Anar Nurizada

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Education

Stony Brook University   **NY, USA**
Ph.D. in Mechanical Engineering, Minor in Computer Science, GPA: **3.71**   *2022 – present*

Stony Brook University   **NY, USA**
M.S. in Mechanical Engineering, GPA: **3.86**   *2020 – 2022*

Experience

Stony Brook University   **Stony Brook, NY**
Graduate Research Assistant   *Sep 2020 – Present*

- **Designed a novel dual-decoder transformer with Mixture-of-Experts (MoE)** for multimodal path synthesis, achieving **15% higher accuracy** (vs. baseline) and <**200ms inference**. Key innovations:
  – **MoE-augmented decoders** (8 experts, **2 active + 1 shared**) with **dynamic gating**, improving sample diversity while maintaining stability via **forced expert utilization**.
  – **Dual-branch architecture**: Parallel decoders (each with **RMSNorm**, **cross-attention**) process structured inputs (curves/graphs) encoded by a **contrastive ResNet backbone**, enabling **multimodal fusion**.
  – **Optimized training**: Combined **Classifier-Free Guidance** with **LoRA fine-tuning** for efficient adaptation to new tasks.
- Extended the framework with **3 complementary architectures**:
  – A **diffusion-augmented transformer** (LLaMa 2 encoder + diffusion decoder) for high-precision synthesis.
  – **Conditional VAEs** (beta-VAE, graph-VAE) with adaptive latent space constraints.
- **Full-stack development**: Built custom datasets, trained models on **HPC (SLURM) & cloud GPUs** (Lambda & VAST.AI), and tracked experiments with **Weights & Biases**. **Tools**: PyTorch (Lightning), Hugging Face, NumPy, SciPy, OpenCV, Git/GitHub.

Zortag   **St. James, NY**
Machine Learning Intern   *Aug 2024 – Present*

- Fine-tuned **YOLOv8** models, increasing detection accuracy from **90%** to nearly **100%** while optimizing inference time to milliseconds. Replaced the previous two-step detection-verification process with a streamlined single-step approach, significantly improving efficiency.
- Led the automation of the **myCobot 280 PI** robotic arm to simulate human hand movements for video and image capture, reducing manual workload by **60%**. Developed an automated data labeling pipeline, accelerating annotation speed by **3×** and reducing dataset compilation time from several hours to approximately an hour.
- Developed an iPhone-based inference system for real-time QR code detection, leveraging **SwiftUI** and **CoreML** for efficient on-device inferencing with minimal latency. Additionally, containerized the model using **Docker** to enable seamless deployment across a wider range of iOS environments, ensuring accessibility and scalability.

Project   **Brooklyn, NY**
Advanced RAG-Powered Document Chatbot   *2024 – Present*

- Built production-ready **RAG** system using **FastAPI** backend and **Together.API**'s free tier (**Llama-3-70B**), achieving <**2s** latency
- Engineered **FAISS** vector search with optimized chunking via **LangChain**'s RecursiveCharacterTextSplitter and **PyPDF**
- Deployed secure **AWS** infrastructure: **S3** (encrypted storage), **DynamoDB** (state management), and **Secrets Manager** (credentials)
- Maintained zero cloud costs through strategic free-tier utilization of all services

Project   **Brooklyn, NY**
ESP32-CAM Object Detection and Control System   *2024*

- Developed a real-time object detection system using ESP32-CAM and a custom TensorFlow.js model, reducing inference times from **4** seconds to **10** milliseconds. Trained the model on Azure and deployed it for inferencing.
- Built a JavaScript server to process detection results over WiFi and communicate back to the ESP32, enabling real-time adjustments via a servo-mounted ESP32 and Arduino.

Publications and Awards

2025: **Nurizada, A.**, Dhaipule, R., Lyu, Z., Purwar, A.. "A Dataset of 3M Single-DOF Planar 4-, 6-, and 8-bar Linkage Mechanisms with Open and Closed Coupler Curves for Machine Learning-Driven Path Synthesis." *ASME Journal of Mechanical Design*, 1-16. doi:10.1115/1.4067014.

2025: **Nurizada, A.**, Lyu, Z., Purwar, A.. "Path Generative Model based on Conditional β- Variational Auto Encoder for Mechanism Design." *ASME Journal of Mechanisms and Robotics*, 1-14. doi:10.1115/1.4067169.

2023: **Nurizada, A.**, Purwar, A.. "An invariant representation of coupler curves using a variational AutoEncoder: Application to path synthesis of four-bar mechanisms." *ASME Journal of Computing and Information Science in Engineering*, doi:10.1115/1.4063726.

2022: **Nurizada, A.**, Purwar, A.. "Transforming hand-drawn sketches of linkage mechanisms into their digital representation." *ASME Journal of Computing and Information Science in Engineering*, doi:10.1115/1.4064037.

2021: **Nurizada, A.**, Kirane, K.. "Induced anisotropy in the fracturing behavior of 3d printed parts analyzed by the size effect method." *Engineering Fracture Mechanics*, 239, 107304. doi:10.1016/j.engfracmech.2020.107304.

2024: **PASHA HACKATHON 4.0 Winner**, Baku, Azerbaijan

2024: **TransitHack Hackathon Winner**, Baku, Azerbaijan