# A Button-Led systems: from objects to actors and services

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#### 1 Requirements

Every IOT system usually performs a basic set of actions:

- Acquire data from sensor devices.
- Perform some control action.
- Send commands to actuator devices.

In this very basic demo, we use a Button as a sensor and a Led as an actuator and the control action represents our business logic. Examples of the business logic implemented by our Button-Led (BLS) system are:

- 1. ROnOff: the Led is turned on/off each time the Button is pressed.
- 2. RBlink: when the Button is pressed, the Led starts blinking. When the Button is pressed again, the Led stop blinking. And so on.
- 3. ...

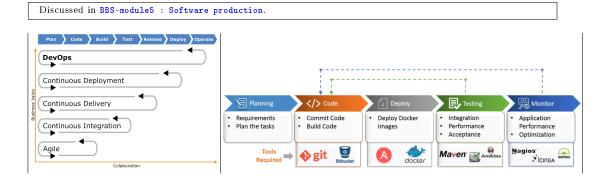
Reference project: it.unibo.bls.oo on https://github.com/anatali/IotUniboDemo.

#### 1.1 Goals

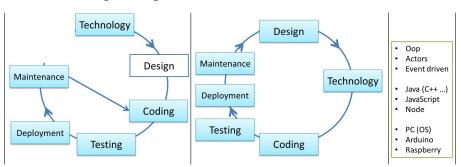
Our goals can be summarized as follows:

- 1. Define a 'technology-independent' architecture/prototype of the BLS in a local, tightly coupled environment.
- 2. Specialize the initial prototype according to different technologies. For example:
  - (a) The devices are implemented as  ${\tt Mock}$  objects in a virtual environment.
  - (b) The devices are concrete things controlled by low-costs devices such as Arduino/RaspberryPi.
- 3. Modify the first working prototype into a loosely-coupled (distributed) system in which each device works within its own computational node: see Subsection 3.3.
- 4. Modify the distributed prototype by 'transforming' each device into a (RESTful) service.
- 5. ...

#### 1.2 Software life cycle process

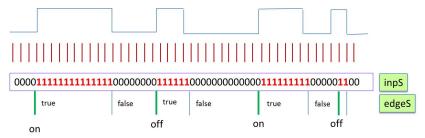


# 1.3 Bottom-up or Top-Down?



# 2 Technology-based design

The button is a source that emits a wave that can be sampled.

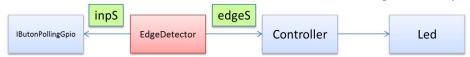


At this level, the problem requires that the following elaborations on the basic input

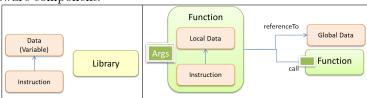
- the detection of the edges in the input sequence
- the detection of edges of type "low to high"

#### 2.1 Function-based software

The responsibility of these functions can be given to two new different entities: an entity EdgeDetector and an entity Controller that realizes the "business logic" of the system.



The code can be structured in imperative style, by using **functions** as a first kind of software component:



If an (application) function is called each time a new input becomes available, the system is 'reactive' or event-driven.

#### 2.2 Event-driven servless applications: AWS Lambda

Usually a function is associated with a definition environment and a run-time environment.

Serverless computing is a cloud-computing execution model in which the cloud provider dynamically manages the allocation of machine resources, including those required to execute a function.

AWS Lambda, introduced by Amazon in 2014, was the first public cloud vendor with an abstract serverless computing offering. AWS Lambda initially supported only Node.js. It now supports Python, Java, C# and Go, and code written in other languages can be invoked indirectly via Node.js.

