

1. In terms of triple products the expressions may be rewritten as

$$\begin{aligned} (\vec{a} \times \vec{b}) \cdot (\vec{c} \times \vec{d}) &= ((\vec{a} \times \vec{b}), \vec{c}, \vec{d}) = (\vec{d}, (\vec{a} \times \vec{b}), \vec{c}) = \vec{d} \cdot ((\vec{a} \times \vec{b}) \times \vec{c}) = -\vec{d} \cdot (\vec{c} \times (\vec{a} \times \vec{b})) = \\ &= -\vec{d} \cdot (\vec{a} (\vec{b} \cdot \vec{c}) - \vec{b} (\vec{a} \cdot \vec{c})) = (\vec{b} \cdot \vec{d}) (\vec{a} \cdot \vec{c}) - (\vec{a} \cdot \vec{d}) (\vec{b} \cdot \vec{c}), \end{aligned}$$

$$\begin{aligned} (\vec{a} \times \vec{b}) \times (\vec{c} \times \vec{d}) &= \vec{c} ((\vec{a} \times \vec{b}) \cdot \vec{d}) - \vec{d} ((\vec{a} \times \vec{b}) \cdot \vec{c}) = \vec{c} (\vec{d}, \vec{a}, \vec{b}) - \vec{d} (\vec{c}, \vec{a}, \vec{b}) = \vec{c} (\vec{a}, \vec{b}, \vec{d}) - \vec{d} (\vec{a}, \vec{b}, \vec{c}) = \\ &= \vec{c} (\vec{a} \cdot (\vec{b} \times \vec{d})) - \vec{d} (\vec{a} \cdot (\vec{b} \times \vec{c})), \end{aligned}$$

q.e.d.

2. Let's denote $\vec{A} = (\vec{a} \cdot \vec{r}) \vec{b}$, $\vec{B} = (\vec{a} \cdot \vec{r}) \vec{r}$, $\vec{C} = \vec{a} \times \vec{r}$, $\vec{D} = (\vec{a} \times \vec{r}) \phi(\vec{r})$, $\vec{E} = \vec{r} \times (\vec{a} \times \vec{r})$, where \vec{r} is the radius-vector. Then

$$\begin{aligned} \nabla \cdot \vec{A} &= (\vec{b} \cdot \nabla) (\vec{a} \cdot \vec{r}) + (\vec{a} \cdot \vec{r}) (\nabla \cdot \vec{b}) = (\vec{b} \cdot \nabla) (\vec{a} \cdot \vec{r}) = b_x a_x + b_y a_y + b_z a_z = \vec{a} \cdot \vec{b}, \\ \nabla \times \vec{A} &= (\vec{a} \cdot \vec{r}) (\nabla \times \vec{b}) - (\vec{b} \times \nabla) (\vec{a} \cdot \vec{r}) = -(\vec{b} \times \nabla) (\vec{a} \cdot \vec{r}) = -\vec{b} \times \vec{a} = \vec{a} \times \vec{b}, \\ \nabla \cdot \vec{B} &= (\vec{r} \cdot \nabla) (\vec{a} \cdot \vec{r}) + (\vec{a} \cdot \vec{r}) (\nabla \cdot \vec{r}) = (x a_x + y a_y + z a_z) + 3 (\vec{a} \cdot \vec{r}) = 4 (\vec{a} \cdot \vec{r}), \\ \nabla \times \vec{B} &= (\vec{a} \cdot \vec{r}) (\nabla \times \vec{r}) - (\vec{r} \times \nabla) (\vec{a} \cdot \vec{r}) = -(\vec{r} \times \nabla) (\vec{a} \cdot \vec{r}) = -\vec{r} \times \vec{a} = \vec{a} \times \vec{r}, \\ \nabla \cdot \vec{C} &= (\nabla, \vec{a}, \vec{r}) = (\vec{r}, \nabla, \vec{a}) = \vec{r} \cdot (\nabla \times \vec{a}) = 0, \\ \nabla \times \vec{C} &= \vec{a} (\nabla \cdot \vec{r}) - \vec{r} (\nabla \cdot \vec{a}) = 3\vec{a}, \\ \nabla \cdot \vec{D} &= ((\vec{a} \times \vec{r}) \cdot \nabla) \phi(\vec{r}) + \phi(\vec{r}) (\nabla \cdot (\vec{a} \times \vec{r})) = ((\vec{a} \times \vec{r}) \cdot \nabla) \phi(\vec{r}), \\ \nabla \times \vec{D} &= \phi(\vec{r}) (\nabla \times \vec{C}) - ((\vec{a} \times \vec{r}) \times \nabla) \phi(\vec{r}) = 3\phi(\vec{r}) \vec{a} + \vec{a} (\vec{r} \cdot \nabla) \phi(\vec{r}) - \vec{r} (\vec{a} \cdot \nabla) \phi(\vec{r}), \end{aligned}$$

where it's denoted

$$(\vec{a} \cdot \nabla) = a_x \frac{\partial}{\partial x} + a_y \frac{\partial}{\partial y} + a_z \frac{\partial}{\partial z}$$

and

$$(\vec{a} \times \nabla) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_x & a_y & a_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{vmatrix},$$

both of these are *operators*. The last ones are easier to calculate with a simplification $\vec{E} = r^2 \vec{a} - \vec{r} (\vec{a} \cdot \vec{r})$. We obtain:

$$\begin{aligned} \nabla \cdot \vec{E} &= 2(a_x x + a_y y + a_z z) - \nabla \cdot \vec{B} = -2(\vec{a} \cdot \vec{r}), \\ \nabla \times \vec{E} &= r^2 (\nabla \times \vec{a}) - (\vec{a} \times \nabla) r^2 - \nabla \times \vec{B} = -2(\vec{a} \times \vec{r}) - (\vec{a} \times \vec{r}) = -3(\vec{a} \times \vec{r}). \end{aligned}$$

3. The plane $z = 0$ will obviously not be equipotential. The potential at an arbitrary point (x_0, y_0, z_0) can be found from

$$\varphi(x_0, y_0, z_0) = \frac{\sigma_0}{4\pi\epsilon_0} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{\sin(\alpha x) \sin(\beta y) dx dy}{\sqrt{(x - x_0)^2 + (y - y_0)^2 + z_0^2}}.$$

In the plane $z = 0$ this simplifies to

$$\varphi(x_0, y_0, 0) = \frac{\sigma_0}{4\pi\epsilon_0} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{\sin(\alpha(x+x_0)) \sin(\beta(y+y_0)) dx dy}{\sqrt{x^2+y^2}} = \frac{\sigma_0}{2\epsilon_0 \sqrt{\alpha^2 + \beta^2}} \sin(\alpha x_0) \sin(\beta y_0).$$