

1. Let μ be the mass of unit length of the rope. Then the net force (in the rotating frame) acting on a small piece dr is

$$dF = \left(-\frac{GM}{r^2} + \omega^2 r \right) \mu dr,$$

where $G = 6.67 \cdot 10^{-11} \text{ m}^3/(\text{kg} \cdot \text{s}^2)$ is the gravitational constant, $M = 5.97 \cdot 10^{24} \text{ kg}$ is the mass of Earth, $\omega = 7.27 \cdot 10^{-5} \text{ rad/s}$ is the frequency of rotation of Earth. Then the net force on the whole rope is

$$\frac{F}{\mu} = -GM \left(\frac{1}{R} - \frac{1}{R+L} \right) + \frac{\omega^2}{2} ((R+L)^2 - R^2) = \frac{\omega^2 L(L+2R)}{2} - \frac{GML}{R(R+L)},$$

where $R = 6.378 \cdot 10^6 \text{ m}$ is the radius of Earth. As the rope hangs free, $F = 0$. So,

$$\frac{2GM}{\omega^2} = R(R+L)(2R+L),$$

or, in terms of the geostationary radius $R_0 = (GM/\omega^2)^{1/3}$,

$$RL^2 + 3R^2L + 2R^3 - 2R_0^3 = 0.$$

The solution of this equation is

$$L = \frac{1}{2R} \left(-3R^2 + \sqrt{R_0^3 + 8R^3} \right) = \frac{R}{2} \left(-3 + \sqrt{1 + \frac{8R_0^3}{R^3}} \right) = 1.44 \cdot 10^8 \text{ m}.$$

2. The angular velocity appears to be $\omega = 1$, and the radius is a . So the linear velocity is $v = \omega a = a$, and the arc length is $l = 2\pi a$.

3. Let x_i ($i = 1, 2, 3$) be the displacements of the bodies. Then due to Newton's law

$$\begin{aligned} x_1'' &= \omega_0^2(x_2 - x_1) + \omega^2 \delta \cos \omega t, \\ x_2'' &= \omega_0^2(x_1 + x_3 - x_2), \\ x_3'' &= \omega_0^2(x_2 - x_3), \end{aligned}$$

where $\omega_0 = \sqrt{k/m}$ and $\delta = f/(m\omega^2)$. The solution of this system is (obtained by *Mathematica*):

$$\begin{aligned} \xi_1 = \frac{x_1}{\delta} &= \frac{3\omega^2(\omega^2 - 3\omega_0^2) \cos \omega_0 t - 6(\omega^4 - 3\omega_0^2\omega^2 + \omega_0^4) \cos \omega t + (\omega^2 - \omega_0^2)(2\omega^2 - 6\omega_0^2 + \omega^2 \cos \omega_0 t \sqrt{3})}{6(\omega^4 - 4\omega_0^2\omega^2 + 3\omega_0^4)}, \\ \xi_2 = \frac{x_2}{\delta} &= \frac{\omega^2(1 - \cos \omega_0 t \sqrt{3}) - 3\omega_0^2(1 - \cos \omega t)}{3(\omega^2 - 3\omega_0^2)}, \\ \xi_3 = \frac{x_3}{\delta} &= \frac{6(\omega^4 - 3\omega_0^2\omega^2 + \omega_0^4) + (\omega^2 - \omega_0^2)(2\omega^2 - 6\omega_0^2 + \omega^2 \cos \omega_0 t \sqrt{3})}{6(\omega^4 - 4\omega_0^2\omega^2 + 3\omega_0^4)}, \end{aligned}$$

or, in a dimensionless form with $\varphi = \omega_0 t$ and $\gamma = \omega/\omega_0$,

$$\xi_1 = \frac{3\gamma^2(\gamma^2 - 3)\cos\varphi - 6(\gamma^4 - 3\gamma^2 + 1)\cos\gamma\varphi + (\gamma^2 - 1)(2\gamma^2 - 6 + \gamma^2\cos\varphi\sqrt{3})}{6(\gamma^4 - 4\gamma^2 + 3)},$$

$$\xi_2 = \frac{\gamma^2(1 - \cos\varphi\sqrt{3}) - 3(1 - \cos\gamma\varphi)}{3(\gamma^2 - 3)},$$

$$\xi_3 = \frac{6(\gamma^4 - 3\gamma^2 + 1) + (\gamma^2 - 1)(2\gamma^2 - 6 + \gamma^2\cos\varphi\sqrt{3})}{6(\gamma^4 - 4\gamma^2 + 3)}.$$

In case of a resonance $\gamma = 1$ this solution is degenerated to

$$\xi_1 = \frac{1}{12} \left(4 - 3\cos\varphi - \cos\varphi\sqrt{3} + 3\varphi\sin\varphi \right),$$

$$\xi_2 = \frac{1}{6} \left(2 - 3\cos\varphi + \cos\varphi\sqrt{3} \right),$$

$$\xi_3 = \frac{1}{12} \left(4 - 3\cos\varphi - \cos\varphi\sqrt{3} - 3\varphi\sin\varphi \right).$$