Before running an example of a function as an AWS Lambda, we:

- 1. Create the function in natAwsServices
- 2. Install the client interface (AWS CLI) on the PC (run AWSCLI64PY3.msi for Windows)
- 3. Work in the installed AWS CLI directory (C:/Program Files/Amazon/AWSCLI/bin)

The function defined at natAwsServices named blsOnOffEdge has the following code:

```
var state = 'off'; //Initialization (state of a Led Mock)

exports.handler = (event, context, callback) => {
    console.log('Received event:', JSON.stringify(event, null, 2));
    console.log('edge =', event.edge);
    if ('edge' in event) {
       state = event['edge'];
    }
    var ledState = 'Led is ' + state;
    console.log(ledState); //Logging to Amazon CloudWatch Log
    callback(null, ledState); // End and return
}
```

The function can be called by the AWS Console on the Web in two ways

- without any testing event
- with a testing event expressed in Json:

As an alternative, we can call the function from a AWS Command Line Interface (AWS-CLI) Installed on our PC. Before doing that, we must configure a (client) user on the PC by using the command aws configure (in C:/Program Files/Amazon/AWSCLI/bin):

```
AWS Access Key ID [None]: ...BCG4A

WS Secret Access Key [None]:...T8eW

Default region name [None]: eu-west-1

Default output format [None]: json
```

To find the Access Key (ID):

- go to the security credentials on your account page (Click on your name in the top right corner
   My security credentials;
- 2. generate access keys over there and use those access keys in your credentials file (aws configure)

Finally we can invoke the function via the AWS-CLI:

```
aws lambda invoke --function-name blsOnOffEdge --payload "{""edge"" : ""on""}" output.txt
aws lambda invoke --function-name blsOnOffEdge --payload "{""edge"" : ""off""}" output.txt
```

in this case the function is executed via the AWS Lambda Invoke API call.

An important point at this stage, is that we can experiment in an easy way some fundamental aspects of functional programming (in JavaScript/Node), including the concept of lexical closure (lambda in Java8).

#### 2.3 Lexical Closures

Operationally, a **closure** is a record storing a function together with an environment: a mapping associating each free variable of the function (variables that are used locally, but defined in an enclosing scope) with the value or reference to which the name was bound when the closure was created.

An example is the function named ClosureExample:

```
function ledClosure(state){
  var doSwitch = function() {
    state = ! state;
  return state
}
```

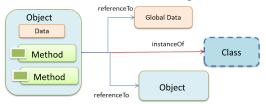
```
return doSwitch
}

var ledSwitch = ledClosure(false);

exports.handler = (event, context, callback) => {
    console.log( ledSwitch() );
    console.log( ledSwitch() );
    console.log( ledSwitch() );
    callback(null, "done"); // End and return
};
```

#### 2.4 Objects

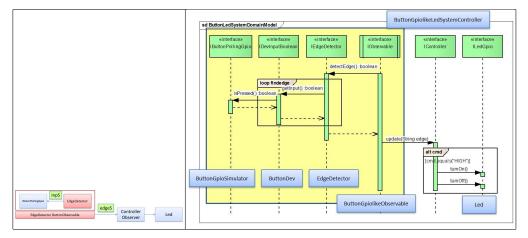
As an alternative of the function-based code of Subsection 2.1, both the *EdgeDetector* and the *Controller* can be modelled as finite state machines (FSM) working as *transducers*. They can be viewed as *objects* interacting via procedure-calls.



In any object-oriented model, all the computation usually takes place within a single thread. In our case the main thread could be the thread related to the component that performs the polling of the wave, i.e. the EdgeDetector. In this case, the *Controller* is called by the *EdgeDetector* that, must explicitly know the *Controller* in order to call it.

#### 2.5 Observable and Observers

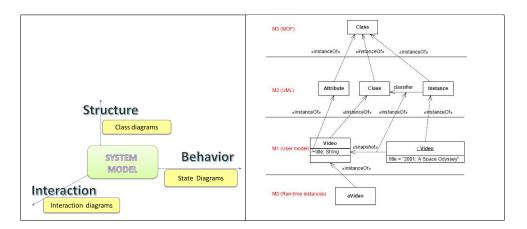
A more flexible architecture an be obtained (without changing the run-time interaction pattern) by conceiving the *Controller* as an *observer* that can be registered to the *EdgeDetector* information source.



