 5, 6, 3, 4) .$$

Find the coordinate of  $\mathbf{w} = (1, 1, 1, 1, 1)$  with respect to  $\mathcal{B}_1$  and  $\mathcal{B}_2$  and check your answers using  $P_{\mathcal{B}_1 \to \mathcal{B}_2}$  and  $P_{\mathcal{B}_2 \to \mathcal{B}_1}$ .

solution.

```
1 %% Looking for and validate the transition matrices.
2 format short;
_3 %- Find the transition matrices
4 % construct the matrices for bases B1 and B2
5 u1 = [3 1 3 2 6]; v1 = [2 6 3 4 2];
_{6} u2 = [4 5 7 2 4]; v2 = [3 1 5 8 3];
7 u3 = [3 2 1 5 4]; v3 = [5 1 2 6 7];
8 u4 = [2 9 1 4 4]; v4 = [8 4 3 2 6];
9 	 u5 = [3 	 3 	 6 	 6 	 7]'; 	 v5 = [5 	 5 	 6 	 3 	 4]';
10
11 U = [u1, u2, u3, u4, u5]; V = [v1, v2, v3, v4, v5];
   % P_B12 means the transition matrix from B1 to B2.
12
   \% P_B21 means the transition matrix from B2 to B1.
13
   [P_B12, P_B21] = TransMatrix(U,V);
15 disp('The transition matrix from B1 to B2 is'); disp(P_B12);
16 disp('The transition matrix from B2 to B1 is'); disp(P_B21);
17
18 %- Validation
19 w = [1 \ 1 \ 1 \ 1 \ 1];
20 \text{ w}_B1 = \text{U}\text{w};
                 % Find the coordinate matrix of w with respect to B1
w_B2 = V \ ;
                  % Find the coordinate matrix of w with respect to B2
22
23 % calculate P_B12 * [w]_B1. We want to be v = [w]_B2.
v = P_B12 * w_B1;
26 % TOL for validation
27 \text{ tol} = 10^-6;
_{28} if abs(v-w_B2) < tol
       disp('[w]_B2 = '); disp(w_B2');
29
       disp('P_(B1->B2) * [w]_B1 = '); disp(v');
30
       disp('They are same thus the equation ''P_B12 * [w]_B1 = [w]_B2''
31
           holds');
  else
32
       disp('Wrong transition matrix!!!!!!!');
33
34
   %% Make a function 'TransMatrix'
   function [P_B12, P_B21] = TransMatrix(U, V)
       [m,n] = size(U);
                            [k,1]=size(V);
37
       if (n~=1)||(m~=n)||(m~=k)
38
           fprintf('Mismatch of the dimension\n');
39
           return
40
       else
41
       P_B12 = V \setminus U;
42
       P_B21 = U \setminus V;
43
       end
44
45 end
```