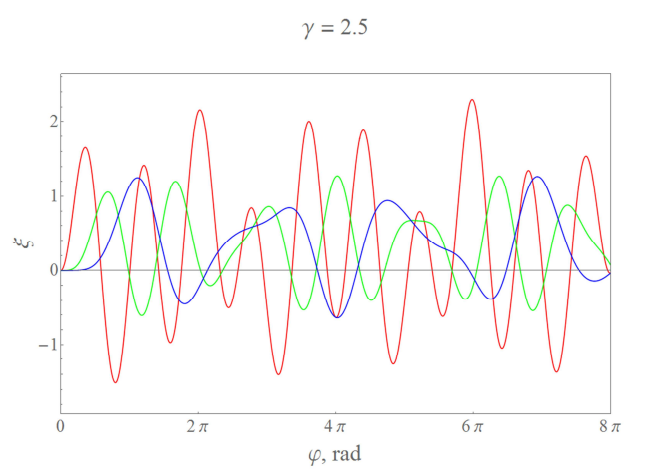
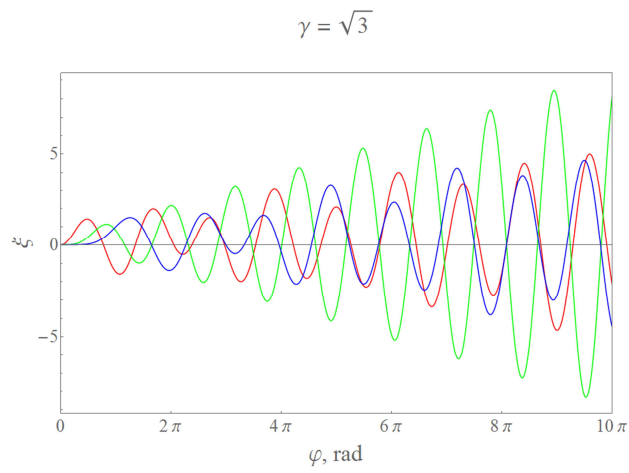
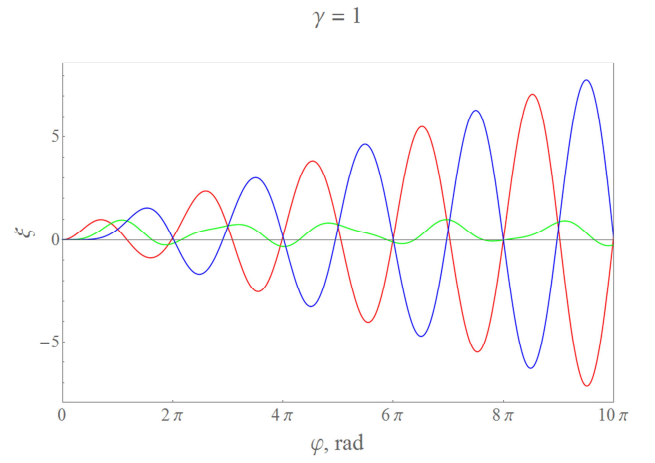
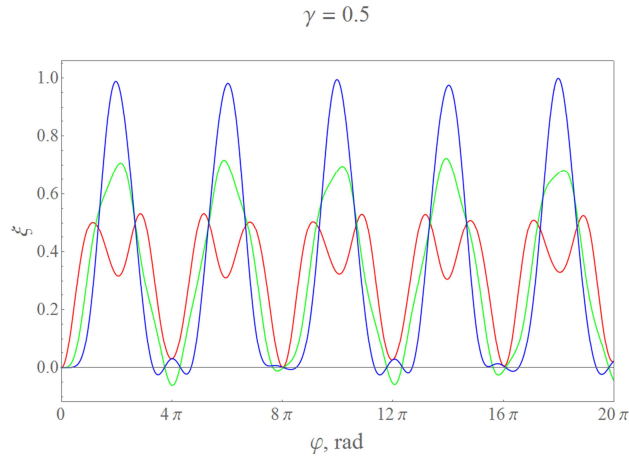
There's also a resonance $\gamma = \sqrt{3}$, in that case

$$\xi_1 = \frac{1}{12} \left(4 + 9\cos\varphi - 13\cos\varphi\sqrt{3} + \varphi\sqrt{3}\sin\varphi\sqrt{3} \right),$$

$$\xi_2 = \frac{1}{6} \left(2 - 2\cos\varphi\sqrt{3} - \varphi\sqrt{3}\sin\varphi\sqrt{3} \right),$$

$$\xi_3 = \frac{1}{12} \left(4 - 9\cos\varphi + 5\cos\varphi\sqrt{3} + \varphi\sqrt{3}\sin\varphi\sqrt{3} \right).$$

The plots of these dependencies are shown below.



The plots of the $\xi(\varphi)$ dependencies for the bodies, body 1 corresponds to the red curve, body 2 — to the green, body 3 — to the blue one.