However, staring from the idea that a Button is an 'edge detector' device is a too low-level approach for modern software applications. An effort has to be made to introduce a more appropriate model of the Button entity in terms of structure, interaction and behavior.

#### 2.6 Models

Nel contesto dei processi di costruzione del software, il termine modello va primariamente inteso come un insieme di concetti e proprietà volti a catturare aspetti essenziali di un sistema, collocandosi in un preciso spazio concettuale. Per l'ingegnere del software quindi un modello costituisce una visione semplificata ma coerente, consitente ed efficace di un sistema che rende il sistema stesso più accessibile alla comprensione e alla valutazione e facilita il trasferimento di informazione e la collaborazione tra persone, soprattutto quando è espresso in forma visuale.



#### 2.7 Modelling a Button

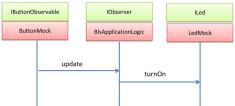
From the structural point of view, a button is intended by a customer as an atomic entity whose behavior can be modelled as a finite state machine (FMS) composed of two states ('pressed' and 'unpressed'). The state transition is performed by some agent external to the system (an user, a program, a device, etc.). From the interaction point of view, the button can expose its internal state in different ways:

- by providing a property operation (e.g. boolean isPressed()) that returns true when the button is in the pressed state. In this way the interaction is based on "polling";
- by providing a synchronizing operation (e.g. void waitPressed()) that blocks a caller until the button transits in the **pressed** state. In this way the interaction is based conventional "procedure-call":
- by working as an observable according to the *Observer* design pattern. In this way the interaction is based on "inversion of control" and involves observers (also called "listeners") that must be explicitly referenced (via a "register" operation) by the button.
- by emitting events handled by an event-based support. In this way the interaction is based on "inversion of control" that involves observers (usually known as "callbacks") referenced by the support and not by the button itself.
- by sending messages handled by a message-based support. In this way the interaction is based on message passing and can follow different "patterns" (in our internal terminology we distinguish between dispatch, invitation, request-response, etc.)

All these "models" could be appropriate in some software application. Thus, a very useful exercise is to define in a formal way each of these models by adopting (at the moment) a test-driven approach.

#### 3 An object-based design

Working in the conceptual space of 'classical' object oriented software development, the logic architecture of the BLS can be summarized by the following UML interaction diagram:



The computation starts from the observable device (*Button*), that calls a method of the object devoted to implement the application logic (that works as the Observer). An example is given in the project it.unibo.bls.oo that is based on the Java lanaguage. The working directory of the project is structured as follows:

- The package it.unibo.bls.interfaces includes the definition of the object interfaces.
- The package it.unibo.bls.devices includes the implementation of the object interfaces related to the devices (Button and Led). For each device, two different implementations are given: a Mock device and a 'virtual' object implemented with a GUI.
- The package it.unibo.bls.applLogic includes the definition of the object that implements the application logic.
- The package it.unibo.bls.appl includes the Main programs.
- The test directory includes examples of test units.

A software system working with the Mock devices should include a configuration phase to create the system components (objects) and properly connect them, according to the system architecture design:

```
public class MainBlsMockBase {
    private IButton btn:
    private ILed led;
     //Factory method
        public static MainBlsMockBase createTheSystem(){
           return new MainBlsMockBase();
        protected MainBlsMockBase( ) {
           createComponents();
10
        protected void createComponents(){
11
            led = LedMock.createLed( );
           BlsApplicationLogic applLogic = new BlsApplicationLogic(led);
13
14
            btn = ButtonMock.createButton( applLogic );
            led.turnOff();
15
```

Listing 1.1. MainBlsMockBase.java: configuration

The system defines also some working activity, to cause the change of the state in the ButtonMock:

```
public void doSomeJob() {
    System.out.println("doSomeJob starts");
    ((ButtonMock)btn).press();
    Utils.delay(1000);
    ((ButtonMock)btn).press();
    System.out.println("doSomeJob ends");
}
```

Listing 1.2. MainBlsMockBase.java: simulated action

Since every system is a **composed** (i.e. it is a **non-atomic**) entity, it provides also **selector-methods** to get its components:

```
public IButton getButton(){ //introduced for testing
    return btn;
}

public ILed getLed(){ //introduced for testing
    return led;
}
```

