

CS229 Machine Learning (summer 2020): Problem Set 0

v1.1

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1 Gradient and Hessians [0 points]

1. Let $f(x) = \frac{1}{2}x^T Ax + b^T x$, where A is a symmetric matrix and $b \in \mathbb{R}^n$ is a vector. What is $\nabla f(x)$?

Solution

$$\nabla f(x) = Ax + b \quad (1)$$

2. Let $f(x) = g(h(x))$, where $g : \mathbb{R} \rightarrow \mathbb{R}$ is differentiable and $h : \mathbb{R}^n \rightarrow \mathbb{R}$ is differentiable. What is $\nabla f(x)$?

Solution

$$\nabla f(x) = \frac{\partial g(h(x))}{\partial h(x)} \frac{\partial h(x)}{\partial x} = g'(h(x)) \nabla h(x) \quad (2)$$

3.

4. Let $f(x) = \frac{1}{2}x^T Ax + b^T x$, where A is a symmetric matrix and $b \in \mathbb{R}^n$ is a vector. What is $\nabla^2 f(x)$?

Solution

$$\nabla^2(f(x)) = A \quad (3)$$

5. Let $f(x) = g(a^T x)$, where $g : \mathbb{R} \rightarrow \mathbb{R}$ is continuously differentiable and $a \in \mathbb{R}^n$ is a

vector. What is $\nabla f(x)$ and $\nabla^2(f(x))$?

Solution

$$\nabla g(x) = \frac{\partial g(x)}{\partial a^T x} \frac{\partial a^T x}{\partial x} = g'(a^T x) a \quad (4)$$

$$\nabla^2(g(x))_{(i,j)} = g''(a^T x) a_i a_j \quad (5)$$

2 Positive definite matrices [0 Points]

- Let $z \in \mathbb{R}^n$. Show that $A = zz^T$ is positive semidefinite.

Solution

Let $x \in \mathbb{R}^n$,

$$\begin{aligned} x^T A x &= x^T z z^T x \\ &= (z^T x)^T (z^T x) \\ &= \|z^T x\|^2 \geq 0 \end{aligned}$$

Which prove that A is **SPD**.

- Let $A = zz^T$, what is the null space of A ? What is the rank of A ?

Solution

The null space $\mathcal{N}(A)$ is given by:

$$\mathcal{N}(A) = \{x \in \mathbb{R}^n \mid (zz^T)x = 0\} \quad (6)$$

$$= \left\{ x \in \mathbb{R}^n \mid \sum_{i=1}^n x_i z_i = 0 \right\} \quad (7)$$

$$= z^\perp \quad (8)$$

$$(9)$$

The rank of A is n - the number of **non null** elements in z .

- Let $A \in \mathbb{R}^{n,n}$ be a semidefinite matrix and $B \in \mathbb{R}^{m,n}$ be an arbitrary matrix. Is BAB^T **PSD**?

Solution

For any $x \in \mathbb{R}^m$, let compute the:

$$x^T BAB^T x = (B^T x)^T A (B^T x) \geq 0 \quad (10)$$

Since A is **PSD**,

3 Eigen vectors and Eigen values

- Suppose $A \in \mathbb{R}^{n,n}$ is diagonalizable, that is, $A = TDT^{-1}$ for an invertible matrix T . Show that $At^{(i)} = \lambda_i t^{(i)}$.

Solution

$$At^{(i)} = TDT^{-1}t^{(i)} \quad (11)$$

$$= TD(T^T t^{(i)}) \quad (12)$$

$$= TD \begin{pmatrix} \dots & 1 & \dots \end{pmatrix}^T \quad (13)$$

$$= T \begin{pmatrix} \dots & \lambda_i & \dots \end{pmatrix}^T \quad (14)$$

$$= \lambda_i t^{(i)} \quad (15)$$

- Two simple equations on digitalization.

4 Probability and multivariate Gaussian

Let $X = (X_1, \dots, X_n)$ is sampled from a *multivariate Gaussian* distribution with mean μ and covariance $\Sigma \in S_+^n$.

- Describe the random variable $Y = X_1 + X_2 + \dots + X_n$. What is the mean and variance?