Listing 1.3. MainBlsMockBase.java: selectors

The selectors can be useful during the testing, to access the state of the single devices. Finally, there is the main method:

```
public static void main(String[] args) {
    MainBlsMockBase sys = createTheSystem();
    sys.doSomeJob();
}

}
```

Listing 1.4. MainBlsMockBase.java: the main method

#### 3.1 A Led as an object in Javascript

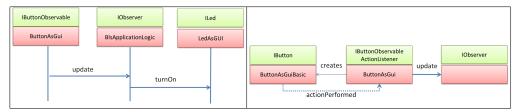
Let us model a Led as an object in JavaScript

```
//State (specific)
     var Led = function(name, guiId){
    //Led Constructor: instance data
         this.name = name;
this.guiId = guiId;
this.ledState = false;
     //Nethods (shared)
     Led.prototype.turnOn = function(){
10
         this.ledState = true;
11
12
     Led.prototype.turnOff = function(){
14
         this.ledState = false;
15
     Led.prototype.switchState = function(){
16
         this.ledState = ! this.ledState;
17
18
     Led.prototype.getState = function(){
20
         return this.ledState;
21
     Led.prototype.getName = function(){
22
         return this.name;
23
24
     Led.prototype.getDefaultRep = function(){
         return this.name+"||"+ this.ledState
27
```

The function defined at natAwsServices named blsR0n0ff has the following code:

#### 3.2 From BLS Mock devices to physical devices

The logical architecture previously introduced does not change if we replace the Mock devices with concrete devices: For example, in the case of virtual devices implemented with a GUI:



The class ButtonAsGuiBasic implements a GUI-based Button by extending the class java.awt.Button. The class ButtonAsGui implements the concept of Button as Observable entity.

Note that ButtonAsGui re-uses the class ButtonAsGuiBasic but without exploiting inheritance. Rather, it creates an instance of ButtonAsGuiBasic and works as its listener. This behaviour is caused by the fact that Java does not support multiple inheritance for classes and ButtonAsGui already extends the class java.util.Observable.

In a more general perspective, we could build this part of our software system by exploiting the Dependency Injection pattern.

#### 3.2.1 Dependency injection and Inversion of Control.

In software engineering, an **injection** is the passing of a dependency to a dependent object (a client) that would use it as a service. In the **dependency injection** pattern, passing the service to the client, rather than allowing a client to build or find the service, is the fundamental requirement.

Dependency injection is one form of the broader technique of Inversion of Control. The client delegates the responsibility of providing its dependencies to external code (the injector). The client is not allowed to call the injector code.

#### 3.3 From a BLS local system to a BLS distributed



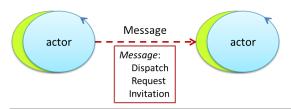
# 4 Evolving the BLS into a distributed, event-driven system

The author of section is Angelo Croatti.

Project it.unibo.bls.oo/it.unibo.bls.vertx on https://github.com/anatali/IotUniboDemo



## 5 Evolving the BLS into a message-driven (AKKA) system



The author of section is Angelo Croatti.

Project ... on https://github.com/anatali/IotUniboDemo

## 6 Evolving the BLS into a RESTful system

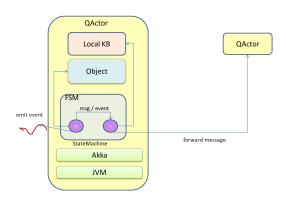
The author of section is Roberto Casadei.

Projects it.unibo.bls.oo/it.unibo.bls.spring.ledService,
it.unibo.bls.oo/it.unibo.bls.spring.buttonService
on https://github.com/anatali/IotUniboDemo

# 7 Evolving the BLS into a message-based, distributed heterogeneous system



**Events** can be emitted by *asynchronous operations* write on a file send a request



# 8 Devices as microservices

Deepened in BBS-module7 : Web and Mobile.